

Oracle® Solaris Studio 12.2: C++ User's Guide

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Preface

The *Oracle Solaris Studio 12.2 C++ User's Guide* describes the environment and command-line options for the Oracle Solaris Studio C++ compiler, **CC**.

This guide is intended for application developers with a working knowledge of the C++ language and Solaris or Linux operating environments who want to learn how to use the Solaris Studio C++ compiler effectively.

Supported Platforms

This Oracle Solaris Studio release supports systems that use the SPARC and x86 families of processor architectures: UltraSPARC, SPARC64, AMD64, Pentium, and Xeon EM64T. The supported systems for the version of the Oracle Solaris operating system you are running are available in the hardware compatibility lists at <http://www.oracle.com/webfolder/technetwork/hcl/index.html>. These documents cite any implementation differences between the platform types.

In this document, these x86 related terms mean the following:

- “x86” refers to the larger family of 64-bit and 32-bit x86 compatible products.
- “x64” points out specific 64-bit information about AMD64 or EM64T systems.
- “32-bit x86” points out specific 32-bit information about x86 based systems.

For supported systems, see the hardware compatibility lists.

Accessing Solaris Studio Documentation

You can access the documentation at the following locations:

- The documentation is available from the documentation index page at <http://www.oracle.com/technetwork/server-storage/solarisstudio/documentation>.
- Online help for all components of the IDE, the Performance Analyzer, dbxtool, and DLight, is available through the Help menu, as well as through the F1 key and Help buttons on many windows and dialog boxes, in these tools.

Documentation in Accessible Formats

The documentation is provided in accessible formats that are readable by assistive technologies for users with disabilities. You can find accessible versions of documentation as described in the following table.

Type of Documentation	Format and Location of Accessible Version
Manuals	HTML from the Oracle Solaris Studio 12.2 collection on OTN
<i>What's New in The Oracle Solaris Studio 12.2 Release</i> (formerly the component README files)	HTML from the Oracle Solaris Studio 12.2 collection on OTN
Man pages	Displayed in an Oracle Solaris terminal using the man command
Online help	HTML available through the Help menu, Help buttons, and F1 key in the IDE, dbxtool, DLight, and the Performance Analyzer
Release notes	HTML from the Oracle Solaris Studio 12.2 collection on OTN

Related Third-Party Web Site References

Third-party URLs are referenced in this document and provide additional, related information.

Note – Oracle is not responsible for the availability of third-party web sites mentioned in this document. Oracle does not endorse and is not responsible or liable for any content, advertising, products, or other materials that are available on or through such sites or resources. Oracle will not be responsible or liable for any actual or alleged damage or loss caused or alleged to be caused by or in connection with use of or reliance on any such content, goods, or services that are available on or through such sites or resources.

Resources for Developers

Visit <http://www.oracle.com/technetwork/server-storage/solarisstudio> to find these frequently updated resources:

- Articles on programming techniques and best practices
- Documentation of the software, as well as corrections to the documentation that is installed with your software
- Tutorials that take you step-by-step through development tasks using Oracle Solaris Studio tools
- Information on support levels

- User forums at <http://forums.oracle.com/forums/category.jspa?categoryID=280>

Typographic Conventions

The following table describes the typographic conventions that are used in this book.

TABLE P-1 Typographic Conventions

Typeface	Meaning	Example
AaBbCc123	The names of commands, files, and directories, and onscreen computer output	Edit your <code>.login</code> file. Use <code>ls -a</code> to list all files. <code>machine_name% you have mail.</code>
AaBbCc123	What you type, contrasted with onscreen computer output	<code>machine_name% su</code> Password:
<i>aabbcc123</i>	Placeholder: replace with a real name or value	The command to remove a file is <i>rm filename</i> .
<i>AaBbCc123</i>	Book titles, new terms, and terms to be emphasized	Read Chapter 6 in the <i>User's Guide</i> . <i>A cache</i> is a copy that is stored locally. Do <i>not</i> save the file. Note: Some emphasized items appear bold online.

Shell Prompts in Command Examples

The following table shows the default UNIX system prompt and superuser prompt for shells that are included in the Oracle Solaris OS. Note that the default system prompt that is displayed in command examples varies, depending on the Oracle Solaris release.

TABLE P-2 Shell Prompts

Shell	Prompt
Bash shell, Korn shell, and Bourne shell	\$
Bash shell, Korn shell, and Bourne shell for superuser	#
C shell	machine_name%
C shell for superuser	machine_name#

Documentation and Support

See the following web sites for additional resources:

- [Documentation \(http://www.oracle.com/technetwork/indexes/documentation/index.html\)](http://www.oracle.com/technetwork/indexes/documentation/index.html)
- [Support \(http://www.oracle.com/us/support/systems/index.html\)](http://www.oracle.com/us/support/systems/index.html)

Oracle Software Resources

[Oracle Technology Network \(http://www.oracle.com/technetwork/index.html\)](http://www.oracle.com/technetwork/index.html) offers a range of resources related to Oracle software:

- Discuss technical problems and solutions on the [Discussion Forums \(http://forums.oracle.com\)](http://forums.oracle.com).
- Get hands-on step-by-step tutorials with [Oracle By Example \(http://www.oracle.com/technetwork/tutorials/index.html\)](http://www.oracle.com/technetwork/tutorials/index.html).

Oracle Welcomes Your Comments

Oracle welcomes your comments and suggestions on the quality and usefulness of its documentation. If you find any errors or have any other suggestions for improvement, send feedback to **solaris-studio-doc-feedback_ww@oracle.com**. Indicate the title and part number of the documentation along with the chapter, section, and page number, if available. Please let us know if you want a reply.

[Oracle Technology Network \(http://www.oracle.com/technetwork/index.html\)](http://www.oracle.com/technetwork/index.html) offers a range of resources related to Oracle software:

- Discuss technical problems and solutions on the [Discussion Forums \(http://forums.oracle.com\)](http://forums.oracle.com).
- Get hands-on step-by-step tutorials with [Oracle By Example \(http://www.oracle.com/technology/obe/start/index.html\)](http://www.oracle.com/technology/obe/start/index.html).
- Download [Sample Code \(http://www.oracle.com/technology/sample_code/index.html\)](http://www.oracle.com/technology/sample_code/index.html).

PART I

C++ Compiler

The C++ Compiler

This chapter provides general information about the current Solaris Studio C++ compiler.

1.1 New Features and Functionality of the Solaris Studio 12.2 C++ 5.11 Compiler

This section provides a summary list of the new and changed features and functionality introduced in the Solaris Studio 12.2 C++ 5.11 Compiler release.

- The `-g` option with any `-O` option or `-x0` option enables inlining. ([“A.2.30 –g” on page 232](#))
- The C++ option `-xalias_level=compatible` asserts that the program meets the requirements of the C++ standard. ([“A.2.106 -xalias_level\[=n\]” on page 266](#))
- Support has been added for the Apache C++ library installed in Oracle Solaris. ([“A.2.49 -library=l\[,l...\]” on page 242](#))
- `-compat=g` option provides some compatibility with Gnu g++. ([“A.2.6 –compat\[={4|5|g}\]” on page 207](#))
- The `-features=[no%]rvalue_ref` option overrides certain compiler checks. ([“A.2.18 –features=a\[,a...\]” on page 218](#))
- Added support for the SPARC VIS3 version of the SPARC-V9 ISA. Compiling with the `-xarch=sparcvis3` option enables the compiler to use instructions from the SPARC-V9 instruction set, plus the UltraSPARC and UltraSPARC-III extensions, the fused multiply-add instructions, and the Visual Instruction Set (VIS) version 3.0. ([“A.2.109 –xarch=isa” on page 269](#))
- The default for the `-xvector` option has changed on x86-based systems to `-xvector=simd`. ([“A.2.187 -xvector\[=a\]” on page 344](#))
- Support for the AMD SSE4a instruction set is now available with the `-xarch=amdsse4a` option. ([“A.2.109 –xarch=isa” on page 269](#))

- The `-t traceback` option enables an executable to print a stack trace if a severe error occurs. (“A.2.94 `-t traceback`[=`{%none|common|signals_list}`]” on page 261)
- The `-mt` option has been changed to `-mt=yes` or `-mt=no`. (“A.2.55 `-mt`[=`{yes|no}`]” on page 248)
- The `#warning` compiler directive issues the text in the directive as a warning and continues compilation. (“2.5.4 Warnings and Errors” on page 39)
- New pragmas `does_not_read_global_data`, `does_not_write_global_data`, and `no_side_effect`. (“2.5.1 Pragmas” on page 38)
- The header file `mbarrier.h` is now available. It defines various memory barrier intrinsics for multithreaded code on SPARC and x86 processors. (“10.5 Memory Barrier Intrinsics” on page 126)
- The `-xprofile=tcov` option has been enhanced to support an optional profile directory pathname, and the ability to generate `tcov`-compatible feedback data. (“A.2.170 `-xprofile=p`” on page 327)
- In this release, the dependency file written by the `-xMD` and `-xMMD` options (C/C++) overwrites any previously existing file. (“A.2.146 `-xMD`” on page 304)

1.2 Special x86 Notes

There are some important issues to be aware of when compiling for x86 Solaris platforms.

The legacy Sun-style parallelization pragmas are no longer available on any platform. Use OpenMP instead. See the *Solaris Studio 12.2: OpenMP API User's Guide* for information on converting legacy parallelization directives to OpenMP.

Programs compiled with `-xarch` set to `sse`, `sse2`, `sse2a`, `sse3`, or beyond must be run only on platforms that provide these extensions and features.

Solaris OS releases starting with Solaris 9 4/04 are SSE/SSE2-enabled on Pentium 4-compatible platforms. Earlier versions of Solaris OS are not SSE/SSE2-enabled. If an instruction set selected by `-xarch` is not enabled in the running Solaris OS, the compiler will not be able to generate or link code for that instruction set.

If you compile and link in separate steps, always link using the compiler and with same `-xarch` setting to ensure that the correct startup routine is linked.

Numerical results on x86 might differ from results on SPARC due to the x86 80-bit floating-point registers. To minimize these differences, use the `-fstore` option or compile with `-xarch=sse2` if the hardware supports SSE2.

Numerical results can also differ between Solaris and Linux because the intrinsic math libraries (for example, `sin(x)`) are not the same.

1.3 Compiling for 64–Bit Platforms

Use the `-m32` option to compile for the ILP32 32-bit model. Use the `-m64` option to compile for the LP64 64-bit model.

The ILP32 model specifies that C++-language `int`, `long`, and pointer data types are all 32-bits wide. The LP64 model specifies that `long` and pointer data types are all 64-bits wide. The Solaris and Linux OS also support large files and large arrays under the LP64 memory model.

When you compile with `-m64`, the resulting executable works only on 64-bit UltraSPARC or x86 processors under Solaris OS or Linux OS running a 64-bit kernel. Compilation, linking, and execution of 64-bit objects can only take place in a Solaris or Linux OS that supports 64-bit execution.

1.4 Binary Compatibility Verification

On Solaris systems, beginning with Sun Studio 11, program binaries compiled with the Solaris Studio compilers are marked with architecture hardware flags indicating the instruction sets assumed by the compiled binary. At runtime these marker flags are checked to verify that the binary can run on the hardware it is attempting to execute on.

If a program does not contain these architecture hardware flags, or if the platform does not enable the appropriate features or instruction set extensions, running the program could result in segmentation faults or incorrect results without any explicit warning messages.

This warning extends also to programs that employ `.i1` inline assembly language functions or `__asm()` assembler code that utilize SSE, SSE2, SSE2a, and SSE3 and newer instructions and extensions.

1.5 Standards Conformance

The C++ compiler (CC) supports the ISO International Standard for C++, ISO IS 14882:2003, *Programming Language—C++*. The readme file that accompanies the current release describes any departures from requirements in the standard.

On SPARC platforms, the compiler provides support for the optimization-exploiting features of SPARC V8 and SPARC V9, including the UltraSPARC implementation. These features are defined in the SPARC Architecture Manuals, Version 8 (ISBN 0-13-825001-4), and Version 9 (ISBN 0-13-099227-5), published by Prentice-Hall for SPARC International.

In this document, “Standard” means conforming to the versions of the standards listed above. “Nonstandard” or “Extension” refers to features that go beyond these versions of these standards.

The responsible standards bodies may revise these standards from time to time. The versions of the applicable standards to which the C++ compiler conforms may be revised or replaced, resulting in features in future releases of the Solaris Studio C++ compiler that create incompatibilities with earlier releases.

1.6 C++ Readme File

The C++ compiler's readme file highlights important information about the compiler. It is now part of the *What's New In Oracle Solaris Studio 12.2* guide and includes:

- Information discovered after the manuals were printed
- New and changed features
- Software corrections
- Problems and workarounds
- Limitations and incompatibilities
- Shippable libraries
- Standards not implemented

The *What's New* guide can be found on the documentation index page for this release at <http://www.oracle.com/technetwork/server-storage/solarisstudio/documentation>

1.7 Man Pages

Online manual (man) pages provide immediate documentation about a command, function, subroutine, or collection of such things.

You can display a man page by running the command:

```
example% man topic
```

Throughout the C++ documentation, man page references appear with the topic name and man section number: CC(1) is accessed with `man CC`. Sections other than 1 (`ieee_flags(3M)` for example) would be accessed with the `-s` option on the man command as follows:

```
example% man -s 3M ieee_flags
```

1.8 Native-Language Support

This release of C++ supports the development of applications in languages other than English, including most European languages, Chinese, and Japanese. As a result, you can easily switch your application from one native language to another. This feature is known as *internationalization*.

In general, the C++ compiler implements internationalization as follows:

- C++ recognizes ASCII characters from international keyboards (in other words, it has keyboard independence and is 8-bit clean).
- C++ allows the printing of some messages in the native language.
- C++ allows native-language characters in comments, strings, and data.
- C++ supports only Extended UNIX Character (EUC) compliant character sets which are character sets in which every null byte in a string is the null character and every byte in the string with the ASCII value of / is the / character.

Variable names cannot be internationalized and must be in the English character set.

You can change your application from one native language to another by setting the locale. For information on this and other native-language support features, see the operating system documentation.

Using the C++ Compiler

This chapter describes how to use the C++ compiler.

The principal use of any compiler is to transform a program written in a high-level language like C++ into a data file that is executable by the target computer hardware. You can use the C++ compiler to do the following:

- Transform source files into relocatable binary (.o) files, to be linked later into an executable file, a static (archive) library (.a) file (using `-xar`), or a dynamic (shared) library (.so) file
- Link or relink object files or library files (or both) into an executable file
- Compile an executable file with runtime debugging enabled (`-g`)
- Compile an executable file with runtime statement or procedure-level profiling (`-pg`)

2.1 Getting Started

This section gives you a brief overview of how to use the C++ compiler to compile and run C++ programs. See [Appendix A, “C++ Compiler Options,”](#) for a full reference to the command-line options.

Note – The command-line examples in this chapter show CC usages. Printed output might be slightly different.

The basic steps for building and running a C++ program involve:

1. Using an editor to create a C++ source file with one of the valid suffixes listed in [Table 2–1](#)
2. Invoking the compiler to produce an executable file
3. Launching the program into execution by typing the name of the executable file

The following program displays a message on the screen:

```
example% cat greetings.cc
#include <iostream>
int main() {
    std::cout << "Real programmers write C++!" << std::endl;
    return 0;
}
example% CC greetings.cc
example% ./a.out
Real programmers write C++!
example%
```

In this example, `CC` compiles the source file `greetings.cc` and, by default, compiles the executable program onto the file, `a.out`. To launch the program, type the name of the executable file, `a.out`, at the command prompt.

Traditionally, UNIX compilers name the executable file `a.out`. It can be awkward to have each compilation write to the same file. Moreover, if such a file already exists, it will be overwritten the next time you run the compiler. Instead, use the `-o` compiler option to specify the name of the executable output file, as in the following example:

```
example% CC- o greetings greetings.cc
```

In this example, the `-o` option tells the compiler to write the executable code to the file `greetings`. (It is common to give a program consisting of a single source file the name of the source file without the suffix.)

Alternatively, you could rename the default `a.out` file using the `mv` command after each compilation. Either way, run the program by typing the name of the executable file:

```
example% ./greetings
Real programmers write C++!
example%
```

2.2 Invoking the Compiler

The remainder of this chapter discusses the conventions used by the `CC` command, compiler source line directives, and other issues concerning the use of the compiler.

2.2.1 Command Syntax

The general syntax of a compiler command line is as follows:

```
CC [options] [source-files] [object-files] [libraries]
```

An *option* is an option keyword prefixed by either a dash (`-`) or a plus sign (`+`). Some options take arguments.

In general, the processing of the compiler options is from left to right, allowing selective overriding of macro options (options that include other options). In most cases, if you specify the same option more than once, the rightmost assignment overrides and there is no accumulation. Note the following exceptions:

- All linker options and the `-features`, `-I`, `-l`, `-L`, `-library`, `-pti`, `-R`, `-staticlib`, `-U`, `-verbose`, `-xdumpmacros`, and `-xprefetch` options accumulate, they do not override.
- All `-U` options are processed after all `-D` options.

Source files, object files, and libraries are compiled and linked in the order in which they appear on the command line.

In the following example, `CC` is used to compile two source files (`growth.C` and `fft.C`) to produce an executable file named `growth` with runtime debugging enabled:

```
example% CC -g -o growth growth.C fft.C
```

2.2.2 File Name Conventions

The suffix attached to a file name appearing on the command line determines how the compiler processes the file. A file name with a suffix other than those listed in the following table, or without a suffix, is passed to the linker.

TABLE 2-1 File Name Suffixes Recognized by the C++ Compiler

Suffix	Language	Action
.c	C++	Compile as C++ source files, put object files in current directory; default name of object file is that of the source but with an .o suffix.
.C	C++	Same action as .c suffix.
.cc	C++	Same action as .c suffix.
.cpp	C++	Same action as .c suffix.
.cxx	C++	Same action as .c suffix.
.c++	C++	Same action as .c suffix.
.i	C++	Preprocessor output file treated as C++ source file. Same action as .c suffix.
.s	Assembler	Assemble source files using the assembler.
.S	Assembler	Assemble source files using both the C language preprocessor and the assembler.

TABLE 2-1 File Name Suffixes Recognized by the C++ Compiler (Continued)

Suffix	Language	Action
.i1	Inline expansion	Process assembly inline-template files for inline expansion. The compiler will use templates to expand inline calls to selected routines. (Inline-template files are special assembler files. See the <code>inline(1)</code> man page.)
.o	Object files	Pass object files through to the linker.
.a	Static (archive) library	Pass object library names to the linker.
.so .so.n	Dynamic (shared) library	Pass names of shared objects to the linker.

2.2.3 Using Multiple Source Files

The C++ compiler accepts multiple source files on the command line. A single source file compiled by the compiler, together with any files that it directly or indirectly supports, is referred to as a *compilation unit*. C++ treats each source as a separate compilation unit.

2.3 Compiling With Different Compiler Versions

This compiler does not use the cache by default. It only uses the cache if you specify `-instances=extern`. If the compiler makes use of the cache, it checks the cache directory's version and issues error messages whenever it encounters cache version problems. Future C++ compilers will also check cache versions. For example, a future compiler that has a different template cache version identification and that processes a cache directory produced by this release of the compiler might issue an error that is similar to the following message:

```
Template Database at ./SunWS_cache is incompatible with
this compiler
```

Similarly, the compiler issues an error if it encounters a cache directory that was produced by a later version of the compiler.

When you upgrade your compiler, it is always good practice to clean the cache. Run `CCadmin -clean` on every directory that contains a template cache directory (in most cases, a template cache directory is named `SunWS_cache`). Alternatively, you can use `rm -rf SunWS_cache`.

2.4 Compiling and Linking

This section describes some aspects of compiling and linking programs. In the following example, `CC` is used to compile three source files and to link the object files to produce an executable file named `prgrm`.

```
example% CC file1.cc file2.cc file3.cc -o prgrm
```

2.4.1 Compile-Link Sequence

In the previous example, the compiler automatically generates the loader object files (`file1.o`, `file2.o` and `file3.o`) and then invokes the system linker to create the executable program for the file `prgrm`.

After compilation, the object files (`file1.o`, `file2.o`, and `file3.o`) remain. This convention permits you to easily relink and recompile your files.

Note – If only one source file is compiled and a program is linked in the same operation, the corresponding `.o` file is deleted automatically. To preserve all `.o` files, do not compile and link in the same operation unless more than one source file gets compiled.

If the compilation fails, you will receive a message for each error. No `.o` files are generated for those source files with errors, and no executable program is written.

2.4.2 Separate Compiling and Linking

You can compile and link in separate steps. The `-c` option compiles source files and generates `.o` object files, but does not create an executable. Without the `-c` option, the compiler invokes the linker. By splitting the compile and link steps, a complete recompilation is not needed just to fix one file. The following example shows how to compile one file and link with others in separate steps:

```
example% CC -c file1.cc           Make new object file
example% CC -o prgrm file1.o file2.o file3.o   Make executable file
```

Be sure that the link step lists *all* the object files needed to make the complete program. If any object files are missing from this step, the link will fail with “undefined external reference” errors (missing routines).

2.4.3 Consistent Compiling and Linking

If you compile and link in separate steps, consistent compiling and linking is critical when using the compiler options listed in “3.3.3 Compile-Time and Link-Time Options” on page 48.

If you compile a subprogram using any of these options, you must link using the same option as well:

- If you compile with the `-library` or `-m64/-m32` options, you must include these same options on all CC commands.
- With `-p`, `-xpg`, and `-xprofile`, including the option in one phase and excluding it from the other phase will not affect the correctness of the program, but you will not be able to do profiling.
- With `-g` and `-g0`, including the option in one phase and excluding it from the other phase will not affect the correctness of the program, but it will affect the ability to debug the program. Any module that is not compiled with either of these options, but is linked with `-g` or `-g0` will not be prepared properly for debugging. Note that compiling the module that contains the function `main` with the `-g` option or the `-g0` option is usually necessary for debugging.

In the following example, the programs are compiled using the `-library=stlport4` compiler option.

```
example% CC -library=stlport4 sbr.cc -c
example% CC -library=stlport4 main.cc -c
example% CC -library=stlport4 sbr.o main.o -o myprogram
```

If you do not use `-library=stlport4` consistently, some parts of the program will use the default `libcstd`, and others will use the optional replacement STLport library. The resulting program might not link, and would not in any case run correctly.

If the program uses templates, it is possible that some templates might get instantiated at link time. In that case, the command-line options from the last line (the link line) will be used to compile the instantiated templates.

2.4.4 Compiling for 64–Bit Memory Model

Use the new `-m64` option to specify the memory model of the target compilation. The resulting executable will work only on 64-bit UltraSPARC or x86 processors under Solaris OS or Linux OS running a 64-bit kernel. Compilation, linking, and execution of 64-bit objects can only take place in a Solaris or Linux OS that supports 64-bit execution.

2.4.5 Compiler Command-Line Diagnostics

The `-v` option displays the name and version number of each program invoked by CC. The `-v` option displays the full command lines invoked by CC.

The `-verbose=all` displays additional information about the compiler.

Any arguments on the command line that the compiler does not recognize are interpreted as linker options, object program file names, or library names.

The basic distinctions are:

- Unrecognized *options*, which are preceded by a dash (–) or a plus sign (+), generate warnings.
- Unrecognized *nonoptions*, which are not preceded by a dash or a plus sign, generate no warnings. (However, they are passed to the linker. If the linker does not recognize them, they generate linker error messages.)

In the following example, note that `-bit` is not recognized by CC and the option is passed on to the linker (`ld`), which tries to interpret it. Because single letter `ld` options can be strung together, the linker sees `-bit` as `-b -i -t`, all of which are legitimate `ld` options. This might not be what you intend or expect:

```
example% CC -bit move.cc                < -bit is not a recognized CC option
```

```
CC: Warning: Option -bit passed to ld, if ld is invoked, ignored otherwise
```

In the next example, the user intended to type the CC option `-fast` but omitted the leading dash. The compiler again passes the argument to the linker, which in turn interprets it as a file name:

```
example% CC fast move.cc                < - The user meant to type -fast
```

```
move.CC:
```

```
ld: fatal: file fast: cannot open file; errno=2
```

```
ld: fatal: File processing errors. No output written to a.out
```

2.4.6 Understanding the Compiler Organization

The C++ compiler package consists of a front end, optimizer, code generator, assembler, template prelinker, and link editor. The CC command invokes each of these components automatically unless you use command-line options to specify otherwise.

Because any of these components may generate an error, and the components perform different tasks, it may be helpful to identify the component that generates an error. Use the `-v` and `-dryrun` options to help with this.

As shown in the following table, input files to the various compiler components have different file name suffixes. The suffix establishes the kind of compilation that is done. Refer to [Table 2–1](#) for the meanings of the file suffixes.

TABLE 2–2 Components of the C++ Compilation System

Component	Description	Notes on Use
ccfe	Front end (compiler preprocessor and compiler)	
iropt	Code optimizer	-x0[2-5], -fast

TABLE 2-2 Components of the C++ Compilation System (Continued)

Component	Description	Notes on Use
ir2hf	x86: Intermediate language translator	-x0[2-5], -fast
inline	SPARC: Inline expansion of assembly language templates	.il file specified
fbe	Assembler	
cg	SPARC: Code generator, inliner, assembler	
ube	x86: Code generator	-x0[2-5], -fast
CCLink	Template pre-linker	used only with the -instances=extern option
ld	link editor	

2.5 Preprocessing Directives and Names

This section discusses information about preprocessing directives that is specific to the C++ compiler.

2.5.1 Pragmas

The preprocessor directive `pragma` is part of the C++ standard but the form, content, and meaning of pragmas is different for every compiler. See [Appendix B, “Pragmas,”](#) for details on the pragmas that the C++ compiler recognizes.

Solaris Studio C++ also supports the C99 keyword `_Pragma`. The following two invocations are equivalent:

```
#pragma dumpmacros(defs)
_Pragma("dumpmacros(defs)")
```

To use `_Pragma` instead of `#pragma`, write the pragma text as a literal string enclosed in parentheses as the one argument of the `_Pragma` keyword.

2.5.2 Macros With a Variable Number of Arguments

The C++ compiler accepts `#define` preprocessor directives of the following form.

```
#define identifier (...) replacement_list
#define identifier (identifier_list, ...) replacement_list
```

If the macro parameter list ends with an ellipsis, an invocation of the macro is allowed to have more arguments than there are macro parameters. The additional arguments are collected into a single string, including commas, that can be referenced by the name `__VA_ARGS__` in the macro replacement list. The following example demonstrates how to use a variable-argument-list macro.

```
#define debug(...) fprintf(stderr, __VA_ARGS__)
#define showlist(...) puts(__VA_ARGS__)
#define report(test, ...) ((test)?puts(#test):\
                          printf(__VA_ARGS__))

debug("Flag");
debug("X = %d\n",x);
showlist(The first, second, and third items.);
report(x>y, "x is %d but y is %d", x, y);
```

which results in the following:

```
fprintf(stderr, "Flag");
fprintf(stderr, "X = %d\n", x);
puts("The first, second, and third items.");
((x>y)?puts("x>y"):printf("x is %d but y is %d", x, y));
```

2.5.3 Predefined Names

[“A.2.8 -Dname\[=def\]” on page 210](#) in the appendix shows the predefined macros. You can use these values in such preprocessor conditionals as `#ifdef`. The `+p` option prevents the automatic definition of the `sun`, `unix`, `sparc`, and `i386` predefined macros.

2.5.4 Warnings and Errors

The `#error` and `#warning` preprocessor directives can be used to generate compile-time diagnostics.

```
#error token-string      Issue error diagnostic token-string and terminate compilation
#warning token-string   Issue warning diagnostic token-string and continue compilation.
```

2.6 Memory Requirements

The amount of memory a compilation requires depends on several parameters, including:

- Size of each procedure
- Level of optimization
- Limits set for virtual memory
- Size of the disk swap file

On the SPARC platform, if the optimizer runs out of memory, it tries to recover by retrying the current procedure at a lower level of optimization. The optimizer then resumes subsequent routines at the original level specified in the `-x0level` option on the command line.

If you compile a single source file that contains many routines, the compiler might run out of memory or swap space. Try reducing the level of optimization. Alternately, split the largest procedures into separate files of their own.

2.6.1 Swap Space Size

The `swap -s` command displays available swap space. See the `swap(1M)` man page for more information.

The following example demonstrates the use of the `swap` command:

```
example% swap -s
total: 40236k bytes allocated + 7280k reserved = 47516k used, 1058708k available
```

2.6.2 Increasing Swap Space

Use `mkfile(1M)` and `swap (1M)` to increase the size of the swap space on a workstation. (You must become superuser to do this.) The `mkfile` command creates a file of a specific size, and `swap -a` adds the file to the system swap space:

```
example# mkfile -v 90m /home/swapfile
/home/swapfile 94317840 bytes
example# /usr/sbin/swap -a /home/swapfile
```

2.6.3 Control of Virtual Memory

Compiling very large routines (thousands of lines of code in a single procedure) at `-x03` or higher can require a large amount of memory. In such cases, performance of the system might degrade. You can control this by limiting the amount of virtual memory available to a single process.

To limit virtual memory in an `sh` shell, use the `ulimit` command. See the `sh(1)` man page for more information.

The following example shows how to limit virtual memory to 4 Gbytes:

```
example$ ulimit -d 4000000
```


In a `cs` shell, use the `limit` command to limit virtual memory. See the `cs(1)` man page for more information.

The next example also shows how to limit virtual memory to 4 Gbytes:

```
example% limit datasize 4G
```

Each of these examples causes the optimizer to try to recover at 4 Gbytes of data space.

The limit on virtual memory cannot be greater than the system's total available swap space and, in practice, must be small enough to permit normal use of the system while a large compilation is in progress.

Be sure that no compilation consumes more than half the swap space.

With 8 Gbytes of swap space, use the following commands:

In an `sh` shell:

```
example$ ulimit -d 4000000
```

In a `cs` shell:

```
example% limit datasize 4G
```

The best setting depends on the degree of optimization requested and the amount of real memory and virtual memory available.

2.6.4 Memory Requirements

A workstation should have at least 2 gigabytes of memory. See the product release notes for detailed requirements.

2.7 Using the `strip` Command with C++ Objects

The Unix `strip` command should not be used with C++ object files, as it can render those object files unusable.

2.8 Simplifying Commands

You can simplify complicated compiler commands by defining special shell aliases, using the `CCFLAGS` environment variable, or by using `make`.

2.8.1 Using Aliases Within the C Shell

The following example defines an alias for a command with frequently used options.

```
example% alias CCfx "CC -fast -xnoibmil"
```

The next example uses the alias `CCfx`.

```
example% CCfx any.C
```

The command `CCfx` is now the same as:

```
example% CC -fast -xnoibmil any.C
```

2.8.2 Using `CCFLAGS` to Specify Compile Options

You can specify options by setting the `CCFLAGS` variable.

The `CCFLAGS` variable can be used explicitly in the command line. The following example shows how to set `CCFLAGS` (C Shell):

```
example% setenv CCFLAGS '-x02 -m64'
```

The next example uses `CCFLAGS` explicitly.

```
example% CC $CCFLAGS any.cc
```

When you use `make`, if the `CCFLAGS` variable is set as in the preceding example and the `makefile`'s compilation rules are implicit, then invoking `make` will result in a compilation equivalent to:

```
CC -x02 -m64 files...
```

2.8.3 Using `make`

The `make` utility is a very powerful program development tool that you can easily use with all Solaris Studio compilers. See the `make(1S)` man page for additional information.

2.8.3.1 Using CCFLAGS Within make

When you are using the *implicit* compilation rules of the makefile (that is, there is no C++ compile line), the make program uses CCFLAGS automatically.

Using the C++ Compiler Options

This chapter explains how to use the command-line C++ compiler options and then summarizes their use by function. Detailed explanations of the options are provided in “A.2 Option Reference” on page 204.

3.1 Syntax Overview

The following table shows examples of typical option syntax formats that are used in this book.

TABLE 3-1 Option Syntax Format Examples

Syntax Format	Example
-option	-E
-optionvalue	-Ipathname
-option=value	-xunroll=4
-option value	-o filename

Parentheses, braces, brackets, pipe characters, and ellipses are *metacharacters* used in the descriptions of the options and are not part of the options themselves. See the typographical conventions in the Preface to this manual for a detailed explanation of the usage syntax.

3.2 General Guidelines

Some general guidelines for the C++ compiler options are:

- The `-lib` option links with library `liblib.a` (or `liblib.so`). It is always safer to put `-lib` after the source and object files to ensure the order in which libraries are searched.
- In general, processing of the compiler options is from left to right (with the exception that `-U` options are processed after all `-D` options), allowing selective overriding of macro options (options that include other options). This rule does not apply to linker options.
- The `-features`, `-I-l`, `-L`, `-library`, `-pti`, `-R`, `-staticlib`, `-U`, `-verbose`, and `-xprefetch` options accumulate, they do not override.
- The `-D` option accumulates. However, multiple `-D` options for the same name override each other.

Source files, object files, and libraries are compiled and linked in the order in which they appear on the command line.

3.3 Options Summarized by Function

In this section, the compiler options are grouped by function to provide a quick reference. For a detailed description of each option, refer to [Appendix A, “C++ Compiler Options.”](#)

The options apply to all platforms except as noted; features that are unique to the Solaris OS on SPARC-based systems are identified as *SPARC*, and the features that are unique to the Solaris OS on x86-based systems are identified as *x86*.

3.3.1 Code Generation Options

TABLE 3-2 Code Generation Options

Option	Action
<code>-compat</code>	Sets the major release compatibility mode of the compiler.
<code>+e{0 1}</code>	Controls virtual table generation.
<code>-g</code>	Compiles for use with the debugger.
<code>-KPIC</code>	Produces position-independent code.
<code>-Kpic</code>	Produces position-independent code.
<code>-mt</code>	Compiles and links for multithreaded code.
<code>-xaddr32</code>	Restrict code to 32-bit address space (x86/x64)

TABLE 3-2 Code Generation Options (Continued)

Option	Action
-xarch	Specify target architecture.
-xcode= <i>a</i>	(SPARC) Specifies the code address space.
-xMerge	(SPARC) Merges the data segment with the text segment.
-xtarget	Specify target system.
-xmodel	Modifies the form of 64-bit objects for the Solaris x86 platforms
+w	Identifies code that might have unintended consequences.
+w2	Emits all the warnings emitted by +w plus warnings about technical violations that are probably harmless, but that might reduce the maximum portability of your program.
-xregs	The compiler can generate faster code if it has more registers available for temporary storage (scratch registers). This option makes available additional scratch registers that might not always be appropriate.
-z <i>arg</i>	Linker option.

3.3.2 Compile-Time Performance Options

TABLE 3-3 Compile-Time Performance Options

Option	Action
-instlib	Inhibits the generation of template instances that are already present in the designated library.
-m32 -m64	Specifies the memory model for the compiled binary object.
-xinstrument	Compiles and instruments your program for analysis by the Thread Analyzer.
-xjobs	Sets the number of processes the compiler can create to complete its work.
-xpch	May reduce compile time for applications whose source files share a common set of include files.
-xpchstop	Specifies the last include file to be considered in creating a pre-compiled header file with -xpch.
-xprofile_ircache	(SPARC) Reuses compilation data saved during -xprofile=collect.

TABLE 3-3 Compile-Time Performance Options (Continued)

Option	Action
-xprofile_pathmap	(SPARC) Support for multiple programs or shared libraries in a single profile directory.

3.3.3 Compile-Time and Link-Time Options

The following table lists the options that must be specified both at link-time and at compile-time.

TABLE 3-4 Compile-Time and Link-Time Options

Option	Action
-fast	Selects the optimum combination of compilation options for speed of executable code.
-m32 -m64	Specifies the memory model for the compiled binary object.
-mt	Macro option that expands to -D_REENTRANT -pthread.
-xarch	Specify instruction set architecture.
-xautopar	Turns on automatic parallelization for multiple processors.
-xhwcprof	(SPARC) Enables compiler support for hardware counter-based profiling.
-xipo	Performs whole-program optimizations by invoking an interprocedural analysis component.
-xlinkopt	Performs link-time optimizations on relocatable object files.
-xmemalign	(SPARC) Specify maximum assumed memory alignment and behavior of misaligned data accesses.
-xopenmp	Supports the OpenMP interface for explicit parallelization including a set of source code directives, run-time library routines, and environment variables
-xpagesize	Sets the preferred page size for the stack and the heap.
-xpagesize_heap	Sets the preferred page size for the heap.
-xpagesize_stack	Sets the preferred page size for the stack.
-xpg	Prepares the object code to collect data for profiling with gprof(1).

TABLE 3-4 Compile-Time and Link-Time Options (Continued)

Option	Action
-xprofile	Collects data for a profile or uses a profile to optimize.
-xvector=lib	Enable automatic generation of calls to the vector library functions.

3.3.4 Debugging Options

TABLE 3-5 Debugging Options

Option	Action
+d	Does not expand C++ inline functions.
-dryrun	Shows options passed by the driver to the compiler, but does not compile.
-E	Runs only the preprocessor on the C++ source files and sends result to stdout. Does not compile.
-g	Compiles for use with the debugger.
-g0	Compiles for debugging, but doesn't disable inlining.
-H	Prints path names of included files.
-keepmp	Retains temporary files created during compilation.
-migration	Explains where to get information about migrating from earlier compilers.
-P	Only preprocesses source; outputs to .i file.
-Qoption	Passes an option directly to a compilation phase.
-readme	Displays the content of the online README file.
-s	Strips the symbol table out of the executable file, thus preventing the ability to debug code.
-temp=dir	Defines directory for temporary files.
-verbose=vlst	Controls compiler verbosity.
-xcheck	Adds a runtime check for stack overflow.
-xdumpmacros	Prints information about macros such as definition, location defined and undefined, and locations used.
-xe	Only checks for syntax and semantic errors.

TABLE 3-5 Debugging Options (Continued)

Option	Action
<code>-xhelp=flags</code>	Displays a summary list of compiler options.
<code>-xport64</code>	Warns against common problems during a port from a 32-bit architecture to a 64-bit architecture.

3.3.5 Floating-Point Options

TABLE 3-6 Floating-Point Options

Option	Action
<code>-fma</code>	(SPARC) Enables automatic generation of floating-point, fused, multiply-add instructions.
<code>-fns [= {no yes}]</code>	(SPARC) Disables or enables the SPARC nonstandard floating-point mode.
<code>-fprecision=<i>p</i></code>	<i>x86</i> : Sets floating-point precision mode.
<code>-fround=<i>r</i></code>	Sets IEEE rounding mode in effect at startup.
<code>-fsimple=<i>n</i></code>	Sets floating-point optimization preferences.
<code>-fstore</code>	<i>x86</i> : Forces precision of floating-point expressions.
<code>-ftrap=<i>lst</i></code>	Sets IEEE trapping mode in effect at startup.
<code>-nofstore</code>	<i>x86</i> : Disables forced precision of expression.
<code>-xlibmieee</code>	Causes <code>libm</code> to return IEEE 754 values for math routines in exceptional cases.

3.3.6 Language Options

TABLE 3-7 Language Options

Option	Action
<code>-compat</code>	Sets the major release compatibility mode of the compiler.
<code>-features=<i>alst</i></code>	Enables or disables various C++ language features.
<code>-xchar</code>	Eases the migration of code from systems where the <code>char</code> type is defined as unsigned.
<code>-xldscope</code>	Controls the default linker scope of variable and function definitions to create faster and safer shared libraries.

TABLE 3-7 Language Options (Continued)

Option	Action
-xthreadvar	(SPARC) Changes the default thread-local storage access mode.
-xtrigraphs	Enables recognition of trigraph sequences.
-xustr	Enables recognition of string literals composed of sixteen-bit characters.

3.3.7 Library Options

TABLE 3-8 Library Options

Option	Action
-Bbinding	Requests symbolic, dynamic, or static library linking.
-d{y n}	Allows or disallows dynamic libraries for the entire executable.
-G	Builds a dynamic shared library instead of an executable file.
-hname	Assigns an internal name to the generated dynamic shared library.
-i	Tells ld(1) to ignore any LD_LIBRARY_PATH setting.
-Ldir	Adds dir to the list of directories to be searched for libraries.
-llib	Adds liblib.a or liblib.so to the linker's library search list.
-library=llst	Forces inclusion of specific libraries and associated files into compilation and linking.
-mt	Compiles and links for multithreaded code.
-norunpath	Does not build path for libraries into executable.
-Rplst	Builds dynamic library search paths into the executable file.
-staticlib=llst	Indicates which C++ libraries are to be linked statically.
-xar	Creates archive libraries.
-xbuiltin[=opt]	Enables or disables better optimization of standard library calls
-xia	(Solaris) Links the appropriate interval arithmetic libraries and sets a suitable floating-point environment.
-xlang=l[,l]	Includes the appropriate runtime libraries and ensures the proper runtime environment for the specified language.
-xlibmieee	Causes libm to return IEEE 754 values for math routines in exceptional cases.

TABLE 3-8 Library Options (Continued)

Option	Action
-xlibmil	Inlines selected <code>libm</code> library routines for optimization.
-xlibmopt	Uses library of optimized math routines.
-xnolib	Disables linking with default system libraries.
-xnolibmil	Cancels <code>-xlibmil</code> on the command line.
-xnolibmopt	Does not use the math routine library.

3.3.8 Obsolete Options

Note – The following options are either currently obsolete and so no longer accepted by the compiler, or they will be removed in a future release.

TABLE 3-9 Obsolete Options

Option	Action
-library=%all	Obsolete option that will be removed in a future release.
-xlic_lib=sunperf	Use <code>-library=sunperf</code> to link to the Sun Performance Library.
-xlicinfo	Deprecated.
-noqueue	Disables license queueing.
-ptr	Ignored by the compiler. A future release of the compiler may reuse this option using a different behavior.
-sb, -sbfast, -xsb, -xsbfast	Deprecated and silently ignored.
-vdelx	Obsolete option that will be removed in a future release.
-x386	Use an appropriate <code>-xtarget</code> option.
-x486	Use an appropriate <code>-xtarget</code> option.
-xcg89	Use <code>-xtarget=ss2</code>
-xcrossfile	Use <code>-xipo</code> instead.
-xnativeconnect	Obsolete, there is no alternative option.
-xprefetch=yes	Use <code>-xprefetch=auto,explicit</code> instead.
-xprefetch=no	Use <code>-xprefetch=no%auto,no%explicit</code> instead.

TABLE 3-9 Obsolete Options (Continued)

Option	Action
-xvector=yes	Use -xvector=lib instead.
-xvector=no	Use -xvector=none instead.

3.3.9 Output Options

TABLE 3-10 Output Options

Option	Action
-c	Compiles only; produces object (.o) files, but suppresses linking.
-dryrun	Shows all the command lines issued by the driver to the compiler, but does not compile.
-E	Runs only the preprocessor on the C++ source files and sends result to stdout. Does not compile.
-eroff	Suppresses compiler warning messages.
-errtags	Displays the message tag for each warning message.
-errwarn	If the indicated warning message is issued, cc exits with a failure status.
-filt	Suppresses the filtering that the compiler applies to linker error messages.
-G	Builds a dynamic shared library instead of an executable file.
-H	Prints path names of included files.
-migration	Explains where to get information about migrating from earlier compilers.
-o filename	Sets name of the output or executable file to filename.
-P	Only preprocesses source; outputs to .i file.
-Qproduce sourcetype	Causes the CC driver to produce output of the type sourcetype.
-s	Strips the symbol table out of the executable file.
-verbose=vlst	Controls compiler verbosity.
+w	Prints extra warnings where necessary.
+w2	Print still more warnings where appropriate.
-w	Suppresses warning messages.

TABLE 3-10 Output Options (Continued)

Option	Action
-xdumpmacros	Prints information about macros such as definition, location defined and undefined, and locations used.
-xe	Performs only syntax and semantic checking on the source file, but does not produce any object or executable code.
-xhelp=flags	Displays a summary list of compiler options
-xhelp=readme	Displays the contents of the online README file.
-xM	Outputs makefile dependency information.
-xM1	Generates dependency information, but excludes <code>/usr/include</code> .
-xtime	Reports execution time for each compilation phase.
-xwe	Converts all warnings to errors.
-z arg	Linker option.

3.3.10 Run-Time Performance Options

TABLE 3-11 Run-Time Performance Options

Option	Action
-fast	Selects a combination of compilation options for optimum execution speed for some programs.
-fma	(SPARC) Enables automatic generation of floating-point, fused, multiply-add instructions.
-g	Instructs both the compiler and the linker to prepare the program for performance analysis (and for debugging).
-s	Strips the symbol table out of the executable.
-m32 -m64	Specifies the memory model for the compiled binary object.
-xalias_level	Enables the compiler to perform type-based alias analysis and optimizations.
-xarch=isa	Specifies target architecture instruction set.
-xbinopt	Prepares the binary for later optimizations, transformations and analysis.
-xbuiltin[=opt]	Enables or disables better optimization of standard library calls

TABLE 3-11 Run-Time Performance Options (Continued)

Option	Action
-xcache=c	(SPARC) Defines target cache properties for the optimizer.
-xcg89	Compiles for generic SPARC v7 architecture.
-xcg92	Compiles for SPARC V8 architecture.
-xchip=c	Specifies target processor chip.
-xF	Enables linker reordering of functions and variables.
-xinline=flst	Specifies which user-written routines can be inlined by the optimizer.
-xipo	Performs interprocedural optimizations.
-xlibmil	Inlines selected <code>libm</code> library routines for optimization.
-xlibmopt	Uses a library of optimized math routines.
-xlinkopt	(SPARC) Performs link-time optimization on the resulting executable or dynamic library over and above any optimizations in the object files.
-xmalign=ab	(SPARC) Specify maximum assumed memory alignment and behavior of misaligned data accesses.
-xnolibmil	Cancels <code>xlibmil</code> on the command line.
-xnolibmopt	Does not use the math routine library.
-xOlevel	Specifies optimization level to <i>level</i> .
-xpagesize	Sets the preferred page size for the stack and the heap.
-xpagesize_heap	Sets the preferred page size for the heap.
-xpagesize_stack	Sets the preferred page size for the stack.
-xprefetch[=lst]	Enables prefetch instructions on architectures that support prefetch.
-xprefetch_level	Control the aggressiveness of automatic insertion of prefetch instructions as set by <code>xprefetch=auto</code>
-xprofile	Collects or optimizes using runtime profiling data.
-xregs=rst	Controls scratch register use.
-xsafe=mem	(SPARC) Allows no memory-based traps.
-xspace	(SPARC) Does not allow optimizations that increase code size.
-xtarget=t	Specifies a target instruction set and optimization system.
-xthreadvar	Changes the default thread-local storage access mode.

TABLE 3-11 Run-Time Performance Options (Continued)

Option	Action
-xunroll= <i>n</i>	Enables unrolling of loops where possible.
-xvis	(SPARC) Enables compiler recognition of the assembly-language templates defined in the VIS instruction set

3.3.11 Preprocessor Options

TABLE 3-12 Preprocessor Options

Option	Action
-D <i>name</i> [= <i>def</i>]	Defines symbol <i>name</i> to the preprocessor.
-E	Runs only the preprocessor on the C++ source files and sends result to stdout. Does not compile.
-H	Prints path names of included files.
-P	Only preprocesses source; outputs to .i file.
-U <i>name</i>	Deletes initial definition of preprocessor symbol <i>name</i> .
-xM	Outputs makefile dependency information.
-xM1	Generates dependency information, but excludes /usr/include.

3.3.12 Profiling Options

TABLE 3-13 Profiling Options

Option	Action
-p	Prepares the object code to collect data for profiling using <code>prof</code> .
-xpg	Compiles for profiling with the <code>gprof</code> profiler.
-xprofile	Collects or optimizes using runtime profiling data.

3.3.13 Reference Options

TABLE 3-14 Reference Options

Option	Action
<code>-migration</code>	Explains where to get information about migrating from earlier compilers.
<code>-xhelp=flags</code>	Displays a summary list of compiler options.
<code>-xhelp=readme</code>	Displays the contents of the online README file.

3.3.14 Source Options

TABLE 3-15 Source Options

Option	Action
<code>-H</code>	Prints path names of included files.
<code>-Ipathname</code>	Adds <i>pathname</i> to the <code>include</code> file search path.
<code>-I-</code>	Changes the include-file search rules
<code>-xM</code>	Outputs makefile dependency information.
<code>-xM1</code>	Generates dependency information, but excludes <code>/usr/include</code> .

3.3.15 Template Options

TABLE 3-16 Template Options

Option	Action
<code>-instances=<i>a</i></code>	Controls the placement and linkage of template instances.
<code>-template=<i>wlst</i></code>	Enables or disables various template options.

3.3.16 Thread Options

TABLE 3-17 Thread Options

Option	Action
<code>-mt</code>	Compiles and links for multithreaded code.

TABLE 3-17 Thread Options (Continued)

Option	Action
-xsafe=mem	(SPARC) Allows no memory-based traps.
-xthreadvar	(SPARC) Changes the default thread-local storage access mode.

PART II

Writing C++ Programs

Language Extensions

This chapter documents the language extensions specific to this compiler. The compiler does not recognize some of the features described in this chapter unless you specify certain compiler options on the command line. The relevant compiler options are listed in each section as appropriate.

The `-features=extensions` option enables you to compile nonstandard code that is commonly accepted by other C++ compilers. You can use this option when you must compile invalid code and you are not permitted to modify the code to make it valid.

This chapter describes the language extensions that the compiler supports when you use the `-features=extensions` options.

Note – You can easily turn each supported instance of invalid code into valid code that all compilers will accept. If you are allowed to make the code valid, you should do so instead of using this option. Using the `-features=extensions` option perpetuates invalid code that will be rejected by some compilers.

4.1 Linker Scoping

Use the following declaration specifiers to help constrain declarations and definitions of extern symbols. The scoping restraints you specify for a static archive or an object file will not take effect until the file is linked into a shared library or an executable. Despite this, the compiler can still perform some optimization given the presence of the linker scoping specifiers.

By using these specifiers, you no longer need to use mapfiles for linker scoping. You can also control the default setting for variable scoping by specifying `-xldscope` on the command line.

For more information, see “[A.2.136 -xldscope={v}](#)” on page 299.

TABLE 4-1 Linker Scoping Declaration Specifiers

Value	Meaning
<code>__global</code>	Symbol definitions have global linker scoping and is the least restrictive linker scoping. All references to the symbol bind to the definition in the first dynamic load module that defines the symbol. This linker scoping is the current linker scoping for extern symbols.
<code>__symbolic</code>	Symbol definitions have symbolic linker scoping and is more restrictive than global linker scoping. All references to the symbol from within the dynamic load module being linked bind to the symbol defined within the module. Outside of the module, the symbol appears as though it were global. This linker scoping corresponds to the linker option <code>-Bsymbolic</code> . Although you cannot use <code>-Bsymbolic</code> with C++ libraries, you can use the <code>__symbolic</code> specifier without causing problems. See <code>ld(1)</code> for more information on the linker.
<code>__hidden</code>	Symbol definitions have hidden linker scoping. Hidden linker scoping is more restrictive than symbolic and global linker scoping. All references within a dynamic load module bind to a definition within that module. The symbol will not be visible outside of the module.

A symbol definition may be redeclared with a more restrictive specifier, but may not be redeclared with a less restrictive specifier. A symbol may not be declared with a different specifier once the symbol has been defined.

`__global` is the least restrictive scoping, `__symbolic` is more restrictive, and `__hidden` is the most restrictive scoping.

All virtual functions must be visible to all compilation units that include the class definition because the declaration of virtual functions affects the construction and interpretation of virtual tables.

You can apply the linker scoping specifiers to struct, class, and union declarations and definitions because C++ classes may require generation of implicit information, such as virtual tables and run-time type information. The specifier, in this case, follows the struct, class, or union keyword. Such an application implies the same linker scoping for all its implicit members.

4.1.1 Compatibility with Microsoft Windows

For compatibility with similar scoping features in Microsoft Visual C++ (MSVC++) for dynamic libraries, the following syntax is also supported:

`__declspec(dllexport)` is equivalent to `__symbolic`

`__declspec(dllimport)` is equivalent to `__global`

When taking advantage of this syntax with Solaris Studio C++, you should add the option `-xldscope=hidden` to CC command lines. The result will be comparable to the results using MSVC++. With MSVC++, `__declspec(dllimport)` is supposed to be used only on declarations of external symbols, not on definitions. Example:

```
__declspec(dllimport) int foo(); // OK
__declspec(dllimport) int bar() { ... } // not OK
```

MSVC++ is lax about allowing `dllimport` on definitions, and the results using Solaris Studio C++ will be different. In particular, using `dllimport` on a definition using Solaris Studio C++ results in the symbol having global linkage instead of symbolic linkage. Dynamic libraries on Microsoft Windows do not support global linkage of symbols. If you run into this problem, you can change the source code to use `dlexport` instead of `dllimport` on definitions. You will then get the same results with MSVC++ and Solaris Studio C++.

4.2 Thread-Local Storage

Take advantage of thread-local storage by declaring thread-local variables. A thread-local variable declaration consists of a normal variable declaration with the addition of the declaration specifier `__thread`. For more information, see [“A.2.182 -xthreadvar\[=o\]” on page 340](#).

You must include the `__thread` specifier in the first declaration of the thread variable. Variables that you declare with the `__thread` specifier are bound as they would be without the `__thread` specifier.

You can declare variables only of static duration with the `__thread` specifier. Variables with static duration include file global, file static, function local static, and class static member. You should not declare variables with dynamic or automatic duration with the `__thread` specifier. A thread variable can have a static initializer, but it cannot have a dynamic initializer or destructors. For example, `__thread int x = 4;` is permitted, but `__thread int x = f();` is not. A thread variable should not have a type with non-trivial constructors and destructors. In particular, a thread variable may not have type `std::string`.

The address-of operator (`&`) for a thread variable is evaluated at run time and returns the address of the current thread’s variable. Therefore, the address of a thread variable is not a constant.

The address of a thread variable is stable for the lifetime of the corresponding thread. Any thread in the process can freely use the address of a thread variable during the variable’s lifetime. You cannot use a thread variable’s address after its thread terminates. All addresses of a thread’s variables are invalid after the thread’s termination.

4.3 Overriding With Less Restrictive Virtual Functions

The C++ standard says that an overriding virtual function must not be less restrictive in the exceptions it allows than any function it overrides. It can have the same restrictions or be more restrictive. Note that the absence of an exception specification allows any exception.

Suppose, for example, that you call a function through a pointer to a base class. If the function has an exception specification, you can count on no other exceptions being thrown. If the overriding function has a less-restrictive specification, an unexpected exception could be thrown, which can result in bizarre program behavior followed by a program abort. This is the reason for the rule.

When you use `-features=extensions`, the compiler will allow overriding functions with less-restrictive exception specifications.

4.4 Making Forward Declarations of enum Types and Variables

When you use `-features=extensions`, the compiler allows the forward declaration of enum types and variables. In addition, the compiler allows the declaration of a variable with an incomplete enum type. The compiler will always assume an incomplete enum type to have the same size and range as type `int` on the current platform.

The following two lines show an example of invalid code that will compile when you use the `-features=extensions` option.

```
enum E; // invalid: forward declaration of enum not allowed
E e;    // invalid: type E is incomplete
```

Because enum definitions cannot reference one another, and no enum definition can cross-reference another type, the forward declaration of an enumeration type is never necessary. To make the code valid, you can always provide the full definition of the enum before it is used.

Note – On 64-bit architectures, it is possible for an enum to require a size that is larger than type `int`. If that is the case, and if the forward declaration and the definition are visible in the same compilation, the compiler will emit an error. If the actual size is not the assumed size and the compiler does not see the discrepancy, the code will compile and link, but might not run properly. Mysterious program behavior can occur, particularly if an 8-byte value is stored in a 4-byte variable.

4.5 Using Incomplete enum Types

When you use `-features=extensions`, incomplete enum types are taken as forward declarations. For example, the following invalid code will compile when you use the `-features=extensions` option.

```
typedef enum E F; // invalid, E is incomplete
```

As noted previously, you can always include the definition of an enum type before it is used.

4.6 Using an enum Name as a Scope Qualifier

Because an enum declaration does not introduce a scope, an enum name cannot be used as a scope qualifier. For example, the following code is invalid.

```
enum E {e1, e2, e3};  
int i = E::e1; // invalid: E is not a scope name
```

To compile this invalid code, use the `-features=extensions` option.

The `-features=extensions` option instructs the compiler to ignore a scope qualifier if it is the name of an enum type.

To make the code valid, remove the invalid qualifier `E::`.

Note – Use of this option increases the possibility of typographical errors yielding incorrect programs that compile without error messages.

4.7 Using Anonymous struct Declarations

An anonymous struct declaration is a declaration that declares neither a tag for the struct, nor an object or typedef name. Anonymous structs are not allowed in C++.

The `-features=extensions` option allows the use of an anonymous struct declaration, but only as member of a union.

The following code is an example of an invalid anonymous struct declaration that compiles when you use the `-features=extensions` option.

```
union U {  
    struct {  
        int a;  
        double b;  
    }; // invalid: anonymous struct  
    struct {
```

```
    char* c;
    unsigned d;
}; // invalid: anonymous struct
};
```

The names of the `struct` members are visible without qualification by a `struct` member name. Given the definition of `U` in this code example, you can write:

```
U u;
u.a = 1;
```

Anonymous structs are subject to the same limitations as anonymous unions.

Note that you can make the code valid by giving a name to each `struct`, such as:

```
union U {
    struct {
        int a;
        double b;
    } A;
    struct {
        char* c;
        unsigned d;
    } B;
};
U u;
U.A.a = 1;
```

4.8 Passing the Address of an Anonymous Class Instance

You are not allowed to take the address of a temporary variable. For example, the following code is invalid because it takes the address of a variable created by a constructor call. However, the compiler accepts this invalid code when you use the `-features=extensions` option.

```
class C {
public:
    C(int);
    ...
};
void f1(C*);
int main()
{
    f1(&C(2)); // invalid
}
```

Note that you can make this code valid by using an explicit variable.

```
C c(2);
f1(&c);
```

The temporary object is destroyed when the function returns. Ensuring that the address of the temporary variable is not retained is the programmer's responsibility. In addition, the data that is stored in the temporary variable (for example, by `f1`) is lost when the temporary variable is destroyed.

4.9 Declaring a Static Namespace-Scope Function as a Class Friend

The following code is invalid.

```
class A {
    friend static void foo(<args>);
    ...
};
```

Because a class name has external linkage and all definitions must be identical, friend functions must also have external linkage. However, when you use the `-features=extensions` option, the compiler accepts this code.

Presumably the programmer's intent with this invalid code was to provide a nonmember "helper" function in the implementation file for class A. You can get the same effect by making `foo` a static member function. You can make it private if you do not want clients to call the function.

Note – If you use this extension, your class can be "hijacked" by any client. Any client can include the class header, then define its own static function `foo`, which will automatically be a friend of the class. The effect will be as if you made all members of the class public.

4.10 Using the Predefined `__func__` Symbol for Function Name

The compiler implicitly declares the identifier `__func__` in each function as a static array of `const char`. If the program uses the identifier, the compiler also provides the following definition where *function-name* is the unadorned name of the function. Class membership, namespaces, and overloading are not reflected in the name.

```
static const char __func__[] = "function-name";
```

For example, consider the following code fragment.

```
#include <stdio.h>
void myfunc(void)
```

```
{  
    printf("%s\n", __func__);  
}
```

Each time the function is called, it will print the following to the standard output stream.

```
myfunc
```

The identifier `__FUNCTION__` is also defined and is equivalent to `__func__`.

4.11 Supported Attributes

The following attributes, invoked by `__attribute__ ((keyword))`, or alternatively by `[[keyword]]`, are implemented by the compiler for compatibility:

- `always_inline` — equivalent to `#pragma inline` and `-xinline`
- `noinline` — equivalent to `#pragma no_inline` and `-xinline`
- `pure` — equivalent to `#pragma does_not_write_global_data`
- `const` — equivalent to `#pragma no_side_effect`
- `malloc` — equivalent to `#pragma returns_new_memory`
- `constructor` — equivalent to `#pragma init`
- `destructor` — equivalent to `#pragma fini`
- `weak` — equivalent to `#pragma weak`
- `noreturn` — equivalent to `#pragma does_not_return`
- `visibility`
- `returns_twice`
- `packed` — *see below*
- `atomic`
- `outer`
- `relaxed`
- `mode`
- `aligned`
- `strong`

4.11.1 `__packed__`

This attribute, attached to `struct` or `union` type definition, specifies that each member (other than zero-width bitfields) of the structure or union is placed to minimize the memory required. When attached to an `enum` definition, it indicates that the smallest integral type should be used.

Specifying this attribute for `struct` and `union` types is equivalent to specifying the `packed` attribute on each of the structure or union members.

In the following example `struct my_packed_struct`'s members are packed closely together, but the internal layout of its `s` member is not packed. To do that, `struct my_unpacked_struct` would also need to be packed.

```
struct my_unpacked_struct
{
    char c;
    int i;
};

struct __attribute__((__packed__)) my_packed_struct
{
    char c;
    int i;
    struct my_unpacked_struct s;
};
```

You may only specify this attribute on the definition of an enum, struct, or union, and not on a typedef that does not also define the enumerated type, structure, or union.

Program Organization

The file organization of a C++ program requires more care than is typical for a C program. This chapter describes how to set up your header files and your template definitions.

5.1 Header Files

Creating an effective header file can be difficult. Often your header file must adapt to different versions of both C and C++. To accommodate templates, make sure your header file is tolerant of multiple inclusions (idempotent).

5.1.1 Language-Adaptable Header Files

You might need to develop header files for inclusion in both C and C++ programs. However, Kernighan and Ritchie C (K&R C), also known as “classic C,” ANSI C, *Annotated Reference Manual C++* (ARM C++), and ISO C++ sometimes require different declarations or definitions for the same program element within a single header file. (See the *C++ Migration Guide* for additional information on the variations between languages and versions.) To make header files acceptable to all these standards, you might need to use conditional compilation based on the existence or value of the preprocessor macros `__STDC__` and `__cplusplus`.

The macro `__STDC__` is not defined in K&R C, but is defined in both ANSI C and C++. Use this macro to separate K&R C code from ANSI C or C++ code. This macro is most useful for separating prototyped from nonprototyped function definitions.

```
#ifndef __STDC__
int function(char*,...);    // C++ & ANSI C declaration
#else
int function();           // K&R C
#endif
```

The macro `__cplusplus` is not defined in C, but is defined in C++.

Note – Early versions of C++ defined the macro `cplusplus` instead of `__cplusplus`. The macro `cplusplus` is no longer defined.

Use the definition of the `__cplusplus` macro to separate C and C++. This macro is most useful in guarding the specification of an extern “C” interface for function declarations, as shown in the following example. To prevent inconsistent specification of extern “C”, never place an `#include` directive within the scope of an extern “C” linkage specification.

```
#include "header.h"
... // ... other include files...
#if defined(__cplusplus)
extern "C" {
#endif
    int g1();
    int g2();
    int g3()
#if defined(__cplusplus)
}
#endif
```

In ARM C++, the `__cplusplus` macro has a value of 1. In ISO C++, the macro has the value 199711L (the year and month of the standard expressed as a long constant). Use the value of this macro to separate ARM C++ from ISO C++. The macro value is most useful for guarding changes in template syntax.

```
// template function specialization
#if __cplusplus < 199711L
int power(int,int); // ARM C++
#else
template <> int power(int,int); // ISO C++
#endif
```

5.1.2 Idempotent Header Files

Your header files should be idempotent. That is, the effect of including a header file many times should be exactly the same as including the header file only once. This property is especially important for templates. You can best accomplish idempotency by setting preprocessor conditions that prevent the body of your header file from appearing more than once.

```
#ifndef HEADER_H
#define HEADER_H
/* contents of header file */
#endif
```


5.2 Template Definitions

You can organize your template definitions in two ways: with definitions included and with definitions separated. The definitions-included organization allows greater control over template compilation.

5.2.1 Template Definitions Included

When you put the declarations and definitions for a template within the file that uses the template, the organization is *definitions-included*. For example:

```
main.cc

template <class Number> Number twice(Number original);
template <class Number> Number twice(Number original )
    { return original + original; }
int main()
    { return twice<int>(-3); }
```

When a file using a template includes a file that contains both the template's declaration and the template's definition, the file that uses the template also has the definitions-included organization. For example:

```
twice.h

#ifndef TWICE_H
#define TWICE_H
template <class Number>
Number twice(Number original);
template <class Number> Number twice( Number original )
    { return original + original; }
#endif

main.cc

#include "twice.h"
int main()
    { return twice(-3); }
```

Note – Making your template headers idempotent is very important. (See [“5.1.2 Idempotent Header Files” on page 72.](#))

5.2.2 Template Definitions Separate

Another way to organize template definitions is to keep the definitions in template definition files, as shown in the following example.

```
twice.h
```

```
#ifndef TWICE_H
#define TWICE_H
template <class Number>
Number twice(Number original);
#endif TWICE_H

twice.cc

template <class Number>
Number twice( Number original )
    { return original + original; }

main.cc

#include "twice.h"
int main( )
    { return twice<int>( -3 ); }
```

Template definition files *must not* include any non-idempotent header files and often need not include any header files at all. (See [“5.1.2 Idempotent Header Files” on page 72.](#)) Note that not all compilers support the definitions-separate model for templates.

Because a separate definitions file is a header file, it might be included implicitly in many files. It therefore should not contain any function or variable definitions, unless they are part of a template definition. A separate definitions file can include type definitions, including typedefs.

Note – Although source-file extensions for template definition files are commonly used (that is, .c, .C, .cc, .cpp, .cxx, or .c++), template definition files are header files. The compiler includes them automatically if necessary. Template definition files should *not* be compiled independently.

If you place template declarations in one file and template definitions in another file, you have to be very careful how you construct the definition file, what you name it, and where you put it. You might also need to identify explicitly to the compiler the location of the definitions. Refer to [“7.5 Template Definition Searching” on page 97](#) for information about the template definition search rules.

When generating preprocessor output with the -E or -P options, the definitions-separate file organization does not allow the template definitions to be included in the .i file. Compiling the .i file can fail due to missing definitions. By conditionally including the template definition file in the template declaration header (see code example below), you can ensure the template definitions are available by using -template=no%extdef on the command line. The libc++ and STLport libraries are implemented in this way.

```
// template declaration file
template <class T> class foo { ... };
#ifdef _TEMPLATE_NO_EXTDEF
#include "foo.cc" //template definition file
#endif
```

However, do not attempt to define the macro `_TEMPLATE_NO_EXTDEF` yourself. When defined without the `-template=no%extdef` option, you can get compilation failures due to multiple inclusion of template definition files.

Creating and Using Templates

Templates make it possible for you to write a single body of code that applies to a wide range of types in a type-safe manner. This chapter introduces template concepts and terminology in the context of function templates, discusses the more complicated (and more powerful) class templates, and describes the composition of templates. Also discussed are template instantiation, default template parameters, and template specialization. The chapter concludes with a discussion of potential problem areas for templates.

6.1 Function Templates

A function template describes a set of related functions that differ only by the types of their arguments or return values.

6.1.1 Function Template Declaration

You must declare a template before you can use it. A *declaration*, as in the following example, provides enough information to use the template, but not enough information to implement the template.

```
template <class Number> Number twice( Number original );
```

In this example, *Number* is a *template parameter*; it specifies the range of functions that the template describes. More specifically, *Number* is a *template type parameter*, and its use within the template definition stands for a type determined at the location where the template is used.

6.1.2 Function Template Definition

If you declare a template, you must also define it. A *definition* provides enough information to implement the template. The following example defines the template declared in the previous example.

```
template <class Number> Number twice( Number original )
{ return original + original; }
```

Because template definitions often appear in header files, a template definition might be repeated in several compilation units. All definitions, however, must be the same. This restriction is called the *One-Definition Rule*.

6.1.3 Function Template Use

Once declared, templates can be used like any other function. Their *use* consists of naming the template and providing function arguments. The compiler can infer the template type arguments from the function argument types. For example, you can use the previously declared template as follows.

```
double twicedouble( double item )
{ return twice( item ); }
```

If a template argument cannot be inferred from the function argument types, it must be supplied where the function is called. For example:

```
template<class T> T func(); // no function arguments
int k = func<int>(); // template argument supplied explicitly
```

6.2 Class Templates

A class template describes a set of related classes or data types that differ only by types, by integral values, by pointers or references to variables with global linkage, or by a combination thereof. Class templates are particularly useful in describing generic, but type-safe, data structures.

6.2.1 Class Template Declaration

A class template declaration provides only the name of the class and its template arguments. Such a declaration is an *incomplete class template*.

The following example is a template declaration for a class named `Array` that takes any type as an argument.

```
template <class Elem> class Array;
```

This template is for a class named `String` that takes an unsigned `int` as an argument.

```
template <unsigned Size> class String;
```

6.2.2 Class Template Definition

A class template definition must declare the class data and function members, as in the following examples.

```
template <class Elem> class Array {
    Elem* data;
    int size;
public:
    Array( int sz );
    int GetSize();
    Elem& operator[]( int idx );
};

template <unsigned Size> class String {
    char data[Size];
    static int overflows;
public:
    String( char *initial );
    int length();
};
```

Unlike function templates, class templates can have both type parameters (such as `class Elem`) and expression parameters (such as `unsigned Size`). An expression parameter can be:

- A value that has an integral type or enumeration
- A pointer or a reference to an object
- A pointer or a reference to a function
- A pointer to a class member function

6.2.3 Class Template Member Definitions

The full definition of a class template requires definitions for its function members and static data members. Dynamic (nonstatic) data members are sufficiently defined by the class template declaration.

6.2.3.1 Function Member Definitions

The definition of a template function member consists of the template parameter specification followed by a function definition. The function identifier is qualified by the class template's class name and the template arguments. The following example shows definitions of two function members of the `Array` class template, which has a template parameter specification of `template <class Elem>`. Each function identifier is qualified by the template class name and the template argument `Array<Elem>`.

```
template <class Elem> Array<Elem>::Array( int sz )
    {size = sz; data = new Elem[size];}

template <class Elem> int Array<Elem>::GetSize()
    { return size; }
```

This example shows definitions of function members of the `String` class template.

```
#include <string.h>
template <unsigned Size> int String<Size>::length( )
    {int len = 0;
      while (len < Size && data[len]!='\0') len++;
      return len;}

template <unsigned Size> String<Size>::String(char *initial)
    {strncpy(data, initial, Size);
      if (length( ) == Size) overflows++;}
```

6.2.3.2 Static Data Member Definitions

The definition of a template static data member consists of the template parameter specification followed by a variable definition, where the variable identifier is qualified by the class template name and its template actual arguments.

```
template <unsigned Size> int String<Size>::overflows = 0;
```

6.2.4 Class Template Use

A template class can be used wherever a type can be used. Specifying a template class consists of providing the values for the template name and arguments. The declaration in the following example creates the variable `int_array` based upon the `Array` template. The variable's class declaration and its set of methods are just like those in the `Array` template except that `Elem` is replaced with `int` (see [“6.3 Template Instantiation” on page 81](#)).

```
Array<int> int_array(100);
```

The declaration in this example creates the `short_string` variable using the `String` template.

```
String<8> short_string("hello");
```

You can use template class member functions as you would any other member function

```
int x = int_array.GetSize( );
```

```
int x = short_string.length( );
```


6.3 Template Instantiation

Template *instantiation* involves generating a concrete class or function (*instance*) for a particular combination of template arguments. For example, the compiler generates a class for `Array<int>` and a different class for `Array<double>`. The new classes are defined by substituting the template arguments for the template parameters in the definition of the template class. In the `Array<int>` example, shown in the preceding section, “[6.2 Class Templates](#)” on page 78, the compiler substitutes `int` wherever `Element` appears.

6.3.1 Implicit Template Instantiation

The use of a template function or template class introduces the need for an instance. If that instance does not already exist, the compiler implicitly instantiates the template for that combination of template arguments.

6.3.2 Explicit Template Instantiation

The compiler implicitly instantiates templates only for those combinations of template arguments that are actually used. This approach may be inappropriate for the construction of libraries that provide templates. C++ provides a facility to explicitly instantiate templates, as seen in the following examples.

6.3.2.1 Explicit Instantiation of Template Functions

To instantiate a template function explicitly, follow the `template` keyword by a declaration (not definition) for the function, with the function identifier followed by the template arguments.

```
template float twice<float>(float original);
```

Template arguments may be omitted when the compiler can infer them.

```
template int twice(int original);
```

6.3.2.2 Explicit Instantiation of Template Classes

To instantiate a template class explicitly, follow the `template` keyword by a declaration (not definition) for the class, with the class identifier followed by the template arguments.

```
template class Array<char>;
```

```
template class String<19>;
```

When you explicitly instantiate a class, all of its members are also instantiated.

6.3.2.3 Explicit Instantiation of Template Class Function Members

To explicitly instantiate a template class function member, follow the `template` keyword by a declaration (not definition) for the function, with the function identifier qualified by the template class, followed by the template arguments.

```
template int Array<char>::GetSize();
```

```
template int String<19>::length();
```

6.3.2.4 Explicit Instantiation of Template Class Static Data Members

To explicitly instantiate a template class static data member, follow the `template` keyword by a declaration (not definition) for the member, with the member identifier qualified by the template class, followed by the template argument.

```
template int String<19>::overflows;
```

6.4 Template Composition

You can use templates in a nested manner. This is particularly useful when defining generic functions over generic data structures, as in the standard C++ library. For example, a template sort function may be declared over a template array class:

```
template <class Elem> void sort(Array<Elem>);
```

and defined as:

```
template <class Elem> void sort(Array<Elem> store)
{int num_elems = store.GetSize();
  for (int i = 0; i < num_elems-1; i++)
    for (int j = i+1; j < num_elems; j++)
      if (store[j-1] > store[j])
        {Elem temp = store[j];
         store[j] = store[j-1];
         store[j-1] = temp;}}
```

The preceding example defines a sort function over the predeclared `Array` class template objects. The next example shows the actual use of the sort function.

```
Array<int> int_array(100); // construct an array of ints
sort(int_array);         // sort it
```

6.5 Default Template Parameters

You can give default values to template parameters for class templates (but not function templates).

```
template <class Elem = int> class Array;
template <unsigned Size = 100> class String;
```

If a template parameter has a default value, all parameters after it must also have default values. A template parameter can have only one default value.

6.6 Template Specialization

There may be performance advantages to treating some combinations of template arguments as a special case, as in the following examples for *twice*. Alternatively, a template description might fail to work for a set of its possible arguments, as in the following examples for *sort*. Template specialization allows you to define alternative implementations for a given combination of actual template arguments. The template specialization overrides the default instantiation.

6.6.1 Template Specialization Declaration

You must declare a specialization before any use of that combination of template arguments. The following examples declare specialized implementations of *twice* and *sort*.

```
template <> unsigned twice<unsigned>( unsigned original );
template <> sort<char*>(Array<char*> store);
```

You can omit the template arguments if the compiler can unambiguously determine them. For example:

```
template <> unsigned twice(unsigned original);
template <> sort(Array<char*> store);
```

6.6.2 Template Specialization Definition

You must define all template specializations that you declare. The following examples define the functions declared in the preceding section.

```
template <> unsigned twice<unsigned>(unsigned original)
    {return original << 1;}
```

```
#include <string.h>
template <> void sort<char*>(Array<char*> store)
{int num_elems = store.GetSize();
  for (int i = 0; i < num_elems-1; i++)
    for (int j = i+1; j < num_elems; j++)
      if (strcmp(store[j-1], store[j]) > 0)
        {char *temp = store[j];
          store[j] = store[j-1];
          store[j-1] = temp;}}
```

6.6.3 Template Specialization Use and Instantiation

A specialization is used and instantiated just as any other template, except that the definition of a completely specialized template is also an instantiation.

6.6.4 Partial Specialization

In the previous examples, the templates are fully specialized. That is, they define an implementation for specific template arguments. A template can also be partially specialized, meaning that only some of the template parameters are specified, or that one or more parameters are limited to certain categories of type. The resulting partial specialization is itself still a template. For example, the following code sample shows a primary template and a full specialization of that template.

```
template<class T, class U> class A {...}; //primary template
template<> class A<int, double> {...}; //specialization
```

The following code shows examples of partial specialization of the primary template.

```
template<class U> class A<int> {...}; // Example 1
template<class T, class U> class A<T*> {...}; // Example 2
template<class T> class A<T**, char> {...}; // Example 3
```

- Example 1 provides a special template definition for cases when the first template parameter is type `int`.
- Example 2 provides a special template definition for cases when the first template parameter is any pointer type.
- Example 3 provides a special template definition for cases when the first template parameter is pointer-to-pointer of any type, and the second template parameter is type `char`.

6.7 Template Problem Areas

This section describes problems you might encounter when using templates.

6.7.1 Nonlocal Name Resolution and Instantiation

Sometimes a template definition uses names that are not defined by the template arguments or within the template itself. If so, the compiler resolves the name from the scope enclosing the template, which could be the context at the point of definition, or at the point of instantiation. A name can have different meanings in different places, yielding different resolutions.

Name resolution is complex. Consequently, you should not rely on nonlocal names, except those provided in a pervasive global environment. That is, use only nonlocal names that are declared and defined the same way everywhere. In the following example, the template function `converter` uses the nonlocal names `intermediary` and `temporary`. These names have different definitions in `use1.cc` and `use2.cc`, and will probably yield different results under different compilers. For templates to work reliably, all nonlocal names (`intermediary` and `temporary` in this case) must have the same definition everywhere.

```
use_common.h
// Common template definition
template <class Source, class Target>
Target converter(Source source)
    {temporary = (intermediary)source;
    return (Target)temporary;}
use1.cc
typedef int intermediary;
int temporary;

#include "use_common.h"
use2.cc
typedef double intermediary;
unsigned int temporary;

#include "use_common.h"
```

A common use of nonlocal names is the use of the `cin` and `cout` streams within a template. Few programmers really want to pass the stream as a template parameter, so they refer to a global variable. However, `cin` and `cout` must have the same definition everywhere.

6.7.2 Local Types as Template Arguments

The template instantiation system relies on type-name equivalence to determine which templates need to be instantiated or reinstantiated. Thus local types can cause serious problems when used as template arguments. Beware of creating similar problems in your code. For example:

EXAMPLE 6-1 Example of Local Type as Template Argument Problem

```

array.h
template <class Type> class Array {
    Type* data;
    int size;
public:
    Array(int sz);
    int GetSize();
};

array.cc
template <class Type> Array<Type>::Array(int sz)
    {size = sz; data = new Type[size];}
template <class Type> int Array<Type>::GetSize()
    {return size;}

file1.cc
#include "array.h"
struct Foo {int data;};
Array<Foo> File1Data(10);

file2.cc
#include "array.h"
struct Foo {double data;};
Array<Foo> File2Data(20);

```

The Foo type as registered in file1.cc is not the same as the Foo type registered in file2.cc. Using local types in this way could lead to errors and unexpected results.

6.7.3 Friend Declarations of Template Functions

Templates must be declared before they are used. A friend declaration constitutes a use of the template, not a declaration of the template. A true template declaration must precede the friend declaration. For example, when the compilation system attempts to link the produced object file for the following example, it generates an undefined error for the operator<< function, which is *not* instantiated.

EXAMPLE 6-2 Example of Friend Declaration Problem

```

array.h
// generates undefined error for the operator<< function
#ifndef ARRAY_H
#define ARRAY_H
#include <iosfwd>

template<class T> class array {
    int size;
public:
    array();
    friend std::ostream&
        operator<<(std::ostream&, const array<T>&);
};

```

EXAMPLE 6-2 Example of Friend Declaration Problem (Continued)

```

#endif

array.cc
#include <stdlib.h>
#include <iostream>

template<class T> array<T>::array() {size = 1024;}

template<class T>
std::ostream&
operator<<(std::ostream& out, const array<T>& rhs)
    {return out <<'[' << rhs.size <<']';}

main.cc
#include <iostream>
#include "array.h"

int main()
{
    std::cout
        << "creating an array of int... " << std::flush;
    array<int> foo;
    std::cout << "done\n";
    std::cout << foo << std::endl;
    return 0;
}

```

Note that there is no error message during compilation because the compiler reads the following as the declaration of a normal function that is a friend of the array class.

```
friend ostream& operator<<(ostream&, const array<T>&);
```

Because `operator<<` is really a template function, you need to supply a template declaration for prior to the declaration of template class `array`. However, because `operator<<` has a parameter of type `array<T>`, you must precede the function declaration with a declaration of `array<T>`. The file `array.h` must look like this:

```

#ifndef ARRAY_H
#define ARRAY_H
#include <iosfwd>

// the next two lines declare operator<< as a template function
template<class T> class array;
template<class T>
    std::ostream& operator<<(std::ostream&, const array<T>&);

template<class T> class array {
    int size;
public:
    array();
    friend std::ostream&
        operator<< <T> (std::ostream&, const array<T>&);
}

```

```
};
#endif
```

6.7.4 Using Qualified Names Within Template Definitions

The C++ standard requires types with qualified names that depend upon template arguments to be explicitly noted as type names with the `typename` keyword. This is true even if the compiler can “know” that it should be a type. The comments in the following example show the types with qualified names that require the `typename` keyword.

```
struct simple {
    typedef int a_type;
    static int a_datum;
};
int simple::a_datum = 0; // not a type
template <class T> struct parametric {
    typedef T a_type;
    static T a_datum;
};
template <class T> T parametric<T>::a_datum = 0; // not a type
template <class T> struct example {
    static typename T::a_type variable1; // dependent
    static typename parametric<T>::a_type variable2; // dependent
    static simple::a_type variable3; // not dependent
};
template <class T> typename T::a_type // dependent
    example<T>::variable1 = 0; // not a type
template <class T> typename parametric<T>::a_type // dependent
    example<T>::variable2 = 0; // not a type
template <class T> simple::a_type // not dependent
    example<T>::variable3 = 0; // not a type
```

6.7.5 Nesting Template Names

Because the “>>” character sequence is interpreted as the right-shift operator, you must be careful when you use one template names inside another. Make sure you separate adjacent “>” characters with at least one blank space.

For example, the following ill-formed statement:

```
Array<String<10>>> short_string_array(100); // >> = right-shift
```

is interpreted as:

```
Array<String<10 >> short_string_array(100);
```

The correct syntax is:

```
Array<String<10> > short_string_array(100);
```


6.7.6 Referencing Static Variables and Static Functions

Within a template definition, the compiler does not support referencing an object or function that is declared static at global scope or in a namespace. If multiple instances are generated, the One-Definition Rule (C++ standard section 3.2) is violated, because each instance refers to a different object. The usual failure indication is missing symbols at link time.

If you want a single object to be shared by all template instantiations, then make the object a nonstatic member of a named namespace. If you want a different object for each instantiation of a template class, then make the object a static member of the template class. If you want a different object for each instantiation of a template function, then make the object local to the function.

6.7.7 Building Multiple Programs Using Templates in the Same Directory

If you are building more than one program or library by specifying `-instances=extern`, it's advisable to build them in separate directories. If you want to build in the same directory then you should clean the repository between the different builds. This avoids any unpredictable errors. For more information see [“7.4.4 Sharing Template Repositories” on page 97](#).

Consider the following example with make files `a.cc`, `b.cc`, `x.h`, and `x.cc`. Note that this example is meaningful only if you specify `-instances=extern`:

```
.....
Makefile
.....
CCC = CC

all: a b

a:
    $(CCC) -I. -instances=extern -c a.cc
    $(CCC) -instances=extern -o a a.o

b:
    $(CCC) -I. -instances=extern -c b.cc
    $(CCC) -instances=extern -o b b.o

clean:
    /bin/rm -rf SunWS_cache *.o a b

...
x.h
...
template <class T> class X {
public:
    int open();
    int create();
```

```
    static int variable;
};

...
x.cc
...
template <class T> int X<T>::create() {
    return variable;
}

template <class T> int X<T>::open() {
    return variable;
}

template <class T> int X<T>::variable = 1;

...
a.cc
...
#include "x.h"

int main()
{
    X<int> temp1;

    temp1.open();
    temp1.create();
}

...
b.cc
...
#include "x.h"

int main()
{
    X<int> temp1;

    temp1.create();
}
```

If you build both a and b, add a make clean between the two builds. The following commands result in an error:

```
example% make a
example% make b
```

The following commands will not produce any error:

```
example% make a
example% make clean
example% make b
```

Compiling Templates

Template compilation requires the C++ compiler to do more than traditional UNIX compilers have done. The C++ compiler must generate object code for template instances on an as-needed basis. It might share template instances among separate compilations using a template repository. It might accept some template compilation options. It must locate template definitions in separate source files and maintain consistency between template instances and mainline code.

7.1 Verbose Compilation

When given the flag `-verbose=template`, the C++ compiler notifies you of significant events during template compilation. Conversely, the compiler does not notify you when given the default, `-verbose=no%template`. The `+w` option might give other indications of potential problems when template instantiation occurs.

7.2 Repository Administration

The `CCadmin(1)` command administers the template repository (used only with the option `-instances=extern`). For example, changes in your program can render some instantiations superfluous, thus wasting storage space. The `CCadmin-clean` command (formerly `ptclean`) clears out all instantiations and associated data. Instantiations are recreated only when needed.

7.2.1 Generated Instances

The compiler treats inline template functions as inline functions for the purposes of template instance generation. The compiler manages them as it does other inline functions, and the descriptions in this chapter do not apply to template inline functions.

7.2.2 Whole-Class Instantiation

The compiler usually instantiates members of template classes independently of other members, so that the compiler instantiates only members that are used within the program. Methods written solely for use through a debugger will therefore not normally be instantiated.

There are two means to ensure that debugging members are available to the debugger.

- First, write a non-template function that uses the template class instance members that are otherwise unused. This function need not be called.
- Second, use the `-template=wholeclass` compiler option, which instructs the compiler to instantiate all non-template non-inline members of a template class if any of those same members are instantiated.

The ISO C++ Standard permits developers to write template classes for which all members may not be legal with a given template argument. As long as the illegal members are not instantiated, the program is still well formed. The ISO C++ Standard Library uses this technique. However, the `-template=wholeclass` option instantiates all members, and hence cannot be used with such template classes when instantiated with the problematic template arguments.

7.2.3 Compile-Time Instantiation

Instantiation is the process by which a C++ compiler creates a usable function or object from a template. The C++ compiler uses compile-time instantiation, which forces instantiations to occur when the reference to the template is being compiled.

The advantages of compile-time instantiation are:

- Debugging is much easier—error messages occur within context, allowing the compiler to give a complete traceback to the point of reference.
- Template instantiations are always up-to-date.
- The overall compilation time, including the link phase, is reduced.

Templates can be instantiated multiple times if source files reside in different directories or if you use libraries with template symbols.

7.2.4 Template Instance Placement and Linkage

By default, instances go into special address sections, and the linker recognizes and discards duplicates. You can instruct the compiler to use one of five instance placement and linkage methods: external, static, global, explicit, and semi-explicit.

- External instances perform best when the following is true:
 - The set of instances in the program is small, but each compilation unit references a large subset of the instances.

- There are few instances referenced in more than one or two compilation units.

Static, deprecated . See below.

- Global instances, the default, are suitable for all development, and perform best when objects reference a variety of instances.
- Explicit instances are suitable for some carefully controlled application compilation environments.
- Semi-explicit instances require slightly less controlled compilation environments but produce larger object files and have restricted uses.

This section discusses the five instance placement and linkage methods. Additional information about generating instances can be found in [“6.3 Template Instantiation” on page 81](#).

7.3 External Instances

With the external instances method, all instances are placed within the template repository. The compiler ensures that exactly one consistent template instance exists; instances are neither undefined nor multiply defined. Templates are reinstantiated only when necessary. For non-debug code, the total size of all object files (including any within the template cache) may be smaller with `-instances=extern` than with `-instances=global`.

Template instances receive global linkage in the repository. Instances are referenced from the current compilation unit with external linkage.

Note – If you are compiling and linking in separate steps and you specify `-instance=extern` for the compilation step, you must also specify it for the link step.

The disadvantage of this method is that the cache must be cleared whenever changing programs or making significant program changes. The cache is a bottleneck for parallel compilation, as when using `dmake` because access to the cache must be restricted to one compilation at a time. Also, you can only build one program within a directory.

It can take longer to determine whether a valid template instance is already in the cache than just to create the instance in the main object file and discard it later if needed.

Specify external linkage with the `-instances=extern` option.

Because instances are stored within the template repository, you must use the `CC` command to link C++ objects that use external instances into programs.

If you wish to create a library that contains all the template instances that it uses, use the `CC` command with the `-xar` option. Do *not* use the `ar` command. For example:

```
example% CC -xar -instances=extern -o libmain.a a.o b.o c.o
```

See [Table 14–3](#) for more information.

7.3.1 Possible Cache Conflicts

Do not run different compiler versions in the same directory due to possible cache conflicts when you specify `-instance=extern`. Consider the following when you use the `-instances=extern` template model:

- Do not create unrelated binaries in the same directory. Any binaries (`.o`, `.a`, `.so`, executable programs) created in the same directory should be related, in that names of all objects, functions, and types common to two or more object files have identical definitions.
- It is safe to run multiple compilations simultaneously in the same directory, such as when using `dmake`. It is not safe to run any compilations or link steps at the same time as another link step. "Link step" means any operation that creates a library or executable program. Be sure that dependencies in a makefile do not allow anything to run in parallel with a link step.

7.3.2 Static Instances

Note – The `-instances=static` option is deprecated. There is no longer any reason to use `-instances=static`, because `-instances=global` now gives you all the advantages of `static` without the disadvantages. This option was provided in earlier compilers to overcome problems that no longer exist.

With the static instances method, all instances are placed within the current compilation unit. As a consequence, templates are reinstantiated during each recompilation; instances are not saved to the template repository.

The disadvantage of this method is that it does not follow language semantics and makes substantially larger objects and executables.

Instances receive static linkage. These instances will not be visible or usable outside the current compilation unit. As a result, templates might have identical instantiations in several object files. Because multiple instances produce unnecessarily large programs, static instance linkage is suitable only for small programs, where templates are unlikely to be multiply instantiated.

Compilation is potentially faster with static instances, so this method might also be suitable during Fix-and-Continue debugging. (See *Debugging a Program With dbx*.)

Note – If your program depends on sharing template instances (such as static data members of template classes or template functions) across compilation units, do not use the static instances method. Your program will not work properly.

Specify static instance linkage with the `-instances=static` compiler option.

7.3.3 Global Instances

Unlike early compiler releases, it is not necessary to guard against multiple copies of a global instance.

The advantage of this method is that incorrect source code commonly accepted by other compilers is now also accepted in this mode. In particular, references to static variables from within a template instances are not legal, but commonly accepted.

The disadvantage of this method is that individual object files may be larger, due to copies of template instances in multiple files. If you compile some object files for debug using the `-g` option, and some without, it is hard to predict whether you will get a debug or non-debug version of a template instance linked into the program.

Template instances receive global linkage. These instances are visible and usable outside the current compilation unit.

Specify global instances with the `-instances=global` option (this is the default).

7.3.4 Explicit Instances

In the explicit instances method, instances are generated only for templates that are explicitly instantiated. Implicit instantiations are not satisfied. Instances are placed within the current compilation unit.

The advantage of this method is that you have the least amount of template compilation and smallest object sizes.

The disadvantage is that you must perform all instantiation manually.

Template instances receive global linkage. These instances are visible and usable outside the current compilation unit. The linker recognizes and discards duplicates.

Specify explicit instances with the `-instances=explicit` option.

7.3.5 Semi-Explicit Instances

When you use the semi-explicit instances method, instances are generated only for templates that are explicitly instantiated or implicitly instantiated within the body of a template. Instances required by explicitly-created instances are generated automatically. Implicit instantiations in the mainline code are not satisfied. Instances are placed within the current compilation unit. As a consequence, templates are reinstantiated during each recompilation; instances receive global linkage and they are not saved to the template repository.

Specify semi-explicit instances with the `-instances=semiexplicit` option.

7.4 The Template Repository

The template repository stores template instances between separate compilations so that template instances are compiled only when it is necessary. The template repository contains all nonsource files needed for template instantiation when using the external instances method. The repository is not used for other kinds of instances.

7.4.1 Repository Structure

The template repository is contained, by default, within a cache directory called `SunWS_cache`.

The cache directory is contained within the directory in which the object files are placed. You can change the name of the cache directory by setting the `SUNWS_CACHE_NAME` environment variable. Note that the value of the `SUNWS_CACHE_NAME` variable must be a directory name and not a path name. This is because the compiler automatically places the template cache directory under the object file directory so the compiler already has a path.

7.4.2 Writing to the Template Repository

When the compiler must store template instances, it stores them within the template repository corresponding to the output file. For example, the following command line writes the object file to `./sub/a.o` and writes template instances into the repository contained within `./sub/SunWS_cache`. If the cache directory does not exist, and the compiler needs to instantiate a template, the compiler will create the directory.

```
example% CC -o sub/a.o a.cc
```

7.4.3 Reading From Multiple Template Repositories

The compiler reads from the template repositories corresponding to the object files that it reads. That is, the following command line reads from `./sub1/SunWS_cache` and `./sub2/SunWS_cache`, and, if necessary, writes to `./SunWS_cache`.

```
example% CC sub1/a.o sub2/b.o
```

7.4.4 Sharing Template Repositories

Templates that are within a repository must not violate the one-definition rule of the ISO C++ standard. That is, a template must have the same source in all uses of the template. Violating this rule produces undefined behavior.

The simplest, though most conservative, way to ensure that the rule is not violated is to build only one program or library within any one directory. Two unrelated programs might use the same type name or external name to mean different things. If the programs share a template repository, template definitions could conflict, thus yielding unpredictable results.

7.4.5 Template Instance Automatic Consistency With `-instances=extern`

The template repository manager ensures that the states of the instances in the repository are consistent and up-to-date with your source files when you specify `-instances=extern`.

For example, if your source files are compiled with the `-g` option (debugging on), the files you need from the database are also compiled with `-g`.

In addition, the template repository tracks changes in your compilation. For example, if you have the `-DDEBUG` flag set to define the name `DEBUG`, the database tracks this. If you omit this flag on a subsequent compile, the compiler reinstantiates those templates on which this dependency is set.

Note – If you remove the source code of a template or stop using a template, instances of the template remain in the cache. If you change the signature of a function template, instances using the old signature remain in the cache. If you run into strange behavior at compile or link time due to these issues, clear the template cache and rebuild the program.

7.5 Template Definition Searching

When you use the definitions-separate template organization, template definitions are not available in the current compilation unit, and the compiler must search for the definition. This section describes how the compiler locates the definition.

Definition searching is somewhat complex and prone to error. Therefore, you should use the definitions-included template file organization if possible. Doing so helps you avoid definition searching altogether. See “[5.2.1 Template Definitions Included](#)” on page 73.

Note – If you use the `-template=no%extdef` option, the compiler will not search for separate source files.

7.5.1 Source File Location Conventions

Without the specific directions provided with an options file, the compiler uses a C front-style method to locate template definition files. This method requires that the template definition file contain the same base name as the template declaration file. This method also requires that the template definition file be on the current `include` path. For example, if the template function `foo()` is located in `foo.h`, the matching template definition file should be named `foo.cc` or some other recognizable source-file extension (`.C`, `.c`, `.cc`, `.cpp`, `.cxx`, or `.c++`). The template definition file must be located in one of the normal `include` directories or in the same directory as its matching header file.

7.5.2 Definitions Search Path

As an alternative to the normal search path set with `-I`, you can specify a search directory for template definition files with the option `-ptidirectory`. Multiple `-pti` flags define multiple search directories—that is, a search path. If you use `-ptidirectory`, the compiler looks for template definition files on this path and ignores the `-I` flag. Since the `-ptidirectory` flag complicates the search rules for source files, use the `-I` option instead of the `-ptidirectory` option.

7.5.3 Troubleshooting a Problematic Search

Sometimes the compiler generates confusing warnings or error messages because it is looking for file that you don't intend to compile. Usually, the problem is that a file, for example `foo.h`, contains template declarations and another file, such as `foo.cc`, gets implicitly included.

If a header file, `foo.h`, has template declarations, the compiler searches for a file called `foo` with a C++ file extension (`.C`, `.c`, `.cc`, `.cpp`, `.cxx`, or `.c++`) by default. If the compiler finds such a file, it includes the file automatically. See [“7.5 Template Definition Searching” on page 97](#) for more information on such searches.

If you have a file `foo.cc` that you don't intend to be treated this way, you have two options:

- Change the name of the `.h` or the `.cc` file to eliminate the name match.
- Disable the automatic search for template definition files by specifying the `-template=no%extdef` option. You must then include all template definitions explicitly in your code and will not be able to use the “definitions separate” model.

Exception Handling

This chapter discusses the C++ compiler's implementation of exception handling. Additional information can be found in “10.2 Using Exceptions in a Multithreaded Program” on page 110. For more information on exception handling, see *The C++ Programming Language*, Third Edition, by Bjarne Stroustrup (Addison-Wesley, 1997).

8.1 Synchronous and Asynchronous Exceptions

Exception handling is designed to support only synchronous exceptions, such as array range checks. The term *synchronous exception* means that exceptions can be originated only from throw expressions.

The C++ standard supports synchronous exception handling with a termination model. *Termination* means that once an exception is thrown, control never returns to the throw point.

Exception handling is not designed to directly handle asynchronous exceptions such as keyboard interrupts. However, you can make exception handling work in the presence of asynchronous events if you are careful. For instance, to make exception handling work with signals, you can write a signal handler that sets a global variable, and create another routine that polls the value of that variable at regular intervals and throws an exception when the value changes. You cannot throw an exception from a signal handler.

8.2 Specifying Runtime Errors

There are five runtime error messages associated with exceptions:

- No handler for the exception
- Unexpected exception thrown
- An exception can only be re-thrown in a handler
- During stack unwinding, a destructor must handle its own exception

- Out of memory

When errors are detected at runtime, the error message displays the type of the current exception and one of the five error messages. By default, the predefined function `terminate()` is called, which then calls `abort()`.

The compiler uses the information provided in the exception specification to optimize code production. For example, table entries for functions that do not throw exceptions are suppressed, and runtime checking for exception specifications of functions is eliminated wherever possible.

8.3 Disabling Exceptions

If you know that exceptions are not used in a program, you can use the compiler option `features=noexcept` to suppress generation of code that supports exception handling. The use of the option results in slightly smaller code size and faster code execution. However, when files compiled with exceptions disabled are linked to files using exceptions, some local objects in the files compiled with exceptions disabled are not destroyed when exceptions occur. By default, the compiler generates code to support exception handling. Unless the time and space overhead is important, it is usually better to leave exceptions enabled.

Note – Because the C++ standard library, `dynamic_cast`, and the default operator `new` require exceptions, you should not turn off exceptions when you compile in standard mode (the default mode).

8.4 Using Runtime Functions and Predefined Exceptions

The standard header `<exception>` provides the classes and exception-related functions specified in the C++ standard. You can access this header only when compiling in standard mode (compiler default mode, or with option `-compat=5`). The following excerpt shows the `<exception>` header file declarations.

```
// standard header <exception>
namespace std {
    class exception {
        exception() throw();
        exception(const exception&) throw();
        exception& operator=(const exception&) throw();
        virtual ~exception() throw();
        virtual const char* what() const throw();
    };
    class bad_exception: public exception {...};
    // Unexpected exception handling
    typedef void (*unexpected_handler)();
```

```

    unexpected_handler
    set_unexpected(unexpected_handler) throw();
    void unexpected();
// Termination handling
typedef void (*terminate_handler)();
terminate_handler set_terminate(terminate_handler) throw();
void terminate();
bool uncaught_exception() throw();
}

```

The standard class `exception` is the base class for all exceptions thrown by selected language constructs or by the C++ standard library. An object of type `exception` can be constructed, copied, and destroyed without generating an exception. The virtual member function `what()` returns a character string that describes the exception.

For compatibility with exceptions as used in C++ release 4.2, the header `<exception.h>` is also provided for use in standard mode. This header allows for a transition to standard C++ code and contains declarations that are not part of standard C++. Update your code to follow the C++ standard (using `<exception>` instead of `<exception.h>`) as development schedules permit.

```

// header <exception.h>, used for transition
#include <exception>
#include <new>
using std::exception;
using std::bad_exception;
using std::set_unexpected;
using std::unexpected;
using std::set_terminate;
using std::terminate;
typedef std::exception xmsg;
typedef std::bad_exception xunexpected;
typedef std::bad_alloc xalloc;

```

In compatibility mode (`-compat [=4]`), header `<exception>` is not available, and header `<exception.h>` refers to the same header provided with C++ release 4.2. It is not reproduced here.

8.5 Mixing Exceptions With Signals and Set jmp/Long jmp

You can use the `set jmp/long jmp` functions in a program where exceptions can occur, as long as they do not interact.

All the rules for using exceptions and `set jmp/long jmp` separately apply. In addition, a `long jmp` from point A to point B is valid only if an exception thrown at A and caught at B would have the same effect. In particular, you must not `long jmp` into or out of a try-block or catch-block (directly or indirectly), or `long jmp` past the initialization or non-trivial destruction of auto variables or temporary variables.

You cannot throw an exception from a signal handler.

8.6 Building Shared Libraries That Have Exceptions

Never use `-Bsymbolic` with programs containing C++ code, use linker map files instead or linker scoping options (See [“4.1 Linker Scoping” on page 61](#)).. With `-Bsymbolic`, references in different modules can bind to different copies of what is supposed to be one global object.

The exception mechanism relies on comparing addresses. If you have two copies of something, their addresses won't compare equal, and the exception mechanism can fail because the exception mechanism relies on comparing what are supposed to be unique addresses.

Improving Program Performance

You can improve the performance of C++ functions by writing those functions in a manner that helps the compiler do a better job of optimizing them. Many books have been written on software performance in general and C++ in particular, and this chapter does not repeat such valuable information, but discusses only those performance techniques that strongly affect the C++ compiler.

9.1 Avoiding Temporary Objects

C++ functions often produce implicit temporary objects, each of which must be created and destroyed. For non-trivial classes, the creation and destruction of temporary objects can be expensive in terms of processing time and memory usage. The C++ compiler does eliminate some temporary objects, but it cannot eliminate all of them.

Write functions to minimize the number of temporary objects as long as your programs remain comprehensible. Techniques include using explicit variables rather than implicit temporary objects and using reference parameters rather than value parameters. Another technique is to implement and use operations such as `+=` rather than implementing and using only `+` and `=`. For example, the first line below introduces a temporary object for the result of `a + b`, while the second line does not.

```
T x = a + b;  
T x(a); x += b;
```

9.2 Using Inline Functions

Calls to small and quick functions can be smaller and quicker when expanded inline than when called normally. Conversely, calls to large or slow functions can be larger and slower when expanded inline than when branched to. Furthermore, all calls to an inline function must be recompiled whenever the function definition changes. Consequently, the decision to use inline functions requires considerable care.

Do not use inline functions when you anticipate changes to the function definition *and* recompiling all callers is expensive. Otherwise, use inline functions when the code to expand the function inline is smaller than the code to call the function *or* the *application* performs significantly faster with the function inline.

The compiler cannot inline all function calls, so making the most effective use of function inlining may require some source changes. Use the `+w` option to learn when function inlining does not occur. In the following situations, the compiler will *not* inline the function:

- The function contains difficult control constructs, such as loops, switch statements, and try/catch statements. Many times these functions execute the difficult control constructs infrequently. To inline such a function, split the function into two parts, an inner part that contains the difficult control constructs and an outer part that decides whether or not to call the inner part. This technique of separating the infrequent part from the frequent part of a function can improve performance even when the compiler can inline the full function.
- The inline function body is large or complicated. Apparently simple function bodies may be complicated because of calls to other inline functions within the body, or because of implicit constructor and destructor calls (as often occurs in constructors and destructors for derived classes). For such functions, inline expansion rarely provides significant performance improvement, and the function is best left unlined.
- The arguments to an inline function call are large or complicated. The compiler is particularly sensitive when the object for an inline member function call is itself the result of an inline function call. To inline functions with complicated arguments, simply compute the function arguments into local variables and then pass the variables to the function.

9.3 Using Default Operators

If a class definition does not declare a parameterless constructor, a copy constructor, a copy assignment operator, or a destructor, the compiler will implicitly declare them. These are called default operators. A C-like struct has these default operators. When the compiler builds a default operator, it knows a great deal about the work that needs to be done and can produce very good code. This code is often much faster than user-written code because the compiler can take advantage of assembly-level facilities while the programmer usually cannot. So, when the default operators do what is needed, the program should not declare user-defined versions of these operators.

Default operators are inline functions, so do not use default operators when inline functions are inappropriate (see the previous section). Otherwise, default operators are appropriate when:

- The user-written parameterless constructor would only call parameterless constructors for its base objects and member variables. Primitive types effectively have “do nothing” parameterless constructors.
- The user-written copy constructor would simply copy all base objects and member variables.
- The user-written copy assignment operator would simply copy all base objects and member variables.
- The user-written destructor would be empty.

Some C++ programming texts suggest that class programmers always define all operators so that any reader of the code will know that the class programmer did not forget to consider the semantics of the default operators. Obviously, this advice interferes with the optimization discussed above. The resolution of the conflict is to place a comment in the code stating that the class is using the default operator.

9.4 Using Value Classes

C++ classes, including structures and unions, are passed and returned by value. For Plain-Old-Data (POD) classes, the C++ compiler is required to pass the struct as would the C compiler. Objects of these classes are passed *directly*. For objects of classes with user-defined copy constructors, the compiler is effectively required to construct a copy of the object, pass a pointer to the copy, and destruct the copy after the return. Objects of these classes are passed *indirectly*. For classes that fall between these two requirements, the compiler can choose. However, this choice affects binary compatibility, so the compiler must choose consistently for every class.

For most compilers, passing objects directly can result in faster execution. This execution improvement is particularly noticeable with small value classes, such as complex numbers or probability values. You can sometimes improve program efficiency by designing classes that are more likely to be passed directly than indirectly.

In compatibility mode (`-compat [=4]`), a class is passed indirectly if it has any one of the following:

- A user-defined constructor
- A virtual function
- A virtual base class
- A base that is passed indirectly
- A non-static data member that is passed indirectly

Otherwise, the class is passed directly.

In standard mode (the default mode), a class is passed indirectly if it has any one of the following:

- A user-defined copy constructor
- A user-defined destructor
- A base that is passed indirectly
- A non-static data member that is passed indirectly

Otherwise, the class is passed directly.

9.4.1 Choosing to Pass Classes Directly

To maximize the chance that a class will be passed directly:

- Use default constructors, especially the default copy constructor, where possible.
- Use the default destructor where possible. The default destructor is not virtual, therefore a class with a default destructor should generally not be a base class.
- Avoid virtual functions and virtual bases.

9.4.2 Passing Classes Directly on Various Processors

Classes (and unions) that are passed directly by the C++ compiler are passed exactly as the C compiler would pass a struct (or union). However, C++ structs and unions are passed differently on different architectures.

TABLE 9-1 Passing of Structs and Unions by Architecture

Architecture	Description
SPARC V7/V8	Structs and unions are passed and returned by allocating storage within the caller and passing a pointer to that storage. (That is, all structs and unions are passed by reference.)
SPARC V9	Structs with a size no greater than 16 bytes (32 bytes) are passed (returned) in registers. Unions and all other structs are passed and returned by allocating storage within the caller and passing a pointer to that storage. (That is, small structs are passed in registers; unions and large structs are passed by reference.) As a consequence, small value classes are passed as efficiently as primitive types.
x86 platforms	Structs and unions are passed by allocating space on the stack and copying the argument onto the stack. Structs and unions are returned by allocating a temporary object in the caller's frame and passing the address of the temporary object as an implicit first parameter.

9.5 Cache Member Variables

Accessing member variables is a common operation in C++ member functions.

The compiler must often load member variables from memory through the `this` pointer. Because values are being loaded through a pointer, the compiler sometimes cannot determine when a second load must be performed or whether the value loaded before is still valid. In these cases, the compiler must choose the safe, but slow, approach and reload the member variable each time it is accessed.

You can avoid unnecessary memory reloads by explicitly caching the values of member variables in local variables, as follows:

- Declare a local variable and initialize it with the value of the member variable.
- Use the local variable in place of the member variable throughout the function.
- If the local variable changes, assign the final value of the local variable to the member variable. However, this optimization may yield undesired results if the member function calls another member function on that object.

This optimization is most productive when the values can reside in registers, as is the case with primitive types. The optimization may also be productive for memory-based values because the reduced aliasing gives the compiler more opportunity to optimize.

This optimization may be counter productive if the member variable is often passed by reference, either explicitly or implicitly.

On occasion, the desired semantics of a class requires explicit caching of member variables, for instance when there is a potential alias between the current object and one of the member function's arguments. For example:

```
complex& operator*=(complex& left, complex& right)
{
    left.real = left.real * right.real + left.imag * right.imag;
    left.imag = left.real * right.imag + left.image * right.real;
}
```

will yield unintended results when called with:

```
x*=x;
```


Building Multithreaded Programs

This chapter explains how to build multithreaded programs. It also discusses the use of exceptions, explains how to share C++ Standard Library objects across threads, and describes how to use classic (old) iostreams in a multithreading environment.

For more information about multithreading, see the *Multithreaded Programming Guide*.

See also the *OpenMP API User's Guide* for information on using OpenMP shared memory parallelization directives to create multithreaded programs.

10.1 Building Multithreaded Programs

All libraries shipped with the C++ compiler are multithreading safe. If you want to build a multithreaded application, or if you want to link your application to a multithreaded library, you must compile and link your program with the `-mt` option. This option passes `-D_REENTRANT` to the preprocessor and passes `-lthread` in the correct order to `ld`. For compatibility mode (`-compat [=4]`), the `-mt` option ensures that `libthread` is linked before `libc`. For standard mode (the default mode), the `-mt` option ensures that `libthread` is linked before `libCrun`. Use of `-mt` is recommended as a simpler and less error-prone alternative to specifying the macro and library.

10.1.1 Indicating Multithreaded Compilation

You can check whether an application is linked to `libthread` or not by using the `ldd` command:

```
example% CC -mt myprog.cc
example% ldd a.out
libm.so.1 => /usr/lib/libm.so.1
libCrun.so.1 => /usr/lib/libCrun.so.1
libthread.so.1 => /usr/lib/libthread.so.1
libc.so.1 => /usr/lib/libc.so.1
libdl.so.1 => /usr/lib/libdl.so.1
```

10.1.2 Using C++ Support Libraries With Threads and Signals

The C++ support libraries, `libCrun`, `libiostream`, `libCstd`, and `libC` are multithread safe but are not `async` safe. This means that in a multithreaded application, functions available in the support libraries should not be used in signal handlers. Doing so can result in a deadlock situation.

It is not safe to use the following in a signal handler in a multithreaded application:

- `Iostreams`
- `new` and `delete` expressions
- `Exceptions`

10.2 Using Exceptions in a Multithreaded Program

The current exception-handling implementation is safe for multithreading; exceptions in one thread do not interfere with exceptions in other threads. However, you cannot use exceptions to communicate across threads; an exception thrown from one thread cannot be caught in another.

Each thread can set its own `terminate()` or `unexpected()` function. Calling `set_terminate()` or `set_unexpected()` in one thread affects only the exceptions in that thread. The default function for `terminate()` is `abort()` for any thread (see [“8.2 Specifying Runtime Errors” on page 99](#)).

10.2.1 Thread Cancellation

Thread cancellation through a call to `pthread_cancel(3T)` results in the destruction of automatic (local nonstatic) objects on the stack except when you specify `-noex` or `-features=no%except`.

`pthread_cancel(3T)` uses the same mechanism as exceptions. When a thread is cancelled, the execution of local destructors is interleaved with the execution of cleanup routines that the user has registered with `pthread_cleanup_push()`. The local objects for functions called after a particular cleanup routine is registered are destroyed before that routine is executed.

10.3 Sharing C++ Standard Library Objects Between Threads

The C++ Standard Library (`libc++ -library=c++`) is MT-Safe, with the exception of some locales, and it ensures that the internals of the library work properly in a multi-threaded environment. You still need to lock around any library objects that you yourself share between threads. See the man pages for `setlocale(3C)` and `attributes(5)`.

For example, if you instantiate a string, then create a new thread and pass that string to the thread by reference, then you must lock around write access to that string, since you are explicitly sharing the one string object between threads. (The facilities provided by the library to accomplish this task are described below.)

On the other hand, if you pass the string to the new thread by value, you do not need to worry about locking, even though the strings in the two different threads may be sharing a representation through Rogue Wave’s “copy on write” technology. The library handles that locking automatically. You are only required to lock when making an object available to multiple threads explicitly, either by passing references between threads or by using global or static objects.

The following describes the locking (synchronization) mechanism used internally in the C++ Standard Library to ensure correct behavior in the presence of multiple threads.

Two synchronization classes provide mechanisms for achieving multithreaded safety; `_RWSTMutex` and `_RWSTGuard`.

The `_RWSTMutex` class provides a platform-independent locking mechanism through the following member functions:

- `void acquire()`—Acquires a lock on self, or blocks until such a lock can be obtained.
- `void release()`—Releases a lock on self.

```
class _RWSTMutex
{
public:
    _RWSTMutex ();
    ~_RWSTMutex ();
    void acquire ();
    void release ();
};
```

The `_RWSTGuard` class is a convenience wrapper class that encapsulates an object of `_RWSTMutex` class. An `_RWSTGuard` object attempts to acquire the encapsulated mutex in its constructor (throwing an exception of type `::thread_error`, derived from `std::exception` on error), and releases the mutex in its destructor (the destructor never throws an exception).

```
class _RWSTGuard
{
public:
```

```
    _RWSTDGuard (_RWSTMutex&);  
    ~_RWSTDGuard ();  
};
```

Additionally, you can use the macro `_RWSTD_MT_GUARD(mutex)` (formerly `_STDGUARD`) to conditionally create an object of the `_RWSTDGuard` class in multithread builds. The object guards the remainder of the code block in which it is defined from being executed by multiple threads simultaneously. In single-threaded builds the macro expands into an empty expression.

The following example illustrates the use of these mechanisms.

```
#include <rw/stdmutex.h>  
  
//  
// An integer shared among multiple threads.  
//  
int I;  
  
//  
// A mutex used to synchronize updates to I.  
//  
_RWSTMutex I_mutex;  
  
//  
// Increment I by one. Uses an _RWSTMutex directly.  
//  
void increment_I ()  
{  
    I_mutex.acquire(); // Lock the mutex.  
    I++;  
    I_mutex.release(); // Unlock the mutex.  
}  
  
//  
// Decrement I by one. Uses an _RWSTDGuard.  
//  
void decrement_I ()  
{  
    _RWSTDGuard guard(I_mutex); // Acquire the lock on I_mutex.  
    --I;  
    //  
    // The lock on I is released when destructor is called on guard.  
    //  
}
```


10.4 Using Classic `iostreams` in a Multithreading Environment

This section describes how to use the `iostream` classes of the `libc` and `libiostream` libraries for input-output (I/O) in a multithreaded environment. It also provides examples of how to extend functionality of the library by deriving from the `iostream` classes. This section is *not* a guide for writing multithreaded code in C++, however.

The discussion here applies only to the old `iostreams` (`libc` and `libiostream`) and does not apply to `libcstd`, the new `iostream` that is part of the C++ Standard Library.

The `iostream` library allows its interfaces to be used by applications in a multithreaded environment by programs that utilize the multithreading capabilities when running supported versions of the Solaris operating system. Applications that utilize the single-threaded capabilities of previous versions of the library are not affected.

A library is defined to be MT-safe if it works correctly in an environment with threads. Generally, this “correctness” means that all of its public functions are reentrant. The `iostream` library provides protection against multiple threads that attempt to modify the state of objects (that is, instances of a C++ class) shared by more than one thread. However, the scope of MT-safety for an `iostream` object is confined to the period in which the object’s public member function is executing.

Note – An application is *not* automatically guaranteed to be MT-safe because it uses MT-safe objects from the `libc` library. An application is defined to be MT-safe only when it executes as expected in a multithreaded environment.

10.4.1 Organization of the MT-Safe `iostream` Library

The organization of the MT-safe `iostream` library is slightly different from other versions of the `iostream` library. The exported interface of the library refers to the public and protected member functions of the `iostream` classes and the set of base classes available, and is consistent with other versions; however, the class hierarchy is different. See “[10.4.2 Interface Changes to the `iostream` Library](#)” on page 119 for details.

The original core classes have been renamed with the prefix `unsafe_`. [Table 10–1](#) lists the classes that are the core of the `iostream` package.

TABLE 10–1 `iostream` Original Core Classes

Class	Description
<code>stream_MT</code>	The base class for MT-safe classes.

TABLE 10-1 `iostream` Original Core Classes (Continued)

Class	Description
<code>streambuf</code>	The base class for buffers.
<code>unsafe_ios</code>	A class that contains state variables that are common to the various stream classes; for example, error and formatting state.
<code>unsafe_istream</code>	A class that supports formatted and unformatted conversion from sequences of characters retrieved from the <code>streambufs</code> .
<code>unsafe_ostream</code>	A class that supports formatted and unformatted conversion to sequences of characters stored into the <code>streambufs</code> .
<code>unsafe_iostream</code>	A class that combines <code>unsafe_istream</code> and <code>unsafe_ostream</code> classes for bidirectional operations.

Each MT-safe class is derived from the base class `stream_MT`. Each MT-safe class, except `streambuf`, is also derived from the existing `unsafe_` base class. Here are some examples:

```
class streambuf: public stream_MT {...};
class ios: virtual public unsafe_ios, public stream_MT {...};
class istream: virtual public ios, public unsafe_istream {...};
```

The class `stream_MT` provides the mutual exclusion (mutex) locks required to make each `iostream` class MT-safe; it also provides a facility that dynamically enables and disables the locks so that the MT-safe property can be dynamically changed. The basic functionality for I/O conversion and buffer management are organized into the `unsafe_` classes; the MT-safe additions to the library are confined to the derived classes. The MT-safe version of each class contains the same protected and public member functions as the `unsafe_` base class. Each member function in the MT-safe version class acts as a wrapper that locks the object, calls the same function in the `unsafe_` base class, and unlocks the object.

Note – The class `streambuf` is *not* derived from an unsafe class. The public and protected member functions of class `streambuf` are reentrant by locking. Unlocked versions, suffixed with `_unlocked`, are also provided.

10.4.1.1 Public Conversion Routines

A set of reentrant public functions that are MT-safe have been added to the `iostream` interface. A user-specified buffer is an additional argument to each function. These functions are described as follows.

TABLE 10-2 MT-Safe Reentrant Public Functions

Function	Description
char *oct_r (char *buf, int buflen, long num, int width)	Returns a pointer to the ASCII string that represents the number in octal. A width of nonzero is assumed to be the field width for formatting. The returned value is not guaranteed to point to the beginning of the user-provided buffer.
char *hex_r (char *buf, int buflen, long num, int width)	Returns a pointer to the ASCII string that represents the number in hexadecimal. A width of nonzero is assumed to be the field width for formatting. The returned value is not guaranteed to point to the beginning of the user-provided buffer.
char *dec_r (char *buf, int buflen, long num, int width)	Returns a pointer to the ASCII string that represents the number in decimal. A width of nonzero is assumed to be the field width for formatting. The returned value is not guaranteed to point to the beginning of the user-provided buffer.
char *chr_r (char *buf, int buflen, long num, int width)	Returns a pointer to the ASCII string that contains character chr. If the width is nonzero, the string contains width blanks followed by chr. The returned value is not guaranteed to point to the beginning of the user-provided buffer.
char *form_r (char *buf, int buflen, long num, int width)	Returns a pointer of the string formatted by sprintf, using the format string format and any remaining arguments. The buffer must have sufficient space to contain the formatted string.

Note – The public conversion routines of the `iostream` library (`oct`, `hex`, `dec`, `chr`, and `form`) that are present to ensure compatibility with an earlier version of `libc` are *not* MT-safe.

10.4.1.2

Compiling and Linking With the MT-Safe `libc` Library

When you build an application that uses the `iostream` classes of the `libc` library to run in a multithreaded environment, compile and link the source code of the application using the `-mt` option. This option passes `-D_REENTRANT` to the preprocessor and `-pthread` to the linker.

Note – Use `-mt` (rather than `-lthread`) to link with `libc` and `libthread`. This option ensures proper linking order of the libraries. Using `-lthread` improperly could cause your application to work incorrectly.

Single-threaded applications that use `iostream` classes do not require special compiler or linker options. By default, the compiler links with the `libc` library.

10.4.1.3 MT-Safe `iostream` Restrictions

The restricted definition of MT-safety for the `iostream` library means that a number of programming idioms used with `iostream` are unsafe in a multithreaded environment using shared `iostream` objects.

Checking Error State

To be MT-safe, error checking must occur in a critical region with the I/O operation that causes the error. The following example illustrates how to check for errors:

EXAMPLE 10-1 Checking Error State

```
#include <iostream.h>
enum iostate {IOok, IOeof, IOfail};

iostate read_number(istream& istr, int& num)
{
    stream_locker sl(istr, stream_locker::lock_now);

    istr >> num;

    if (istr.eof()) return IOeof;
    if (istr.fail()) return IOfail;
    return IOok;
}
```

In this example, the constructor of the `stream_locker` object `sl` locks the `istream` object `istr`. The destructor of `sl`, called at the termination of `read_number`, unlocks `istr`.

Obtaining Characters Extracted by Last Unformatted Input Operation

To be MT-safe, the `gcount` function must be called within a thread that has exclusive use of the `istream` object for the period that includes the execution of the last input operation and `gcount` call. The following example shows a call to `gcount`:

EXAMPLE 10-2 Calling `gcount`

```
#include <iostream.h>
#include <rlocks.h>
void fetch_line(istream& istr, char* line, int& linecount)
```

EXAMPLE 10-2 Calling gcount (Continued)

```

{
    stream_locker sl(istr, stream_locker::lock_defer);

    sl.lock(); // lock the stream istr
    istr >> line;
    linecount = istr.gcount();
    sl.unlock(); // unlock istr
    ...
}

```

In this example, the `lock` and `unlock` member functions of class `stream_locker` define a mutual exclusion region in the program.

User-Defined I/O Operations

To be MT-safe, I/O operations defined for a user-defined type that involve a specific ordering of separate operations must be locked to define a critical region. The following example shows a user-defined I/O operation:

EXAMPLE 10-3 User-Defined I/O Operations

```

#include <rlocks.h>
#include <iostream.h>
class mystream: public istream {

    // other definitions...
    int getRecord(char* name, int& id, float& gpa);
};

int mystream::getRecord(char* name, int& id, float& gpa)
{
    stream_locker sl(this, stream_locker::lock_now);

    *this >> name;
    *this >> id;
    *this >> gpa;

    return this->fail() == 0;
}

```

10.4.1.4 Reducing Performance Overhead of MT-Safe Classes

Using the MT-safe classes in this version of the `libc` library results in some amount of performance overhead, even in a single-threaded application; however, if you use the `unsafe_` classes of `libc`, this overhead can be avoided.

The scope resolution operator can be used to execute member functions of the base `unsafe_` classes; for example:

```
cout.unsafe_ostream::put('4');
```

```
cin.unsafe_istream::read(buf, len);
```

Note – The `unsafe_` classes cannot be safely used in multithreaded applications.

Instead of using `unsafe_` classes, you can make the `cout` and `cin` objects `unsafe` and then use the normal operations. A slight performance deterioration results. The following example shows how to use `unsafe` `cout` and `cin`:

EXAMPLE 10-4 Disabling MT-Safety

```
#include <iostream.h>
//disable mt-safety
cout.set_safe_flag(stream_MT::unsafe_object);
//disable mt-safety
cin.set_safe_flag(stream_MT::unsafe_object);
cout.put("4");
cin.read(buf, len);
```

When an `iostream` object is MT-safe, mutex locking is provided to protect the object's member variables. This locking adds unnecessary overhead to an application that only executes in a single-threaded environment. To improve performance, you can dynamically switch an `iostream` object to and from MT-safety. The following example makes an `iostream` object MT-unsafe:

EXAMPLE 10-5 Switching to MT-Unsafe

```
fs.set_safe_flag(stream_MT::unsafe_object); // disable MT-safety
... do various i/o operations
```

You can safely use an MT-unsafe stream in code where an `iostream` is *not* shared by threads; for example, in a program that has only one thread, or in a program where each `iostream` is private to a thread.

If you explicitly insert synchronization into the program, you can also safely use MT-unsafe `iostreams` in an environment where an `iostream` is shared by threads. The following example illustrates the technique:

EXAMPLE 10-6 Using Synchronization With MT-Unsafe Objects

```
generic_lock();
fs.set_safe_flag(stream_MT::unsafe_object);
... do various i/o operations
generic_unlock();
```

where the `generic_lock` and `generic_unlock` functions can be any synchronization mechanism that uses such primitives as mutex, semaphores, or reader/writer locks.

Note – The `stream_locker` class provided by the `libc` library is the preferred mechanism for this purpose.

See “10.4.5 Object Locks” on page 122 for more information.

10.4.2 Interface Changes to the `iostream` Library

This section describes the interface changes made to the `iostream` library to make it MT-Safe.

10.4.2.1 The New Classes

The following table lists the new classes added to the `libc` interfaces.

EXAMPLE 10-7 New Classes

```
stream_MT
stream_locker
unsafe_ios
unsafe_istream
unsafe_ostream
unsafe_iostream
unsafe_fstreambase
unsafe_strstreambase
```

10.4.2.2 The New Class Hierarchy

The following table lists the new class hierarchy added to the `iostream` interfaces.

EXAMPLE 10-8 New Class Hierarchy

```
class streambuf: public stream_MT {...};
class unsafe_ios {...};
class ios: virtual public unsafe_ios, public stream_MT {...};
class unsafe_fstreambase: virtual public unsafe_ios {...};
class fstreambase: virtual public ios, public unsafe_fstreambase
    {...};
class unsafe_strstreambase: virtual public unsafe_ios {...};
class strstreambase: virtual public ios, public unsafe_strstreambase {...};
class unsafe_istream: virtual public unsafe_ios {...};
class unsafe_ostream: virtual public unsafe_ios {...};
class istream: virtual public ios, public unsafe_istream {...};
class ostream: virtual public ios, public unsafe_ostream {...};
class unsafe_iostream: public unsafe_istream, public unsafe_ostream {...};
```

10.4.2.3 The New Functions

The following table lists the new functions added to the `iostream` interfaces.

EXAMPLE 10-9 New Functions

```

class streambuf {
public:
    int sgetc_unlocked();
    void sgetn_unlocked(char *, int);
    int snextc_unlocked();
    int sbumpc_unlocked();
    void stosscc_unlocked();
    int in_avail_unlocked();
    int sputbackc_unlocked(char);
    int sputc_unlocked(int);
    int sputn_unlocked(const char *, int);
    int out_waiting_unlocked();
protected:
    char* base_unlocked();
    char* ebuf_unlocked();
    int blen_unlocked();
    char* pbase_unlocked();
    char* eback_unlocked();
    char* gptra_unlocked();
    char* egptr_unlocked();
    char* pptra_unlocked();
    void setp_unlocked(char*, char*);
    void setg_unlocked(char*, char*, char*);
    void pbump_unlocked(int);
    void gbump_unlocked(int);
    void setb_unlocked(char*, char*, int);
    int unbuffered_unlocked();
    char *eptra_unlocked();
    void unbuffered_unlocked(int);
    int allocate_unlocked(int);
};

class filebuf: public streambuf {
public:
    int is_open_unlocked();
    filebuf* close_unlocked();
    filebuf* open_unlocked(const char*, int, int =
        filebuf::openprot);

    filebuf* attach_unlocked(int);
};

class strstreambuf: public streambuf {
public:
    int freeze_unlocked();
    char* str_unlocked();
};

unsafe_ostream& endl(unsafe_ostream&);
unsafe_ostream& ends(unsafe_ostream&);
unsafe_ostream& flush(unsafe_ostream&);
unsafe_istream& ws(unsafe_istream&);
unsafe_ios& dec(unsafe_ios&);
unsafe_ios& hex(unsafe_ios&);
unsafe_ios& oct(unsafe_ios&);

```


EXAMPLE 10-9 New Functions (Continued)

```
char* dec_r (char* buf, int buflen, long num, int width)
char* hex_r (char* buf, int buflen, long num, int width)
char* oct_r (char* buf, int buflen, long num, int width)
char* chr_r (char* buf, int buflen, long chr, int width)
char* str_r (char* buf, int buflen, const char* format, int width
            = 0);
char* form_r (char* buf, int buflen, const char* format,...)
```

10.4.3 Global and Static Data

Global and static data in a multithreaded application are not safely shared among threads. Although threads execute independently, they share access to global and static objects within the process. If one thread modifies such a shared object, all the other threads within the process observe the change, making it difficult to maintain state over time. In C++, class objects (instances of a class) maintain state by the values in their member variables. If a class object is shared, it is vulnerable to changes made by other threads.

When a multithreaded application uses the `iostream` library and includes `iostream.h`, the standard streams—`cout`, `cin`, `cerr`, and `clog`—are, by default, defined as global shared objects. Since the `iostream` library is MT-safe, it protects the state of its shared objects from access or change by another thread while a member function of an `iostream` object is executing. However, the scope of MT-safety for an object is confined to the period in which the object's public member function is executing. For example,

```
int c;
cin.get(c);
```

gets the next character in the `get` buffer and updates the buffer pointer in *ThreadA*. However, if the next instruction in *ThreadA* is another `get` call, the `libc` library does not guarantee to return the next character in the sequence. It is not guaranteed because, for example, *ThreadB* may have also executed the `get` call in the intervening period between the two `get` calls made in *ThreadA*.

See “10.4.5 Object Locks” on page 122 for strategies for dealing with the problems of shared objects and multithreading.

10.4.4 Sequence Execution

Frequently, when `iostream` objects are used, a sequence of I/O operations must be MT-safe. For example, the code:

```
cout << " Error message:" << strerror[err_number] << "\n";
```

involves the execution of three member functions of the `cout` stream object. Since `cout` is a shared object, the sequence must be executed atomically as a critical section to work correctly in a multithreaded environment. To perform a sequence of operations on an `iostream` class object atomically, you must use some form of locking.

The `libc` library now provides the `stream_locker` class for locking operations on an `iostream` object. See “[10.4.5 Object Locks](#)” on page 122 for information about the `stream_locker` class.

10.4.5 Object Locks

The simplest strategy for dealing with the problems of shared objects and multithreading is to avoid the issue by ensuring that `iostream` objects are local to a thread. For example,

- Declare objects locally within a thread’s entry function.
- Declare objects in thread-specific data. (For information on how to use thread specific data, see the `thr_keycreate(3T)` man page.)
- Dedicate a stream object to a particular thread. The object thread is `private` by convention.

However, in many cases, such as default shared standard stream objects, it is not possible to make the objects local to a thread, and an alternative strategy is required.

To perform a sequence of operations on an `iostream` class object atomically, you must use some form of locking. Locking adds some overhead even to a single-threaded application. The decision whether to add locking or make `iostream` objects private to a thread depends on the thread model chosen for the application: Are the threads to be independent or cooperating?

- If each independent thread is to produce or consume data using its own `iostream` object, the `iostream` objects are private to their respective threads and locking is not required.
- If the threads are to cooperate (that is, they are to share the same `iostream` object), then access to the shared object must be synchronized and some form of locking must be used to make sequential operations atomic.

10.4.5.1 Class `stream_locker`

The `iostream` library provides the `stream_locker` class for locking a series of operations on an `iostream` object. You can, therefore, minimize the performance overhead incurred by dynamically enabling or disabling locking in `iostream` objects.

Objects of class `stream_locker` can be used to make a sequence of operations on a stream object atomic. For example, the code shown in the example below seeks to find a position in a file and reads the next block of data.

EXAMPLE 10–10 Example of Using Locking Operations

```
#include <fstream.h>
#include <rlocks.h>
```

EXAMPLE 10-10 Example of Using Locking Operations (Continued)

```

void lock_example (fstream& fs)
{
    const int len = 128;
    char buf[len];
    int offset = 48;
    stream_locker s_lock(fs, stream_locker::lock_now);
    ....// open file
    fs.seekg(offset, ios::beg);
    fs.read(buf, len);
}

```

In this example, the constructor for the `stream_locker` object defines the beginning of a mutual exclusion region in which only one thread can execute at a time. The destructor, called after the return from the function, defines the end of the mutual exclusion region. The `stream_locker` object ensures that both the seek to a particular offset in a file and the read from the file are performed together, atomically, and that *ThreadB* cannot change the file offset before the original *ThreadA* reads the file.

An alternative way to use a `stream_locker` object is to explicitly define the mutual exclusion region. In the following example, to make the I/O operation and subsequent error checking atomic, `lock` and `unlock` member function calls of a `stream_locker` object are used.

EXAMPLE 10-11 Making I/O Operation and Error Checking Atomic

```

{
    ...
    stream_locker file_lck(openfile_stream,
                          stream_locker::lock_defer);
    ....
    file_lck.lock(); // lock openfile_stream
    openfile_stream << "Value: " << int_value << "\n";
    if(!openfile_stream) {
        file_error("Output of value failed\n");
        return;
    }
    file_lck.unlock(); // unlock openfile_stream
}

```

For more information, see the `stream_locker(3CC4)` man page.

10.4.6 MT-Safe Classes

You can extend or specialize the functionality of the `iostream` classes by deriving new classes. If objects instantiated from the derived classes will be used in a multithreaded environment, the classes must be MT-safe.

Considerations when deriving MT-safe classes include:

- Making a class object MT-safe by protecting the internal state of the object from multiple-thread modification. To do this, serialize access to member variables in public and protected member functions with mutex locks.
- Making a sequence of calls to member functions of an MT-safe base class atomic, using a `stream_locker` object.
- Avoiding locking overhead by using the `_unlocked` member functions of `streambuf` within critical regions defined by `stream_locker` objects.
- Locking the public virtual functions of class `streambuf` in case the functions are called directly by an application. These functions are: `xsgetn`, `underflow`, `pbackfail`, `xsputn`, `overflow`, `seekoff`, and `seekpos`.
- Extending the formatting state of an `ios` object by using the member functions `iword` and `pword` in class `ios`. However, a problem can occur if more than one thread is sharing the same index to an `iword` or `pword` function. To make the threads MT-safe, use an appropriate locking scheme.
- Locking member functions that return the value of a member variable greater in size than a `char`.

10.4.7 Object Destruction

Before an `iostream` object that is shared by several threads is deleted, the main thread must verify that the subthreads are finished with the shared object. The following example shows how to safely destroy a shared object.

EXAMPLE 10-12 Destroying a Shared Object

```
#include <fstream.h>
#include <thread.h>
fstream* fp;

void *process_rtn(void*)
{
    // body of sub-threads which uses fp...
}

void multi_process(const char* filename, int numthreads)
{
    fp = new fstream(filename, ios::in); // create fstream object
                                        // before creating threads.
    // create threads
    for (int i=0; i<numthreads; i++)
        thr_create(0, STACKSIZE, process_rtn, 0, 0, 0);

    ...
    // wait for threads to finish
    for (int i=0; i<numthreads; i++)
        thr_join(0, 0, 0);

    delete fp; // delete fstream object after
```

EXAMPLE 10-12 Destroying a Shared Object (Continued)

```

    fp = NULL;                // all threads have completed.
}

```

10.4.8 An Example Application

The following code provides an example of a multiply-threaded application that uses `iostream` objects from the `libc` library in an MT-safe way.

The example application creates up to 255 threads. Each thread reads a different input file, one line at a time, and outputs the line to an output file, using the standard output stream, `cout`. The output file, which is shared by all threads, is tagged with a value that indicates which thread performed the output operation.

EXAMPLE 10-13 Using `iostream` Objects in an MT-Safe Way

```

// create tagged thread data
// the output file is of the form:
//   <tag><string of data>\n
// where tag is an integer value in a unsigned char.
// Allows up to 255 threads to be run in this application
// <string of data> is any printable characters
// Because tag is an integer value written as char,
// you need to use od to look at the output file, suggest:
//   od -c out.file |more

#include <stdlib.h>
#include <stdio.h>
#include <iostream.h>
#include <fstream.h>
#include <thread.h>

struct thread_args {
    char* filename;
    int thread_tag;
};

const int thread_bufsize = 256;

// entry routine for each thread
void* ThreadDuties(void* v) {
    // obtain arguments for this thread
    thread_args* tt = (thread_args*)v;
    char ibuf[thread_bufsize];
    // open thread input file
    ifstream instr(tt->filename);
    stream_locker lockout(cout, stream_locker::lock_defer);
    while(1) {
        // read a line at a time
        instr.getline(ibuf, thread_bufsize - 1, '\n');
        if(instr.eof())
            break;
    }
}

```

EXAMPLE 10-13 Using `iostream` Objects in an MT-Safe Way (Continued)

```

// lock cout stream so the i/o operation is atomic
lockout.lock();
// tag line and send to cout
cout << (unsigned char)tt->thread_tag << ibuf << "\n";
lockout.unlock();
}
return 0;
}

int main(int argc, char** argv) {
// argv: 1+ list of filenames per thread
if(argc < 2) {
    cout << "usage: " << argv[0] << " <files..>\n";
    exit(1);
}
int num_threads = argc - 1;
int total_tags = 0;

// array of thread ids
thread_t created_threads[thread_bufsize];
// array of arguments to thread entry routine
thread_args thr_args[thread_bufsize];
int i;
for(i = 0; i < num_threads; i++) {
    thr_args[i].filename = argv[1 + i];
// assign a tag to a thread - a value less than 256
    thr_args[i].thread_tag = total_tags++;
// create threads
    thr_create(0, 0, ThreadDuties, &thr_args[i],
        THR_SUSPENDED, &created_threads[i]);
}

for(i = 0; i < num_threads; i++) {
    thr_continue(created_threads[i]);
}
for(i = 0; i < num_threads; i++) {
    thr_join(created_threads[i], 0, 0);
}
return 0;
}

```

10.5 Memory Barrier Intrinsic

The compiler provides the header file `mbarrier.h`, which defines various memory barrier intrinsic for SPARC and x86 processors. These intrinsic may be of use for developers writing multithreaded code using their own synchronization primitives. Users are advised to refer to the documentation of their processors to determine when and whether these intrinsic are necessary for their particular situation.

Memory ordering intrinsic supported by `mbarrier.h`:

- `__machine_r_barrier()` — This is a *read* barrier. It ensures that all the load operations before the barrier will be completed before all the load operations after the barrier.

- `__machine_w_barrier()` — This is a *write* barrier. It ensures that all the store operations before the barrier will be completed before all the store operations after the barrier.
- `__machine_rw_barrier()` — This is a *read—write* barrier. It ensures that all the load and store operations before the barrier will be completed before all the load and store operations after the barrier.
- `__machine_acq_barrier()` — This is a barrier with *acquire* semantics. It ensures that all the load operations before the barrier will be completed before all the load and store operations after the barrier.
- `__machine_rel_barrier()` — This is a barrier with *release* semantics. It ensures that all the load and store operations before the barrier will be completed before all the store operations after the barrier.
- `__compiler_barrier()` — Prevents the compiler from moving memory accesses across the barrier.

All the barrier intrinsics with the exception of the `__compiler_barrier()` intrinsic generate memory ordering instructions, on x86 these are `mfence`, `sfence`, or `lfence` instructions, on SPARC platforms these are `membar` instructions.

The `__compiler_barrier()` intrinsic generates no instructions and instead informs the compiler that all previous memory operations must be completed before any future memory operations are initiated. The practical result of this is that all non-local variables and local variables with the `static` storage class specifier will be stored back to memory before the barrier, and reloaded after the barrier, and the compiler will not mix memory operations from before the barrier with those after. All other barriers implicitly include the behaviour of the `__compiler_barrier()` intrinsic.

For example, in the following code the presence of the `__compiler_barrier()` intrinsic stops the compiler from merging the two loops:

```
#include "mbarrier.h"
int thread_start[16];
void start_work()
{
    /* Start all threads */
    for (int i=0; i<8; i++)
    {
        thread_start[i]=1;
    }
    __compiler_barrier();
    /* Wait for all threads to complete */
    for (int i=0; i<8; i++)
    {
        while (thread_start[i]==1){}
    }
}
```


PART III

Libraries

Using Libraries

Libraries provide a way to share code among several applications and a way to reduce the complexity of very large applications. The C++ compiler gives you access to a variety of libraries. This chapter explains how to use these libraries.

11.1 The C Libraries

The Oracle Solaris operating system comes with several libraries installed in `/usr/lib`. Most of these libraries have a C interface. Of these, the `libc` and `libm` libraries are linked by the `CC` driver by default. The library `libthread` is linked if you use the `-mt` option. To link any other system library, use the appropriate `-l` option at link time. For example, to link the `libdemangle` library, pass `-ldemangle` on the `CC` command line at link time:

```
example% CC text.c -ldemangle
```

The C++ compiler has its own runtime support libraries. All C++ applications are linked to these libraries by the `CC` driver. The C++ compiler also comes with several other useful libraries, as explained in the following section.

11.2 Libraries Provided With the C++ Compiler

Several libraries are shipped with the C++ compiler. Some of these libraries are available only in compatibility mode (`-compat=4`), some are available only in the standard mode (`-compat=5`), and some are available in both modes. The `libc` and `libdemangle` libraries have a C interface and can be linked to an application in either mode.

The following table lists the libraries that are shipped with the C++ compiler and the modes in which they are available.

TABLE 11-1 Libraries Shipped With the C++ Compiler

Library	Description	Available Modes
libstlport	STLport implementation of the standard library.	-compat=5
libstlport_dbg	STLport library for debug mode	-compat=5
libCrun	C++ runtime	-compat=5
libCstd	C++ standard library	-compat=5
libiostream	Classic iostreams	-compat=5
libC	C++ runtime, classic iostreams	-compat=4
libcsunimath	Supports the -xia option	-compat=5
libcomplex	complex-number library	-compat=4
librwtool	Tools.h++ 7	-compat=4, -compat=5
librwtool_dbg	Debug-enabled Tools.h++ 7	-compat=4, -compat=5
libgc	Garbage collection	C interface
libdemangle	Demangling	C interface

Note – Do not redefine or modify any of the configuration macros for STLport, Rogue Wave or Solaris Studio C++ libraries. The libraries are configured and built in a way that works with the C++ compiler. libCstd and Tool.h++ are configured to inter-operate so modifying the configuration macros results in programs that will not compile, will not link, or do not run properly.

11.2.1 C++ Library Descriptions

A brief description of each of these libraries follows.

- **libCrun:** This library contains the runtime support needed by the compiler in the standard mode (-compat=5). It provides support for new/delete, exceptions, and RTTI.

libCstd: This is the C++ standard library. In particular, it includes iostreams. If you have existing sources that use the classic iostreams and you want to make use of the standard iostreams, you have to modify your sources to conform to the new interface. See the *C++ Standard Library Reference* online manual for details.

- `libiostream`: This is the classic iostreams library built with `-compat=5`. If you have existing sources that use the classic iostreams and you want to compile these sources with the standard mode (`-compat=5`), you can use `libiostream` without modifying your sources. Use `-library=iostream` to get this library.

Note – Much of the standard library depends on using standard iostreams. Using classic iostreams in the same program can cause problems.

- `libc`: This is the library needed in compatibility mode (`-compat=4`). It contains the C++ runtime support as well as the classic iostreams.
- `libcomplex`: This library provides complex arithmetic in compatibility mode (`-compat=4`). In the standard mode, the complex arithmetic functionality is available in `libcstd`.
- `libstlport`: This is the STLport implementation of the C++ standard library. You can use this library instead of the default `libcstd` by specifying the option `-library=stlport4`. However, you cannot use `libstlport` and `libcstd` in the same program. You must compile and link everything, including imported libraries, using one or the other exclusively.
- `librwtool (Tools.h++)`: `Tools.h++` is a C++ foundation class library from RogueWave. Version 7 is provided. This library is obsolete and use of the library is deprecated in new code. It is provided to accommodate programs written for C++ 4.2 that used `RW Tools.h++`.
- `libgc`: This library is used in deployment mode or garbage collection mode. Simply linking with the `libgc` library automatically and permanently fixes a program's memory leaks. When you link your program with the `libgc` library, you can program without calling `free` or `delete` while otherwise programming normally. The garbage collection library has a dependency on the dynamic load library so specify `-lgc` and `-ldl` when you link your program.

Additional information can be found in the `gcFixPrematureFrees(3)` and `gcInitialize(3)` man pages.

- `libdemangle`: This library is used for demangling C++ mangled names.

11.2.2 Accessing the C++ Library Man Pages

The man pages associated with the libraries described in this section are located in sections 1, 3, 3C++, and 3cc4.

To access man pages for the C++ libraries, type:

```
example% man library-name
```

To access man pages for version 4.2 of the C++ libraries, type:

```
example% man -s 3CC4 library-name
```

11.2.3 Default C++ Libraries

Some of the C++ libraries are linked by default by the CC driver, while others need to be linked explicitly. In the standard mode, the following libraries are linked by default by the CC driver:

```
-lCstd -lCrun -lm -lc
```

In compatibility mode (`-compat`), the following libraries are linked by default:

```
-lC -lm -lc
```

See “A.2.49 `-library=I[,L...]`” on page 242 for more information.

11.3 Related Library Options

The CC driver provides several options to help you use libraries.

- Use the `-l` option to specify a library to be linked.
- Use the `-L` option to specify a directory to be searched for the library.
- Use the `-mt` option compile and link multithreaded code.
- Use the `-xia` option to link the interval arithmetic libraries.
- Use the `-xlang` option to link Fortran or C99 runtime libraries.
- Use the `-library` option to specify the following libraries that are shipped with the Solaris Studio C++ compiler:
 - `libCrun`
 - `libCstd`
 - `libiostream`
 - `libC`
 - `libcomplex`
 - `libstlport, libstlport_dbg`
 - `librwtool, librwtool_dbg`
 - `libgc`

Note – To use the classic-iostreams form of `librwtool`, use the `-library=rwtools7` option. To use the standard-iostreams form of `librwtool`, use the `-library=rwtools7_std` option.

A library that is specified using both `-library` and `-staticlib` options will be linked statically. Some examples:

- `libstdcxx` (distributed as part of the Solaris OS)

The following command links the classic-iostreams form of `Tools.h++` version 7 and `libiostream` libraries dynamically.

```
example% CC test.cc -library=rwtools7,iostream
```

- The following command links the `libgc` library statically.

```
example% CC test.cc -library=gc -staticlib=gc
```

- The following command compiles `test.cc` in compatibility mode and links `libc` statically. Because `libc` is linked by default in compatibility mode, you are not required to specify this library using the `-library` option.

```
example% CC test.cc -compat=4 -staticlib=libc
```

- The following command excludes the libraries `libCrun` and `libcstd`, which would otherwise be included by default.

```
example% CC test.cc -library=no%Crunch,no%Cstd
```

By default, `CC` links various sets of system libraries depending on the command line options. If you specify `-xnoLib` (or `-noLib`), `CC` links only those libraries that are specified explicitly with the `-l` option on the command line. (When `-xnoLib` or `-noLib` is used, the `-library` option is ignored, if present.)

The `-R` option allows you to build dynamic library search paths into the executable file. At execution time, the runtime linker searches these paths for the shared libraries needed by the application. The `CC` driver passes `-R<install_directory>/lib` to `ld` by default (if the compiler is installed in the standard location). You can use `-norunpath` to disable building the default path for shared libraries into the executable.

The linker searches `/lib` and `/usr/lib` by default. Do not specify these directories or any compiler installation directories in `-L` options.

Programs built for deployment should be built with `-norunpath` or an `-R` option that that avoids looking in the compiler directory for libraries. (See “[11.6 Using Shared Libraries](#)” on page 139).

11.4 Using Class Libraries

Generally, two steps are involved in using a class library:

1. Include the appropriate header in your source code.
2. Link your program with the object library.

11.4.1 The `iostream` Library

The C++ compiler provides two implementations of iostreams:

- **Classic iostreams.** This term refers to the iostreams library shipped with the C++ 4.0, 4.0.1, 4.1, and 4.2 compilers, and earlier with the `cf front`-based 3.0.1 compiler. There is no standard for this library. It is part of `libc` in compatibility mode and is also available in `libiostream` in the standard mode.
- **Standard iostreams.** This is part of the C++ standard library, `libcstd`, and is available only in standard mode. It is neither binary-, nor source-compatible with the classic iostreams library.

If you have existing C++ sources, your code might look like the following example, which uses classic iostreams.

```
// file prog1.cc
#include <iostream.h>

int main() {
    cout << "Hello, world!" << endl;
    return 0;
}
```

The following command compiles in compatibility mode and links `prog1.cc` into an executable program called `prog1`. The classic iostream library is part of `libc`, which is linked by default in compatibility mode.

```
example% CC -compat prog1.cc -o prog1
```

The next example uses standard iostreams.

```
// file prog2.cc
#include <iostream>

int main() {
    std::cout << "Hello, world!" << std::endl;
    return 0;
}
```

The following command compiles and links `prog2.cc` into an executable program called `prog2`. The program is compiled in standard mode and `libcstd`, which includes the standard iostream library, is linked by default.

```
example% CC prog2.cc -o prog2
```

For a full discussion of compilation modes, see the *C++ Migration Guide*.

11.4.2 The complex Library

The standard library provides a templated complex library that is similar to the complex library provided with the C++ 4.2 compiler. If you compile in standard mode, you must use `<complex>` instead of `<complex.h>`. You cannot use `<complex>` in compatibility mode.

In compatibility mode, you must explicitly ask for the complex library when linking. In standard mode, the complex library is included in `libcstd`, and is linked by default.

There is no `complex.h` header for standard mode. In C++ 4.2, “complex” is the name of a class, but in standard C++, “complex” is the name of a template. It is not possible to provide typedefs that allow old code to work unchanged. Therefore, code written for 4.2 that uses complex numbers will need some straightforward editing to work with the standard library. For example, the following code was written for 4.2 and will compile in compatibility mode.

```
// file ex1.cc (compatibility mode)
#include <iostream.h>
#include <complex.h>

int main()
{
    complex x(3,3), y(4,4);
    complex z = x * y;
    cout << "x=" << x << ", y=" << y << ", z=" << z << endl;
}
```

The following example compiles and links `ex1.cc` in compatibility mode, and then executes the program.

```
example% CC -compat ex1.cc -library=complex
example% a.out
x=(3, 3), y=(4, 4), z=(0, 24)
```

Here is `ex1.cc` rewritten as `ex2.cc` to compile in standard mode:

```
// file ex2.cc (ex1.cc rewritten for standard mode)
#include <iostream>
#include <complex>
using std::complex;

int main()
{
    complex<double> x(3,3), y(4,4);
    complex<double> z = x * y;
    std::cout << "x=" << x << ", y=" << y << ", z=" << z <<
        std::endl;
}
```

The following example compiles and links the rewritten `ex2.cc` in standard mode, and then executes the program.

```
% CC ex2.cc
% a.out
x=(3,3), y=(4,4), z=(0,24)
```

For more information about using the complex arithmetic library, see [Table 13–4](#).

11.4.3 Linking C++ Libraries

The following table shows the compiler options for linking the C++ libraries. See “[A.2.49 -library=l\[,l...\]” on page 242](#) for more information.

TABLE 11–2 Compiler Options for Linking C++ Libraries

Library	Compilation Mode	Option
Classic <code>iostream</code>	<code>-compat=4</code>	None needed
	<code>-compat=5</code>	<code>-library=iostream</code>
complex	<code>-compat=4</code>	<code>-library=complex</code>
	<code>-compat=5</code>	None needed
Tools.h++ version 7	<code>-compat=4</code>	<code>-library=rwtools7</code>
	<code>-compat=5</code>	<code>-library=rwtools7,iostream</code>
		<code>-library=rwtools7_std</code>
Tools.h++ version 7 debug	<code>-compat=4</code>	<code>-library=rwtools7_dbg</code>
	<code>-compat=5</code>	<code>-library=rwtools7_dbg,iostream</code>
		<code>-library=rwtools7_std_dbg</code>
Garbage collection	<code>-compat=4</code>	<code>-library=gc</code>
	<code>-compat=5</code>	<code>-library=gc</code>
STLport version 4	<code>-compat=5</code>	<code>-library=stlport4</code>
STLport version 4 debug	<code>-compat=5</code>	<code>-library=stlport4_dbg</code>
Apache <code>stdcxx</code> version 4	<code>-compat=5</code>	<code>-library=stdcxx4</code>

11.5 Statically Linking Standard Libraries

The CC driver links in shared versions of several libraries by default, including `libc` and `libm`, by passing a `-lib` option for each of the default libraries to the linker. (See “[11.2.3 Default C++ Libraries” on page 134](#) for the list of default libraries for compatibility mode and standard mode.)

If you want any of these default libraries to be linked statically, you can use the `-library` option along with the `-staticlib` option to link a C++ library statically. For example:

```
example% CC test.c -staticlib=Crun
```

In this example, the `-library` option is not explicitly included in the command. In this case the `-library` option is not necessary because the default setting for `-library` is `Cstd,Crun` in standard mode (the default mode).

Alternately, you can use the `-xnoLib` compiler option. With the `-xnoLib` option, the driver does not pass any `-l` options to `ld`; you must pass these options yourself. The following example shows how you would link statically with `libCrun`, and dynamically with `libm`, and `libc` in the Solaris 8, or Solaris 9 operating systems:

```
example% CC test.c -xnoLib -lCstd -Bstatic -lCrun -lBdynamic -lm -lc
```

The order of the `-l` options is important. The `-lCstd`, `-lCrun`, and `-lm` options appear before `-lc`.

Note – Linking the `libCrun` and `libCstd` statically is not recommended. The dynamic versions in `/usr/lib` are built to work with the version of Solaris where they are installed.

Some CC options link to other libraries. These library links are also suppressed by `-xnoLib`. For example, using the `-mt` option causes the CC driver to pass `-lthread` to `ld`. However, if you use both `-mt` and `-xnoLib`, the CC driver does not pass `-lthread` to `ld`. See [“A.2.153 `-xnoLib`” on page 308](#) for more information. See *Linker and Libraries Guide* for more information about `ld`.

Note – Static versions of Solaris libraries in `/lib` and `/usr/lib` are no longer available. For example this attempt to link `libc` statically will fail:

```
CC hello.cc -xnoLib -lCrun -lCstd -Bstatic -lc
```

11.6 Using Shared Libraries

The following C++ runtime shared libraries are shipped as part of the C++ compiler:

- `libCexcept.so.1` (SPARC Solaris only)
- `libcomplex.so.5` (Solaris only)
- `librwtool.so.2`
- `libstlport.so.1`

On Linux, these additional libraries are shipped as part of the C++ compiler:

- `libCrun.so.1`

- `libCstd.so.1`
- `libdemangle.so`
- `libiostream.so.1`

On Solaris 10, those additional libraries, along with some others, are installed as part of the Solaris C++ runtime library package, SUNWlibC.

If your application uses any of the shared libraries that are shipped as part of the C++ compiler, the CC driver arranges for a *runpath* (refer to the `-R` option) pointing to the location of the library to be built into the executable. If the executable is later deployed to a different computer where the same compiler version is not installed in the same location, the required shared library will not be found.

At program start time, the library might not be found at all, or the wrong version of the library might be used, leading to incorrect program behavior. In such a case, you should ship the required libraries along with the executable, and build with a *runpath* that points to where they will be installed.

The article *Using and Redistributing Solaris Studio Libraries in an Application* contains a full discussion of this topic, along with examples and can be found at <http://developers.sun.com/sunstudio/documentation/techart/stdlibdistr.html>

11.7 Replacing the C++ Standard Library

Replacing the standard library that is distributed with the compiler is risky, and good results are not guaranteed. The basic operation is to disable the standard headers and library supplied with the compiler, and to specify the directories where the new header files and library are found, as well as the name of the library itself.

The compiler supports the STLport and Apache `stdcxx` implementations of the standard library. See “12.3 STLport” on page 160 and “12.4 Apache `stdcxx` Standard Library” on page 162 for more information.

11.7.1 What Can Be Replaced

You can replace most of the standard library and its associated headers. The replaced library is `libCstd`, and the associated headers are the following:

```
<algorithm> <bitset> <complex> <deque> <fstream <functional> <iomanip> <ios>
<iosfwd> <iostream> <istream> <iterator> <limits> <list> <locale> <map> <memory>
<numeric> <ostream> <queue> <set> <sstream> <stack> <stdexcept> <streambuf>
<string> <stringstream> <utility> <valarray> <vector>
```

The replaceable part of the library consists of what is loosely known as “STL”, plus the string classes, the `iostream` classes, and their helper classes. Because these classes and headers are

interdependent, replacing just a portion of them is unlikely to work. You should replace all of the headers and all of `libCstd` if you replace any part.

11.7.2 What Cannot Be Replaced

The standard headers `<exception>`, `<new>`, and `<typeinfo>` are tied tightly to the compiler itself and to `libCrun`, and cannot reliably be replaced. The library `libCrun` contains many “helper” functions that the compiler depends on, and cannot be replaced.

The 17 standard headers inherited from C (`<stdlib.h>`, `<stdio.h>`, `<string.h>`, and so forth) are tied tightly to the Solaris operating system and the basic Solaris runtime library `libc`, and cannot reliably be replaced. The C++ versions of those headers (`<cstdlib>`, `<cstdio>`, `<cstring>`, and so forth) are tied tightly to the basic C versions and cannot reliably be replaced.

11.7.3 Installing the Replacement Library

To install the replacement library, you must first decide on the locations for the replacement headers and on the replacement for `libCstd`. For purposes of discussion, assume the headers are placed in `/opt/mycstd/include` and the library is placed in `/opt/mycstd/lib`. Assume the library is called `libmyCstd.a`. (It is often convenient if the library name starts with “lib”.)

11.7.4 Using the Replacement Library

On each compilation, use the `-I` option to point to the location where the headers are installed. In addition, use the `-library=no%Cstd` option to prevent finding the compiler’s own versions of the `libCstd` headers. For example:

```
example% CC -I/opt/mycstd/include -library=no%Cstd... (compile)
```

During compiling, the `-library=no%Cstd` option prevents searching the directory where the compiler’s own version of these headers is located.

On each program or library link, use the `-library=no%Cstd` option to prevent finding the compiler’s own `libCstd`, the `-L` option to point to the directory where the replacement library is, and the `-l` option to specify the replacement library. Example:

```
example% CC -library=no%Cstd -L/opt/mycstd/lib -lmyCstd... (link)
```

Alternatively, you can use the full path name of the library directly, and omit using the `-L` and `-l` options. For example:

```
example% CC -library=no%Cstd /opt/mycstd/lib/libmyCstd.a... (link)
```

During linking, the `-library=no%Cstd` option prevents linking the compiler’s own version of `libCstd`.

11.7.5 Standard Header Implementation

C has 17 standard headers (`<stdio.h>`, `<string.h>`, `<stdlib.h>`, and others). These headers are delivered as part of the Solaris operating system, in the directory `/usr/include`. C++ has those same headers, with the added requirement that the various declared names appear in both the global namespace and in namespace `std`. On versions of the Solaris operating system prior to version 8, the C++ compiler supplies its own versions of these headers instead of replacing those in the `/usr/include` directory.

C++ also has a second version of each of the C standard headers (`<cstdio>`, `<cstring>`, and `<cstdlib>`, and others) with the various declared names appearing only in namespace `std`. Finally, C++ adds 32 of its own standard headers (`<string>`, `<utility>`, `<iostream>`, and others).

The obvious implementation of the standard headers would use the name found in C++ source code as the name of a text file to be included. For example, the standard headers `<string>` (or `<string.h>`) would refer to a file named `string` (or `string.h`) in some directory. That obvious implementation has the following drawbacks:

- You cannot search for just header files or create a `makefile` rule for the header files if they do not have file name suffixes.
- If you have a directory or executable program named `string`, it might erroneously be found instead of the standard header file.
- On versions of the Solaris operating system prior to the Solaris 8 operating system, the default dependencies for makefiles when `.KEEP_STATE` is enabled can result in attempts to replace standard headers with an executable program. (A file without a suffix is assumed by default to be a program to be built.)

To solve these problems, the compiler `include` directory contains a file with the same name as the header, along with a symbolic link to it that has the unique suffix `.SUNWCCh` (`SUNW` is the prefix for all compiler-related packages, `CC` is the C++ compiler, and `h` is the usual suffix for header files). When you specify `<string>`, the compiler rewrites it to `<string.SUNWCCh>` and searches for that name. The suffixed name will be found only in the compiler's own `include` directory. If the file so found is a symbolic link (which it normally is), the compiler dereferences the link exactly once and uses the result (`string` in this case) as the file name for error messages and debugger references. The compiler uses the suffixed name when emitting file dependency information.

The name rewriting occurs only for the two forms of the 17 standard C headers and the 32 standard C++ headers, only when they appear in angle brackets and without any path specified. If you use quotes instead of angle brackets, specify any path components, or specify some other header, no rewriting occurs.

The following table illustrates common situations.

TABLE 11-3 Header Search Examples

Source Code	Compiler Searches For	Comments
<code><string></code>	<code>string.SUNWCCh</code>	C++ string templates
<code><cstring></code>	<code>cstring.SUNWCCh</code>	C++ version of C <code>string.h</code>
<code><string.h></code>	<code>string.h.SUNWCCh</code>	C <code>string.h</code>
<code><fcntl.h></code>	<code>fcntl.h</code>	Not a standard C or C++ header
<code>"string"</code>	<code>string</code>	Double-quotation marks, not angle brackets
<code><../string></code>	<code>../string</code>	Path specified

If the compiler does not find `header.SUNWCCh`, the compiler restarts the search looking for the name as provided in the `#include` directive. For example, given the directive `#include <string>`, the compiler attempts to find a file named `string.SUNWCCh`. If that search fails, the compiler looks for a file named `string`.

11.7.5.1 Replacing Standard C++ Headers

Because of the search algorithm described in “11.7.5 Standard Header Implementation” on page 142, you do not need to supply `SUNWCCh` versions of the replacement headers described in “11.7.3 Installing the Replacement Library” on page 141. But you might run into some of the described problems. If so, the recommended solution is to add symbolic links having the suffix `.SUNWCCh` for each of the unsuffixed headers. That is, for file `utility`, you would run the command

```
example% ln -s utility utility.SUNWCCh
```

When the compiler looks first for `utility.SUNWCCh`, it will find it, and not be confused by any other file or directory called `utility`.

11.7.5.2 Replacing Standard C Headers

Replacing the standard C headers is not supported. If you nevertheless wish to provide your own versions of standard headers, the recommended procedure is as follows:

- Put all the replacement headers in one directory.
- Create a `.SUNWCCh` symbolic link to each of the replacement headers in that directory.
- Cause the directory that contains the replacement headers to be searched by using the `-I` directives on each invocation of the compiler.

For example, suppose you have replacements for `<stdio.h>` and `<cstdio>`. Put the files `stdio.h` and `cstdio` in directory `/myproject/myhdr`. In that directory, run these commands:

```
example% ln -s stdio.h stdio.h.SUNWCCh  
example% ln -s cstdio cstdio.SUNWCCh
```

Use the option `-I/myproject/mydir` on every compilation.

Caveats:

- If you replace any C headers, you must replace them in pairs. For example, if you replace `<time.h>`, you should also replace `<ctime>`.
- Replacement headers must have the same effects as the versions being replaced. That is, the various runtime libraries such as `libCrun`, `libC`, `libCstd`, `libc`, and `librwtool` are built using the definitions in the standard headers. If your replacements do not match, your program is unlikely to work.

Using The C++ Standard Library

When compiling in default (standard) mode, the compiler has access to the complete library specified by the C++ standard. The library components include what is informally known as the Standard Template Library (STL), as well as the following components.

- string classes
- numeric classes
- the standard version of stream I/O classes
- basic memory allocation
- exception classes
- run-time type information

The term STL does not have a formal definition, but is usually understood to include containers, iterators, and algorithms. The following subset of the standard library headers can be thought of as comprising the STL.

- `<algorithm>`
- `<deque>`
- `<iterator>`
- `<list>`
- `<map>`
- `<memory>`
- `<queue>`
- `<set>`
- `<stack>`
- `<utility>`
- `<vector>`

The C++ standard library (`libCstd`) is based on the RogueWave Standard C++ Library, Version 2. This library is available only for the default mode (`-compat=5`) of the compiler and is not supported with use of the `-compat[=4]` option.

The C++ compiler also supports STLport’s Standard Library implementation version 4.5.3. `libcstd` is still the default library, but STLport’s product is available as an alternative. See “[12.3 STLport](#)” on page 160 for more information.

If you need to use your own version of the C++ standard library instead of one of the versions that is supplied with the compiler, you can do so by specifying the `-library=no%Cstd` option. Replacing the standard library that is distributed with the compiler is risky, and good results are not guaranteed. For more information, see “[11.7 Replacing the C++ Standard Library](#)” on page 140.

For details about the standard library, see the *Standard C++ Library User’s Guide* and the *Standard C++ Class Library Reference*.

12.1 C++ Standard Library Header Files

Table 12–1 lists the headers for the complete standard library along with a brief description of each.

TABLE 12–1 C++ Standard Library Header Files

Header File	Description
<code><algorithm></code>	Standard algorithms that operate on containers
<code><bitset></code>	Fixed-size sequences of bits
<code><complex></code>	The numeric type representing complex numbers
<code><deque></code>	Sequences supporting addition and removal at each end
<code><exception></code>	Predefined exception classes
<code><fstream></code>	Stream I/O on files
<code><functional></code>	Function objects
<code><iomanip></code>	<code>iostream</code> manipulators
<code><ios></code>	<code>iostream</code> base classes
<code><iosfwd></code>	Forward declarations of <code>iostream</code> classes
<code><iostream></code>	Basic stream I/O functionality
<code><istream></code>	Input I/O streams
<code><iterator></code>	Class for traversing a sequence
<code><limits></code>	Properties of numeric types
<code><list></code>	Ordered sequences

TABLE 12-1 C++ Standard Library Header Files (Continued)

Header File	Description
<locale>	Support for internationalization
<map>	Associative containers with key/value pairs
<memory>	Special memory allocators
<new>	Basic memory allocation and deallocation
<numeric>	Generalized numeric operations
<ostream>	Output I/O streams
<queue>	Sequences supporting addition at the head and removal at the tail
<set>	Associative container with unique keys
<sstream>	Stream I/O using an in-memory string as source or sink
<stack>	Sequences supporting addition and removal at the head
<stdexcept>	Additional standard exception classes
<streambuf>	Buffer classes for iostreams
<string>	Sequences of characters
<typeinfo>	Run-time type identification
<utility>	Comparison operators
<valarray>	Value arrays useful for numeric programming
<vector>	Sequences supporting random access

12.2 C++ Standard Library Man Pages

Table 12-2 lists the documentation available for each of the components of the standard library.

TABLE 12-2 Man Pages for C++ Standard Library

Man Page	Overview
Algorithms	Generic algorithms for performing various operations on containers and sequences
Associative_Containers	Ordered containers
Bidirectional_Iterators	An iterator that can both read and write and can traverse a container in both directions
Containers	A standard template library (STL) collection

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
Forward_Iterators	A forward-moving iterator that can both read and write
Function_Objects	Object with an operator() defined
Heap_Operations	See entries for make_heap, pop_heap, push_heap and sort_heap
Input_Iterators	A read-only, forward moving iterator
Insert_Iterators	An iterator adaptor that allows an iterator to insert into a container rather than overwrite elements in the container
Iterators	Pointer generalizations for traversal and modification of collections
Negators	Function adaptors and function objects used to reverse the sense of predicate function objects
Operators	Operators for the C++ Standard Template Library Output
Output_Iterators	A write-only, forward moving iterator
Predicates	A function or a function object that returns a boolean (true/false) value or an integer value
Random_Access_Iterators	An iterator that reads, writes, and allows random access to a container
Sequences	A container that organizes a set of sequences
Stream_Iterators	Includes iterator capabilities for ostream and istream that allow generic algorithms to be used directly on streams
__distance_type	Determines the type of distance used by an iterator— obsolete
__iterator_category	Determines the category to which an iterator belongs—obsolete
__reverse_bi_iterator	An iterator that traverses a collection backwards
accumulate	Accumulates all elements within a range into a single value
adjacent_difference	Outputs a sequence of the differences between each adjacent pair of elements in a range
adjacent_find	Find the first adjacent pair of elements in a sequence that are equivalent
advance	Moves an iterator forward or backward (if available) by a certain distance
allocator	The default allocator object for storage management in Standard Library containers
auto_ptr	A simple, smart pointer class

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>binary_search</code>	Performs a binary search for a value on a container
<code>bind1st</code>	Templatized utilities to bind values to function objects
<code>bind2nd</code>	Templatized utilities to bind values to function objects
<code>binder1st</code>	Templatized utilities to bind values to function objects
<code>binder2nd</code>	Templatized utilities to bind values to function objects
<code>bitset</code>	A template class and related functions for storing and manipulating fixed-size sequences of bits
<code>cerr</code>	Controls output to an unbuffered stream buffer associated with the object <code>stderr</code> declared in <code><cstdio></code>
<code>char_traits</code>	A traits class with types and operations for the <code>basic_string</code> container and <code>iostream</code> classes
<code>cin</code>	Controls input from a stream buffer associated with the object <code>stdin</code> declared in <code><cstdio></code>
<code>clog</code>	Controls output to a stream buffer associated with the object <code>stderr</code> declared in <code><cstdio></code>
<code>codecvt</code>	A code conversion facet
<code>codecvt_byname</code>	A facet that includes code set conversion classification facilities based on the named locales
<code>collate</code>	A string collation, comparison, and hashing facet
<code>collate_byname</code>	A string collation, comparison, and hashing facet
<code>compare</code>	A binary function or a function object that returns true or false
<code>complex</code>	C++ complex number library
<code>copy</code>	Copies a range of elements
<code>copy_backward</code>	Copies a range of elements
<code>count</code>	Count the number of elements in a container that satisfy a given condition
<code>count_if</code>	Count the number of elements in a container that satisfy a given condition
<code>cout</code>	Controls output to a stream buffer associated with the object <code>stdout</code> declared in <code><cstdio></code>
<code>ctype</code>	A facet that includes character classification facilities

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>ctype_byname</code>	A facet that includes character classification facilities based on the named locales
<code>deque</code>	A sequence that supports random access iterators and efficient insertion/deletion at both beginning and end
<code>distance</code>	Computes the distance between two iterators
<code>divides</code>	Returns the result of dividing its first argument by its second
<code>equal</code>	Compares two ranges for equality
<code>equal_range</code>	Finds the largest subrange in a collection into which a given value can be inserted without violating the ordering of the collection
<code>equal_to</code>	A binary function object that returns true if its first argument equals its second
<code>exception</code>	A class that supports logic and runtime errors
<code>facets</code>	A family of classes used to encapsulate categories of locale functionality
<code>filebuf</code>	Class that associates the input or output sequence with a file
<code>fill</code>	Initializes a range with a given value
<code>fill_n</code>	Initializes a range with a given value
<code>find</code>	Finds an occurrence of value in a sequence
<code>find_end</code>	Finds the last occurrence of a sub-sequence in a sequence
<code>find_first_of</code>	Finds the first occurrence of any value from one sequence in another sequence
<code>find_if</code>	Finds an occurrence of a value in a sequence that satisfies a specified predicate
<code>for_each</code>	Applies a function to each element in a range
<code>fpos</code>	Maintains position information for the iostream classes
<code>front_insert_iterator</code>	An insert iterator used to insert items at the beginning of a collection
<code>front_inserter</code>	An insert iterator used to insert items at the beginning of a collection
<code>fstream</code>	Supports reading and writing of named files or devices associated with a file descriptor

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
generate	Initialize a container with values produced by a value-generator class
generate_n	Initialize a container with values produced by a value-generator class
get_temporary_buffer	Pointer based primitive for handling memory
greater	A binary function object that returns true if its first argument is greater than its second
greater_equal	A binary function object that returns true if its first argument is greater than or equal to its second
gslice	A numeric array class used to represent a generalized slice from an array
gslice_array	A numeric array class used to represent a BLAS-like slice from a valarray
has_facet	A function template used to determine if a locale has a given facet
ifstream	Supports reading from named files or other devices associated with a file descriptor
includes	A basic set of operation for sorted sequences
indirect_array	A numeric array class used to represent elements selected from a valarray
inner_product	Computes the inner product $A \cdot X \cdot B$ of two ranges A and B
inplace_merge	Merges two sorted sequences into one
insert_iterator	An insert iterator used to insert items into a collection rather than overwrite the collection
inserter	An insert iterator used to insert items into a collection rather than overwrite the collection
ios	A base class that includes the common functions required by all streams
ios_base	Defines member types and maintains data for classes that inherit from it
iosfwd	Declares the input/output library template classes and specializes them for wide and tiny characters
isalnum	Determines if a character is alphabetic or numeric
isalpha	Determines if a character is alphabetic

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>iscntrl</code>	Determines if a character is a control character
<code>isdigit</code>	Determines if a character is a decimal digit
<code>isgraph</code>	Determines if a character is a graphic character
<code>islower</code>	Determines whether a character is lower case
<code>isprint</code>	Determines if a character is printable
<code>ispunct</code>	Determines if a character is punctuation
<code>isspace</code>	Determines if a character is a space
<code>istream</code>	Assists in reading and interpreting input from sequences controlled by a stream buffer
<code>istream_iterator</code>	A stream iterator that has iterator capabilities for istreams
<code>istreambuf_iterator</code>	Reads successive characters from the stream buffer for which it was constructed
<code>istreamstream</code>	Supports reading objects of class <code>basic_string<charT, traits, Allocator></code> from an array in memory
<code>istrstream</code>	Reads characters from an array in memory
<code>isupper</code>	Determines whether a character is upper case
<code>isxdigit</code>	Determines whether a character is a hexadecimal digit
<code>iter_swap</code>	Exchanges values in two locations
<code>iterator</code>	A base iterator class
<code>iterator_traits</code>	Returns basic information about an iterator
<code>less</code>	A binary function object that returns true if its first argument is less than its second
<code>less_equal</code>	A binary function object that returns true if its first argument is less than or equal to its second
<code>lexicographical_compare</code>	Compares two ranges lexicographically
<code>limits</code>	Refer to <code>numeric_limits</code>
<code>list</code>	A sequence that supports bidirectional iterators
<code>locale</code>	A localization class containing a polymorphic set of facets

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
logical_and	A binary function object that returns true if both of its arguments are true
logical_not	A unary function object that returns true if its argument is false
logical_or	A binary function object that returns true if either of its arguments are true
lower_bound	Determines the first valid position for an element in a sorted container
make_heap	Creates a heap
map	An associative container with access to non-key values using unique keys
mask_array	A numeric array class that gives a masked view of a valarray
max	Finds and returns the maximum of a pair of values
max_element	Finds the maximum value in a range
mem_fun	Function objects that adapt a pointer to a member function, to take the place of a global function
mem_fun1	Function objects that adapt a pointer to a member function, to take the place of a global function
mem_fun_ref	Function objects that adapt a pointer to a member function, to take the place of a global function
mem_fun_ref1	Function objects that adapt a pointer to a member function, to take the place of a global function
merge	Merges two sorted sequences into a third sequence
messages	Messaging facets
messages_byname	Messaging facets
min	Finds and returns the minimum of a pair of values
min_element	Finds the minimum value in a range
minus	Returns the result of subtracting its second argument from its first
mismatch	Compares elements from two sequences and returns the first two elements that don't match each other
modulus	Returns the remainder obtained by dividing the first argument by the second argument
money_get	Monetary formatting facet for input

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>money_put</code>	Monetary formatting facet for output
<code>moneypunct</code>	Monetary punctuation facets
<code>moneypunct_byname</code>	Monetary punctuation facets
<code>multimap</code>	An associative container that gives access to non-key values using keys
<code>multiplies</code>	A binary function object that returns the result of multiplying its first and second arguments
<code>multiset</code>	An associative container that allows fast access to stored key values
<code>negate</code>	Unary function object that returns the negation of its argument
<code>next_permutation</code>	Generates successive permutations of a sequence based on an ordering function
<code>not1</code>	A function adaptor used to reverse the sense of a unary predicate function object
<code>not2</code>	A function adaptor used to reverse the sense of a binary predicate function object
<code>not_equal_to</code>	A binary function object that returns true if its first argument is not equal to its second
<code>nth_element</code>	Rearranges a collection so that all elements lower in sorted order than the <i>n</i> th element come before it and all elements higher in sorted order than the <i>n</i> th element come after it
<code>num_get</code>	A numeric formatting facet for input
<code>num_put</code>	A numeric formatting facet for output
<code>numeric_limits</code>	A class for representing information about scalar types
<code>numpunct</code>	A numeric punctuation facet
<code>numpunct_byname</code>	A numeric punctuation facet
<code>ofstream</code>	Supports writing into named files or other devices associated with a file descriptor
<code>ostream</code>	Assists in formatting and writing output to sequences controlled by a stream buffer
<code>ostream_iterator</code>	Stream iterators allow for use of iterators with ostreams and istreams

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>ostreambuf_iterator</code>	Writes successive characters onto the stream buffer object from which it was constructed
<code>ostringstream</code>	Supports writing objects of class <code>basic_string<charT, traits, Allocator></code>
<code>ostrstream</code>	Writes to an array in memory
<code>pair</code>	A template for heterogeneous pairs of values
<code>partial_sort</code>	Templatized algorithm for sorting collections of entities
<code>partial_sort_copy</code>	Templatized algorithm for sorting collections of entities
<code>partial_sum</code>	Calculates successive partial sums of a range of values
<code>partition</code>	Places all of the entities that satisfy the given predicate before all of the entities that do not
<code>permutation</code>	Generates successive permutations of a sequence based on an ordering function
<code>plus</code>	A binary function object that returns the result of adding its first and second arguments
<code>pointer_to_binary_function</code>	A function object that adapts a pointer to a binary function, to take the place of a <code>binary_function</code>
<code>pointer_to_unary_function</code>	A function object class that adapts a pointer to a function, to take the place of a <code>unary_function</code>
<code>pop_heap</code>	Moves the largest element off the heap
<code>prev_permutation</code>	Generates successive permutations of a sequence based on an ordering function
<code>priority_queue</code>	A container adapter that behaves like a priority queue
<code>ptr_fun</code>	A function that is overloaded to adapt a pointer to a function, to take the place of a function
<code>push_heap</code>	Places a new element into a heap
<code>queue</code>	A container adaptor that behaves like a queue (first in, first out)
<code>random_shuffle</code>	Randomly shuffles elements of a collection
<code>raw_storage_iterator</code>	Enables iterator-based algorithms to store results into uninitialized memory

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>remove</code>	Moves desired elements to the front of a container, and returns an iterator that describes where the sequence of desired elements ends
<code>remove_copy</code>	Moves desired elements to the front of a container, and returns an iterator that describes where the sequence of desired elements ends
<code>remove_copy_if</code>	Moves desired elements to the front of a container, and returns an iterator that describes where the sequence of desired elements ends
<code>remove_if</code>	Moves desired elements to the front of a container, and returns an iterator that describes where the sequence of desired elements ends
<code>replace</code>	Substitutes elements in a collection with new values
<code>replace_copy</code>	Substitutes elements in a collection with new values, and moves the revised sequence into result
<code>replace_copy_if</code>	Substitutes elements in a collection with new values, and moves the revised sequence into result
<code>replace_if</code>	Substitutes elements in a collection with new values
<code>return_temporary_buffer</code>	A pointer-based primitive for handling memory
<code>reverse</code>	Reverses the order of elements in a collection
<code>reverse_copy</code>	Reverses the order of elements in a collection while copying them to a new collection
<code>reverse_iterator</code>	An iterator that traverses a collection backwards
<code>rotate</code>	Swaps the segment that contains elements from first through middle-minus-one with the segment that contains the elements from middle through last
<code>rotate_copy</code>	Swaps the segment that contains elements from first through middle-minus-one with the segment that contains the elements from middle through last
<code>search</code>	Finds a sub-sequence within a sequence of values that is element-wise equal to the values in an indicated range
<code>search_n</code>	Finds a sub-sequence within a sequence of values that is element-wise equal to the values in an indicated range
<code>set</code>	An associative container that supports unique keys
<code>set_difference</code>	A basic set operation for constructing a sorted difference

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>set_intersection</code>	A basic set operation for constructing a sorted intersection
<code>set_symmetric_difference</code>	A basic set operation for constructing a sorted symmetric difference
<code>set_union</code>	A basic set operation for constructing a sorted union
<code>slice</code>	A numeric array class for representing a BLAS-like slice from an array
<code>slice_array</code>	A numeric array class for representing a BLAS-like slice from a <code>valarray</code>
<code>smanip</code>	Helper classes used to implement parameterized manipulators
<code>smanip_fill</code>	Helper classes used to implement parameterized manipulators
<code>sort</code>	A templated algorithm for sorting collections of entities
<code>sort_heap</code>	Converts a heap into a sorted collection
<code>stable_partition</code>	Places all of the entities that satisfy the given predicate before all of the entities that do not, while maintaining the relative order of elements in each group
<code>stable_sort</code>	A templated algorithm for sorting collections of entities
<code>stack</code>	A container adapter that behaves like a stack (last in, first out)
<code>streambuf</code>	Abstract base class for deriving various stream buffers to facilitate control of character sequences
<code>string</code>	A typedef for <code>basic_string<char, char_traits<char>, allocator<char>></code>
<code>stringbuf</code>	Associates the input or output sequence with a sequence of arbitrary characters
<code>stringstream</code>	Supports writing and reading objects of class <code>basic_string<charT, traits, Allocator></code> to/from an array in memory
<code>strstream</code>	Reads and writes to an array in memory
<code>strstreambuf</code>	Associates either the input sequence or the output sequence with a tiny character array whose elements store arbitrary values
<code>swap</code>	Exchanges values
<code>swap_ranges</code>	Exchanges a range of values in one location with those in another
<code>time_get</code>	A time formatting facet for input

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
<code>time_get_byname</code>	A time formatting facet for input, based on the named locales
<code>time_put</code>	A time formatting facet for output
<code>time_put_byname</code>	A time formatting facet for output, based on the named locales
<code>tolower</code>	Converts a character to lower case.
<code>toupper</code>	Converts a character to upper case
<code>transform</code>	Applies an operation to a range of values in a collection and stores the result
<code>unary_function</code>	A base class for creating unary function objects
<code>unary_negate</code>	A function object that returns the complement of the result of its unary predicate
<code>uninitialized_copy</code>	An algorithm that uses <code>construct</code> to copy values from one range to another location
<code>uninitialized_fill</code>	An algorithm that uses the <code>construct</code> algorithm for setting values in a collection
<code>uninitialized_fill_n</code>	An algorithm that uses the <code>construct</code> algorithm for setting values in a collection
<code>unique</code>	Removes consecutive duplicates from a range of values and places the resulting unique values into the result
<code>unique_copy</code>	Removes consecutive duplicates from a range of values and places the resulting unique values into the result
<code>upper_bound</code>	Determines the last valid position for a value in a sorted container
<code>use_facet</code>	A template function used to obtain a facet
<code>valarray</code>	An optimized array class for numeric operations
<code>vector</code>	A sequence that supports random access iterators
<code>wcerr</code>	Controls output to an unbuffered stream buffer associated with the object <code>stderr</code> declared in <code><cstdio></code>
<code>wcin</code>	Controls input from a stream buffer associated with the object <code>stdin</code> declared in <code><cstdio></code>
<code>wclog</code>	Controls output to a stream buffer associated with the object <code>stderr</code> declared in <code><cstdio></code>
<code>wcout</code>	Controls output to a stream buffer associated with the object <code>stdout</code> declared in <code><cstdio></code>

TABLE 12-2 Man Pages for C++ Standard Library (Continued)

Man Page	Overview
wfilebuf	Class that associates the input or output sequence with a file
wfstream	Supports reading and writing of named files or devices associated with a file descriptor
wifstream	Supports reading from named files or other devices associated with a file descriptor
wios	A base class that includes the common functions required by all streams
wistream	Assists in reading and interpreting input from sequences controlled by a stream buffer
wstringstream	Supports reading objects of class <code>basic_string<charT, traits, Allocator></code> from an array in memory
wofstream	Supports writing into named files or other devices associated with a file descriptor
wostream	Assists in formatting and writing output to sequences controlled by a stream buffer
wstringstream	Supports writing objects of class <code>basic_string<charT, traits, Allocator></code>
wstreambuf	Abstract base class for deriving various stream buffers to facilitate control of character sequences
wstring	A typedef for <code>basic_string<wchar_t, char_traits<wchar_t>, allocator<wchar_t>></code>
wstringbuf	Associates the input or output sequence with a sequence of arbitrary characters

12.3 STLport

Use the STLport implementation of the standard library if you wish to use an alternative standard library to `libcstd`. You can issue the following compiler option to turn off `libcstd` and use the STLport library instead:

- `-library=stlport4`

See “A.2.49 `-library=l[,l..]`” on page 242 for more information.

This release includes both a static archive called `libstlport.a` and a dynamic library called `libstlport.so`.

Consider the following information before you decide whether or not you are going to use the STLport implementation:

- STLport is an open source product and does not guarantee compatibility across different releases. In other words, compiling with a future version of STLport may break applications compiled with STLport 4.5.3. It also might not be possible to link binaries compiled using STLport 4.5.3 with binaries compiled using a future version of STLport.
- The `stlport4`, `Cstd` and `iostream` libraries provide their own implementation of I/O streams. Specifying more than one of these with the `-library` option can result in undefined program behavior.
- Future releases of the compiler might not include STLport4. They might include only a later version of STLport. The compiler option `-library=stlport4` might not be available in future releases, but could be replaced by an option referring to a later STLport version.
- `Tools.h++` is not supported with STLport.
- STLport is binary incompatible with the default `libcstd`. If you use the STLport implementation of the standard library, then you must compile and link all files, including third-party libraries, with the option `-library=stlport4`. This means, for example, that you cannot use the STLport implementation and the C++ interval math library `libcsumath` together. The reason for this is that `libcsumath` was compiled with the default library headers, not with STLport.
- If you decide to use the STLport implementation, be certain to include header files that your code implicitly references. The standard headers are allowed, but not required, to include one another as part of the implementation.
- You cannot use the STLport implementation if you compile with `-compat=4`.

12.3.1 Redistribution and Supported STLport Libraries

See the Distribution Readme for a list of libraries and object files that you can redistribute with your executables or libraries under the terms of the End User Object Code License. The C++ section of this readme lists which version of the STLport .so this release of the compiler supports. This readme can be found on the legal page for this release of Oracle Solaris Studio software, at <http://www.oracle.com/technetwork/server-storage/solarisstudio/overview/index.html>

The following test case does not compile with STLport because the code in the test case makes unportable assumptions about the library implementation. In particular, it assumes that either `<vector>` or `<iostream>` automatically include `<iterator>`, which is not a valid assumption.

```
#include <vector>
#include <iostream>

using namespace std;
```

```
int main ()
{
    vector <int> v1 (10);
    vector <int> v3 (v1.size());
    for (int i = 0; i < v1.size (); i++)
        {v1[i] = i; v3[i] = i;}
    vector <int> v2(v1.size ());
    copy_backward (v1.begin (), v1.end (), v2.end ());
    ostream_iterator<int> iter (cout, " ");
    copy (v2.begin (), v2.end (), iter);
    cout << endl;
    return 0;
}
```

To fix the problem, include `<iterator>` in the source.

12.4 Apache stdcxx Standard Library

Use the Apache stdcxx version 4 C++ standard library in Solaris, instead of the default libCstd by compiling with `-library=stdcxx4`. This option also sets the `-mt` option implicitly. The stdcxx library requires multi-threading mode. This option must be used consistently on every compilation and link command in the entire application. Code compiled with `-library=stdcxx4` cannot be used in the same program as code compiled with the default `-library=Cstd` or the optional `-library=stlport4`.

Using the Classic `iostream` Library

C++, like C, has no built-in input or output statements. Instead, I/O facilities are provided by a library. The C++ compiler provides both the classic implementation and the ISO standard implementation of the `iostream` classes.

- In compatibility mode (`-compat [=4]`), the classic `iostream` classes are contained in `libc`.
- In standard mode (default mode), the classic `iostream` classes are contained in `libiostream`. Use `libiostream` when you have source code that uses the classic `iostream` classes and you want to compile the source in standard mode. To use the classic `iostream` facilities in standard mode, include the `iostream.h` header file and compile using the `-library=iostream` option.
- The standard `iostream` classes are available only in standard mode, and are contained in the C++ standard library, `libcstd`.

This chapter provides an introduction to the classic `iostream` library and provides examples of its use. This chapter does not provide a complete description of the `iostream` library. See the `iostream` library man pages for more details. To access the classic `iostream` man pages type:
`man -s 3CC4 name`

13.1 Predefined `iostreams`

There are four predefined `iostreams`:

- `cin`, connected to standard input
- `cout`, connected to standard output
- `cerr`, connected to standard error
- `clog`, connected to standard error

The predefined `iostreams` are fully buffered, except for `cerr`. See “13.3.1 Output Using `iostream`” on page 165 and “13.3.2 Input Using `iostream`” on page 168.

13.2 Basic Structure of `iostream` Interaction

By including the `iostream` library, a program can use any number of input or output streams. Each stream has some source or sink, which may be one of the following:

- Standard input
- Standard output
- Standard error
- A file
- An array of characters

A stream can be restricted to input or output, or a single stream can allow both input and output. The `iostream` library implements these streams using two processing layers.

- The lower layer implements sequences, which are simply streams of characters. These sequences are implemented by the `streambuf` class, or by classes derived from it.
- The upper layer performs formatting operations on sequences. These formatting operations are implemented by the `istream` and `ostream` classes, which have as a member an object of a type derived from class `streambuf`. An additional class, `iostream`, is for streams on which both input and output can be performed.

Standard input, output, and error are handled by special class objects derived from class `istream` or `ostream`.

The `ifstream`, `ofstream`, and `fstream` classes, which are derived from `istream`, `ostream`, and `iostream` respectively, handle input and output with files.

The `istrstream`, `ostrstream`, and `strstream` classes, which are derived from `istream`, `ostream`, and `iostream` respectively, handle input and output to and from arrays of characters.

When you open an input or output stream, you create an object of one of these types, and associate the `streambuf` member of the stream with a device or file. You generally do this association through the stream constructor, so you don't work with the `streambuf` directly. The `iostream` library predefines stream objects for the standard input, standard output, and error output, so you don't have to create your own objects for those streams.

You use operators or `iostream` member functions to insert data into a stream (output) or extract data from a stream (input), and to control the format of data that you insert or extract.

When you want to insert and extract a new data type—one of your classes—you generally overload the insertion and extraction operators.

13.3 Using the Classic `iostream` Library

To use routines from the classic `iostream` library, you must include the header files for the part of the library you need. The header files are described in the following table.

TABLE 13-1 `iostream` Routine Header Files

Header File	Description
<code>iostream.h</code>	Declares basic features of <code>iostream</code> library.
<code>fstream.h</code>	Declares <code>istream</code> s and <code>streambuf</code> s specialized to files. Includes <code>iostream.h</code> .
<code>strstream.h</code>	Declares <code>istream</code> s and <code>streambuf</code> s specialized to character arrays. Includes <code>iostream.h</code> .
<code>iomanip.h</code>	Declares manipulators: values you insert into or extract from <code>istream</code> s to have different effects. Includes <code>iostream.h</code> .
<code>stdiostream.h</code>	(obsolete) Declares <code>istream</code> s and <code>streambuf</code> s specialized to use <code>stdio</code> <code>FILE</code> s. Includes <code>iostream.h</code> .
<code>stream.h</code>	(obsolete) Includes <code>iostream.h</code> , <code>fstream.h</code> , <code>iomanip.h</code> , and <code>stdiostream.h</code> . For compatibility with old-style streams from C++ version 1.2.

You usually do not need all of these header files in your program. Include only the ones that contain the declarations you need. In compatibility mode (`-compat [=4]`), the classic `iostream` library is part of `libc`, and is linked automatically by the CC driver. In standard mode (the default), `libiostream` contains the classic `iostream` library.

13.3.1 Output Using `iostream`

Output using `iostream` usually relies on the overloaded left-shift operator (`<<`) which, in the context of `iostream`, is called the insertion operator. To output a value to standard output, you insert the value in the predefined output stream `cout`. For example, given a value `someValue`, you send it to standard output with a statement like:

```
cout << someValue;
```

The insertion operator is overloaded for all built-in types, and the value represented by `someValue` is converted to its proper output representation. If, for example, `someValue` is a `float` value, the `<<` operator converts the value to the proper sequence of digits with a decimal point. Where it inserts `float` values on the output stream, `<<` is called the float inserter. In general, given a type `X`, `<<` is called the `X` inserter. The format of output and how you can control it is discussed in the `ios(3CC4)` man page.

The `iostream` library does not support user-defined types. If you define types that you want to output in your own way, you must define an inserter (that is, overload the `<<` operator) to handle them correctly.

The `<<` operator can be applied repetitively. To insert two values on `cout`, you can use a statement like the one in the following example:

```
cout << someValue << anotherValue;
```

The output from the above example will show no space between the two values. So you may want to write the code this way:

```
cout << someValue << " " << anotherValue;
```

The `<<` operator has the precedence of the left shift operator (its built-in meaning). As with other operators, you can always use parentheses to specify the order of action. It is often a good idea to use parentheses to avoid problems of precedence. Of the following four statements, the first two are equivalent, but the last two are not.

```
cout << a+b;           // + has higher precedence than <<
cout << (a+b);
cout << (a&y);        // << has precedence higher than &
cout << a&y;          // probably an error: (cout << a) & y
```

13.3.1.1 Defining Your Own Insertion Operator

The following example defines a `string` class:

```
#include <stdlib.h>
#include <iostream.h>

class string {
private:
    char* data;
    size_t size;

public:
    // (functions not relevant here)

    friend ostream& operator<<(ostream&, const string&);
    friend istream& operator>>(istream&, string&);
};
```

The insertion and extraction operators must in this case be defined as friends because the data part of the `string` class is private.

```
ostream& operator<< (ostream& ostr, const string& output)
{    return ostr << output.data;}
```

Here is the definition of `operator<<` overloaded for use with `strings`.

```
cout << string1 << string2;
```

operator<< takes `ostream&` (that is, a reference to an `ostream`) as its first argument and returns the same `ostream`, making it possible to combine insertions in one statement.

13.3.1.2 Handling Output Errors

Generally, you don't have to check for errors when you overload operator<< because the `iostream` library is arranged to propagate errors.

When an error occurs, the `iostream` where it occurred enters an error state. Bits in the `iostream`'s state are set according to the general category of the error. The inserters defined in `iostream` ignore attempts to insert data into any stream that is in an error state, so such attempts do not change the `iostream`'s state.

In general, the recommended way to handle errors is to periodically check the state of the output stream in some central place. If there is an error, you should handle it in some way. This chapter assumes that you define a function `error`, which takes a string and aborts the program. `error` is not a predefined function. See “13.3.9 Handling Input Errors” on page 171 for an example of an error function. You can examine the state of an `iostream` with the operator `!`, which returns a nonzero value if the `iostream` is in an error state. For example:

```
if (!cout) error("output error");
```

There is another way to test for errors. The `ios` class defines operator `void *()`, so it returns a `NULL` pointer when there is an error. You can use a statement like:

```
if (cout << x) return; // return if successful
```

You can also use the function `good`, a member of `ios`:

```
if (cout.good()) return; // return if successful
```

The error bits are declared in the enum:

```
enum io_state {goodbit=0, eofbit=1, failbit=2,
badbit=4, hardfail=0x80};
```

For details on the error functions, see the `iostream` man pages.

13.3.1.3 Flushing

As with most I/O libraries, `iostream` often accumulates output and sends it on in larger and generally more efficient chunks. If you want to flush the buffer, you simply insert the special value `flush`. For example:

```
cout << "This needs to get out immediately." << flush;
```

`flush` is an example of a kind of object known as a *manipulator*, which is a value that can be inserted into an `ostream` to have some effect other than causing output of its value. It is really a function that takes an `ostream&` or `istream&` argument and returns its argument after performing some actions on it (see “13.7 Manipulators” on page 175).

13.3.1.4 Binary Output

To obtain output in the raw binary form of a value, use the member function `write` as shown in the following example. This example shows the output in the raw binary form of `x`.

```
cout.write((char*)&x, sizeof(x));
```

The previous example violates type discipline by converting `&x` to `char*`. Doing so is normally harmless, but if the type of `x` is a class with pointers, virtual member functions, or one that requires nontrivial constructor actions, the value written by the above example cannot be read back in properly.

13.3.2 Input Using `istream`

Input using `istream` is similar to output. You use the extraction operator `>>` and you can string together extractions the way you can with insertions. For example:

```
cin >> a >> b;
```

This statement gets two values from standard input. As with other overloaded operators, the extractors used depend on the types of `a` and `b` (and two different extractors are used if `a` and `b` have different types). The format of input and how you can control it is discussed in some detail in the `ios(3CC4)` man page. In general, leading whitespace characters (spaces, newlines, tabs, form-feeds, and so on) are ignored.

13.3.3 Defining Your Own Extraction Operators

When you want input for a new type, you overload the extraction operator for it, just as you overload the insertion operator for output.

Class `string` defines its extraction operator in the following code example:

EXAMPLE 13-1 `string` Extraction Operator

```
istream& operator>> (istream& istr, string& input)
{
    const int maxline = 256;
    char holder[maxline];
    istr.get(holder, maxline, "\n");
    input = holder;
    return istr;
}
```


EXAMPLE 13-1 string Extraction Operator (Continued)

```
}
```

The `get` function reads characters from the input stream `istr` and stores them in `holder` until `maxLine-1` characters have been read, or a new line is encountered, or EOF, whichever happens first. The data in `holder` is then null-terminated. Finally, the characters in `holder` are copied into the target string.

By convention, an extractor converts characters from its first argument (in this case, `istream& istr`), stores them in its second argument, which is always a reference, and returns its first argument. The second argument must be a reference because an extractor is meant to store the input value in its second argument.

13.3.4 Using the `char*` Extractor

This predefined extractor is mentioned here because it can cause problems. Use it like this:

```
char x[50];
cin >> x;
```

This extractor skips leading whitespace and extracts characters and copies them to `x` until it reaches another whitespace character. It then completes the string with a terminating null (`0`) character. Be careful, because input can overflow the given array.

You must also be sure the pointer points to allocated storage. For example, here is a common error:

```
char * p; // not initialized
cin >> p;
```

There is no telling where the input data will be stored, and it may cause your program to abort.

13.3.5 Reading Any Single Character

In addition to using the `char` extractor, you can get a single character with either form of the `get` member function. For example:

```
char c;
cin.get(c); // leaves c unchanged if input fails

int b;
b = cin.get(); // sets b to EOF if input fails
```

Note – Unlike the other extractors, the `char` extractor does not skip leading whitespace.

Here is a way to skip only blanks, stopping on a tab, newline, or any other character:

```
int a;
do {
    a = cin.get();
}
while(a == ' ');
```

13.3.6 Binary Input

If you need to read binary values (such as those written with the member function `write`), you can use the `read` member function. The following example shows how to input the raw binary form of `x` using the `read` member function, and is the inverse of the earlier example that uses `write`.

```
cin.read((char*)&x, sizeof(x));
```

13.3.7 Peeking at Input

You can use the `peek` member function to look at the next character in the stream without extracting it. For example:

```
if (cin.peek() != c) return 0;
```

13.3.8 Extracting Whitespace

By default, the `iostream` extractors skip leading whitespace. You can turn off the `skip` flag to prevent this from happening. The following example turns off whitespace skipping from `cin`, then turns it back on:

```
cin.unsetf(ios::skipws); // turn off whitespace skipping
...
cin.setf(ios::skipws); // turn it on again
```

You can use the `iostream` manipulator `ws` to remove leading whitespace from the `iostream`, whether or not skipping is enabled. The following example shows how to remove the leading whitespace from `iostream` `istr`:

```
istr >> ws;
```

13.3.9 Handling Input Errors

By convention, an extractor whose first argument has a nonzero error state should not extract anything from the input stream and should not clear any error bits. An extractor that fails should set at least one error bit.

As with output errors, you should check the error state periodically and take some action, such as aborting, when you find a nonzero state. The `!` operator tests the error state of an `istream`. For example, the following code produces an input error if you type alphabetic characters for input:

```
#include <stdlib.h>
#include <iostream.h>
void error (const char* message) {
    cerr << message << "\n";
    exit(1);
}
int main() {
    cout << "Enter some characters: ";
    int bad;
    cin >> bad;
    if (!cin) error("aborted due to input error");
    cout << "If you see this, not an error." << "\n";
    return 0;
}
```

Class `ios` has member functions that you can use for error handling. See the man pages for details.

13.3.10 Using `istream`s With `stdio`

You can use `stdio` with C++ programs, but problems can occur when you mix `istream`s and `stdio` in the same standard stream within a program. For example, if you write to both `stdout` and `cout`, independent buffering occurs and produces unexpected results. The problem is worse if you input from both `stdin` and `cin`, since independent buffering may turn the input into trash.

To eliminate this problem with standard input, standard output and standard error, use the following instruction before performing any input or output. It connects all the predefined `istream`s with the corresponding predefined `stdio` FILES.

```
ios::sync_with_stdio();
```

Such a connection is not the default because there is a significant performance penalty when the predefined streams are made unbuffered as part of the connection. You can use both `stdio` and `istream`s in the same program applied to different files. That is, you can write to `stdout` using `stdio` routines and write to other files attached to `istream`s. You can open `stdio` FILES for input and also read from `cin` so long as you don't also try to read from `stdin`.

13.4 Creating `istream`s

To read or write a stream other than the predefined `istream`s, you need to create your own `istream`. In general, that means creating objects of types defined in the `istream` library. This section discusses the various types available.

13.4.1 Dealing With Files Using Class `fstream`

Dealing with files is similar to dealing with standard input and standard output; classes `ifstream`, `ofstream`, and `fstream` are derived from classes `istream`, `ostream`, and `istream`, respectively. As derived classes, they inherit the insertion and extraction operations (along with the other member functions) and also have members and constructors for use with files.

Include the file `fstream.h` to use any of the `fstreams`. Use an `ifstream` when you only want to perform input, an `ofstream` for output only, and an `fstream` for a stream on which you want to perform both input and output. Use the name of the file as the constructor argument.

For example, copy the file `thisFile` to the file `thatFile` as in the following example:

```
ifstream fromFile("thisFile");
if (!fromFile)
    error("unable to open 'thisFile' for input");
ofstream toFile ("thatFile");
if (!toFile)
    error("unable to open 'thatFile' for output");
char c;
while (toFile && fromFile.get(c)) toFile.put(c);
```

This code:

- Creates an `ifstream` object called `fromFile` with a default mode of `ios::in` and connects it to `thisFile`. It opens `thisFile`.
- Checks the error state of the new `ifstream` object and, if it is in a failed state, calls the `error` function, which must be defined elsewhere in the program.
- Creates an `ofstream` object called `toFile` with a default mode of `ios::out` and connects it to `thatFile`.
- Checks the error state of `toFile` as above.
- Creates a `char` variable to hold the data while it is passed.
- Copies the contents of `fromFile` to `toFile` one character at a time.

Note – It is, of course, undesirable to copy a file this way, one character at a time. This code is provided just as an example of using `fstreams`. You should instead insert the `streambuf` associated with the input stream into the output stream. See “[13.10 Streambufs](#)” on [page 179](#), and the man page `sbufpub(3CC4)`.

13.4.1.1 Open Mode

The mode is constructed by or-ing bits from the enumerated type `open_mode`, which is a public type of class `ios` and has the definition:

```
enum open_mode {binary=0, in=1, out=2, ate=4, app=8, trunc=0x10,
               nocreate=0x20, noreplace=0x40};
```

Note – The `binary` flag is not needed on UNIX, but is provided for compatibility with systems that do need it. Portable code should use the `binary` flag when opening binary files.

You can open a file for both input and output. For example, the following code opens file `someName` for both input and output, attaching it to the `fstream` variable `inoutFile`.

```
fstream inoutFile("someName", ios::in|ios::out);
```

13.4.1.2 Declaring an `fstream` Without Specifying a File

You can declare an `fstream` without specifying a file and open the file later. For example, the following creates the `ofstream` `toFile` for writing.

```
ofstream toFile;
toFile.open(argv[1], ios::out);
```

13.4.1.3 Opening and Closing Files

You can close the `fstream` and then open it with another file. For example, to process a list of files provided on the command line:

```
ifstream infile;
for (char** f = &argv[1]; *f; ++f) {
    infile.open(*f, ios::in);
    ...;
    infile.close();
}
```

13.4.1.4 Opening a File Using a File Descriptor

If you know a file descriptor, such as the integer 1 for standard output, you can open it like this:

```
ofstream outfile;
outfile.attach(1);
```

When you open a file by providing its name to one of the `fstream` constructors or by using the `open` function, the file is automatically closed when the `fstream` is destroyed (by a `delete` or when it goes out of scope). When you attach a file to an `fstream`, it is not automatically closed.

13.4.1.5 Repositioning Within a File

You can alter the reading and writing position in a file. Several tools are supplied for this purpose.

- `streampos` is a type that can record a position in an `iostream`.
- `tellg` (`tellp`) is an `istream` (`ostream`) member function that reports the file position. Since `istream` and `ostream` are the parent classes of `fstream`, `tellg` and `tellp` can also be invoked as a member function of the `fstream` class.
- `seekg` (`seekp`) is an `istream` (`ostream`) member function that finds a given position.
- The `seek_dir` enum specifies relative positions for use with `seek`.

```
enum seek_dir {beg=0, cur=1, end=2};
```

For example, given an `fstream` `aFile`:

```
streampos original = aFile.tellp();    //save current position
aFile.seekp(0, ios::end); //reposition to end of file
aFile << x;                          //write a value to file
aFile.seekp(original);    //return to original position
```

`seekg` (`seekp`) can take one or two parameters. When it has two parameters, the first is a position relative to the position indicated by the `seek_dir` value given as the second parameter. For example:

```
aFile.seekp(-10, ios::end);
```

moves to 10 bytes from the end while

```
aFile.seekp(10, ios::cur);
```

moves to 10 bytes forward from the current position.

Note – Arbitrary seeks on text streams are not portable, but you can always return to a previously saved `streampos` value.

13.5 Assignment of `ostreams`

`ostreams` does not allow assignment of one stream to another.

The problem with copying a stream object is that there are then two versions of the state information, such as a pointer to the current write position within an output file, which can be changed independently. As a result, problems could occur.

13.6 Format Control

Format control is discussed in detail in man page `ios(3CC4)`.

13.7 Manipulators

Manipulators are values that you can insert into or extract from `ostreams` to have special effects.

Parameterized manipulators are manipulators that take one or more parameters.

Because manipulators are ordinary identifiers, and therefore use up possible names, `ostream` doesn't define them for every possible function. A number of manipulators are discussed with member functions in other parts of this chapter.

There are 13 predefined manipulators, as described in [Table 13–2](#). When using that table, assume the following:

- `i` has type `long`.
- `n` has type `int`.
- `c` has type `char`.
- `istr` is an input stream.
- `ostr` is an output stream.

TABLE 13–2 `ostream` Predefined Manipulators

	Predefined Manipulator	Description
1	<code>ostr << dec, istr >> dec</code>	Makes the integer conversion base 10.
2	<code>ostr << endl</code>	Inserts a newline character ('\n') and invokes <code>ostream::flush()</code> .
3	<code>ostr << ends</code>	Inserts a null (0) character. Useful when dealing with <code>stringstream</code> .
4	<code>ostr << flush</code>	Invokes <code>ostream::flush()</code> .

TABLE 13–2 `iostream` Predefined Manipulators (Continued)

	Predefined Manipulator	Description
5	<code>ostr << hex, istr >> hex</code>	Makes the integer conversion base 16.
6	<code>ostr << oct, istr >> oct</code>	Make the integer conversion base 8.
7	<code>istr >> ws</code>	Extracts whitespace characters (skips whitespace) until a non-whitespace character is found (which is left in <code>istr</code>).
8	<code>ostr << setbase(n), istr >> setbase(n)</code>	Sets the conversion base to <code>n</code> (0, 8, 10, 16 only).
9	<code>ostr << setw(n), istr >> setw(n)</code>	Invokes <code>ios::width(n)</code> . Sets the field width to <code>n</code> .
10	<code>ostr << resetiosflags(i), istr >> resetiosflags(i)</code>	Clears the flags bitvector according to the bits set in <code>i</code> .
11	<code>ostr << setiosflags(i), istr >> setiosflags(i)</code>	Sets the flags bitvector according to the bits set in <code>i</code> .
12	<code>ostr << setfill(c), istr >> setfill(c)</code>	Sets the fill character (for padding a field) to <code>c</code> .
13	<code>ostr << setprecision(n), istr >> setprecision(n)</code>	Sets the floating-point precision to <code>n</code> digits.

To use predefined manipulators, you must include the file `iomanip.h` in your program.

You can define your own manipulators. There are two basic types of manipulator:

- Plain manipulator—Takes an `istream&`, `ostream&`, or `ios&` argument, operates on the stream, and then returns its argument.
- Parameterized manipulator—Takes an `istream&`, `ostream&`, or `ios&` argument, one additional argument (the parameter), operates on the stream, and then returns its stream argument.

13.7.1 Using Plain Manipulators

A plain manipulator is a function that:

- Takes a reference to a stream
- Operates on it in some way
- Returns its argument

The shift operators taking (a pointer to) such a function are predefined for `ostreams`, so the function can be put in a sequence of input or output operators. The shift operator calls the function rather than trying to read or write a value. An example of a tab manipulator that inserts a tab in an `ostream` is:

```
ostream& tab(ostream& os) {
    return os << '\t';
}
...
cout << x << tab << y;
```

This is an elaborate way to achieve the following:

```
const char tab = '\t';
...
cout << x << tab << y;
```

The following code is another example, which cannot be accomplished with a simple constant. Suppose you want to turn whitespace skipping on and off for an input stream. You can use separate calls to `ios::setf` and `ios::unsetf` to turn the `skipws` flag on and off, or you could define two manipulators.

```
#include <iostream.h>
#include <iomanip.h>
istream& skipon(istream &is) {
    is.setf(ios::skipws, ios::skipws);
    return is;
}
istream& skipoff(istream& is) {
    is.unsetf(ios::skipws);
    return is;
}
...
int main ()
{
    int x,y;
    cin >> skipon >> x >> skipoff >> y;
    return 1;
}
```

13.7.2 Parameterized Manipulators

One of the parameterized manipulators that is included in `iomanip.h` is `setfill`. `setfill` sets the character that is used to fill out field widths. It is implemented as shown in the following example:

```
//file setfill.cc
#include<iostream.h>
#include<iomanip.h>

//the private manipulator
```

```

static ios& sfill(ios& i, int f) {
    i.fill(f);
    return i;
}
//the public applicator
smanip_int setfill(int f) {
    return smanip_int(sfill, f);
}

```

A parameterized manipulator is implemented in two parts:

- The *manipulator*. It takes an extra parameter. In the previous code example, it takes an extra `int` parameter. You cannot place this manipulator function in a sequence of input or output operations, since there is no shift operator defined for it. Instead, you must use an auxiliary function, the applicator.
- The *applicator*. It calls the manipulator. The applicator is a global function, and you make a prototype for it available in a header file. Usually the manipulator is a static function in the file containing the source code for the applicator. The manipulator is called only by the applicator, and if you make it static, you keep its name out of the global address space.

Several classes are defined in the header file `iomanip.h`. Each class holds the address of a manipulator function and the value of one parameter. The `iomanip` classes are described in the man page `manip(3CC4)`. The previous example uses the `smanip_int` class, which works with an `ios`. Because it works with an `ios`, it also works with an `istream` and an `ostream`. The previous example also uses a second parameter of type `int`.

The applicator creates and returns a class object. In the previous code example the class object is an `smanip_int`, and it contains the manipulator and the `int` argument to the applicator. The `iomanip.h` header file defines the shift operators for this class. When the applicator function `setfill` appears in a sequence of input or output operations, the applicator function is called, and it returns a class. The shift operator acts on the class to call the manipulator function with its parameter value, which is stored in the class.

In the following example, the manipulator `print_hex`:

- Puts the output stream into the hex mode.
- Inserts a long value into the stream.
- Restores the conversion mode of the stream.

The class `omanip_long` is used because this code example is for output only, and it operates on a long rather than an `int`:

```

#include <iostream.h>
#include <iomanip.h>
static ostream& xfield(ostream& os, long v) {
    long save = os.setf(ios::hex, ios::basefield);
    os << v;
    os.setf(save, ios::basefield);
    return os;
}

```

```
omanip_long print_hex(long v) {  
    return manip_long(xfield, v);  
}
```

13.8 Strstreams: iostreams for Arrays

See the `strstream(3CC4)` man page.

13.9 Stdiobufs: iostreams for stdio Files

See the `stdiobuf(3CC4)` man page.

13.10 Streambufs

`iostreams` are the formatting part of a two-part (input or output) system. The other part of the system is made up of `streambufs`, which deal in input or output of unformatted streams of characters.

You usually use `streambufs` through `iostreams`, so you don't have to worry about the details of `streambufs`. You can use `streambufs` directly if you choose to, for example, if you need to improve efficiency or to get around the error handling or formatting built into `iostreams`.

13.10.1 Working With Streambufs

A `streambuf` consists of a stream or sequence of characters and one or two pointers into that sequence. Each pointer points between two characters. (Pointers cannot actually point between characters, but it is helpful to think of them that way.) There are two kinds of `streambuf` pointers:

- A *put* pointer, which points just before the position where the next character will be stored
- A *get* pointer, which points just before the next character to be fetched

A `streambuf` can have one or both of these pointers.

13.10.1.1 Position of Pointers

The positions of the pointers and the contents of the sequences can be manipulated in various ways. Whether or not both pointers move when manipulated depends on the kind of `streambuf` used. Generally, with queue-like `streambufs`, the `get` and `put` pointers move independently; with file-like `streambufs` the `get` and `put` pointers always move together. A `strstream` is an example of a queue-like stream; an `fstream` is an example of a file-like stream.

13.10.2 Using Streambufs

You never create an actual `streambuf` object, but only objects of classes derived from class `streambuf`. Examples are `filebuf` and `strstreambuf`, which are described in man pages `filebuf(3CC4)` and `ssbuf(3)`, respectively. Advanced users may want to derive their own classes from `streambuf` to provide an interface to a special device or to provide other than basic buffering. Man pages `sbufpub(3CC4)` and `sbufprot(3CC4)` discuss how to do this.

Apart from creating your own special kind of `streambuf`, you may want to access the `streambuf` associated with an `istream` to access the public member functions, as described in the man pages referenced above. In addition, each `istream` has a defined inserter and extractor which takes a `streambuf` pointer. When a `streambuf` is inserted or extracted, the entire stream is copied.

Here is another way to do the file copy discussed earlier, with the error checking omitted for clarity:

```
ifstream fromFile("thisFile");
ofstream toFile ("thatFile");
toFile << fromFile.rdbuf();
```

We open the input and output files as before. Every `istream` class has a member function `rdbuf` that returns a pointer to the `streambuf` object associated with it. In the case of an `ifstream`, the `streambuf` object is type `filebuf`. The entire file associated with `fromFile` is copied (inserted into) the file associated with `toFile`. The last line could also be written like this:

```
fromFile >> toFile.rdbuf();
```

The source file is then extracted into the destination. The two methods are entirely equivalent.

13.11 `iostream` Man Pages

A number of C++ man pages give details of the `iostream` library. The following table gives an overview of what is in each man page.

To access a classic `iostream` library man page, type:

```
example% man -s 3CC4 name
```

TABLE 13-3 `iostream` Man Pages Overview

Man Page	Overview
<code>filebuf</code>	Details the public interface for the class <code>filebuf</code> , which is derived from <code>streambuf</code> and is specialized for use with files. See the <code>sbufpub(3CC4)</code> and <code>sbufprot(3CC4)</code> man pages for details of features inherited from class <code>streambuf</code> . Use the <code>filebuf</code> class through class <code>fstream</code> .
<code>fstream</code>	Details specialized member functions of classes <code>ifstream</code> , <code>ofstream</code> , and <code>fstream</code> , which are specialized versions of <code>istream</code> , <code>ostream</code> , and <code>iostream</code> for use with files.
<code>ios</code>	Details parts of class <code>ios</code> , which functions as a base class for <code>iostreams</code> . It contains state data common to all streams.
<code>ios.intro</code>	Gives an introduction to and overview of <code>iostreams</code> .
<code>istream</code>	Details the following: <ul style="list-style-type: none"> ■ Member functions for class <code>istream</code>, which supports interpretation of characters fetched from a <code>streambuf</code> ■ Input formatting ■ Positioning functions described as part of class <code>ostream</code>. ■ Some related functions ■ Related manipulators
<code>manip</code>	Describes the input and output manipulators defined in the <code>iostream</code> library.
<code>ostream</code>	Details the following: <ul style="list-style-type: none"> ■ Member functions for class <code>ostream</code>, which supports interpretation of characters written to a <code>streambuf</code> ■ Output formatting ■ Positioning functions described as part of class <code>ostream</code> ■ Some related functions ■ Related manipulators
<code>sbufprot</code>	Describes the interface needed by programmers who are coding a class derived from class <code>streambuf</code> . Also refer to the <code>sbufpub(3CC4)</code> man page because some public functions are not discussed in the <code>sbufprot(3CC4)</code> man page.

TABLE 13–3 *iostream* Man Pages Overview (Continued)

Man Page	Overview
<code>sbufpub</code>	Details the public interface of class <code>streambuf</code> , in particular, the public member functions of <code>streambuf</code> . This man page contains the information needed to manipulate a <code>streambuf</code> -type object directly, or to find out about functions that classes derived from <code>streambuf</code> inherit from it. If you want to derive a class from <code>streambuf</code> , also see the <code>sbufprot(3CC4)</code> man page.
<code>ssbuf</code>	Details the specialized public interface of class <code>strstreambuf</code> , which is derived from <code>streambuf</code> and specialized for dealing with arrays of characters. See the <code>sbufpub(3CC4)</code> man page for details of features inherited from class <code>streambuf</code> .
<code>stdiobuf</code>	Contains a minimal description of class <code>stdiobuf</code> , which is derived from <code>streambuf</code> and specialized for dealing with <code>stdio</code> FILES. See the <code>sbufpub(3CC4)</code> man page for details of features inherited from class <code>streambuf</code> .
<code>strstream</code>	Details the specialized member functions of <code>strstreams</code> , which are implemented by a set of classes derived from the <i>iostream</i> classes and specialized for dealing with arrays of characters.

13.12 *iostream* Terminology

The *iostream* library descriptions often use terms similar to terms from general programming, but with specialized meanings. The following table defines these terms as they are used in discussing the *iostream* library.

TABLE 13–4 *iostream* Terminology

<i>iostream</i> Term	Definition
Buffer	<p>A word with two meanings, one specific to the <i>iostream</i> package and one more generally applied to input and output.</p> <p>When referring specifically to the <i>iostream</i> library, a buffer is an object of the type defined by the class <code>streambuf</code>.</p> <p>A buffer, generally, is a block of memory used to make efficient transfer of characters for input or output. With buffered I/O, the actual transfer of characters is delayed until the buffer is full or forcibly flushed.</p> <p>An unbuffered buffer refers to a <code>streambuf</code> where there is no buffer in the general sense defined above. This chapter avoids use of the term <code>buffer</code> to refer to <code>streambufs</code>. However, the man pages and other C++ documentation do use the term <code>buffer</code> to mean <code>streambufs</code>.</p>

TABLE 13-4 `iostream` Terminology (Continued)

<code>iostream</code> Term	Definition
Extraction	The process of taking input from an <code>iostream</code> .
<code>Fstream</code>	An input or output stream specialized for use with files. Refers specifically to a class derived from class <code>iostream</code> when printed in <code>courier</code> font.
Insertion	The process of sending output into an <code>iostream</code> .
<code>iostream</code>	Generally, an input or output stream.
<code>iostream</code> library	The library implemented by the include files <code>iostream.h</code> , <code>fstream.h</code> , <code>stringstream.h</code> , <code>iomanip.h</code> , and <code>stdiostream.h</code> . Because <code>iostream</code> is an object-oriented library, you should extend it. So, some of what you can do with the <code>iostream</code> library is not implemented.
Stream	An <code>iostream</code> , <code>fstream</code> , <code>stringstream</code> , or user-defined stream in general.
<code>Streambuf</code>	A buffer that contains a sequence of characters with a <code>put</code> or <code>get</code> pointer, or both. When printed in <code>courier</code> font, it means the particular class. Otherwise, it refers generally to any object of class <code>streambuf</code> or a class derived from <code>streambuf</code> . Any stream object contains an object, or a pointer to an object, of a type derived from <code>streambuf</code> .
<code>stringstream</code>	An <code>iostream</code> specialized for use with character arrays. It refers to the specific class when printed in <code>courier</code> font.

Using the Complex Arithmetic Library

Complex numbers are numbers made up of a *real* part and an *imaginary* part. For example:

$3.2 + 4i$
 $1 + 3i$
 $1 + 2.3i$

In the degenerate case, $0 + 3i$ is an entirely imaginary number generally written as $3i$, and $5 + 0i$ is an entirely real number generally written as 5 . You can represent complex numbers using the `complex` data type.

Note – The complex arithmetic library (`libcomplex`) is available only for compatibility mode (`-compat[=4]`). In standard mode (the default mode), complex number classes with similar functionality are included with the C++ Standard Library `libcstd`.

14.1 The Complex Library

The complex arithmetic library implements a complex number data type as a new data type and provides:

- Operators
- Mathematical functions (defined for the built-in numerical types)
- Extensions (for iostreams that allow input and output of complex numbers)
- Error handling mechanisms

Complex numbers can also be represented as an *absolute value* (or *magnitude*) and an *argument* (or *angle*). The library provides functions to convert between the real and imaginary (Cartesian) representation and the magnitude and angle (polar) representation.

The *complex conjugate* of a number has the opposite sign in its imaginary part.

14.1.1 Using the Complex Library

To use the complex library, include the header file `complex.h` in your program, and compile and link with the `-library=complex` option.

14.2 Type `complex`

The complex arithmetic library defines one class: class `complex`. An object of class `complex` can hold a single complex number. The complex number is constructed of two parts:

- The real part
- The imaginary part

```
class complex {
    double re, im;
};
```

The value of an object of class `complex` is a pair of `double` values. The first value represents the real part; the second value represents the imaginary part.

14.2.1 Constructors of Class `complex`

There are two constructors for `complex`. Their definitions are:

```
complex::complex()           {re=0.0; im=0.0;}
complex::complex(double r, double i = 0.0) {re=r; im=i;}
```

If you declare a complex variable without specifying parameters, the first constructor is used and the variable is initialized, so that both parts are `0`. The following example creates a complex variable whose real and imaginary parts are both `0`:

```
complex aComp;
```

You can give either one or two parameters. In either case, the second constructor is used. When you give only one parameter, that parameter is taken as the value for the real part and the imaginary part is set to `0`. For example:

```
complex aComp(4.533);
```

creates a complex variable with the following value:

```
4.533 + 0i
```

If you give two values, the first value is taken as the value of the real part and the second as the value of the imaginary part. For example:

```
complex aComp(8.999, 2.333);
```

creates a complex variable with the following value:

```
8.999 + 2.333i
```

You can also create a complex number using the `polar` function, which is provided in the complex arithmetic library (see “14.3 Mathematical Functions” on page 188). The `polar` function creates a complex value given the polar coordinates magnitude and angle.

There is no destructor for type `complex`.

14.2.2 Arithmetic Operators

The complex arithmetic library defines all the basic arithmetic operators. Specifically, the following operators work in the usual way and with the usual precedence:

```
+ - / * =
```

The subtraction operator (`-`) has its usual binary and unary meanings.

In addition, you can use the following operators in the usual way:

- Addition assign operator (`+=`)
- Subtraction assign operator (`-=`)
- Multiplication assign operator (`*=`)
- Division assign operator (`/=`)

However, the preceding four operators do not produce values that you can use in expressions. For example, the following expressions do not work:

```
complex a, b;
...
if ((a+=2)==0) {...}; // illegal
b = a *= b; // illegal
```

You can also use the equality operator (`==`) and the inequality operator (`!=`) in their regular meaning.

When you mix real and complex numbers in an arithmetic expression, C++ uses the complex operator function and converts the real values to complex values.

14.3 Mathematical Functions

The complex arithmetic library provides a number of mathematical functions. Some are peculiar to complex numbers; the rest are complex-number versions of functions in the standard C mathematical library.

All of these functions produce a result for every possible argument. If a function cannot produce a mathematically acceptable result, it calls `complex_error` and returns some suitable value. In particular, the functions try to avoid actual overflow and call `complex_error` with a message instead. The following tables describe the remainder of the complex arithmetic library functions.

Note – The implementation of the `sqrt` and `atan2` functions is aligned with the C99 `csqrt` Annex G specification.

TABLE 14-1 Complex Arithmetic Library Functions

Complex Arithmetic Library Function	Description
<code>double abs(const complex)</code>	Returns the magnitude of a complex number.
<code>double arg(const complex)</code>	Returns the angle of a complex number.
<code>complex conj(const complex)</code>	Returns the complex conjugate of its argument.
<code>double imag(const complex&)</code>	Returns the imaginary part of a complex number.
<code>double norm(const complex)</code>	Returns the square of the magnitude of its argument. Faster than <code>abs</code> , but more likely to cause an overflow. For comparing magnitudes.
<code>complex polar(double mag, double ang=0.0)</code>	Takes a pair of polar coordinates that represent the magnitude and angle of a complex number and returns the corresponding complex number.
<code>double real(const complex&)</code>	Returns the real part of a complex number.

TABLE 14-2 Complex Mathematical and Trigonometric Functions

Complex Arithmetic Library Function	Description
<code>complex acos(const complex)</code>	Returns the angle whose cosine is its argument.

TABLE 14–2 Complex Mathematical and Trigonometric Functions (Continued)

Complex Arithmetic Library Function	Description
<code>complex asin(const complex)</code>	Returns the angle whose sine is its argument.
<code>complex atan(const complex)</code>	Returns the angle whose tangent is its argument.
<code>complex cos(const complex)</code>	Returns the cosine of its argument.
<code>complex cosh(const complex)</code>	Returns the hyperbolic cosine of its argument.
<code>complex exp(const complex)</code>	Computes e^{**x} , where e is the base of the natural logarithms, and x is the argument given to <code>exp</code> .
<code>complex log(const complex)</code>	Returns the natural logarithm of its argument.
<code>complex log10(const complex)</code>	Returns the common logarithm of its argument.
<code>complex pow(double b, const complex exp)</code> <code>complex pow(const complex b, int exp)</code> <code>complex pow(const complex b, double exp)</code> <code>complex pow(const complex b, const complex exp)</code>	Takes two arguments: <code>pow(b, exp)</code> . It raises b to the power of <code>exp</code> .
<code>complex sin(const complex)</code>	Returns the sine of its argument.
<code>complex sinh(const complex)</code>	Returns the hyperbolic sine of its argument.
<code>complex sqrt(const complex)</code>	Returns the square root of its argument.
<code>complex tan(const complex)</code>	Returns the tangent of its argument.
<code>complex tanh(const complex)</code>	Returns the hyperbolic tangent of its argument.

14.4 Error Handling

The complex library has these definitions for error handling:

```
extern int errno;
class c_exception {...};
int complex_error(c_exception&);
```

The external variable `errno` is the global error state from the C library. `errno` can take on the values listed in the standard header `errno.h` (see the man page `error(3)`). No function sets `errno` to zero, but many functions set it to other values.

To determine whether a particular operation fails:

1. Set `errno` to zero before the operation.
2. Test the operation.

The function `complex_error` takes a reference to type `c_exception` and is called by the following complex arithmetic library functions:

- `exp`
- `log`
- `log10`
- `sinh`
- `cosh`

The default version of `complex_error` returns zero. This return of zero means that the default error handling takes place. You can provide your own replacement function `complex_error` that performs other error handling. Error handling is described in the man page `plxerr(3CC4)`.

Default error handling is described in the man pages `plxtrig(3CC4)` and `plxexp(3CC4)`. It is also summarized in the following table.

Complex Arithmetic Library Function	Default Error Handling Summary
<code>exp</code>	If overflow occurs, sets <code>errno</code> to <code>ERANGE</code> and returns a huge complex number.
<code>log</code> , <code>log10</code>	If the argument is zero, sets <code>errno</code> to <code>EDOM</code> and returns a huge complex number.
<code>sinh</code> , <code>cosh</code>	If the imaginary part of the argument causes overflow, returns a complex zero. If the real part causes overflow, returns a huge complex number. In either case, sets <code>errno</code> to <code>ERANGE</code> .

14.5 Input and Output

The complex arithmetic library provides default *extractors* and *inserters* for complex numbers, as shown in the following example:

```
ostream& operator<<(ostream&, const complex&); //inserter
istream& operator>>(istream&, complex&); //extractor
```

For basic information on extractors and inserters, see “13.2 Basic Structure of `iostream` Interaction” on page 164 and “13.3.1 Output Using `iostream`” on page 165.

For input, the complex extractor `>>` extracts a pair of numbers (surrounded by parentheses and separated by a comma) from the input stream and reads them into a complex object. The first number is taken as the value of the real part; the second as the value of the imaginary part. For example, given the declaration and input statement:

```
complex x;
cin >> x;
```

and the input `(3.45, 5)`, the value of `x` is equivalent to `3.45 + 5.0i`. The reverse is true for inserters. Given `complex x(3.45, 5)`, `cout<<x` prints `(3.45, 5)`.

The input usually consists of a pair of numbers in parentheses separated by a comma; white space is optional. If you provide a single number, with or without parentheses and white space, the extractor sets the imaginary part of the number to zero. Do not include the symbol `i` in the input text.

The inserter inserts the values of the real and imaginary parts enclosed in parentheses and separated by a comma. It does not include the symbol `i`. The two values are treated as `double`s.

14.6 Mixed-Mode Arithmetic

Type `complex` is designed to fit in with the built-in arithmetic types in mixed-mode expressions. Arithmetic types are silently converted to type `complex`, and there are `complex` versions of the arithmetic operators and most mathematical functions. For example:

```
int i, j;
double x, y;
complex a, b;
a = sin((b+i)/y) + x/j;
```

The expression `b+i` is mixed-mode. Integer `i` is converted to type `complex` via the constructor `complex::complex(double, double=0)`, the integer first being converted to type `double`. The result is to be divided by `y`, a `double`, so `y` is also converted to `complex` and the complex divide operation is used. The quotient is thus type `complex`, so the complex sine routine is called, yielding another `complex` result, and so on.

Not all arithmetic operations and conversions are implicit, or even defined, however. For example, complex numbers are not well-ordered, mathematically speaking, and complex numbers can be compared for equality only.

```
complex a, b;
a == b; // OK
a != b; // OK
a < b; // error: operator < cannot be applied to type complex
a >= b; // error: operator >= cannot be applied to type complex
```

Similarly, there is no automatic conversion from type `complex` to any other type, because the concept is not well-defined. You can specify whether you want the real part, imaginary part, or magnitude, for example.

```
complex a;
double f(double);
f(abs(a)); // OK
f(a);     // error: no match for f(complex)
```

14.7 Efficiency

The design of the `complex` class addresses efficiency concerns.

The simplest functions are declared `inline` to eliminate function call overhead.

Several overloaded versions of functions are provided when that makes a difference. For example, the `pow` function has versions that take exponents of type `double` and `int` as well as `complex`, since the computations for the former are much simpler.

The standard C math library header `math.h` is included automatically when you include `complex.h`. The C++ overloading rules then result in efficient evaluation of expressions like this:

```
double x;
complex x = sqrt(x);
```

In this example, the standard math function `sqrt(double)` is called, and the result is converted to type `complex`, rather than converting to type `complex` first and then calling `sqrt(complex)`. This result falls right out of the overload resolution rules, and is precisely the result you want.

14.8 Complex Man Pages

The remaining documentation of the complex arithmetic library consists of the man pages listed in the following table.

TABLE 14-3 Man Pages for Type `complex`

Man Page	Overview
<code>plx.intro(3CC4)</code>	General introduction to the complex arithmetic library
<code>cartpol(3CC4)</code>	Cartesian and polar functions
<code>plxerr(3CC4)</code>	Error-handling functions
<code>plxexp(3CC4)</code>	Exponential, log, and square root functions

TABLE 14-3 Man Pages for Type `complex` (Continued)

Man Page	Overview
<code>cplxops(3CC4)</code>	Arithmetic operator functions
<code>cplxtrig(3CC4)</code>	Trigonometric functions

Building Libraries

This chapter explains how to build your own libraries.

15.1 Understanding Libraries

Libraries provide two benefits. First, they provide a way to share code among several applications. If you have such code, you can create a library with it and link the library with any application that needs it. Second, libraries provide a way to reduce the complexity of very large applications. Such applications can build and maintain relatively independent portions as libraries and so reduce the burden on programmers working on other portions.

Building a library simply means creating `.o` files (by compiling your code with the `-c` option) and combining the `.o` files into a library using the `CC` command. You can build two kinds of libraries, static (archive) libraries and dynamic (shared) libraries.

With static (archive) libraries, objects within the library are linked into the program's executable file at link time. Only those `.o` files from the library that are needed by the application are linked into the executable. The name of a static (archive) library generally ends with a `.a` suffix.

With dynamic (shared) libraries, objects within the library are not linked into the program's executable file, but rather the linker notes in the executable that the program depends on the library. When the program is executed, the system loads the dynamic libraries that the program requires. If two programs that use the same dynamic library execute at the same time, the operating system shares the library among the programs. The name of a dynamic (shared) library ends with a `.so` suffix.

Linking dynamically with shared libraries has several advantages over linking statically with archive libraries:

- The size of the executable is smaller.

- Significant portions of code can be shared among programs at runtime, reducing the amount of memory use.
- The library can be replaced at runtime without relinking with the application. (This is the primary mechanism that enables programs to take advantage of many improvements in the Solaris operating system without requiring relinking and redistribution of programs.)
- The shared library can be loaded at runtime, using the `dlopen()` function call.

However, dynamic libraries have some disadvantages:

- Runtime linking has an execution-time cost.
- Distributing a program that uses dynamic libraries might require simultaneous distribution of the libraries it uses.
- Moving a shared library to a different location can prevent the system from finding the library and executing the program. (The environment variable `LD_LIBRARY_PATH` helps overcome this problem.)

15.2 Building Static (Archive) Libraries

The mechanism for building static (archive) libraries is similar to that of building an executable. A collection of object (`.o`) files can be combined into a single library using the `-xar` option of `CC`.

You should build static (archive) libraries using `CC -xar` instead of using the `ar` command directly. The C++ language generally requires that the compiler maintain more information than can be accommodated with traditional `.o` files, particularly template instances. The `-xar` option ensures that all necessary information, including template instances, is included in the library. You might not be able to accomplish this in a normal programming environment since `make` might not know which template files are actually created and referenced. Without `CC -xar`, referenced template instances might not be included in the library, as required. For example:

```
% CC -c foo.cc # Compile main file, templates objects are created.  
% CC -xar -o foo.a foo.o # Gather all objects into a library.
```

The `-xar` flag causes `CC` to create a static (archive) library. The `-o` directive is required to name the newly created library. The compiler examines the object files on the command line, cross-references the object files with those known to the template repository, and adds those templates required by the user's object files (along with the main object files themselves) to the archive.

Note – Use the `-xar` flag for creating or updating an existing archive only. Do not use it to maintain an archive. The `-xar` option is equivalent to `ar -cr`.

It is a good idea to have only one function in each `.o` file. If you are linking with an archive, an entire `.o` file from the archive is linked into your application when a symbol is needed from that particular `.o` file. Having one function in each `.o` file ensures that only those symbols needed by the application will be linked from the archive.

15.3 Building Dynamic (Shared) Libraries

Dynamic (shared) libraries are built the same way as static (archive) libraries, except that you use `-G` instead of `-xar` on the command line.

You should not use `ld` directly. As with static libraries, the `CC` command ensures that all the necessary template instances from the template repository are included in the library if you are using templates. All static constructors in a dynamic library that is linked to an application are called *before* `main()` is executed and all static destructors are called *after* `main()` exits. If a shared library is opened using `dlopen()`, all static constructors are executed at `dlopen()` and all static destructors are executed at `dclose()`.

You should use `CC -G` to build a dynamic library. When you use `ld` (the link-editor) or `cc` (the C compiler) to build a dynamic library, exceptions might not work and the global variables that are defined in the library are not initialized.

To build a dynamic (shared) library, you must create relocatable object files by compiling each object with the `-Kpic` or `-KPIC` option of `CC`. You can then build a dynamic library with these relocatable object files. If you get any bizarre link failures, you might have forgotten to compile some objects with `-Kpic` or `-KPIC`.

To build a C++ dynamic library named `libfoo.so` that contains objects from source files `lsrc1.cc` and `lsrc2.cc`, type:

```
% CC -G -o libfoo.so -h libfoo.so -Kpic lsrc1.cc lsrc2.cc
```

The `-G` option specifies the construction of a dynamic library. The `-o` option specifies the file name for the library. The `-h` option specifies an internal name for the shared library. The `-Kpic` option specifies that the object files are to be position-independent.

The `CC -G` command does not pass any `-l` options to the linker, `ld`. To ensure proper initialization order, a shared library must have an explicit dependency on each other shared library it needs. To create the dependencies, use a `-l` option for each such library. Typical C++ shared libraries will use one of the following sets of options:

```
-lcstd -lCrun -lc  
-library=stlport4 -lCrun -lc
```

To be sure you have listed all needed dependencies, build the library with the `-zdefs` option. The linker will issue an error message for each missing symbol definition. To provide the missing definitions, add a `-l` option for those libraries.

To find out if you have included unneeded dependencies, use the commands

```
ldd -u -r mylib.so  
ldd -U -r mylib.so
```

You can then rebuild `mylib.so` without the unneeded dependencies.

15.4 Building Shared Libraries That Contain Exceptions

Never use `-Bsymbolic` with programs containing C++ code, use linker map files instead. With `-Bsymbolic`, references in different modules can bind to different copies of what is supposed to be one global object.

The exception mechanism relies on comparing addresses. If you have two copies of something, their addresses won't compare equal, and the exception mechanism can fail because the exception mechanism relies on comparing what are supposed to be unique addresses.

15.5 Building Libraries for Private Use

When an organization builds a library for internal use only, the library can be built with options that are not advised for more general use. In particular, the library need not comply with the system's application binary interface (ABI). For example, the library can be compiled with the `-fast` option to improve its performance on a known architecture. Likewise, it can be compiled with the `-xregs=float` option to improve performance.

15.6 Building Libraries for Public Use

When an organization builds a library for use by other organizations, the management of the libraries, platform generality, and other issues become significant. A simple test for whether or not a library is public is to ask if the application programmer can recompile the library easily. Public libraries should be built in conformance with the system's application binary interface (ABI). In general, this means that any processor-specific options should be avoided. (For example, do not use `-fast` or `-xtarget`.)

The SPARC ABI reserves some registers exclusively for applications. For V7 and V8, these registers are `%g2`, `%g3`, and `%g4`. For V9, these registers are `%g2` and `%g3`. Since most compilations are for applications, the C++ compiler, by default, uses these registers for scratch registers, improving program performance. However, use of these registers in a public library is generally not compliant with the SPARC ABI. When building a library for public use, compile all objects with the `-xregs=no%appl` option to ensure that the application registers are not used.

15.7 Building a Library That Has a C API

If you want to build a library that is written in C++ but that can be used with a C program, you must create a C API (application programming interface). To do this, make all the exported functions `extern "C"`. Note that this can be done only for global functions and not for member functions.

If a C-interface library needs C++ run-time support and you are linking with `cc`, then you must also link your application with either `libc` (compatibility mode) or `libCrun` (standard mode) when you use the C-interface library. (If the C-interface library does not need C++ run-time support, then you do not have to link with `libc` or `libCrun`.) The steps for linking differ for archived and shared libraries.

When providing an *archived* C-interface library, you must provide instructions on how to use the library.

- If the C-interface library was built with `CC` in *standard mode* (the default), add `-lCrun` to the `cc` command line when using the C-interface library.
- If the C-interface library was built with `CC` in *compatibility mode* (`-compat`), add `-lc` to the `cc` command line when using the C-interface library.

When providing a *shared* C-interface library you must create a dependency on `libc` or `libCrun` at the time that you build the library. When the shared library has the correct dependency, you do not need to add `-lc` or `-lCrun` to the command line when you use the library.

- If you are building the C-interface library in *compatibility mode* (`-compat`), add `-lc` to the `CC` command line when you build the library.
- If you are building the C-interface library in *standard mode* (the default), add `-lCrun` to the `CC` command line when you build the library.

If you want to remove any dependency on the C++ runtime libraries, you should enforce the following coding rules in your library sources:

- Do not use any form of `new` or `delete` unless you provide your own corresponding versions.
- Do not use exceptions.
- Do not use runtime type information (RTTI).

15.8 Using `dlopen` to Access a C++ Library From a C Program

If you want to use `dlopen()` to open a C++ shared library from a C program, make sure that the shared library has a dependency on the appropriate C++ runtime (`libc.so.5` for `-compat=4`, or `libCrun.so.1` for `-compat=5`).

To do this, add `-lc` for `-compat=4` or add `-lCrun` for `-compat=5` to the command line when building the shared library. For example:

```
example% CC -G -compat=4... -lC  
example% CC -G -compat=5... -lCrun
```

If the shared library uses exceptions and does not have a dependency on the C++ runtime library, your C program might behave erratically.

P A R T I V

Appendixes

C++ Compiler Options

This appendix details the command-line options for the C++ compiler. The features described apply to all platforms except as noted; features that are unique to the Solaris OS on SPARC-based systems are identified as *SPARC*, and the features that are unique to the Solaris and Linux OS on x86-based systems are identified as *x86*. Features limited to the Solaris OS only are marked *Solaris*; features limited only to Linux OS are marked *Linux*. Note that references to the Solaris OS imply the OpenSolaris OS as well.

The typographical conventions that are listed in the Preface are used in this section of the manual to describe individual options.

Parentheses, braces, brackets, pipe characters, and ellipses are *metacharacters* used in the descriptions of the options and are not part of the options themselves.

A.1 How Option Information Is Organized

To help you find information, compiler option descriptions are separated into the following subsections. If the option is one that is replaced by or identical to some other option, see the description of the other option for full details.

TABLE A-1 Option Subsections

Subsection	Contents
Option Definition	A short definition immediately follows each option. (There is no heading for this category.)
Values	If the option has one or more values, this section defines each value.

Subsection	Contents
Defaults	<p>If the option has a primary or secondary default value, it is stated here.</p> <p>The primary default is the option value in effect if the option is not specified. For example, if <code>-compat</code> is not specified, the default is <code>-compat=5</code>.</p> <p>The secondary default is the option in effect if the option is specified, but no value is given. For example, if <code>-compat</code> is specified without a value, the default is <code>-compat=4</code>.</p>
Expansions	If the option has a macro expansion, it is shown in this section.
Examples	If an example is needed to illustrate the option, it is given here.
Interactions	If the option interacts with other options, the relationship is discussed here.
Warnings	If there are cautions regarding use of the option, they are noted here, as are actions that might cause unexpected behavior.
See also	This section contains references to further information in other options or documents.
“Replace with” “Same as”	<p>If an option has become obsolete and has been replaced by another option, the replacement option is noted here. Options described this way may not be supported in future releases.</p> <p>If there are two options with the same general meaning and purpose, the preferred option is referenced here. For example, “Same as <code>-x0</code>” indicates that <code>-x0</code> is the preferred option.</p>

A.2 Option Reference

The following section alphabetically lists all the C++ compiler options and indicates any platform restrictions.

A.2.1 `-386`

x86: Same as `-xtarget=386`. *This option is obsolete and provided for backward compatibility only.*

A.2.2 `-486`

x86: Same as `-xtarget=486`. *This option is obsolete and provided for backward compatibility only.*

A.2.3 **-Bbinding**

Specifies whether a library binding for linking is `symbolic`, `dynamic` (shared), or `static` (nonshared).

You can use the `-B` option several times on a command line. This option is passed to the linker, `ld`.

Note – Many system libraries are only available as dynamic libraries in the Solaris 64-bit compilation environment. Therefore, do not use `-Bstatic` as the last toggle on the command line.

A.2.3.1 **Values**

binding must be one of the following:

Value	Meaning
<code>dynamic</code>	Directs the link editor to look for <code>liblib.so</code> (shared) files, and if they are not found, to look for <code>liblib.a</code> (static, nonshared) files. Use this option if you want shared library bindings for linking.
<code>static</code>	Directs the link editor to look only for <code>liblib.a</code> (static, nonshared) files. Use this option if you want nonshared library bindings for linking.
<code>symbolic</code>	Forces symbols to be resolved within a shared library if possible, even when a symbol is already defined elsewhere. See the <code>ld(1)</code> man page.

(No space is allowed between `-B` and the *binding* value.)

Defaults

If `-B` is not specified, `-Bdynamic` is assumed.

Interactions

To link the C++ default libraries statically, use the `-staticlib` option.

The `-Bstatic` and `-Bdynamic` options affect the linking of the libraries that are provided by default. To ensure that the default libraries are linked dynamically, the last use of `-B` should be `-Bdynamic`.

In a 64-bit environment, many system libraries are available only as shared dynamic libraries. These include `libm.so` and `libc.so` (`libm.a` and `libc.a` are not provided). As a result, `-Bstatic` and `-dn` may cause linking errors in 64-bit Solaris operating systems. Applications must link with the dynamic libraries in these cases.

Examples

The following compiler command links `libfoo.a` even if `libfoo.so` exists; all other libraries are linked dynamically:

```
example% CC a.o -Bstatic -lfoo -Bdynamic
```

Warnings

Never use `-Bsymbolic` with programs containing C++ code, use linker map files instead.

With `-Bsymbolic`, references in different modules can bind to different copies of what is supposed to be one global object.

The exception mechanism relies on comparing addresses. If you have two copies of something, their addresses won't compare equal, and the exception mechanism can fail because the exception mechanism relies on comparing what are supposed to be unique addresses.

If you compile and link in separate steps and are using the `-Bbinding` option, you must include the option in the link step.

See also

`-nolib`, `-staticlib`, `ld(1)`, [“11.5 Statically Linking Standard Libraries” on page 138](#), *Linker and Libraries Guide*

A.2.4 `-c`

Compile only; produce object `.o` files, but suppress linking.

This option directs the `CC` driver to suppress linking with `ld` and produce a `.o` file for each source file. If you specify only one source file on the command line, then you can explicitly name the object file with the `-o` option.

A.2.4.1 Examples

If you enter `CC -c x.cc`, the `x.o` object file is generated.

If you enter `CC -c x.cc -o y.o`, the `y.o` object file is generated.

Warnings

When the compiler produces object code for an input file (.c, .i), the compiler always produces a .o file in the working directory. If you suppress the linking step, the .o files are not removed.

See also

-o filename, -xe

A.2.5 -cg{89|92}

(SPARC) Obsolete, do not use this option. Current Solaris operating system software no longer support SPARC V7 architecture. Compiling with this option generates code that runs slower on current SPARC platforms. Use -x0 instead and take advantage of compiler defaults for -xarch, -xchip, and -xcache.

A.2.6 -compat[={4|5|g}]

Sets the major release compatibility mode of the compiler. This option controls the `__SUNPRO_CC_COMPAT` and `__cplusplus` macros.

The C++ compiler has three principal modes. The compatibility mode accepts ARM semantics and language defined by the 4.2 compiler. The standard mode accepts constructs according to the ANSI/ISO 1998 C++ standard as updated in 2003. These modes are incompatible with each other because the ANSI/ISO standard forces significant, incompatible changes in name mangling, vtable layout, and other ABI details. The `-compat=g` option adds compatibility with the `gcc/g++` compiler on Linux.

These modes are differentiated by the `-compat` option as shown in the following values.

A.2.6.1 Values

The `-compat` option can have the following values.

Value	Meaning
<code>-compat=4</code>	(Compatibility mode) Set language and binary compatibility to that of the 4.0.1, 4.1, and 4.2 compilers. Set the <code>__cplusplus</code> preprocessor macro to 1 and the <code>__SUNPRO_CC_COMPAT</code> preprocessor macro to 4.
<code>-compat=5</code>	(Standard mode) Set language and binary compatibility to ANSI/ISO standard mode. Set the <code>__cplusplus</code> preprocessor macro to 199711L and the <code>__SUNPRO_CC_COMPAT</code> preprocessor macro to 5.

Value	Meaning
<code>-compat=g</code>	(Linux only) enables recognition of g++ language extensions and causes the compiler to generate code that is binary compatible with g++ on the Linux platform. Sets the <code>__cplusplus</code> preprocessor macro to 199711L and the <code>__SUNPRO_CC_COMPAT</code> preprocessor macro to 'G'.

With `-compat=g`, binary compatibility extends only to shared (dynamic or `.so`) libraries, not to individual `.o` files or archive (`.a`) libraries.

For example, linking a g++ shared library to C++ main program:

```
% g++ -shared -o libfoo.so -fpic a.cc b.cc c.cc
% CC -compat=g main.cc -L. -lfoo
```

And, linking a C++ shared library to a g++ main program:

```
% CC -compat=g -G -o libfoo.so -Kpic a.cc b.cc c.cc
% g++ main.cc -L. -lfoo
```

Defaults

If the `-compat` option is not specified, `-compat=5` is assumed.

If only `-compat` is specified, `-compat=4` is assumed.

Interactions

You cannot use the standard libraries in compatibility mode (`-compat[=4]`).

Use of `-compat[=4]` with any of the following options is not supported.

- `-Bsymbolic`
- `-features=[no%]strictdestorder`
- `-features=[no%]tmplife`
- `-library=[no%]iostream`
- `-library=[no%]Cstd`
- `-library=[no%]Crun`
- `-library=[no%]rwtools7_std`
- `-xarch=native64`, `-xarch=generic64`, `-xarch=v9`, `-xarch=v9a`, or `-xarch=v9b`

Use of `-compat=5` with any of the following options is not supported.

- `-Bsymbolic`
- `+e`
- `features=[no%]arraynew`
- `features=[no%]explicit`
- `features=[no%]namespace`

- `features=[no%]rtti`
- `library=[no%]complex`
- `library=[no%]libc`
- `-vdelx`

Warnings

When building a shared library do not use `-Bsymbolic`.

See also

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A.2.7 +d

Does not expand C++ inline functions.

Under the C++ language rules, a C++ inline function is a function for which one of the following statements is true.

- The function is defined using the `inline` keyword,
- The function is defined (not just declared) inside a class definition
- The function is a compiler-generated class member function

Under the C++ language rules, the compiler can choose whether actually to inline a call to an inline function. The C++ compiler inlines calls to an inline function unless:

- The function is too complex,
- The `+d` option is selected, or
- The `-g` option is selected without a `-x0n` optimization level specified

A.2.7.1 Examples

By default, the compiler may inline the functions `f()` and `mf2()` in the following code example. In addition, the class has a default compiler-generated constructor and destructor that the compiler may inline. When you use `+d`, the compiler will not inline `f()` and `C::mf2()`, the constructor, and the destructor.

```
inline int f() {return 0;} // may be inlined
class C {
    int mf1(); // not inlined unless inline definition comes later
    int mf2() {return 0;} // may be inlined
};
```

Interactions

This option is automatically turned on when you specify `-g`, the debugging option.

The `-g0` debugging option does not turn on `+d`.

The `+d` option has no effect on the automatic inlining that is performed when you use `-xO4` or `-xO5`.

See also

`-g0`, `-g`

A.2.8 `-Dname[=def]`

Defines the macro symbol *name* to the preprocessor.

Using this option is equivalent to including a `#define` directive at the beginning of the source. You can use multiple `-D` options.

See the CC(1) man page for a list of compiler predefined macros.

A.2.9 `-d{y|n}`

Allows or disallows dynamic libraries for the entire executable.

This option is passed to `ld`.

This option can appear only once on the command line.

A.2.9.1 Values

Value	Meaning
<code>-dy</code>	Specifies dynamic linking in the link editor.
<code>-dn</code>	Specifies static linking in the link editor.

Defaults

If no `-d` option is specified, `-dy` is assumed.

Interactions

In a 64-bit environment, many system libraries are available only as shared dynamic libraries. These include `libm.so` and `libc.so` (`libm.a` and `libc.a` are not provided). As a result, `-Bstatic` and `-dn` may cause linking errors in 64-bit Solaris operating systems. Applications must link with the dynamic libraries in these cases.

Warnings

This option causes fatal errors if you use it in combination with dynamic libraries. Most system libraries are only available as dynamic libraries.

See also

`ld(1)`, *Linker and Libraries Guide*

A.2.10 `-dalign`

(SPARC)-`dalign` is equivalent to `-xmemalign=8s`. See “[A.2.151 -xmemalign=ab](#)” on page 306 for more information.

This option is silently ignored on x86 platforms.

A.2.10.1 Warnings

If you compile one program unit with `-dalign`, compile all units of a program with `-dalign`, or you might get unexpected results.

A.2.11 `-dryrun`

Shows the subcommands built by driver, but does not compile.

This option directs the CC driver to show, but not execute, the subcommands constructed by the compilation driver.

A.2.12 `-E`

Runs the preprocessor on source files; does not compile.

Directs the CC driver to run only the preprocessor on C++ source files, and to send the result to `stdout` (standard output). No compilation is done; no `.o` files are generated.

This option causes preprocessor-type line number information to be included in the output.

To compile the output of the `-E` option when the source code involves templates, you might need to use the `-template=no%extdef` option with the `-E` option. If application code uses the “definitions separate” template source code model, the output of the `-E` option might still not compile. Refer to the chapters on templates for more information.

A.2.12.1 Examples

This option is useful for determining the changes made by the preprocessor. For example, the following program, `foo.cc`, generates the output shown in “[A.2.12.1 Examples](#)” on page 211

EXAMPLE A-1 Preprocessor Example Program `foo.cc`

```
#if __cplusplus < 199711L
int power(int, int);
#else
template <> int power(int, int);
#endif

int main () {
    int x;
    x=power(2, 10);
}
.
```

EXAMPLE A-2 Preprocessor Output of `foo.cc` Using `-E` Option

```
example% CC -E foo.cc
#4 "foo.cc"
template < > int power (int, int);

int main () {
int x;
x = power (2, 10);
}
```

Warnings

Output of this option might not be usable as input to a C++ compilation if the code contains templates under the "definitions-separate" model.

See also

`-P`

A.2.13 `+e{0|1}`

Controls virtual table generation in compatibility mode (`-compat[=4]`). Invalid and ignored when in standard mode (the default mode).

A.2.13.1 Values

The `+e` option can have the following values.

Value	Meaning
0	Suppresses the generation of virtual tables and creates external references to those that are needed.
1	Creates virtual tables for all defined classes with virtual functions.

Interactions

When you compile with this option, also use the `-features=noexcept` option. Otherwise, the compiler generates virtual tables for internal types used in exception handling.

If template classes have virtual functions, ensuring that the compiler generates all needed virtual tables, but does not duplicate these tables, might not be possible.

See also

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A.2.14 `-erroff[=t]`

This command suppresses C++ compiler warning messages and has no effect on error messages. This option applies to all warning messages whether or not they have been designated by `-errwarn` to cause a non-zero exit status.

A.2.14.1 Values

t is a comma-separated list that consists of one or more of the following: *tag*, `no%tag`, `%all`, `%none`. Order is important; for example, `%all, no%tag` suppresses all warning messages except *tag*. The following table lists the `-erroff` values:

TABLE A-2 The `-erroff` Values

Value	Meaning
<i>tag</i>	Suppresses the warning message specified by this <i>tag</i> . You can display the tag for a message by using the <code>-errtags=yes</code> option.
<code>no%tag</code>	Enables the warning message specified by this <i>tag</i> .
<code>%all</code>	Suppresses all warning messages.
<code>%none</code>	Enables all warning messages (default).

Defaults

The default is `-erroff=%none`. Specifying `-erroff` is equivalent to specifying `-erroff=%all`.

Examples

For example, `-erroff=tag` suppresses the warning message specified by this *tag*. On the other hand, `-erroff=%all,no%tag` suppresses all warning messages except the messages identified by *tag*.

You can display the tag for a warning message by using the `-errtags=yes` option.

Warnings

Only warning messages from the C++ compiler front-end that display a tag when the `-errtags` option is used can be suppressed with the `-erroff` option.

See Also

`-errtags`, `-errwarn`

A.2.15 `-errtags[=a]`

Displays the message tag for each warning message of the C++ compiler front-end that can be suppressed with the `-erroff` option or made a fatal warning with the `-errwarn` option.

A.2.15.1 Values and Defaults

a can be either yes or no. The default is `-errtags=no`. Specifying `-errtags` is equivalent to specifying `-errtags=yes`.

Warnings

Messages from the C++ compiler driver and other components of the compilation system do not have error tags, and cannot be suppressed with `-erroff` or made fatal with `-errwarn`.

See Also

`-erroff`, `-errwarn`

A.2.16 `-errwarn[=t]`

Use `-errwarn` to cause the C++ compiler to exit with a failure status for the given warning messages.

A.2.16.1 Values

t is a comma-separated list that consists of one or more of the following: *tag*, `no%tag`, `%all`, `%none`. Order is important; for example `%all, no%tag` causes `cc` to exit with a fatal status if any warning except *tag* is issued.

The following table details the `-errwarn` values:

TABLE A-3 The `-errwarn` Values

Value	Meaning
<i>tag</i>	Cause CC to exit with a fatal status if the message specified by <i>tag</i> is issued as a warning message. Has no effect if <i>tag</i> is not issued.
<code>no%tag</code>	Prevent CC from exiting with a fatal status if the message specified by <i>tag</i> is issued only as a warning message. Has no effect if the message specified by <i>tag</i> is not issued. Use this option to revert a warning message that was previously specified by this option with <i>tag</i> or <code>%all</code> from causing cc to exit with a fatal status when issued as a warning message.
<code>%all</code>	Cause CC to exit with a fatal status if any warning messages are issued. <code>%all</code> can be followed by <code>no%tag</code> to exempt specific warning messages from this behavior.
<code>%none</code>	Prevents any warning message from causing CC to exit with a fatal status should any warning message be issued.

Defaults

The default is `-errwarn=%none`. If you specify `-errwarn` alone, it is equivalent to `-errwarn=%all`.

Warnings

Only warning messages from the C++ compiler front-end that display a tag when the `-errtags` option is used can be specified with the `-errwarn` option to cause the compiler to exit with a failure status.

The warning messages generated by the C++ compiler change from release to release as the compiler error checking improves and features are added. Code that compiles using `-errwarn=%all` without error may not compile without error in the next release of the compiler.

See Also

`-erroff`, `-errtags`, `-xwe`

A.2.17 `-fast`

This option is a macro that can be effectively used as a starting point for tuning an executable for maximum runtime performance. `-fast` is a macro that can change from one release of the compiler to the next and expands to options that are target platform specific. Use the `-dryrun` or `-xdryrun` option to examine the expansion of `-fast`, and incorporate the appropriate options of `-fast` into the ongoing process of tuning the executable.

This option is a macro that selects a combination of compilation options for optimum execution speed on the machine upon which the code is compiled.

A.2.17.1 Expansions

This option provides near maximum performance for many applications by expanding to the following compilation options.

TABLE A-4 The `-fast` Expansion

Option	SPARC	x86
<code>-fns</code>	X	X
<code>-fsimple=2</code>	X	X
<code>-nofstore</code>	-	X
<code>-xarch</code>	X	X
<code>-xbuiltin=%all</code>	X	X
<code>-xcache</code>	X	X
<code>-xchip</code>	X	X
<code>-xlibmil</code>	X	X
<code>-xlibmopt</code>	X	X
<code>-xmemalign</code>	X	-
<code>-x05</code>	X	X
<code>-xregs=frameptr</code>	-	X
<code>-xtarget=native</code>	X	X

Interactions

The `-fast` macro expands into compilation options that may affect other specified options. For example, in the following command, the expansion of the `-fast` macro includes `-xtarget=native` which reverts `-xarch` to one of the 32-bit architecture options.

Incorrect:

```
example% CC -xarch=v9 -fast test.cc
```

Correct:

```
example% CC -fast -xarch=v9 test.cc
```

See the description for each option to determine possible interactions.

The code generation option, the optimization level, the optimization of built-in functions, and the use of inline template files can be overridden by subsequent options (see examples). The optimization level that you specify overrides a previously set optimization level.

The `-fast` option includes `-fns-ftrap=%none`; that is, this option turns off all trapping.

On x86 the `-fast` option includes `-xregs=frameptr`. See the discussion of this option for details, especially when compiling mixed C, Fortran, and C++ source codes.

Examples

The following compiler command results in an optimization level of `-x03`.

```
example% CC -fast -x03
```

The following compiler command results in an optimization level of `-x05`.

```
example% CC -x03 -fast
```

Warnings

If you compile and link in separate steps, the `-fast` option must appear in both the compile command and the link command.

Object binaries compiled with the `-fast` option are not portable. For example, using the following command on an UltraSPARC III system generates a binary that will not execute on an UltraSPARC II system.

```
example% CC -fast test.cc
```

Do not use this option for programs that depend on IEEE standard floating-point arithmetic; different numerical results, premature program termination, or unexpected SIGFPE signals can occur.

In previous SPARC releases, the `-fast` macro expanded to `-fsimple=1`. Now it expands to `-fsimple=2`.

The expansion of `-fast` includes `-D_MATHERR_ERRNO_DONTCARE`.

With `-fast`, the compiler is free to replace calls to floating point functions with equivalent optimized code that does not set the `errno` variable. Further, `-fast` also defines the macro `__MATHERR_ERRNO_DONTCARE`, which allows the compiler to ignore ensuring the validity of `errno`. As a result, user code that relies on the value of `errno` after a floating point function call could produce inconsistent results.

One way around this problem is to avoid compiling such codes with `-fast`. However, if `-fast` optimization is required and the code depends on the value of `errno` being set properly after floating-point library calls, you should compile with the options

```
-xbuiltin=none -U__MATHERR_ERRNO_DONTCARE -xnolibmopt -xnolibmil
```

following `-fast` on the command line to inhibit the compiler from optimizing out such library calls and to insure that `errno` is handled properly.

To display the expansion of `-fast` on any platform, run the command `CC -dryrun -fast`

```
>CC -dryrun -fast
###      command line files and options (expanded):
### -dryrun -x05 -xarch=sparcvvis2 -xcache=64/32/4:1024/64/4 \
-xchip=ultra3i -xmemalign=8s -fsimple=2 -fns=yes -ftrap=%none \
-xlibmil -xlibmopt -xbuiltin=%all -D__MATHERR_ERRNO_DONTCARE
```

See also

`-fns`, `-fsimple`, `-ftrap=%none`, `-xlibmil`, `-nofstore`, `-x05`, `-xlibmopt`, `-xtarget=native`

A.2.18 `-features=a[, a...]`

Enables/disables various C++ language features named in a comma-separated list.

A.2.18.1 Values

In both compatibility mode (`-compat [=4]`) and standard mode (the default mode), *a* can have the following values.

TABLE A-5 The `-features` Values for Compatibility Mode and Standard Mode

Value	Meaning
<code>%all</code>	All the <code>-features</code> options that are valid for the specified mode (compatibility mode or standard mode).
<code>[no%]altspell</code>	[Do not] Recognize alternative token spellings (for example, “and” for “&&”). The default is <code>no%altspell</code> in compatibility mode and <code>altspell</code> in standard mode.
<code>[no%]anachronisms</code>	[Do not] Allow anachronistic constructs. When disabled (that is, <code>-features=no%anachronisms</code>), no anachronistic constructs are allowed. The default is <code>anachronisms</code> .
<code>[no%]bool</code>	[Do not] Allow the <code>bool</code> type and literals. When enabled, the macro <code>_BOOL=1</code> . When not enabled, the macro is not defined. The default is <code>no%bool</code> in compatibility mode and <code>bool</code> in standard mode.
<code>[no%]conststrings</code>	[Do not] Put literal strings in read-only memory. The default is <code>no%conststrings</code> in compatibility mode and <code>conststrings</code> in standard mode.
<code>[no%]except</code>	[Do not] Allow C++ exceptions. When C++ exceptions are disabled (that is, <code>-features=no%except</code>), a throw-specification on a function is accepted but ignored; the compiler does not generate exception code. Note that the keywords <code>try</code> , <code>throw</code> , and <code>catch</code> are always reserved. See “8.3 Disabling Exceptions” on page 100. The default is <code>except</code> .

TABLE A-5 The `-features` Values for Compatibility Mode and Standard Mode (Continued)

Value	Meaning
<code>[no%]export</code>	[Do not] Recognize the keyword <code>export</code> . The default is <code>no%export</code> in compatibility mode and <code>export</code> in standard mode. This feature is not yet implemented, but the <code>export</code> keyword is recognized.
<code>[no%]extensions</code>	[Do not] allow nonstandard code that is commonly accepted by other C++ compilers. The default is <code>no%extensions</code> .
<code>[no%]iddollar</code>	[Do not] Allow a <code>\$</code> symbol as a noninitial identifier character. The default is <code>no%iddollar</code> .
<code>[no%]localfor</code>	[Do not] Use new standard-conforming local-scope rules for the <code>for</code> statement. The default is <code>no%localfor</code> in compatibility mode and <code>localfor</code> in standard mode.
<code>[no%]mutable</code>	[Do not] Recognize the keyword <code>mutable</code> . The default is <code>no%mutable</code> in compatibility mode and <code>mutable</code> in standard mode.
<code>[no%]nestedaccess</code>	(Standard mode only) [Do not] Allow nested classes to access private members of the enclosing class. Default: <code>-features=nestedaccess</code>
<code>[no%]rvalueref</code>	[Do not] Allow binding a non-const reference to an rvalue or temporary. Default: <code>-features=no%rvalueref</code> The C++ compiler, by default, enforces the rule that a non-const reference cannot be bound to a temporary or rvalue. To override this rule, use the option <code>-features=rvalueref</code> .
<code>[no%]split_init</code>	[Do not] Put initializers for nonlocal static objects into individual functions. When you use <code>-features=no%split_init</code> , the compiler puts all the initializers in one function. Using <code>-features=no%split_init</code> minimizes code size at the possible expense of compile time. The default is <code>split_init</code> .
<code>[no%]transitions</code>	[Do not] allow ARM language constructs that are problematic in standard C++ and that may cause the program to behave differently than expected or that may be rejected by future compilers. When you use <code>-features=no%transitions</code> , the compiler treats these as errors. When you use <code>-features=transitions</code> in standard mode, the compiler issues warnings about these constructs instead of error messages. When you use <code>-features=transitions</code> in compatibility mode (<code>-compat[=4]</code>), the compiler displays the warnings about these constructs only if <code>+w</code> or <code>+w2</code> is specified. The following constructs are considered to be transition errors: redefining a template after it was used, omitting the <code>typename</code> directive when it is needed in a template definition, and implicitly declaring type <code>int</code> . The set of transition errors may change in a future release. The default is <code>transitions</code> .
<code>%none</code>	Turn off all the features that can be turned off for the specified mode.

In standard mode (the default mode), *a* can have the following additional values.

TABLE A-6 The `-features` Values for Standard Mode Only

Value	Meaning
<code>[no%]strictdestorder</code>	[Do not] Follow the requirements specified by the C++ standard regarding the order of the destruction of objects with static storage duration. The default is <code>strictdestorder</code> .
<code>[no%]tmplrefstatic</code>	[Do not] allow function templates to refer to dependent static functions or static function templates. The default is the standard conformant <code>no%tmplrefstatic</code> .
<code>[no%]tmplife</code>	[Do not] Clean up the temporary objects that are created by an expression at the end of the full expression, as defined in the ANSI/ISO C++ Standard. (When <code>-features=no%tmplife</code> is in effect, most temporary objects are cleaned up at the end of their block.) The default is <code>no%tmplife</code> in <code>compat=4</code> mode and <code>tmplife</code> in standard mode.

In compatibility mode (`-compat [=4]`), *a* can have the following additional values.

TABLE A-7 The `-features` Values for Compatibility Mode Only

Value	Meaning
<code>[no%]arraynew</code>	[Do not] Recognize array forms of operator <code>new</code> and operator <code>delete</code> (for example, operator <code>new [] (void*)</code>). When enabled, the macro <code>__ARRAYNEW=1</code> . When not enabled, the macro is not defined. The default is <code>no%arraynew</code> .
<code>[no%]explicit</code>	[Do not] Recognize the keyword <code>explicit</code> . The default is <code>no%explicit</code> .
<code>[no%]namespace</code>	[Do not] Recognize the keywords <code>namespace</code> and <code>using</code> . The default is <code>no%namespace</code> . The purpose of <code>-features=namespace</code> is to aid in converting code to standard mode. By enabling this option, you get error messages if you use these keywords as identifiers. The keyword recognition options allow you to find uses of the added keywords without having to compile in standard mode.
<code>[no%]rtti</code>	[Do not] Allow runtime type information (RTTI). RTTI must be enabled to use the <code>dynamic_cast<></code> and <code>typeid</code> operators. For <code>-compat=4</code> mode, the default is <code>no%rtti</code> . Otherwise, the default is <code>-features=rtti</code> , and the option <code>-features=no%rtti</code> is not allowed.

Note – The `[no%]castop` setting is allowed for compatibility with makefiles written for the C++ 4.2 compiler, but has no effect on later compiler versions. The new style casts (`const_cast`, `dynamic_cast`, `reinterpret_cast`, and `static_cast`) are always recognized and cannot be disabled.

Defaults

If `-features` is not specified, the default in compatibility mode (`-compat[=4]`) is:

```
-features=%none,anachronisms,except,split_init,transitions
```

In the default “standard mode”,

```
-features=%all,no%altspell,no%bool,no%conststrings,no%extensions,no%iddollar,\
no%rvaluref,no%tmplrefstatic
```

is assumed.

Interactions

This option accumulates instead of overrides.

Use of the following in standard mode (the default) is not compatible with the standard libraries and headers:

- `no%bool`
- `no%except`
- `no%mutable`
- `no%explicit`

In compatibility mode (`-compat[=4]`), the `-features=transitions` option has no effect unless you specify the `+w` option or the `+w2` option.

Warnings

Be careful when you specify `-features=%all` or `-features=%none`. The set of features can change with each compiler release and with each patch. Consequently, you can get unintended behavior.

The behavior of a program might change when you use the `-features=tmplife` option. Testing whether the program works both with and without the `-features=tmplife` option is one way to test the program’s portability.

The compiler assumes `-features=split_init` by default in compat mode (`-compt=4`). If you use the `-features=%none` option to turn off other features, you may find it desirable to turn the splitting of initializers into separate functions back on by using `-features=%none,split_init` instead.

See also

[Table 3–17](#) and the *C++ Migration Guide*

A.2.19 -filt[=*filter*[,*filter*...]]

Controls the filtering that the compiler normally applies to linker and compiler error messages.

A.2.19.1 Values

filter must be one of the following values.

TABLE A–8 The -filt Values

Value	Meaning
[no%]errors	[Do not] Show the C++ explanations of the linker error messages. The suppression of the explanations is useful when the linker diagnostics are provided directly to another tool.
[no%]names	[Do not] Demangle the C++ mangled linker names.
[no%]returns	[Do not] Demangle the return types of functions. Suppression of this type of demangling helps you to identify function names more quickly, but note that in the case of co-variant returns some functions differ only in the return type.
[no%]stdlib	[Do not] Simplify names from the standard library in both the linker and compiler error messages. This makes it easier for you to recognize the names of standard library template types.
%all	Equivalent to -filt=errors,names,returns,stdlib. This is the default behavior.
%none	Equivalent to -filt=no%errors,no%names,no%returns,no%stdlib.

Defaults

If you do not specify the -filt option, or if you specify -filt without any values, then the compiler assumes -filt=%all.

Examples

The following examples show the effects of compiling this code with the -filt option.

```
// filt_demo.cc
class type {
public:
    virtual ~type(); // no definition provided
};
```

```
int main()
{
    type t;
}
```

When you compile the code without the `-filt` option, the compiler assumes `-filt=errors, names, returns, stdlib` and displays the standard output.

```
example% CC filt_demo.cc
Undefined          first referenced
 symbol           in file
type::~~type()    filt_demo.o
type::__vtbl      filt_demo.o
[Hint: try checking whether the first non-inlined, /
non-pure virtual function of class type is defined]
```

```
ld: fatal: Symbol referencing errors. No output written to a.out
```

The following command suppresses the demangling of the of the C++ mangled linker names and suppresses the C++ explanations of linker errors.

```
example% CC -filt=no%names,no%errors filt_demo.cc
Undefined          first referenced
 symbol           in file
__1cEtype2T6M_v_  filt_demo.o
__1cEtypeG_vtbl_  filt_demo.o
ld: fatal: Symbol referencing errors. No output written to a.out
```

Now consider this code:

```
#include <string>
#include <list>
int main()
{
    std::list<int> l;
    std::string s(l); // error here
}
```

Here's the output when you specify `-filt=no%stdlib`:

```
Error: Cannot use std::list<int, std::allocator<int>> to initialize
std::basic_string<char, std::char_traits<char>,
std::allocator<char>>.
```

Here's the output when you specify `-filt=stdlib`:

```
Error: Cannot use std::list<int> to initialize std::string .
```

Interactions

When you specify `no%names`, neither `returns` nor `no%returns` has an effect. That is, the following options are equivalent:

- `-filt=no%names`

- `-filt=no%names,no%returns`
- `-filt=no%names,returns`

A.2.20 `-flags`

Same as `-xhelp=flags`.

A.2.21 `-fma[={none|fused}]`

(SPARC) Enables automatic generation of floating-point, fused, multiply-add instructions. `-fma=none` disables generation of these instructions. `-fma=fused` allows the compiler to attempt to find opportunities to improve the performance of the code by using floating-point, fused, multiply-add instructions.

The default is `-fma=none`.

The minimum requirements are `-xarch=sparcmaf` and an optimization level of at least `-xO2` for the compiler to generate fused multiply-add instructions. The compiler marks the binary program if fused multiply-add instructions are generated in order to prevent the program from executing on platforms that do not support them.

Fused multiply-adds eliminate the intermediate rounding step between the multiply and the add. Consequently, programs may produce different results when compiled with `-fma=fused`, although precision will tend to be increased rather than decreased.

A.2.22 `-fnonstd`

Causes hardware traps to be enabled for floating-point overflow, division by zero, and invalid operations exceptions. These results are converted into SIGFPE signals; if the program has no SIGFPE handler, it terminates with a memory dump (unless you limit the core dump size to 0).

SPARC: In addition, `-fnonstd` selects SPARC nonstandard floating point.

A.2.22.1 Defaults

If `-fnonstd` is not specified, IEEE 754 floating-point arithmetic exceptions do not abort the program, and underflows are gradual.

Expansions

x86: `-fnonstd` expands to `-fttrap=common`.

SPARC: `-fnonstd` expands to `-fns -fttrap=common`.

See also

`-fns`, `-ft rap=common`, *Numerical Computation Guide*.

A.2.23 `-fns[={yes|no}]`

- SPARC: Enables/disables the SPARC nonstandard floating-point mode.
 - `fns=yes` (or `-fns`) causes the nonstandard floating point mode to be enabled when a program begins execution.
 - This option provides a way of toggling the use of nonstandard or standard floating-point mode following some other macro option that includes `-fns`, such as `-fast`.
 - On some SPARC devices, the nonstandard floating-point mode disables “gradual underflow,” causing tiny results to be flushed to zero rather than to produce subnormal numbers. It also causes subnormal operands to be silently replaced by zero.
 - On those SPARC devices that do not support gradual underflow and subnormal numbers in hardware, `-fns=yes` (or `-fns`) can significantly improve the performance of some programs.
- (x86) Selects SSE flush-to-zero mode and, where available, denormals-are-zero mode.
 - This option causes subnormal results to be flushed to zero. Where available, this option also causes subnormal operands to be treated as zero.
 - This option has no effect on traditional x86 floating-point operations that do not utilize the SSE or SSE2 instruction set.

A.2.23.1 Values

The `-fns` option can have the following values.

TABLE A-9 The `-fns` Values

Value	Meaning
yes	Selects nonstandard floating-point mode
no	Selects standard floating-point mode

Defaults

If `-fns` is not specified, the nonstandard floating point mode is not enabled automatically. Standard IEEE 754 floating-point computation takes place, that is, underflows are gradual.

If only `-fns` is specified, `-fns=yes` is assumed.

Examples

In the following example, `-fast` expands to several options, one of which is `-fns=yes` which selects nonstandard floating-point mode. The subsequent `-fns=no` option overrides the initial setting and selects floating-point mode.

```
example% CC foo.cc -fast -fns=no
```

Warnings

When nonstandard mode is enabled, floating-point arithmetic can produce results that do not conform to the requirements of the IEEE 754 standard.

If you compile one routine with the `-fns` option, then compile all routines of the program with the `-fns` option; otherwise, you might get unexpected results.

This option is effective only on SPARC devices, and only if used when compiling the main program. On x86 devices, the option is ignored.

Use of the `-fns=yes` (or `-fns`) option might generate the following message if your program experiences a floating-point error normally managed by the IEEE floating-point trap handlers:

See also

Numerical Computation Guide, `ieee_sun(3M)`

A.2.24 `-fprecision=p`

x86: Sets the non-default floating-point precision mode.

The `-fprecision` option sets the rounding precision mode bits in the Floating Point Control Word. These bits control the precision to which the results of basic arithmetic operations (add, subtract, multiply, divide, and square root) are rounded.

A.2.24.1 Values

p must be one of the following values.

TABLE A-10 The `-fprecision` Values

Value	Meaning
single	Rounds to an IEEE single-precision value.
double	Rounds to an IEEE double-precision value.
extended	Rounds to the maximum precision available.

If `p` is `single` or `double`, this option causes the rounding precision mode to be set to `single` or `double` precision, respectively, when a program begins execution. If `p` is `extended` or the `-fprecision` option is not used, the rounding precision mode remains at the extended precision.

The `single` precision rounding mode causes results to be rounded to 24 significant bits, and `double` precision rounding mode causes results to be rounded to 53 significant bits. In the default `extended` precision mode, results are rounded to 64 significant bits. This mode controls only the precision to which results in registers are rounded, and it does not affect the range. All results in register are rounded using the full range of the extended double format. Results that are stored in memory are rounded to both the range and precision of the destination format, however.

The nominal precision of the `float` type is `single`. The nominal precision of the `long double` type is `extended`.

Defaults

When the `-fprecision` option is not specified, the rounding precision mode defaults to `extended`.

Warnings

This option is effective only on x86 systems and only if used when compiling the main program, but is ignored if compiling for 64-bit (`-m64`) or SSE2-enabled (`-xarch=sse2`) processors. It is also ignored on SPARC systems.

A.2.25 `-fround=r`

Sets the IEEE rounding mode in effect at startup.

This option sets the IEEE 754 rounding mode that:

- Can be used by the compiler in evaluating constant expressions
- Is established at runtime during the program initialization

The meanings are the same as those for the `ieee_flags` subroutine, which can be used to change the mode at runtime.

A.2.25.1 Values

`r` must be one of the following values.

TABLE A-11 The -fround Values

Value	Meaning
nearest	Rounds towards the nearest number and breaks ties to even numbers.
tozero	Rounds to zero.
negative	Rounds to negative infinity.
positive	Rounds to positive infinity.

Defaults

When the `-fround` option is not specified, the rounding mode defaults to `-fround=nearest`.

Warnings

If you compile one routine with `-fround=r`, compile all routines of the program with the same `-fround=r` option; otherwise, you might get unexpected results.

This option is effective only if used when compiling the main program.

A.2.26 `-fsimple[=n]`

Selects floating-point optimization preferences.

This option allows the optimizer to make simplifying assumptions concerning floating-point arithmetic.

A.2.26.1 Values

If `n` is present, it must be 0, 1, or 2.

TABLE A-12 The -fsimple Values

Value	Meaning
0	Permit no simplifying assumptions. Preserve strict IEEE 754 conformance.

TABLE A-12 The `-fsimple` Values (Continued)

Value	Meaning
1	<p>Allow conservative simplification. The resulting code does not strictly conform to IEEE 754, but numeric results of most programs are unchanged.</p> <p>With <code>-fsimple=1</code>, the optimizer can assume the following:</p> <ul style="list-style-type: none"> ■ IEEE754 default rounding/trapping modes do not change after process initialization. ■ Computation producing no visible result other than potential floating-point exceptions can be deleted. ■ Computation with infinities or NaNs as operands needs to propagate NaNs to their results; that is, <code>x*0</code> can be replaced by 0. ■ Computations do not depend on sign of zero. <p>With <code>-fsimple=1</code>, the optimizer is not allowed to optimize completely without regard to roundoff or exceptions. In particular, a floating-point computation cannot be replaced by one that produces different results when rounding modes are held constant at runtime.</p>
2	<p>Includes all the functionality of <code>-fsimple=1</code> and also permits aggressive floating-point optimization that can cause many programs to produce different numeric results due to changes in rounding. For example, permit the optimizer to replace all computations of <code>x/y</code> in a given loop with <code>x*z</code>, where <code>x/y</code> is guaranteed to be evaluated at least once in the loop <code>z=1/y</code>, and the values of <code>y</code> and <code>z</code> are known to have constant values during execution of the loop.</p>

Defaults

If `-fsimple` is not designated, the compiler uses `-fsimple=0`.

If `-fsimple` is designated but no value is given for `n`, the compiler uses `-fsimple=1`.

Interactions

`-fast` implies `-fsimple=2`.

Warnings

This option can break IEEE 754 conformance.

See also

`-fast`

Techniques for Optimizing Applications: High Performance Computing written by Rajat Garg and Ilya Sharapov for a more detailed explanation of how optimization can impact precision.

A.2.27 **-fstore**

x86:

Forces precision of floating-point expressions.

This option causes the compiler to convert the value of a floating-point expression or function to the type on the left side of an assignment rather than leave the value in a register when the following is true:

- The expression or function is assigned to a variable.
- The expression is cast to a shorter floating-point type.

To turn off this option, use the `-nofstore` option.

A.2.27.1 **Warnings**

Due to roundoffs and truncation, the results can be different from those that are generated from the register values.

See also

`-nofstore`

A.2.28 **-fttrap=t[, t...]**

Sets the IEEE trapping mode in effect at startup but does not install a SIGFPE handler. You can use `ieee_handler(3M)` or `fex_set_handling(3M)` to simultaneously enable traps and install a SIGFPE handler. If you specify more than one value, the list is processed sequentially from left to right.

A.2.28.1 **Values**

t can be one of the following values.

TABLE A-13 The -fttrap Values

Value	Meaning
[no%]division	[Do not] Trap on division by zero.
[no%]inexact	[Do not] Trap on inexact result.
[no%]invalid	[Do not] Trap on invalid operation.
[no%]overflow	[Do not] Trap on overflow.
[no%]underflow	[Do not] Trap on underflow.

TABLE A-13 The `-fttrap` Values (Continued)

Value	Meaning
<code>%all</code>	Trap on all of the above.
<code>%none</code>	Trap on none of the above.
<code>common</code>	Trap on invalid, division by zero, and overflow.

Note that the `[no%]` form of the option is used only to modify the meaning of the `%all` and `common` values, and must be used with one of these values, as shown in the example. The `[no%]` form of the option by itself does not explicitly cause a particular trap to be disabled.

Defaults

If you do not specify `-fttrap`, the compiler assumes `-fttrap=%none`.

Examples

`-fttrap=%all, no%inexact` means to set all traps except `inexact`.

Warnings

If you compile one routine with `-fttrap=t`, compile all routines of the program with the same `-fttrap=t` option; otherwise, you might get unexpected results.

Use the `-fttrap=inexact` trap with caution. Use of `-fttrap=inexact` results in the trap being issued whenever a floating-point value cannot be represented exactly. For example, the following statement generates this condition:

```
x = 1.0 / 3.0;
```

This option is effective only if used when compiling the main program. Be cautious when using this option. If you wish to enable the IEEE traps, use `-fttrap=common`.

See also

`ieee_handler(3M)`, `fex_set_handling(3M)` man pages.

A.2.29

—G

Build a dynamic shared library instead of an executable file.

All source files specified in the command line are compiled with `-xcode=pic13` by default.

When building a shared library from files that involve templates and were compiled with the `-instances=extern` option, any template instances referenced by the `.o` files will be included from the template cache automatically.

If you are creating a shared object by specifying `-G` along with other compiler options that must be specified at both compile time and link time, make sure that those same options are also specified at both compile time and link time when you link with the resulting shared object.

When you create a shared object, all the object files compiled with `-xarch=v9`, must also be compiled with an explicit `-xcode=a` as recommended in [“A.2.118 `-xcode=a`” on page 281](#).

A.2.29.1 Interactions

The following options are passed to the linker if `-c` (the compile-only option) is not specified:

- `-dy`
- `-G`
- `-R`

Warnings

Do not use `ld -G` to build shared libraries; use `CC -G`. The `CC` driver automatically passes several options to `ld` that are needed for C++.

When you use the `-G` option, the compiler does not pass any default `-l` options to `ld`. If you want the shared library to have a dependency on another shared library, you must pass the necessary `-l` option on the command line. For example, if you want the shared library to be dependent upon `libcrun`, you must pass `-lcrun` on the command line.

See also

`-dy`, `-Kpic`, `-xcode=pic13`, `-ztext`, `ld(1)` man page, [“15.3 Building Dynamic \(Shared\) Libraries” on page 197](#).

A.2.30 `-g`

Produces additional symbol table information for debugging with `dbx(1)` or the Debugger and for analysis with the Performance Analyzer `analyzer(1)`.

Instructs both the compiler and the linker to prepare the file or program for debugging and for performance analysis.

The tasks include:

- Producing detailed information, known as *stabs*, in the symbol table of the object files and the executable
- Producing some “helper functions,” which the debugger can call to implement some of its features
- Disabling the inline generation of functions, if no optimization level is specified; that is, using this option implies the `+d` option if no optimization level is also specified. `-g` with any `-O` or `-xO` level does not disable inlining.

- Disabling certain levels of optimization

A.2.30.1 Interactions

If you use this option with `-x0level` (or its equivalent options, such as `-O`), you will get limited debugging information. For more information, see “A.2.157 `-x0level`” on page 310.

If you use this option and the optimization level is `-xO4` or higher, the compiler provides best-effort symbolic information with full optimization. If you use `-g` without an optimization level specified, inlining of function calls will be disabled. (Inlining is enabled when an optimization level is specified with `-g`.)

When you specify this option, the `+d` option is specified automatically unless you also specify `-O` or `-xO`.

Note – In previous releases, this option forced the compiler to use the incremental linker (`i ld`) by default instead of the linker (`ld`) for link-only invocations of the compiler. That is, with `-g`, the compiler’s default behavior was to automatically invoke `i ld` in place of `ld` whenever you used the compiler to link object files, unless you specified `-G` or source files on the command line. This is no longer the case. The incremental linker is no longer available.

To use the full capabilities of the Performance Analyzer, compile with the `-g` option. While some performance analysis features do not require `-g`, you must compile with `-g` to view annotated source, some function level information, and compiler commentary messages. See the `analyzer(1)` man page and “Compiling Your Program for Data Collection and Analysis” in *Program Performance Analysis Tools* for more information.

The commentary messages that are generated with `-g` describe the optimizations and transformations that the compiler made while compiling your program. Use the `er_src(1)` command to display the messages, which are interleaved with the source code.

Warnings

If you compile and link your program in separate steps, then including the `-g` option in one step and excluding it from the other step will not affect the correctness of the program, but it will affect the ability to debug the program. Any module that is not compiled with `-g` (or `-g0`), but is linked with `-g` (or `-g0`) will not be prepared properly for debugging. Note that compiling the module that contains the function `main` with the `-g` option (or the `-g0` option) is usually necessary for debugging.

See also

`+d`, `-g0`, `-xs`, `analyzer(1)` man page, `er_src(1)` man page, `ld(1)` man page, *Debugging a Program With dbx* (for details about stabs), *Program Performance Analysis Tools*.

A.2.31 **-g0**

Compiles and links for debugging, but does not disable inlining.

This option is the same as `-g`, except that `+d` is disabled and `dbx` cannot step into inlined functions.

If you specify `-g0` and the optimization level is `-xO3` or lower, the compiler provides best-effort symbolic information with almost full optimization. Tail-call optimization and back-end inlining are disabled.

A.2.31.1 **See also**

`+d`, `-g`, *Debugging a Program With `dbx`*

A.2.32 **-H**

Prints path names of included files.

On the standard error output (`stderr`), this option prints, one per line, the path name of each `#include` file contained in the current compilation.

A.2.33 **-h[]name**

Assigns the name *name* to the generated dynamic shared library.

This is a linker option, passed to `ld`. In general, the name after `-h` should be exactly the same as the one after `-o`. A space between the `-h` and *name* is optional.

The compile-time loader assigns the specified name to the shared dynamic library you are creating. It records the name in the library file as the intrinsic name of the library. If there is no `-hname` option, then no intrinsic name is recorded in the library file.

Every executable file has a list of shared library files that are needed. When the runtime linker links the library into an executable file, the linker copies the intrinsic name from the library into that list of needed shared library files. If there is no intrinsic name of a shared library, then the linker copies the path of the shared library file instead.

When a shared library is built without the `-h` option, the runtime loader looks only for the file name of the library. You can replace the library with a different library with the same file name. If the shared library has an intrinsic name, the loader checks the intrinsic name when loading the file. If the intrinsic name does not match, the loader will not use the replacement file.

A.2.33.1 **Examples**

```
example% CC -G -o libx.so.1 -h libx.so.1 a.o b.o c.o
```

A.2.34 `-help`

Same as `-xhelp=flags`.

A.2.35 `-Ipathname`

Add *pathname* to the `#include` file search path.

This option adds *pathname* to the list of directories that are searched for `#include` files with relative file names (those that do not begin with a slash).

The compiler searches for quote-included files (of the form `#include "foo.h"`) in this order.

1. In the directory containing the source
2. In the directories named with `-I` options, if any
3. In the `include` directories for compiler-provided C++ header files, ANSI C header files, and special-purpose files
4. In the `/usr/include` directory

The compiler searches for bracket-included files (of the form `#include <foo.h>`) in this order.

1. In the directories named with `-I` options, if any
2. In the `include` directories for compiler-provided C++ header files, ANSI C header files, and special-purpose files
3. In the `/usr/include` directory

Note – If the spelling matches the name of a standard header file, also refer to [“11.7.5 Standard Header Implementation” on page 142](#).

A.2.35.1 Interactions

The `-I` option allows you to override the default search rules.

If you specify `-library=no%Cstd`, then the compiler does not include in its search path the compiler-provided header files that are associated with the C++ standard libraries. See [“11.7 Replacing the C++ Standard Library” on page 140](#).

If `-ptipath` is not used, the compiler looks for template files in `-Ipathname`.

Use `-Ipathname` instead of `-ptipath`.

This option accumulates instead of overrides.

Warnings

Never specify the compiler installation area, `/usr/include`, `/lib`, or `/usr/lib`, as search directories.

See also

- I -

A.2.36

- I -

Change the include-file search rules to the following:

For include files of the form `#include "foo.h"`, search the directories in the following order:

1. The directories named with `-I` options (both before and after `-I`).
2. The directories for compiler-provided C++ header files, ANSI C header files, and special-purpose files.
3. The `/usr/include` directory.

For include files of the form `#include <foo.h>`, search the directories in the following order:

1. The directories named in the `-I` options that appear after `-I`.
2. The directories for compiler-provided C++ header files, ANSI C header files, and special-purpose files.
3. The `/usr/include` directory.

Note – If the name of the include file matches the name of a standard header, also refer to “[11.7.5 Standard Header Implementation](#)” on page 142.

A.2.36.1

Examples

The following example shows the results of using `-I` when compiling `prog.cc`.

```
prog.cc
#include "a.h"
#include <b.h>
#include "c.h"
c.h
#ifdef _C_H_1
#define _C_H_1
int c1;
#endif
```

```

inc/a.h
#ifndef _A_H
#define _A_H
#include "c.h"
int a;
#endif
inc/b.h
#ifndef _B_H
#define _B_H
#include <c.h>
int b;
#endif
inc/c.h
#ifndef _C_H_2
#define _C_H_2
int c2;
#endif

```

The following command shows the default behavior of searching the current directory (the directory of the including file) for include statements of the form `#include "foo.h"`. When processing the `#include "c.h"` statement in `inc/a.h`, the compiler includes the `c.h` header file from the `inc` subdirectory. When processing the `#include "c.h"` statement in `prog.cc`, the compiler includes the `c.h` file from the directory containing `prog.cc`. Note that the `-H` option instructs the compiler to print the paths of the included files.

```

example% CC -c -Iinc -H prog.cc
inc/a.h
      inc/c.h
inc/b.h
      inc/c.h
c.h

```

The next command shows the effect of the `-I-` option. The compiler does not look in the including directory first when it processes statements of the form `#include "foo.h"`. Instead, it searches the directories named by the `-I` options in the order that they appear in the command line. When processing the `#include "c.h"` statement in `inc/a.h`, the compiler includes the `./c.h` header file instead of the `inc/c.h` header file.

```

example% CC -c -I. -I- -Iinc -H prog.cc
inc/a.h
      ./c.h
inc/b.h
      inc/c.h
./c.h

```

Interactions

When `-I-` appears in the command line, the compiler never searches the current directory, unless the directory is listed explicitly in a `-I` directive. This effect applies even for include statements of the form `#include "foo.h"`.

Warnings

Only the first `-I` in a command line causes the described behavior.

Never specify the compiler installation area, `/usr/include`, `/lib`, or `/usr/lib`, as search directories.

A.2.37 `-i`

Tells the linker, `ld`, to ignore any `LD_LIBRARY_PATH` setting.

A.2.38 `-include filename`

This option causes the compiler to treat *filename* as if it appears in the first line of a primary source file as a `#include` preprocessor directive. Consider the source file `t.c`:

```
main()
{
    ...
}
```

If you compile `t.c` with the command `cc -include t.h t.c`, the compilation proceeds as if the source file contains the following:

```
#include "t.h"
main()
{
    ...
}
```

The first directory the compiler searches for *filename* is the current working directory and not the directory containing the main source file, as is the case when a file is explicitly included. For example, the following directory structure contains two header files with the same name, but at different locations:

```
foo/
  t.c
  t.h
  bar/
    u.c
    t.h
```

If your working directory is `foo/bar` and you compile with the command `cc ../t.c -include t.h`, the compiler includes `t.h` from `foo/bar`, not `foo/` as would be the case with a `#include` directive from within the source file `t.c`.

If the compiler cannot find the file specified with `-include` in the current working directory, it searches the normal directory paths for the file. If you specify multiple `-include` options, the files are included in the order they appear on the command line.

A.2.39 `-inline`

Same as `-xinline`.

A.2.40 `-instances=a`

Controls the placement and linkage of template instances.

A.2.40.1 Values

a must be one of the following values.

TABLE A-14 The `-instances` Values

Value	Meaning
<code>extern</code>	Places all needed instances into the template repository within <code>comdat</code> sections and gives them global linkage. (If an instance in the repository is out of date, it is reinstated.) Note: If you are compiling and linking in separate steps and you specify <code>-instance=extern</code> for the compilation step, you must also specify it for the link step.
<code>explicit</code>	Places explicitly instantiated instances into the current object file and gives them global linkage. Does not generate any other needed instances.
<code>global</code>	Places all needed instances into the current object file and gives them global linkage.
<code>semiexplicit</code>	Places explicitly instantiated instances into the current object file and gives them global linkage. Places all instances needed by the explicit instances into the current object file and gives them global linkage. Does not generate any other needed instances.
<code>static</code>	Note: <code>-instances=static</code> is deprecated. There is no longer any reason to use <code>-instances=static</code> , because <code>-instances=global</code> now gives you all the advantages of static without the disadvantages. This option was provided in earlier compilers to overcome problems that do not exist in this version of the compiler. Places all needed instances into the current object file and gives them static linkage.

Defaults

If `-instances` is not specified, `-instances=global` is assumed.

See also

[“7.2.4 Template Instance Placement and Linkage” on page 92.](#)

A.2.41 `-instlib=filename`

Use this option to inhibit the generation of template instances that are duplicated in a library, either shared or static, and the current object. In general, if your program shares large numbers of instances with libraries, try `-instlib=filename` and see whether compilation time improves.

A.2.41.1 Values:

Use the *filename* argument to specify the library that you know contains the existing template instances. The filename argument must contain a forward slash '/' character. For paths relative to the current directory, use dot-slash './'.

Defaults:

The `-instlib=filename` option has no default and is only used if you specify it. This option can be specified multiple times and accumulates.

Example:

Assume that the `libfoo.a` and `libbar.so` libraries instantiate many template instances that are shared with your source file `a.cc`. Adding `-instlib=filename` and specifying the libraries helps reduce compile time by avoiding the redundancy.

```
example% CC -c -instlib=./libfoo.a -instlib=./libbar.so a.cc
```

Interactions:

When you compile with `-g`, if the library specified with `-instlib=file` is not compiled with `-g`, those template instances will not be debuggable. The workaround is to avoid `-instlib=file` when you use `-g`.

Warning

If you specify a library with `-instlib`, you must link with that library.

See Also:

`-template`, `-instances`, `-pti`

A.2.42 **-KPIC**

SPARC: Same as `-xcode=pic32`.

x86: Same as `-Kpic`.

Use this option to compile source files when building a shared library. Each reference to a global datum is generated as a dereference of a pointer in the global offset table. Each function call is generated in pc-relative addressing mode through a procedure linkage table.

A.2.43 **-Kpic**

SPARC: Same as `-xcode=pic13`.

x86: Compiles with position-independent code.

Use this option to compile source files when building a shared library. Each reference to a global datum is generated as a dereference of a pointer in the global offset table. Each function call is generated in pc-relative addressing mode through a procedure linkage table.

A.2.44 **-keeptmp**

Retains temporary files created during compilation.

Along with `-verbose=diags`, this option is useful for debugging.

A.2.44.1 **See also**

`-v`, `-verbose`

A.2.45 **-Lpath**

Adds *path* to list of directories to search for libraries.

This option is passed to `ld`. The directory that is named by *path* is searched before compiler-provided directories.

A.2.45.1 **Interactions**

This option accumulates instead of overrides.

Warnings

Never specify the compiler installation area, `/usr/include`, `/lib`, or `/usr/lib`, as search directories.

A.2.46 **-llib**

Adds library `llib.a` or `llib.so` to the linker's list of search libraries.

This option is passed to `ld`. Normal libraries have names such as `llib.a` or `llib.so`, where the `lib` and `.a` or `.so` parts are required. You should specify the `lib` part with this option. Put as many libraries as you want on a single command line; they are searched in the order specified with `-Ldir`.

Use this option after your object file name.

A.2.46.1 **Interactions**

This option accumulates instead of overrides.

It is always safer to put `-lx` *after* the list of sources and objects to insure that libraries are searched in the correct order.

Warnings

To ensure proper library linking order, you must use `-mt`, rather than `-lthread`, to link with `libthread`.

See also

`-Ldir`, `-mt`, [“10.4.8 An Example Application” on page 125](#), and *Tools.h++ Class Library Reference*

A.2.47 **-libmieee**

Same as `-xlibmieee`.

A.2.48 **-libmil**

Same as `-xlibmil`.

A.2.49 **-library=[,l...]**

Incorporates specified CC-provided libraries into compilation and linking.

A.2.49.1 **Values**

For compatibility mode (`-compat [-4]`), `l` must be one of the following values.

TABLE A-15 The `-library` Values for Compatibility Mode

Value	Meaning
[no%]f77	Deprecated. Use <code>-xlang=f77</code> instead.
[no%]f90	Deprecated. Use <code>-xlang=f90</code> instead.
[no%]f95	Deprecated. Use <code>-xlang=f95</code> instead.
[no%]rwttools7	[Do not] Use classic-iostreams <code>Tools.h++</code> version 7.
[no%]rwttools7_dbg	[Do not] Use debug-enabled <code>Tools.h++</code> version 7.
[no%]complex	[Do not] Use <code>libcomplex</code> for complex arithmetic.
[no%]interval	Deprecated. Do not use. Use <code>-xia</code> .
[no%]libc	[Do not] Use <code>libc</code> , the C++ support library.
[no%]gc	[Do not] Use <code>libgc</code> , garbage collection.
[no%]sunperf	[Do not] Use the Sun Performance Library
%none	Use no C++ libraries except for <code>libc</code> .

For standard mode (the default mode), *l* must be one of the following:

TABLE A-16 The `-library` Values for Standard Mode

Value	Meaning
[no%]f77	Deprecated. Use <code>-xlang=f77</code> instead.
[no%]f90	Deprecated. Use <code>-xlang=f90</code> instead.
[no%]f95	Deprecated. Use <code>-xlang=f95</code> instead.
[no%]rwttools7	[Do not] Use classic-iostreams <code>Tools.h++</code> version 7.
[no%]rwttools7_dbg	[Do not] Use debug-enabled <code>Tools.h++</code> version 7.
[no%]rwttools7_std	[Do not] Use standard-iostreams <code>Tools.h++</code> version 7.
[no%]rwttools7_std_dbg	[Do not] Use debug-enabled standard-iostreams <code>Tools.h++</code> version 7.
[no%]interval	Deprecated. Do not use. Use <code>-xia</code> .
[no%]iostream	[Do not] Use <code>libiostream</code> , the classic iostreams library.
[no%]Cstd	[Do not] Use <code>libCstd</code> , the C++ standard library. [Do not] Include the compiler-provided C++ standard library header files.

TABLE A-16 The `-library` Values for Standard Mode (Continued)

Value	Meaning
[no%]Crun	[Do not] Use <code>libCrun</code> , the C++ runtime library.
[no%]gc	[Do not] Use <code>libgc</code> , garbage collection.
[no%]stlport4	[Do not] Use STLport's Standard Library implementation version 4.5.3 instead of the default <code>libCstd</code> . For more information about using STLport's implementation, see "12.3 STLport" on page 160.
[no%]stlport4_dbg	[Do not] Use STLport's debug-enabled library.
[no%]sunperf	[Do not] Use the Sun Performance Library.
[no%]stdcxx4	[Do not] Use the Apache <code>stdcxx</code> version 4 C++ standard library in Solaris, instead of the default <code>libCstd</code> . This option also sets the <code>-mt</code> option implicitly. The <code>stdcxx</code> library requires multi-threading mode. This option must be used consistently on every compilation and link command in the entire application. Code compiled with <code>-library=stdcxx4</code> cannot be used in the same program as code compiled with the default <code>-library=Cstd</code> or the optional <code>-library=stlport4</code> .
%none	Use no C++ libraries, except for <code>libCrun</code> .

Defaults

- **Compatibility mode** (`-compat [=4]`)
 - If `-library` is not specified, `-library=libC` is assumed.
 - The `libC` library is always included unless it is specifically excluded using `-library=no%libC`.

Standard mode (the default mode)

- The `libCstd` library is always included unless it is specifically excluded using `-library=%none` or `-library=no%Cstd` or `-library=stlport4`.
- The `libCrun` library always is included unless it is specifically excluded using `-library=no%Crun`.

Regardless of standard or compat mode, the `libm` and `libc` libraries are always included, even if you specify `-library=%none`.

Examples

To link in standard mode without any C++ libraries (except `libCrun`), use:

```
example% CC -library=%none
```

To include the classic-iostreams Rogue Wave `tools.h++` library in standard mode:

```
example% CC -library=rwtools7,iostream
```

To include the standard-iostreams Rogue Wave `tools.h++` library in standard mode:

```
example% CC -library=rwtools7_std
```

To include the classic-iostreams Rogue Wave `tools.h++` library in compatibility mode:

```
example% CC -compat -library=rwtools7
```

Interactions

If a library is specified with `-library`, the proper `-I` paths are set during compilation. The proper `-L`, `-Y P`, `-R` paths and `-l` options are set during linking.

This option accumulates instead of overrides.

When you use the interval arithmetic libraries, you must include one of the following libraries: `libC`, `libCstd`, or `libiostream`.

Use of the `-library` option ensures that the `-l` options for the specified libraries are emitted in the right order. For example, the `-l` options are passed to `ld` in the order `-lrwtool` `-liostream` for both `-library=rwtools7,iostream` and `-library=iostream,rwtools7`.

The specified libraries are linked before the system support libraries are linked.

For `-library=stdcxx4`, the Apache `stdcxx` library must be installed in `/usr/include` and `/usr/lib` on Solaris OS. The library is also available on recent OpenSolaris releases.

You cannot use `-library=sunperf` and `-xlic_lib=sunperf` on the same command line.

You can use at most only one of `-library=stlport4`, `-library=stdcxx4`, or `-library=Cstd` options on any command line.

Only one Rogue Wave tools library can be used at a time and you cannot use any Rogue Wave tools library with `-library=stlport4` or `-library=stdcxx4`.

When you include the classic-iostreams Rogue Wave tools library in standard mode (the default mode), you must also include `libiostream` (see the *C++ Migration Guide* for additional information). You can use the standard-iostreams Rogue Wave tools library in standard mode only. The following command examples show both valid and invalid use of the Rogue Wave `tools.h++` library options.

```
% CC -compat -library=rwtools7 foo.cc      <-- valid
% CC -compat -library=rwtools7_std foo.cc  <-- invalid
```

```
% CC -library=rwtools7,iostream foo.cc      <-- valid, classic iostreams
% CC -library=rwtools7 foo.cc                <-- invalid

% CC -library=rwtools7_std foo.cc           <-- valid, standard iostreams
% CC -library=rwtools7_std,iostream foo.cc <-- invalid
```

If you include both `libCstd` and `libiostream`, you must be careful to not use the old and new forms of `iostreams` (for example, `cout` and `std::cout`) within a program to access the same file. Mixing standard `iostreams` and classic `iostreams` in the same program is likely to cause problems if the same file is accessed from both classic and standard `iostream` code.

Compatibility-mode programs that do not link the `libC` library cannot use all features of the C++ language. Similarly, standard-mode programs that do not link `Crun` or any of the `Cstd`, or `stlport4` libraries, cannot use all features of the C++ language.

If `-xnolib` is specified, `-library` is ignored.

Warnings

If you compile and link in separate steps, the set of `-library` options that appear in the compile command must appear in the link command.

The `stlport4`, `Cstd`, and `iostream` libraries provide their own implementation of I/O streams. Specifying more than one of these with the `-library` option can result in undefined program behavior. For more information about using STLport's implementation, see [“12.3 STLport” on page 160](#).

The set of libraries is not stable and might change from release to release.

See also

`-I`, `-l`, `-R`, `-staticlib`, `-xia`, `-xlang`, `-xnolib`, [“10.4.8 An Example Application” on page 125](#), [“Caveats:” on page 144](#), [“12.3.1 Redistribution and Supported STLport Libraries” on page 161](#), *Tools.h++ User's Guide*, *Tools.h++ Class Library Reference*, *Standard C++ Class Library Reference*, *C++ Interval Arithmetic Programming Reference*.

For information on using the `-library=no%cstd` option to enable use of your own C++ standard library, see [“11.7 Replacing the C++ Standard Library” on page 140](#).

A.2.50 `-m32|-m64`

Specifies the memory model for the compiled binary object.

Use `-m32` to create 32-bit executables and shared libraries. Use `-m64` to create 64-bit executables and shared libraries.

The ILP32 memory model (32-bit int, long, pointer data types) is the default on all Solaris platforms and on Linux platforms that are not 64-bit enabled. The LP64 memory model (64-bit long, pointer data types) is the default on Linux platforms that are 64-bit enabled. `-m64` is permitted only on platforms that are enabled for the LP64 model.

Object files or libraries compiled with `-m32` cannot be linked with object files or libraries compiled with `-m64`.

Modules that are compiled with `-m32|-m64` must also be linked with `-m32|-m64`. For a complete list of compiler options that must be specified at both compile time and at link time, see “[3.3.3 Compile-Time and Link-Time Options](#)” on page 48.

When compiling applications with large amounts of static data on x64 platforms, using `-m64`, `-xmodel=medium` may also be required. Be aware that some Linux platforms do not support the medium model.

Note that in previous compiler releases, the memory model, ILP32 or LP64, was implied by the choice of the instruction set with `-xarch`. Starting with the Solaris Studio 12 compilers, this is no longer the case. On most platforms, just adding `-m64` to the command line is sufficient to create 64-bit objects.

On Solaris, `-m32` is the default. On Linux systems supporting 64-bit programs, `-m64 -xarch=sse2` is the default.

See also `-xarch`.

A.2.51 `-mc`

Removes duplicate strings from the `.comment` section of the object file. When you use the `-mc` option, the `mcs -c` command is invoked. (See the `mcs(1)` man page for details.)

A.2.52 `-migration`

Explains where to get information about migrating source code that was built for earlier versions of the compiler.

Note – This option might cease to exist in the next release.

A.2.53 `-misalign`

SPARC: Permits misaligned data, which would otherwise generate an error, in memory. This is shown in the following code:

```
char b[100];
int f(int * ar) {
return *(int *) (b +2) + *ar;
}
```

This option informs the compiler that some data in your program is not properly aligned. Thus, very conservative loads and stores must be used for any data that might be misaligned, that is, one byte at a time. Using this option may cause significant degradation in runtime performance. The amount of degradation is application dependent.

A.2.53.1 Interactions

When using `#pragma pack` on a SPARC platform to pack denser than the type's default alignment, the `-misalign` option must be specified for both the compilation and the linking of the application.

Misaligned data is handled by a trap mechanism that is provided by `ld` at runtime. If an optimization flag (`-xO{1|2|3|4|5}` or an equivalent flag) is used with the `-misalign` option, the additional instructions required for alignment of misaligned data are inserted into the resulting object file and will not generate runtime misalignment traps.

Warnings

If possible, do not link aligned and misaligned parts of the program.

If compilation and linking are performed in separate steps, the `-misalign` option must appear in both the compile and link commands.

A.2.54 `-mr[, string]`

Removes all strings from the `.comment` section of the object file and, if *string* is supplied, places *string* in that section. If the string contains blanks, the string must be enclosed in quotation marks. When you use this option, the command `mcs -d [-a string]` is invoked.

A.2.55 `-mt[={yes|no}]`

Use this option to compile and link multithreaded code using the Solaris threads or POSIX threads API. The `-mt=yes` option assures that libraries are linked in the appropriate order.

This option passes `-D_REENTRANT` to the preprocessor.

To use Solaris threads, include the `thread.h` header file and compile with the `-mt=yes` option. To use POSIX threads on Solaris platforms, include the `pthread.h` header file and compile with the `-mt=yes -lpthread` options.

On Linux platforms, only the POSIX threads API is available. (There is no `libthread` on Linux platforms.) Consequently, `-mt=yes` on Linux platforms adds `-lpthread` instead of `-lthread`. To use POSIX threads on Linux platforms, compile with `-mt=yes`.

Note that when compiling with `-G`, neither `-lthread` nor `-lpthread` are automatically included by `-mt=yes`. You will need to explicitly list these libraries when building a shared library.

The `-xopenmp` option (for using the OpenMP shared-memory parallelization API) includes `-mt=yes` automatically.

If you compile with `-mt=yes` and link in a separate step, you must use the `-mt=yes` option in the link step as well as the compile step. If you compile and link one translation unit with `-mt`, you must compile and link all units of the program with `-mt`

`-mt=yes` is the default behavior of the compiler. If this behavior is not desired, compile with `-mt=no`.

The option `-mt` is equivalent to `-mt=yes`.

A.2.55.1 See Also

`-xnoLib`, and the Solaris *Multithreaded Programming Guide*, and *Linker and Libraries Guide*

A.2.56 `-native`

Same as `-xtarget=native`.

A.2.57 `-noex`

Same as `-features=no%except`.

A.2.58 `-nofstore`

x86: Disables forced precision of an expression.

This option does not force the value of a floating-point expression or function to the type on the left side of an assignment, but leaves the value in a register when either of the following are true:

- The expression or function is assigned to a variable
- or
- The expression or function is cast to a shorter floating-point type

A.2.58.1 See also

`-fstore`

A.2.59 **-noLib**

Same as `-xnoLib`.

A.2.60 **-noLibmil**

Same as `-xnoLibmil`.

A.2.61 **-noqueue**

(*Obsolete*) Disables license queueing.

If no license is available, this option returns without queuing your request and without compiling. A nonzero status is returned for testing makefiles. *This option is obsolete and is ignored.*

A.2.62 **-norunpath**

Does not build a runtime search path for shared libraries into the executable.

If an executable file uses shared libraries, then the compiler normally builds in a path that points the runtime linker to those shared libraries. To do so, the compiler passes the `-R` option to `ld`. The path depends on the directory where you have installed the compiler.

This option is recommended for building executables that will be shipped to customers who may have a different path for the shared libraries that are used by the program. Refer to [“11.6 Using Shared Libraries” on page 139](#)

A.2.62.1 **Interactions**

If you use any shared libraries under the compiler installed area and you also use `-norunpath`, then you should either use the `-R` option at link time or set the environment variable `LD_LIBRARY_PATH` at runtime to specify the location of the shared libraries. Doing so allows the runtime linker to find the shared libraries.

A.2.63 **-O**

The `-O` macro now expands to `-xO3` instead of `-xO2`.

The change in default yields higher run-time performance. However, `-xO3` may be inappropriate for programs that rely on all variables being automatically considered volatile. Typical programs that might have this assumption are device drivers and older multi-threaded applications that implement their own synchronization primitives. The work around is to compile with `-xO2` instead of `-O`.

A.2.64 `-Olevel`

Same as `-xOlevel`.

A.2.65 `-o filename`

Sets the name of the output file or the executable file to *filename*.

A.2.65.1 Interactions

When the compiler must store template instances, it stores them in the template repository in the output file's directory. For example, the following command writes the object file to `./sub/a.o` and writes template instances into the repository contained within `./sub/SunWS_cache`.

```
example% CC -instances=extern -o sub/a.o a.cc
```

The compiler reads from the template repositories corresponding to the object files that it reads. For example, the following command reads from `./sub1/SunWS_Cache` and `./sub2/SunWS_cache`, and, if necessary, writes to `./SunWS_cache`.

```
example% CC -instances=extern sub1/a.o sub2/b.o
```

For more information, see [“7.4 The Template Repository”](#) on page 96.

Warnings

The *filename* must have the appropriate suffix for the type of file to be produced by the compilation. It cannot be the same file as the source file, since the CC driver does not overwrite the source file.

A.2.66 `+p`

Ignore nonstandard preprocessor asserts.

A.2.66.1 Defaults

If `+p` is not present, the compiler recognizes nonstandard preprocessor asserts.

Interactions

If `+p` is used, the following macros are not defined:

- `sun`
- `unix`

- `sparc`
- `i386`

A.2.67 `-P`

Only preprocesses source; does not compile. (Outputs a file with a `.i` suffix.)

This option does not include preprocessor-type line number information in the output.

A.2.67.1 **See also**

`-E`

A.2.68 `-p`

Obsolete, see “[A.2.165 `-xpg`](#)” on page 320.

A.2.69 `-pentium`

x86: Replace with `-xtarget=pentium`.

A.2.70 `-pg`

Same as `-xpg`.

A.2.71 `-PIC`

SPARC: Same as `-xcode=pic32`.

x86: Same as `-Kpic`.

A.2.72 `-pic`

SPARC: Same as `-xcode=pic13`.

x86: Same as `-Kpic`.

A.2.73 `-pta`

Same as `-template=wholeclass`.

A.2.74 `-ptipath`

Specifies an additional search directory for template source.

This option is an alternative to the normal search path set by `-Ipathname`. If the `-ptipath` option is used, the compiler looks for template definition files on this path and ignores the `-Ipathname` option.

Using the `-Ipathname` option instead of `-ptipath` produces less confusion.

A.2.74.1 Interactions

This option accumulates instead of overrides.

See also

`-Ipathname`, and [“7.5.2 Definitions Search Path” on page 98](#)

A.2.75 `-pto`

Same as `-instances=static`.

A.2.76 `-ptr`

This option is obsolete and is ignored by the compiler.

A.2.76.1 Warnings

Even though the `-ptr` option is ignored, you should remove `-ptr` from all compilation commands because, in a later release, it may be reused with a different behavior.

See also

For information about repository directories, see [“7.4 The Template Repository” on page 96](#).

A.2.77 `-ptv`

Same as `-verbose=template`.

A.2.78 `-Qoption phase option[,option...]`

Passes *option* to the compilation *phase*.

To pass multiple options, specify them in order as a comma-separated list. Options that are passed to components with `-Q` might be reordered. Options that the driver recognizes are kept in the correct order. Do not use `-Q` for options that the driver already recognizes. For example, the C++ compiler recognizes the `-z` option for the linker (`ld`). If you issue a command like this

```
CC -G -zallextract mylib.a -zdefaultextract ... // correct
```

the `-z` options are passed in order to the linker. But if you specify the command like this

```
CC -G -Qoption ld -zallextract mylib.a -Qoption ld -zdefaultextract ... // error
```

the `-z` options can be reordered, giving incorrect results.

A.2.78.1

Values

phase must have one of the following values.

TABLE A-17 The `-Qoption` Values

SPARC	x86
ccfe	ccfe
iropt	iropt
cg	ube
CClink	CClink
ld	ld
—	ir2hf
fbe	fbe

Examples

In the following command line, when `ld` is invoked by the CC driver, `-Qoption` passes the `-i` and `-m` options to `ld`.

```
example% CC -Qoption ld -i, -m test.c
```

Warnings

Be careful to avoid unintended effects. For example,

```
-Qoption ccfe -features=bool,iddollar
```

is interpreted as

```
-Qoption ccfe -features=bool -Qoption ccfe iddollar
```

The correct usage is

```
-Qoption ccfe -features=bool, -features=iddollar
```

A.2.79 **-Qoption** *phase option*

Same as `-Qoption`.

A.2.80 **-qp**

Same as `-p`.

A.2.81 **-Qproduce** *sourcetype*

Causes the CC driver to produce output of the type *sourcetype*.

Sourcetype suffixes are defined below.

TABLE A-18 The `-Qproduce` Values

Suffix	Meaning
.i	Preprocessed C++ source from <code>ccfe</code>
.o	Object file the code generator
.s	Assembler source from <code>cg</code>

A.2.82 **-qproduce** *sourcetype*

Same as `-Qproduce`.

A.2.83 **-Rpathname[:pathname...]**

Builds dynamic library search paths into the executable file.

This option is passed to `ld`.

A.2.83.1 **Defaults**

If the `-R` option is not present, the library search path that is recorded in the output object and passed to the runtime linker depends upon the target architecture instruction specified by the `-xarch` option (when `-xarch` is not present, `-xarch=generic` is assumed).

Examine the output from `-dryrun` and the `-R` option passed to the linker, `ld`, to see the default paths assumed by the compiler.

Interactions

This option accumulates instead of overrides.

If the `LD_RUN_PATH` environment variable is defined and the `-R` option is specified, then the path from `-R` is scanned and the path from `LD_RUN_PATH` is ignored.

See also

`-norunpath`, *Linker and Libraries Guide*

A.2.84 `-readme`

Same as `-xhelp=readme`.

A.2.85 `-S`

Compiles and generates only assembly code.

This option causes the CC driver to compile the program and output an assembly source file, without assembling the program. The assembly source file is named with a `.s` suffix.

A.2.86 `-s`

Strips the symbol table from the executable file.

This option removes all symbol information from output executable files. This option is passed to `ld`.

A.2.87 `-sb`

Obsolete and silently ignored.

A.2.88 `-sbfast`

Obsolete and silently ignored.

A.2.89 `-staticlib=[[,l...]`

Indicates which C++ libraries, specified by the `-library` option (including its defaults), by the `-xlang` option, and by the `-xia` option, are to be linked statically.

A.2.89.1 Values

`l` must be one of the following values.

TABLE A-19 The `-staticlib` Values

Value	Meaning
<code>[no%]library</code>	[Do not] link <i>library</i> statically. The valid values for <i>library</i> are all the valid values for <code>-library</code> (except <code>%all</code> and <code>%none</code>), all the valid values for <code>-xlang</code> , and <code>interval</code> (to be used in conjunction with <code>-xia</code>).
<code>%all</code>	Statically link all the libraries specified in the <code>-library</code> option, all the libraries specified in the <code>-xlang</code> option, and, if <code>-xia</code> is specified in the command line, the interval libraries.
<code>%none</code>	Link no libraries specified in the <code>-library</code> option and the <code>-xlang</code> option statically. If <code>-xia</code> is specified in the command line, link no interval libraries statically.

Defaults

If `-staticlib` is not specified, `-staticlib=%none` is assumed.

Examples

The following command line links `libCrun` statically because `Crun` is a default value for `-library`:

```
example% CC -staticlib=Crun (correct)
```

However, the following command line does not link `libgc` because `libgc` is not linked unless explicitly specified with the `-library` option:

```
example% CC -staticlib=gc (incorrect)
```

To link `libgc` statically, use the following command:

```
example% CC -library=gc -staticlib=gc (correct)
```

With the following command, the `librwtool` library is linked dynamically. Because `librwtool` is not a default library and is not selected using the `-library` option, `-staticlib` has no effect:

```
example% CC -lrwtool -library=iostream \  
-staticlib=rwtools7 (incorrect)
```

This command links the `librwtool` library statically:

```
example% CC -library=rwtools7,iostream -staticlib=rwtools7 (correct)
```

This command will link the Sun Performance Libraries dynamically because `-library=sunperf` must be used in conjunction with `-staticlib=sunperf` in order for the `-staticlib` option to have an effect on the linking of these libraries:

```
example% CC -xlic_lib=sunperf -staticlib=sunperf (incorrect)  
This command links the Sun Performance Libraries statically:
```

```
example% CC -library=sunperf -staticlib=sunperf (correct)
```

Interactions

This option accumulates instead of overrides.

The `-staticlib` option only works for the C++ libraries that are selected explicitly with the `-xia` option, the `-xlang` option, and the `-library` option, in addition to the C++ libraries that are selected implicitly by default. In compatibility mode (`-compat=[4]`), `libC` is selected by default. In standard mode (the default mode), `Cstd` and `Crun` are selected by default.

When using `-xarch=v9`, `-xarch=v9a`, or `-xarch=v9b` (or equivalent 64-bit architecture options), some C++ libraries are not available as static libraries.

Warnings

The set of allowable values for *library* is not stable and might change from release to release.

When using `-xarch=v9`, `-xarch=v9a`, or `-xarch=v9b`, (or equivalent 64-bit architecture options), some libraries are not available as static libraries.

The options `-staticlib=Crun` and `-staticlib=Cstd` do not work on 64-bit Solaris x86 platforms. Sun recommends against linking these libraries statically on any platform. In some cases, static linking can prevent a program from working.

See also

`-library`, “[11.5 Statically Linking Standard Libraries](#)” on page 138

A.2.90 `-sync_stdio=[yes|no]`

Use this option when your run-time performance is degraded due to the synchronization between C++ iostreams and C stdio. Synchronization is needed only when you use iostreams to write to `cout` and stdio to write to `stdout` in the same program. The C++ standard requires

synchronization so the C++ compiler turns it on by default. However, application performance is often much better without synchronization. If your program does not write to both `cout` and `stdout`, you can use the option `-sync_stdio=no` to turn off synchronization.

A.2.90.1 **Defaults:**

If you do not specify `-sync_stdio`, the compiler sets it to `-sync_stdio=yes`.

Examples:

Consider the following example:

```
#include <stdio.h>
#include <iostream>
int main()
{
    std::cout << "Hello ";
    printf("beautiful ");
    std::cout << "world!";
    printf("\n");
}
```

With synchronization, the program prints on a line by itself

```
Hello beautiful world!
:
```

Without synchronization, the output gets scrambled.

Warnings:

This option is only effective for linking of executables, not for libraries.

A.2.91 **`-temp=path`**

Defines the directory for temporary files.

This option sets the path name of the directory for storing the temporary files which are generated during the compilation process. The compiler gives precedence to the value set by `-temp` over the value of `TMPDIR`.

A.2.91.1 **See also**

`-keeptmp`

A.2.92 **`-template=opt[,opt...]`**

Enables/disables various template options.

A.2.92.1 Values

opt must be one of the following values.

TABLE A-20 The `-template` Values

Value	Meaning
<code>[no%]extdef</code>	[Do not] Search for template definitions in separate source files. With <code>no%extdef</code> , the compiler predefines <code>_TEMPLATE_NO_EXTDEF</code>
<code>[no%]geninlinefuncs</code>	[Do not] Generate unreferenced inline member functions for explicitly instantiated class templates.
<code>[no%]wholeclass</code>	[Do not] Instantiate a whole template class, rather than only those functions that are used. You must reference at least one member of the class; otherwise, the compiler does not instantiate any members for the class.

Defaults

If the `-template` option is not specified, `-template=no%wholeclass,extdef` is assumed.

Examples

Consider the following code:

```
example% cat Example.cc
    template <class T> struct S {
        void imf() {}
        static void smf() {}
    };

    template class S <int>;

    int main() {
    }
example%
```

When you specify `-template=geninlinefuncs`, even though the two member functions of `S` are not called in the program, they are generated in the object file.

```
example% CC -c -template=geninlinefuncs Example.cc
example% nm -C Example.o
```

Example.o:

```
[Index] Value Size Type Bind Other Shndx Name
[5]      0  0  NOTY GLOB  0  ABS  __fsr_init_value
[1]      0  0  FILE LOCL  0  ABS  b.c
[4]     16 32  FUNC GLOB  0  2    main
[3]    104 24  FUNC LOCL  0  2    void S<int>::imf()
```

```
[2]    64    20  FUNC  LOCL  0    2    [__1cBS4Ci_Dimf6M_v_]
      void S<int>::smf()
      [__1cBS4Ci_Dsmf6F_v_]
```

See also

“7.2.2 Whole-Class Instantiation” on page 92, “7.5 Template Definition Searching” on page 97

A.2.93 `-time`

Same as `-xtime`.

A.2.94 `-t traceback[={%none|common|signals_list}]`

Issue a stack trace if a severe error occurs in execution.

The `-t traceback` option causes the executable to issue a stack trace to `stderr`, dump core, and exit if certain signals are generated by the program. If multiple threads generate a signal, a stack trace will only be produced for the first one.

To use traceback, add the `-t traceback` option to the compiler command line when linking. The option is also accepted at compile-time but is ignored unless an executable binary is generated. Using `-t traceback` with `-G` to create a shared library is an error.

TABLE A-21 `-t traceback` Options

Option	Meaning
<code>common</code>	specifies that a stack trace should be issued if any of a set of common signals occurs: <code>sigill</code> , <code>sigfpe</code> , <code>sigbus</code> , <code>sigsegv</code> , or <code>sigabrt</code> .
<code>signals_list</code>	specifies a comma-separated list of names of signals that should generate a stack trace, in lower case. The following signals (those that cause the generation of a core file) can be caught: <code>sigquit</code> , <code>sigill</code> , <code>sigtrap</code> , <code>sigabrt</code> , <code>sigemt</code> , <code>sigfpe</code> , <code>sigbus</code> , <code>sigsegv</code> , <code>sigsys</code> , <code>sigxcpu</code> , <code>sigxfsz</code> . Any of these can be preceded with <code>no%</code> to disable catching the signal. For example: <code>-t traceback=sigsegv, sigfpe</code> will produce a stack trace and core dump if either <code>sigsegv</code> or <code>sigfpe</code> occurs.
<code>%none</code> or <code>none</code>	disables traceback

If the option is not specified, the default is `-t traceback=%none`

`-t traceback` alone, without a `=` sign, implies `-t traceback=common`

Note: If the core dump is not wanted, users may set the `coredumpsize` limit to zero using:

```
% limit coredumpsize 0
```

The `-traceback` option has no effect on runtime performance.

A.2.95 `-Uname`

Deletes initial definition of the preprocessor symbol *name*.

This option removes any initial definition of the macro symbol *name* created by `-D` on the command line including those implicitly placed there by the CC driver. This option has no effect on any other predefined macros, nor on macro definitions in source files.

To see the `-D` options that are placed on the command line by the CC driver, add the `-dryrun` option to your command line.

A.2.95.1 Examples

The following command undefines the predefined symbol `__sun`. Preprocessor statements in `foo.cc` such as `#ifdef(__sun)` will sense that the symbol is undefined.

```
example% CC -U__sun foo.cc
```

Interactions

You can specify multiple `-U` options on the command line.

All `-U` options are processed after any `-D` options that are present. That is, if the same *name* is specified for both `-D` and `-U` on the command line, *name* is undefined, regardless of the order the options appear.

See also

`-D`

A.2.96 `-unroll=n`

Same as `-xunroll=n`.

A.2.97 `-V`

Same as `-verbose=version`.

A.2.98 `-v`

Same as `-verbose=diags`.

A.2.99 `-vdelx`

Deprecated, do not use.

Compatibility mode only (`-compat [=4]`):

For expressions using `delete[]`, this option generates a call to the runtime library function `_vector_deletex_` instead of generating a call to `_vector_delete_`. The function `_vector_delete_` takes two arguments: the pointer to be deleted and the size of each array element.

The function `_vector_deletex_` behaves the same as `_vector_delete_` except that it takes a third argument: the address of the destructor for the class. This third argument is not used by the function, but is provided to be used by third-party vendors.

A.2.99.1 **Default**

The compiler generates a call to `_vector_delete_` for expressions using `delete[]`.

Warnings

This is an obsolete option that will be removed in future releases. Do not use this option unless you have bought some software from a third-party vendor and the vendor recommends using this option.

A.2.100 `-verbose=v[, v...]`

Controls compiler verbosity.

A.2.100.1 **Values**

`v` must be one of the following values.

TABLE A-22 The `-verbose` Values

Value	Meaning
<code>[no%]diags</code>	[Do not] Print the command line for each compilation pass.
<code>[no%]template</code>	[Do not] Turn on the template instantiation verbose mode (sometimes called the “verify” mode). The verbose mode displays each phase of instantiation as it occurs during compilation.
<code>[no%]version</code>	[Do not] Direct the CC driver to print the names and version numbers of the programs it invokes.
<code>%all</code>	Invokes all of the above.

TABLE A-22 The `-verbose` Values (Continued)

Value	Meaning
<code>%none</code>	<code>-verbose=%none</code> is the same as <code>-verbose=no%template,no%diags,no%version</code> .

Defaults

If `-verbose` is not specified, `-verbose=%none` is assumed.

Interactions

This option accumulates instead of overrides.

A.2.101 `+w`

Identifies code that might have unintended consequences. The `+w` option no longer generates a warning if a function is too large to inline or if a declared program element is unused. These warnings do not identify real problems in the source, and were thus inappropriate to some development environments. Removing these warnings from `+w` enables more aggressive use of `+w` in those environments. These warnings are still available with the `+w2` option.

This option generates additional warnings about questionable constructs that are:

- Nonportable
- Likely to be mistakes
- Inefficient

A.2.101.1 Defaults

If `+w` is not specified, the compiler warns about constructs that are almost certainly problems.

See also

`-w`, `+w2`

A.2.102 `+w2`

Emits all the warnings emitted by `+w` plus warnings about technical violations that are probably harmless, but that might reduce the maximum portability of your program.

The `+w2` option no longer warns about the use of implementation-dependent constructs in the system header files. Because the system header files are the implementation, the warning was inappropriate. Removing these warnings from `+w2` enables more aggressive use of the option.

A.2.102.1 See also

+w

A.2.103 -w

Suppresses most warning messages.

This option causes the compiler *not* to print warning messages. However, some warnings, particularly warnings regarding serious anachronisms, cannot be suppressed.

A.2.103.1 See also

+w

A.2.104 -Xm

Same as `-features=iddollar`.

A.2.105 -xaddr32

(*Solaris x86/x64 only*) The `-xaddr32=yes` compilation flag restricts the resulting executable or shared object to a 32-bit address space.

An executable that is compiled in this manner results in the creation of a process that is restricted to a 32-bit address space.

When `-xaddr32=no` is specified a usual 64 bit binary is produced.

If the `-xaddr32` option is not specified, **-xaddr32=no** is assumed.

If only `-xaddr32` is specified `-xaddr32=yes` is assumed.

This option is only applicable to `-m64` compilations and only on Solaris platforms supporting `SF1_SUNW_ADDR32` software capability. Since Linux kernels do not support address space limitation, this option is not available on Linux.

When linking, if a single object file was compiled with `-xaddr32=yes` the whole output file is assumed to be compiled with `-xaddr32=yes`.

A shared object that is restricted to a 32-bit address space must be loaded by a process that executes within a restricted 32-bit mode address space.

For more information refer to the `SF1_SUNW_ADDR32` software capabilities definition, described in the *Linker and Libraries Guide*.

A.2.106 -xalias_level[=*n*]

The C++ compiler can perform type-based alias-analysis and optimizations when you specify the following command:

- -xalias_level[=*n*]
where *n* is any, simple, or compatible.
- -xalias_level=any

At this level of analysis, the compiler assumes that any type may alias any other type. However, despite this assumption, some optimization is possible.

- -xalias_level=simple

The compiler assumes that simple types are not aliased. Specifically, a storage object with a dynamic type that is one of the following simple types:

char	short int	long int	float
signed char	unsigned short int	unsigned long int	double
unsigned char	int	long long int	long double
wchar_t	unsigned int	unsigned long long int	enumeration types
data pointer types	function pointer types	data member pointer types	function member pointer types

is only accessed through lvalues of the following types:

- The dynamic type of the object
- A constant or volatile qualified version of the dynamic type of the object, a type that is the signed or unsigned type corresponding to the dynamic type of the object
- A type that is the signed or unsigned type corresponding to a constant or volatile qualified version of the dynamic type of the object
- An aggregate or union type that includes one of the aforementioned types among its members (including, recursively, a member of a subaggregate or contained union)
- A char or unsigned char type
- -xalias_level=compatible

The compiler assumes that layout-incompatible types are not aliased. A storage object is only accessed through lvalues of the following types:

- The dynamic type of the object
- A constant or volatile qualified version of the dynamic type of the object, a type that is the signed or unsigned type which corresponds to the dynamic type of the object

- A type that is the signed or unsigned type which corresponds to the `constant` or `volatile` qualified version of the dynamic type of the object
- An aggregate or union type that includes one of the aforementioned types among its members (including, recursively, a member of a subaggregate or contained union)
- A type that is (possibly `constant` or `volatile` qualified) base class type of the dynamic type of the object
- A `char` or unsigned `char` type.

The compiler assumes that the types of all references are layout compatible with the dynamic type of the corresponding storage object. Two types are layout-compatible under the following conditions:

- If two types are the same type, then they are layout-compatible types.
- If two types differ only in `constant` or `volatile` qualification, then they are layout-compatible types.
- For each of the signed integer types, there exists a corresponding (but different) unsigned integer type. These corresponding types are layout compatible.
- Two enumeration types are layout-compatible if they have the same underlying type.
- Two Plain Old Data (POD) struct types are layout compatible if they have the same number of members, and corresponding members (in order) have layout compatible types.
- Two POD union types are layout compatible if they have the same number of members, and corresponding members (in any order) have layout compatible types.

References may be non-layout-compatible with the dynamic type of the storage object under limited circumstances:

- If a POD union contains two or more POD structs that share a common initial sequence, and if the POD union object currently contains one of those POD structs, it is permitted to inspect the common initial part of any of them. Two POD structs share a common initial sequence if corresponding members have layout compatible types and, as applicable to bit fields, the same widths, for a sequence of one or more initial members.
- A pointer to a POD struct object, suitably converted using `reinterpret_cast`, points to its initial member, or if that member is a bit field, to the unit in which it resides.

A.2.106.1 Defaults

If you do not specify `-xalias_level`, the compiler sets the option to `-xalias_level=any`. If you specify `-xalias_level` but do not provide a value, the compiler sets the option to `-xalias_level=compatible`.

Interactions

The compiler does not perform type-based alias analysis at optimization level `-xO2` and below.

Warning

If you are using `reinterpret_cast` or an equivalent old-style cast, the program may violate the assumptions of the analysis. Also, union type punning, as shown in the following example, violates the assumptions of the analysis.

```
union bitbucket{
    int i;
    float f;
};

int bitsof(float f){
    bitbucket var;
    var.f=3.6;
    return var.i;
}
```

A.2.107 -xannotate[=yes|no]

(*Solaris*) Instructs the compiler to create binaries that can later be transformed by binary modification tools like `binopt(1)`. Future binary analysis, code coverage and memory error detection tools will also work with binaries built with this option.

Use the `-xannotate=no` option to prevent the modification of the binary file by these tools.

The `-xannotate=yes` option must be used with optimization level `-xO1` or higher to be effective, and it is only effective on systems with the new linker support library interface `-ld_open()`. If the compiler is used on an operating system without this linker interface, such as the Solaris 9 OS, the compiler silently reverts to `-xannotate=no`. The new linker interface is available in Solaris 10 patch 127111-07, Solaris 10 Update 5 and OpenSolaris.

The default is `-xannotate=yes`, but if either of the above conditions is not met, the default reverts to `-xannotate=no`.

This option is not available on Linux platforms.

A.2.108 -xar

Creates archive libraries.

When building a C++ archive that uses templates, it is necessary to include in the archive those template functions that are instantiated in the template repository. The template repository is used only when at least one object file was compiled using the `-instances=extern` option. Using this option automatically adds those templates to the archive as needed.

A.2.108.1 Values

Specify `-xar` to invoke `ar -c -r` and create an archive from scratch.

Examples

The following command line archives the template functions contained in the library and object files.

```
example% CC -xar -o libmain.a a.o b.o c.o
```

Warnings

Do not add `.o` files from the template database on the command line.

Do not use the `ar` command directly for building archives. Use `CC -xar` to ensure that template instantiations are automatically included in the archive.

See also

`ar(1)`, [Table 14–3](#)

A.2.109 `-xarch=isa`

Specifies the target instruction set architecture (*ISA*).

This option limits the code generated by the compiler to the instructions of the specified instruction set architecture. This option does not guarantee use of any target-specific instructions. However, use of this option may affect the portability of a binary program.

Note – Use the `-m64` or `-m32` option to specify the intended memory model, LP64 (64-bits) or ILP32 (32-bits) respectively. The `-xarch` option no longer indicates the memory model, except for compatibility with previous releases, as indicated below.

If you compile and link in separate steps, make sure you specify the same value for `-xarch` in both steps. For complete list of all compiler options that must be specified at both compile time and at link time, see “[3.3.3 Compile-Time and Link-Time Options](#)” on page 48.

A.2.109.1 `-xarch` Flags for SPARC

The following table gives the details for each of the `-xarch` keywords on SPARC platforms.

TABLE A–23 The `-xarch` Flags for SPARC Platforms

Flag	Meaning
<code>generic</code>	Uses the instruction set common to most processors. This is the default.

TABLE A-23 The `-xarch` Flags for SPARC Platforms (Continued)

Flag	Meaning
<code>generic64</code>	Compile for good performance on most 64-bit platforms. (Solaris only). This option is equivalent to <code>-m64 -xarch=generic</code> and is provided for compatibility with earlier releases. Use <code>-m64</code> to specify 64-bit compilation instead of <code>-xarch=generic64</code> .
<code>native</code>	Compile for good performance on this system. The compiler chooses the appropriate setting for the current system processor it is running on.
<code>native64</code>	Compile for good performance on this system (Solaris only). This option is equivalent to <code>-m64 -xarch=native</code> and is provided for compatibility with earlier releases.
<code>sparc</code>	Compile for the SPARC-V9 ISA, but without the Visual Instruction Set (VIS), and without other implementation-specific ISA extensions. This option enables the compiler to generate code for good performance on the V9 ISA.
<code>sparcvis</code>	Compile for SPARC-V9 plus the Visual Instruction Set (VIS) version 1.0, and with UltraSPARC extensions. This option enables the compiler to generate code for good performance on the UltraSPARC architecture.
<code>sparcvis2</code>	Enables the compiler to generate object code for the UltraSPARC architecture, plus the Visual Instruction Set (VIS) version 2.0, and with UltraSPARC III extensions.
<code>sparcvis3</code>	Compile for the SPARC VIS version 3 of the SPARC-V9 ISA. Enables the compiler to use instructions from the SPARC-V9 instruction set, plus the UltraSPARC extensions, including the Visual Instruction Set (VIS) version 1.0, the UltraSPARC-III extensions, including the Visual Instruction Set (VIS) version 2.0, the fused multiply-add instructions, and the Visual Instruction Set (VIS) version 3.0
<code>sparcfmaf</code>	Enables the compiler to use instructions from the SPARC-V9 instruction set, plus the UltraSPARC extensions, including the Visual Instruction Set (VIS) version 1.0, the UltraSPARC-III extensions, including the Visual Instruction Set (VIS) version 2.0, and the SPARC64 VI extensions for floating-point multiply-add. You must use <code>-xarch=sparcfmaf</code> in conjunction with <code>fma=fused</code> and some optimization level to get the compiler to attempt to find opportunities to use the multiply-add instructions automatically.
<code>sparcima</code>	Compile for the <code>sparcima</code> version of the SPARC-V9 ISA. Enables the compiler to use instructions from the SPARC-V9 instruction set, plus the UltraSPARC extensions, including the Visual Instruction Set (VIS) version 1.0, the UltraSPARC-III extensions, including the Visual Instruction Set (VIS) version 2.0, the SPARC64 VI extensions for floating-point multiply-add, and the SPARC64 VII extensions for integer multiply-add.

TABLE A-23 The `-xarch` Flags for SPARC Platforms (Continued)

Flag	Meaning
v9	Is equivalent to <code>-m64 -xarch=sparc</code> . Legacy makefiles and scripts that use <code>-xarch=v9</code> to obtain the 64-bit memory model need only use <code>-m64</code> .
v9a	Is equivalent to <code>-m64 -xarch=sparcv9</code> and is provided for compatibility with earlier releases.
v9b	Is equivalent to <code>-m64 -xarch=sparcv9s2</code> and is provided for compatibility with earlier releases.

Also note the following:

- Object binary files (`.o`) compiled with `generic`, `sparc`, `sparcv9s2`, `sparcv9s3`, `sparcfmaf`, `sparcima` can be linked and can execute together, but can only run on a processor supporting all the instruction sets linked.
- For any particular choice, the generated executable might not run or run much more slowly on legacy architectures. Also, because quad-precision (long double) floating-point instructions are not implemented in any of these instruction set architectures, the compiler does not use these instructions in the code it generates.

A.2.109.2 `-xarch` Flags for x86

The following table lists the `-xarch` flags on x86 platforms.

TABLE A-24 The `-xarch` Flags on x86

Flag	Meaning
amd64	Is equivalent to <code>-m64 -xarch=sse2</code> (Solaris only). Legacy makefiles and scripts that use <code>-xarch=amd64</code> to obtain the 64-bit memory model need only use <code>-m64</code> .
amd64a	Is equivalent to <code>-m64 -xarch=sse2a</code> (Solaris only).
generic	Uses the instruction set common to most processors. This is the default, and is equivalent to <code>pentium_pro</code> when compiling with <code>-m32</code> , and <code>sse2</code> with <code>-m64</code> .
generic64	Compile for good performance on most 64-bit platforms. (Solaris only). This option is equivalent to <code>-m64 -xarch=generic</code> and is provided for compatibility with earlier releases. Use <code>-m64</code> to specify 64-bit compilation instead of <code>-xarch=generic64</code> .
native	Compile for good performance on this system. The compiler chooses the appropriate setting for the current system processor it is running on.
native64	Compile for good performance on this system (Solaris only). This option is equivalent to <code>-m64 -xarch=native</code> and is provided for compatibility with earlier releases.
pentium_pro	Limits the instruction set to the 32-bit <code>pentium_pro</code> architecture.

TABLE A-24 The `-xarch` Flags on x86 (Continued)

Flag	Meaning
<code>pentium_proa</code>	Adds the AMD extensions (3DNow!, 3DNow! extensions, and MMX extensions) to the 32-bit <code>pentium_pro</code> architecture.
<code>sse</code>	Adds the SSE instruction set to the <code>pentium_pro</code> architecture.
<code>ssea</code>	Adds the AMD extensions (3DNow!, 3DNow! extensions, and MMX extensions) to the 32-bit SSE architecture.
<code>sse2</code>	Adds the SSE2 instruction set to the <code>pentium_pro</code> architecture.
<code>sse2a</code>	Adds the AMD extensions (3DNow!, 3DNow! extensions, and MMX extensions) to the 32-bit SSE2 architecture.
<code>sse3</code>	Adds the SSE3 instruction set to SSE2 instruction set.
<code>ssse3</code>	Supplements the <code>pentium_pro</code> , SSE, SSE2, and SSE3 instruction sets with the SSSE3 instruction set.
<code>sse4_1</code>	Supplements the <code>pentium_pro</code> , SSE, SSE2, SSE3, and SSSE3 instruction sets with the SSE4.1 instruction set.
<code>sse4_2</code>	Supplements the <code>pentium_pro</code> , SSE, SSE2, SSE3, SSSE3, and SSE4.1 instruction sets with the SSE4.2 instruction set.
<code>amdsse4a</code>	Uses the AMD SSE4a Instruction set.

A.2.109.3 Special x86 Notes

There are some important issues to be aware of when compiling for x86 Solaris platforms.

The legacy Sun-style parallelization pragmas are not available on x86. Use OpenMP instead. See the *Solaris Studio OpenMP API User's Guide* for information on converting legacy parallelization directives to OpenMP.

Programs compiled with `-xarch` set to `sse`, `sse2`, `sse2a`, `sse3`, or beyond must be run only on platforms that provide these extensions and features.

Solaris OS releases are SSE/SSE2-enabled on Pentium 4-compatible platforms. Earlier versions of Solaris OS are not SSE/SSE2-enabled. If an instruction set selected by `-xarch` is not enabled in the running Solaris OS, the compiler will not be able to generate or link code for that instruction set.

If you compile and link in separate steps, always link using the compiler and using the same `-xarch` setting to ensure that the correct startup routine is linked.

Numerical results on x86 may differ from results on SPARC due to the x86 80-bit floating-point registers. To minimize these differences, use the `-fstore` option or compile with `-xarch=sse2` if the hardware supports SSE2.

Numerical results can also differ between Solaris and Linux because the intrinsic math libraries (for example, `sin(x)`) are not the same.

A.2.109.4 Binary Compatibility Verification

Starting with Solaris Studio 11 and the Solaris 10 OS, program binaries compiled and built using these specialized `-xarch` hardware flags are verified that they are being run on the appropriate platform.

On systems prior to Solaris 10, no verification is done and it is the user's responsibility to ensure objects built using these flags are deployed on suitable hardware.

Running programs compiled with these `-xarch` options on platforms that are not enabled with the appropriate features or instruction set extensions could result in segmentation faults or incorrect results occurring without any explicit warning messages.

This warning extends also to programs that employ `.il` inline assembly language functions or `__asm()` assembler code that utilize SSE, SSE2, SSE2a, and SSE3 instructions and extensions.

A.2.109.5 Interactions

Although this option can be used alone, it is part of the expansion of the `-xtarget` option and may be used to override the `-xarch` value that is set by a specific `-xtarget` option. For example, `-xtarget=ultra2` expands to `-xarch=v8plusa -xchip=ultra2 -xcache=16/32/1:512/64/1`. In the following command `-xarch=v8plusb` overrides the `-xarch=v8plusa` that is set by the expansion of `-xtarget=ultra2`.

```
example% CC -xtarget=ultra2 -xarch=v8plusb foo.cc
```

Use of `-compat[=4]` with `-xarch=generic64`, `-xarch=native64`, `-xarch=v9`, `-xarch=v9a`, or `-xarch=v9b` is not supported.

A.2.109.6 Warnings

If you use this option with optimization, the appropriate choice can provide good performance of the executable on the specified architecture. An inappropriate choice, however, might result in serious degradation of performance or in a binary program that is not executable on the intended target platform.

If you compile and link in separate steps, make sure you specify the same value for `-xarch` in both steps.

A.2.110 -xautopar

Note – This option does not accept OpenMP parallelization directives. The Sun-specific MP pragmas have been deprecated and are no longer supported. See the *Solaris Studio OpenMP API User's Guide* for migration information to the directives of the standard.

(SPARC) Turns on automatic parallelization for multiple processors. Does dependence analysis (analyze loops for inter-iteration data dependence) and loop restructuring. If optimization is not at -xO3 or higher, optimization is raised to -xO3 and a warning is issued.

Avoid -xautopar if you do your own thread management.

To achieve faster execution, this option requires a multiple processor system. On a single-processor system, the resulting binary usually runs slower.

To run a parallelized program in a multithreaded environment, you must set the OMP_NUM_THREADS environment variable prior to execution. See the *Solaris Studio OpenMP API User's Guide* for more information.

If you use -xautopar and compile and link in one step, then linking automatically includes the microtasking library and the threads-safe C runtime library. If you use -xautopar and compile and link in separate steps, then you must also link with -xautopar.

A.2.110.1 See Also

“A.2.158 -xopenmp[=i]” on page 313

A.2.111 -xbinopt={prepare|off}

(SPARC) Instructs the compiler to prepare the binary for later optimizations, transformations and analysis, see `binopt(1)`. This option may be used for building executables or shared objects. If you compile in separate steps, -xbinopt must appear on both compile and link steps:

```
example% cc -c -xO1 -xbinopt=prepare a.c b.c
example% cc -o myprog -xbinopt=prepare a.o
```

If some source code is not available for compilation, this option may still be used to compile the remainder of the code. It should then be used in the link step that creates the final binary. In such a situation, only the code compiled with this option can be optimized, transformed or analyzed.

A.2.111.1 Defaults

The default is -xbinopt=off.

Interactions

This option must be used with optimization level `-xO1` or higher to be effective. There is a modest increase in size of the binary when built with this option.

Compiling with `-xbinopt=prepare` and `-g` increases the size of the executable by including debugging information.

A.2.112 `-xbuiltin[={%all|%none}]`

Enables or disables better optimization of standard library calls.

By default, the functions declared in standard library headers are treated as ordinary functions by the compiler. However, some of those functions can be recognized as “intrinsic” or “built-in” by the compiler. When treated as a built-in, the compiler can generate more efficient code. For example, the compiler can recognize that some functions have no side effects, and always return the same output given the same input. Some functions can be generated inline directly by the compiler. See the `er_src(1)` man page for an explanation of how to read compiler commentary in object files to determine for which functions the compiler actually makes a substitution.

The `-xbuiltin=%all` option asks the compiler to recognize as many of the built-in standard functions as possible. The exact list of recognized functions varies with the version of the compiler code generator.

The `-xbuiltin=%none` option results in the default compiler behavior, and the compiler does not do any special optimizations for built-in functions.

A.2.112.1 Defaults

If the `-xbuiltin` option is not specified, then the compiler assumes `-xbuiltin=%none`.

If only `-xbuiltin` is specified, then the compiler assumes `-xbuiltin=%all`.

Interactions

The expansion of the macro `-fast` includes `-xbuiltin=%all`.

Examples

The following compiler command requests special handling of the standard library calls.

```
example% CC -xbuiltin -c foo.cc
```

The following compiler command requests that there be no special handling of the standard library calls. Note that the expansion of the macro `-fast` includes `-xbuiltin=%all`.

```
example% CC -fast -xbuiltin=%none -c foo.cc
```

A.2.113 `-xcache=c`

Defines cache properties for use by the optimizer. This option does not guarantee that any particular cache property is used.

Note – Although this option can be used alone, it is part of the expansion of the `-xtarget` option; its primary use is to override a value supplied by the `-xtarget` option.

This release introduces an optional property `[/ti]` which sets the number of threads that can share the cache.

A.2.113.1 Values

`c` must be one of the following values.

TABLE A-25 The `-xcache` Values

Value	Meaning
<code>generic</code>	This is the default value which directs the compiler to use cache properties for good performance on most x86 and SPARC processors, without major performance degradation on any of them. With each new release, these best timing properties will be adjusted, if appropriate.
<code>native</code>	Set the parameters for the best performance on the host environment.
<code>s1/l1/a1[/t1]</code>	Defines level 1 cache properties
<code>s1/l1/a1[/t1]:s2/l2/a2[/t2]</code>	Defines level 1 and 2 cache properties
<code>s1/l1/a1[/t1]:s2/l2/a2[/t2]:s3/l3/a3[/t3]</code>	Defines level 1, 2, and 3 cache properties

The definitions of the cache properties `si/li/ai/ti` are as follows:

Property	Definition
<code>s<i>i</i></code>	The <i>size</i> of the data cache at level <i>i</i> , in kilobytes
<code>l<i>i</i></code>	The <i>line size</i> of the data cache at level <i>i</i> , in bytes
<code>a<i>i</i></code>	The <i>associativity</i> of the data cache at level <i>i</i>

For example, `i=1` designates level 1 cache properties, `s1/l1/a1`.

Defaults

If `-xcache` is not specified, the default `-xcache=generic` is assumed. This value directs the compiler to use cache properties for good performance on most SPARC processors, without major performance degradation on any of them.

If you do not specify a value for `t`, the default is 1.

Examples

`-xcache=16/32/4:1024/32/1` specifies the following:

Level 1 Cache Has	Level 2 Cache Has
16 Kbytes	1024 Kbytes
32 bytes line size	32 bytes line size
4-way associativity	Direct mapping associativity

See also

`-xtarget=t`

A.2.114 `-xcg[89|92]`

(SPARC) Obsolete, do not use this option. Current Solaris operating system software no longer support SPARC V7 architecture. Compiling with this option generates code that runs slower on current SPARC platforms. Use `-x0` instead and take advantage of compiler defaults for `-xarch`, `-xchip`, and `-xcache`.

A.2.115 `-xchar[=o]`

The option is provided solely for the purpose of easing the migration of code from systems where the `char` type is defined as unsigned. Unless you are migrating from such a system, do not use this option. Only code that relies on the sign of a `char` type needs to be rewritten to explicitly specify signed or unsigned.

A.2.115.1 Values

You can substitute one of the following for `o`:

TABLE A-26 The -xchar Values

Value	Meaning
signed	Treat character constants and variables declared as char as signed. This impacts the behavior of compiled code, it does not affect the behavior of library routines.
s	Equivalent to signed
unsigned	Treat character constants and variables declared as char as unsigned. This impacts the behavior of compiled code, it does not affect the behavior of library routines.
u	Equivalent to unsigned

Defaults

If you do not specify `-xchar`, the compiler assumes `-xchar=s`.

If you specify `-xchar`, but do not specify a value, the compiler assumes `-xchar=s`.

Interactions

The `-xchar` option changes the range of values for the type `char` only for code compiled with `-xchar`. This option does not change the range of values for type `char` in any system routine or header file. In particular, the value of `CHAR_MAX` and `CHAR_MIN`, as defined by `limits.h`, do not change when this option is specified. Therefore, `CHAR_MAX` and `CHAR_MIN` no longer represent the range of values encodable in a plain `char`.

Warnings

If you use `-xchar=unsigned`, be particularly careful when you compare a `char` against a predefined system macro because the value in the macro may be signed. This is most common for any routine that returns an error code which is accessed through a macro. Error codes are typically negative values so when you compare a `char` against the value from such a macro, the result is always false. A negative number can never be equal to any value of an unsigned type.

It is strongly recommended that you never use `-xchar` to compile routines for any interface exported through a library. The Solaris ABI specifies type `char` as signed, and system libraries behave accordingly. The effect of making `char` unsigned has not been extensively tested with system libraries. Instead of using this option, modify your code so that it does not depend on whether type `char` is signed or unsigned. The signedness of type `char` varies among compilers and operating systems.

A.2.116 -xcheck[=*i*]

SPARC: Compiling with `-xcheck=stkovf` adds a runtime check for stack overflow of the main thread in a singly-threaded program as well as slave-thread stacks in a multithreaded program. If a stack overflow is detected, a SIGSEGV is generated. If your application needs to handle a SIGSEGV caused by a stack overflow differently than it handles other address-space violations, see `sigaltstack(2)`.

A.2.116.1 Values

i must be one of the following:

TABLE A-27 The -xcheck Values

Value	Meaning
<code>%all</code>	Perform all checks.
<code>%none</code>	Perform no checks.
<code>stkovf</code>	Turns on stack-overflow checking.
<code>no%stkovf</code>	Turns off stack-overflow checking.
<code>init_local</code>	Initialize local variables. See the C User's Guide for details.
<code>no%init_local</code>	Do not initialize local variables. (Default)

Defaults

If you do not specify `-xcheck`, the compiler defaults to `-xcheck=%none`.

If you specify `-xcheck` without any arguments, the compiler defaults to `-xcheck=%none`.

The `-xcheck` option does not accumulate on the command line. The compiler sets the flag in accordance with the last occurrence of the command.

A.2.117 -xchip=C

Specifies target processor for use by the optimizer.

The `-xchip` option specifies timing properties by specifying the target processor. This option affects:

- The ordering of instructions—that is, scheduling
- The way the compiler uses branches
- The instructions to use in cases where semantically equivalent alternatives are available

Note – Although this option can be used alone, it is part of the expansion of the `-xtarget` option; its primary use is to override a value supplied by the `-xtarget` option.

A.2.117.1 Values

`c` must be one of the following values.

TABLE A-28 The `-xchip` Values

Platform	Value	Optimize Using Timing Properties for
SPARC	generic	good performance on most SPARC processors
	native	good performance on the system on which the compiler is running
	old	processors earlier than the SuperSPARC processor
	sparc64vi	SPARC64 VI processor
	sparc64vii	SPARC64 VII processor
	super	SuperSPARC processor
	super2	SuperSPARC II processor
	micro	microSPARC processor
	micro2	microSPARC II processor
	hyper	hyperSPARC processor
	hyper2	hyperSPARC II processor
	powerup	the Weitek PowerUp processor
	ultra	UltraSPARC processor
	ultra2	UltraSPARC II processor
	ultra2e	UltraSPARC IIe processor
	ultra2i	UltraSPARC IIi processor
	ultra3	UltraSPARC III processor
	ultra3cu	UltraSPARC III Cu processor
	ultra3i	UltraSparc IIIi processors.
	ultra4	UltraSPARC IV processors.

TABLE A-28 The `-xchip` Values (Continued)

Platform	Value	Optimize Using Timing Properties for
	<code>ultra4plus</code>	UltraSPARC IVplus processor.
	<code>ultraT1</code>	UltraSPARC T1 processor.
	<code>ultraT2</code>	UltraSPARC T2 processor.
	<code>ultraT2plus</code>	UltraSPARC T2+ processor.
	<code>ultraT3</code>	UltraSPARC T3 processor.
x86	<code>generic</code>	most x86 processors
	<code>core2</code>	Intel Core2 processor
	<code>nehalem</code>	Intel Nehalem processor
	<code>opteron</code>	AMD Opteron processor
	<code>penryn</code>	Intel Penryn processor
	<code>pentium</code>	Intel Pentium processor
	<code>pentium_pro</code>	Intel Pentium Pro processor
	<code>pentium3</code>	Intel Pentium 3 style processor
	<code>pentium4</code>	Intel Pentium 4 style processor
	<code>amdfam10</code>	AMD AMDFAM10 processor

Defaults

On most processors, `generic` is the default value that directs the compiler to use the best timing properties for good performance without major performance degradation on any of the processors.

A.2.118 `-xcode=a`

SPARC: Specifies the code address space.

Note – You should build shared objects by specifying `-xcode=pic13` or `-xcode=pic32`. Shared objects built without `pic13` or `pic32` will not work correctly, and might not build at all.

A.2.118.1 Values

`a` must be one of the following values.

TABLE A-29 The -xcode Values

Value	Meaning
abs32	Generates 32-bit absolute addresses, which are fast, but have limited range. Code + data + bss size is limited to 2**32 bytes.
abs44	SPARC: Generates 44-bit absolute addresses, which have moderate speed and moderate range. Code + data + bss size is limited to 2**44 bytes. Available only on 64-bit architectures. Do not use this value with dynamic (shared) libraries.
abs64	SPARC: Generates 64-bit absolute addresses, which are slow, but have full range. Available only on 64-bit architectures.
pic13	Generates position-independent code (small model), which is fast, but has limited range. Equivalent to <code>-Kpic</code> . Permits references to at most 2**11 unique external symbols on 32-bit architectures; 2**10 on 64-bit.
pic32	Generates position-independent code (large model), which might not be as fast as <code>pic13</code> , but has full range. Equivalent to <code>-KPIC</code> . Permits references to at most 2**30 unique external symbols on 32-bit architectures; 2**29 on 64-bit.

To determine whether to use `-xcode=pic13` or `-xcode=pic32`, check the size of the Global Offset Table (GOT) by using `elfdump -c` (see the `elfdump(1)` man page for more information) and for the section header, `sh_name: .got`. The `sh_size` value is the size of the GOT. If the GOT is less than 8,192 bytes, specify `-xcode=pic13`, otherwise specify `-xcode=pic32`.

In general, use the following guidelines to determine how you should use `-xcode`:

- If you are building an executable you should not use `-xcode=pic13` or `-xcode=pic32`.
- If you are building an archive library only for linking into executables you should not use `-xcode=pic13` or `-xcode=pic32`.
- If you are building a shared library, start with `-xcode=pic13` and once the GOT size exceed 8,192 bytes, use `-xcode=pic32`.
- If you are building an archive library for linking into shared libraries you should just use `-xcode=pic32`.

Defaults

The default is `-xcode=abs32` for 32-bit architectures. The default for 64-bit architectures is `-xcode=abs44`.

When building shared dynamic libraries, the default `-xcode` values of `abs44` and `abs32` will not work with 64-bit architectures. Specify `-xcode=pic13` or `-xcode=pic32` instead. There are two nominal performance costs with `-xcode=pic13` and `-xcode=pic32` on SPARC:

- A routine compiled with either `-xcode=pic13` or `-xcode=pic32` executes a few extra instructions upon entry to set a register to point at a table (`_GLOBAL_OFFSET_TABLE_`) used for accessing a shared library's global or static variables.
- Each access to a global or static variable involves an extra indirect memory reference through `_GLOBAL_OFFSET_TABLE_`. If the compile is done with `-xcode=pic32`, there are two additional instructions per global and static memory reference.

When considering the above costs, remember that the use of `-xcode=pic13` and `-xcode=pic32` can significantly reduce system memory requirements, due to the effect of library code sharing. Every page of code in a shared library compiled `-xcode=pic13` or `-xcode=pic32` can be shared by every process that uses the library. If a page of code in a shared library contains even a single non-pic (that is, absolute) memory reference, the page becomes nonsharable, and a copy of the page must be created each time a program using the library is executed.

The easiest way to tell whether or not a `.o` file has been compiled with `-xcode=pic13` or `-xcode=pic32` is with the `nm` command:

```
% nm file.o | grep _GLOBAL_OFFSET_TABLE_ U _GLOBAL_OFFSET_TABLE_
```

A `.o` file containing position-independent code contains an unresolved external reference to `_GLOBAL_OFFSET_TABLE_`, as indicated by the letter U.

To determine whether to use `-xcode=pic13` or `-xcode=pic32`, use `nm` to identify the number of distinct global and static variables used or defined in the library. If the size of `_GLOBAL_OFFSET_TABLE_` is under 8,192 bytes, you can use `-Kpic`. Otherwise, you must use `-xcode=pic32`.

A.2.119 `-xcrossfile[=n]`

Obsolete, do not use. Use `-xipo` instead.

A.2.120 `-xdebugformat=[stabs | dwarf]`

The compiler is migrating the format of debugger information from the stabs format to the dwarf format as specified in 'DWARF Debugging Information Format'. The default setting is `-xdebugformat=dwarf`.

If you maintain software which reads debugging information, you now have the option to transition your tools from the stabs format to the dwarf format.

Use this option as a way of accessing the new format for the purpose of porting tools. There is no need to use this option unless you maintain software which reads debugger information, or unless a specific tool tells you that it requires debugger information in one of these formats.

TABLE A-30 The `-xdebugformat` Flags

Value	Meaning
<code>stabs</code>	<code>-xdebugformat=stabs</code> generates debugging information using the stabs standard format.
<code>dwarf</code>	<code>-xdebugformat=dwarf</code> generates debugging information using the dwarf standard format.

If you do not specify `-xdebugformat`, the compiler assumes `-xdebugformat=stabs`. This option requires an argument.

This option affects the format of the data that is recorded with the `-g` option. Some small amount of debugging information is recorded even without `-g`, and the format of that information is also controlled with this option. So `-xdebugformat` has an effect even when `-g` is not used.

The dbx and Performance Analyzer software understand both stabs and dwarf format so using this option does not have any effect on the functionality of either tool.

Note – This is a transitional interface so expect it to change in incompatible ways from release to release, even in a minor release. The details of any specific fields or values in either stabs or dwarf are also evolving.

See also the `dumpstabs(1)` and `dwarfdump(1)` man pages for more information.

A.2.121 `-xdepend=[yes|no]`

(SPARC) Analyzes loops for inter-iteration data dependencies and does loop restructuring, including loop interchange, loop fusion, scalar replacement, and elimination of “dead array” assignments.

On SPARC, `-xdepend` defaults to `-xdepend=on` for all optimization levels `-xO3` and above. Otherwise `-xdepend` defaults to `-xdepend=off`. Specifying an explicit setting of `-xdepend` overrides any default setting.

On x86, `-xdepend` defaults to `-xdepend=off`. When `-xdepend` is specified and optimization is not at `-xO3` or higher, the compiler raises the optimization to `-xO3` and issues a warning.

Specifying `-xdepend` without an argument is equivalent to `-xdepend=yes`.

Dependency analysis is included in `-xautopar`. Dependency analysis is done at compile time.

Dependency analysis may help on single-processor systems. However, if you use `-xdepend` on single-processor systems, you should not also specify `-xautopar`, because the `-xdepend` optimization will be done for a multiprocessor system.

See Also: `-xprefetch_auto_type`

A.2.122 `-xdumpmacros[=value[, value...]]`

Use this option when you want to see how macros are behaving in your program. This option provides information such as macro defines, undefines, and instances of usage. It prints output to the standard error (`stderr`), based on the order macros are processed. The `-xdumpmacros` option is in effect through the end of the file or until it is overridden by the `dumpmacros` or `end_dumpmacros` pragma. See “[B.2.5 #pragma dumpmacros](#)” on page 352.

A.2.122.1 Values

You can substitute the following arguments in place of *value*:

TABLE A-31 The `-xdumpmacros` Values

Value	Meaning
<code>[no]defs</code>	[Do not] Print all macro defines
<code>[no]undefs</code>	[Do not] Print all macro undefines
<code>[no]use</code>	[Do not] Print information about macros used
<code>[no]loc</code>	[Do not] Print location (path name and line number) also for <code>defs</code> , <code>undefs</code> , and <code>use</code>
<code>[no]conds</code>	[Do not] Print use information for macros used in conditional directives
<code>[no]sys</code>	[Do not] Print all macros defines, undefines, and use information for macros in system header files
<code>%all</code>	Sets the option to <code>-xdumpmacros=defs,undefs,use,loc,conds,sys</code> . A good way to use this argument is in conjunction with the <code>[no%]</code> form of the other arguments. For example, <code>-xdumpmacros=%all,no%sys</code> would exclude system header macros from the output but still provide information for all other macros.
<code>%none</code>	Do not print any macro information

The option values accumulate so specifying `-xdumpmacros=sys -xdumpmacros=undefs` has the same effect as `-xdumpmacros=undefs,sys`.

Note – The sub-options `loc`, `conds`, and `sys` are qualifiers for `defs`, `undefs` and `use` options. By themselves, `loc`, `conds`, and `sys` have no effect. For example, `-xdumpmacros=loc,conds,sys` has no effect.

Defaults

If you specify `-xdumpmacros` without any arguments, it means `-xdumpmacros=defs, undefs, sys`. If you do not specify `-xdumpmacros`, it defaults to `-xdumpmacros=%none`.

Examples

If you use the option `-xdumpmacros=use,no%loc`, the name of each macro that is used is printed only once. However, if you want more detail, use the option `-xdumpmacros=use,loc` so the location and macro name is printed every time a macro is used.

Consider the following file `t.c`:

```
example% cat t.c
#ifdef FOO
#undef FOO
#define COMPUTE(a, b) a+b
#else
#define COMPUTE(a,b) a-b
#endif
int n = COMPUTE(5,2);
int j = COMPUTE(7,1);
#if COMPUTE(8,3) + NN + MM
int k = 0;
#endif
```

The following examples show the output for file `t.c` based on the `defs`, `undefs`, `sys`, and `loc` arguments.

```
example% CC -c -xdumpmacros -DFOO t.c
#define __SunOS_5_9 1
#define __SUNPRO_CC 0x590
#define unix 1
#define sun 1
#define sparc 1
#define __sparc 1
#define __unix 1
#define __sun 1
#define __BUILTIN_VA_ARG_INCR 1
#define __SVR4 1
#define __SUNPRO_CC_COMPAT 5
#define __SUN_PREFETCH 1
#define FOO 1
#undef FOO
#define COMPUTE(a, b) a + b

example% CC -c -xdumpmacros=defs,undefs,loc -DFOO -UBAR t.c
command line: #define __SunOS_5_9 1
command line: #define __SUNPRO_CC 0x590
command line: #define unix 1
command line: #define sun 1
command line: #define sparc 1
command line: #define __sparc 1
```

```

command line: #define __unix 1
command line: #define __sun 1
command line: #define __BUILTIN_VA_ARG_INCR 1
command line: #define __SVR4 1
command line: #define __SUNPRO_CC_COMPAT 5
command line: #define __SUN_PREFETCH 1
command line: #define FOO 1
command line: #undef BAR
t.c, line 2: #undef FOO
t.c, line 3: #define COMPUTE(a, b) a + b

```

The following examples show how the use, loc, and conds arguments report macro behavior in file t.c:

```

example% CC -c -xdumpmacros=use t.c
used macro COMPUTE

```

```

example% CC -c -xdumpmacros=use,loc t.c
t.c, line 7: used macro COMPUTE
t.c, line 8: used macro COMPUTE

```

```

example% CC -c -xdumpmacros=use,conds t.c
used macro FOO
used macro COMPUTE
used macro NN
used macro MM

```

```

example% CC -c -xdumpmacros=use,conds,loc t.c
t.c, line 1: used macro FOO
t.c, line 7: used macro COMPUTE
t.c, line 8: used macro COMPUTE
t.c, line 9: used macro COMPUTE
t.c, line 9: used macro NN
t.c, line 9: used macro MM

```

Consider the file y.c:

```

example% cat y.c
#define X 1
#define Y X
#define Z Y
int a = Z;

```

Here is the output from -xdumpmacros=use,loc based on the macros in y.c:

```

example% CC -c -xdumpmacros=use,loc y.c
y.c, line 4: used macro Z
y.c, line 4: used macro Y
y.c, line 4: used macro X

```

See Also

Use the dumpmacros pragma and the end_dumpmacros pragma when you want to override the scope of -xdumpmacros.

A.2.123 -xe

Checks only for syntax and semantic errors. When you specify `-xe`, the compiler does not produce any object code. The output for `-xe` is directed to `stderr`.

Use the `-xe` option if you do not need the object files produced by compilation. For example, if you are trying to isolate the cause of an error message by deleting sections of code, you can speed the edit and compile cycle by using `-xe`.

A.2.123.1 See Also

`-c`

A.2.124 -xF[=*v*[,*v*...]]

Enables optimal reordering of functions and variables by the linker.

This option instructs the compiler to place functions and/or data variables into separate section fragments, which enables the linker, using directions in a mapfile specified by the linker's `-M` option, to reorder these sections to optimize program performance. Generally, this optimization is only effective when page fault time constitutes a significant fraction of program run time.

Reordering of variables can help solve the following problems which negatively impact run-time performance:

- Cache and page contention caused by unrelated variables that are near each other in memory.
- Unnecessarily large work-set size as a result of related variables which are not near each other in memory.
- Unnecessarily large work-set size as a result of unused copies of weak variables that decrease the effective data density.

Reordering variables and functions for optimal performance requires the following operations:

1. Compiling and linking with `-xF`.
2. Following the instructions in the “Program Performance Analysis Tools” manual regarding how to generate a mapfile for functions or following the instructions in the “Linker and Libraries Guide” regarding how to generate a mapfile for data.
3. Relinking with the new mapfile by using the linker's `-M` option.
4. Re-executing under the Analyzer to verify improvement.

A.2.124.1 Values

v can be one or more of the following:

TABLE A-32 The -xF Values

Value	Meaning
[no%]func	[Do not] fragment functions into separate sections.
[no%]gbldata	[Do not] fragment global data (variables with external linkage) into separate sections.
[no%]lclldata	[Do not] fragment local data (variables with internal linkage) into separate sections.
%all	Fragment functions, global data, and local data.
%none	Fragment nothing.

Defaults

If you do not specify -xF, the default is -xF=%none. If you specify -xF without any arguments, the default is -xF=%none, func.

Interactions

Using -xF=lclldata inhibits some address calculation optimizations, so you should only use this flag when it is experimentally justified.

See also

analyzer(1), ld(1) man pages

A.2.125 -xhelp=flags

Displays a brief description of each compiler option.

A.2.126 -xhelp=readme

Displays contents of the online readme file.

The readme file is paged by the command specified in the environment variable, PAGER. If PAGER is not set, the default paging command is more.

A.2.127 -xhwcpof

(SPARC) Enables compiler support for hardware counter-based profiling.

When `-xhwcprof` is enabled, the compiler generates information that helps tools associate profiled load and store instructions with the data-types and structure members (in conjunction with symbolic information produced with `-gto` which they refer. It associates profile data with the data space of the target, rather than the instruction space, and provides insight into behavior that is not easily obtained from only instruction profiling.

You can compile a specified set of object files with `-xhwcprof`. However, `-xhwcprof` is most useful when applied to all object files in the application. This will provide coverage to identify and correlate all memory references distributed in the application's object files.

If you are compiling and linking in separate steps, use `-xhwcprof` at link time as well. Future extensions to `-xhwcprof` may require its use at link time.

An instance of `-xhwcprof=enable` or `-xhwcprof=disable` overrides all previous instances of `-xhwcprof` in the same command line.

`-xhwcprof` is disabled by default. Specifying `-xhwcprof` without any arguments is the equivalent to `-xhwcprof=enable`.

`-xhwcprof` requires that optimization be turned on and that the debug data format be set to DWARF (`-xdebugformat=dwarf`).

The combination of `-xhwcprof` and `-g` increases compiler temporary file storage requirements by more than the sum of the increases due to `-xhwcprof` and `-g` specified alone.

The following command compiles `example.cc` and specifies support for hardware counter profiling and symbolic analysis of data types and structure members using DWARF symbols:

```
example% CC -c -O -xhwcprof -g -xdebugformat=dwarf example.cc
```

For more information on hardware counter-based profiling, see the *Program Performance Analysis Tools* manual.

A.2.128 **-xia**

Links the appropriate interval arithmetic libraries and sets a suitable floating-point environment.

Note – The C++ interval arithmetic library is compatible with interval arithmetic as implemented in the Fortran compiler.

On x86 platforms, requires support of SSE2 instruction set.

A.2.128.1 Expansions

The `-xia` option is a macro that expands to `-fsimple=0 -ftrap=%none -fns=no -library=interval`. If you use intervals and override what is set by `-xia` by specifying a different flag for `-fsimple`, `-ftrap`, `-fns` or `-library`, you may cause the compiler to exhibit incorrect behavior.

Interactions

To use the interval arithmetic libraries, include `<suninterval.h>`.

When you use the interval arithmetic libraries, you must include one of the following libraries: `libc`, `Cstd`, or `iostreams`. See `-library` for information on including these libraries.

Warnings

If you use intervals and you specify different values for `-fsimple`, `-ftrap`, or `-fns`, then your program may have incorrect behavior.

C++ interval arithmetic is experimental and evolving. The specifics may change from release to release.

See Also

`-library`

A.2.129 `-xinline[=func_spec[,func_spec...]]`

Specifies which user-written routines can be inlined by the optimizer at `-x03` levels or higher.

A.2.129.1 Values

func_spec must be one of the following values.

TABLE A-33 The `-xinline` Values

Value	Meaning
<code>%auto</code>	Enable automatic inlining at optimization levels <code>-x04</code> or higher. This argument tells the optimizer that it can inline functions of its choosing. Note that without the <code>%auto</code> specification, automatic inlining is normally turned off when explicit inlining is specified on the command line by <code>-xinline=[no%]<i>func_name</i>...</code>

TABLE A-33 The `-xinline` Values (Continued)

Value	Meaning
<i>func_name</i>	Strongly request that the optimizer inline the function. If the function is not declared as extern "C", the value of <i>func_name</i> must be mangled. You can use the <code>nm</code> command on the executable file to find the mangled function names. For functions declared as extern "C", the names are not mangled by the compiler.
<code>no%func_name</code>	When you prefix the name of a routine on the list with <code>no%</code> , the inlining of that routine is inhibited. The rule about mangled names for <i>func_name</i> applies to <code>no%func_name</code> as well.

Only routines in the file being compiled are considered for inlining unless you use `-xipo[=1|2]`. The optimizer decides which of these routines are appropriate for inlining.

Defaults

If the `-xinline` option is not specified, the compiler assumes `-xinline=%auto`.

If `-xinline=` is specified with no arguments, no functions are inlined, regardless of the optimization level.

Examples

To enable automatic inlining while disabling inlining of the function declared `int foo()`, use

```
example% CC -xO5 -xinline=%auto,no%_1cDfoo6F_i_ -c a.cc
```

To strongly request the inlining of the function declared as `int foo()`, and to make all other functions as the candidates for inlining, use

```
example% CC -xO5 -xinline=%auto,_1cDfoo6F_i_ -c a.cc
```

To strongly request the inlining of the function declared as `int foo()`, and to not allow inlining of any other functions, use

```
example% CC -xO5 -xinline=_1cDfoo6F_i_ -c a.cc
```

Interactions

The `-xinline` option has no effect for optimization levels below `-xO3`. At `-xO4` and higher, the optimizer decides which functions should be inlined, and does so without the `-xinline` option being specified. At `-xO4` and higher, the compiler also attempts to determine which functions will improve performance if they are inlined.

A routine is inlined if any of the following conditions apply.

- Optimization is `-xO3` or greater
- Inlining is judged to be profitable and safe
- The function is in the file being compiled, or the function is in a file that was compiled with `-xipo[=1|2]`

Warnings

If you force the inlining of a function with `-xinline`, you might actually diminish performance.

See Also

[“A.2.136 `-xldscope={v}`” on page 299](#)

A.2.130 `-xinstrument=[no%]datarace`

Specify this option to compile and instrument your program for analysis by the Thread Analyzer. For more information on the Thread Analyzer, see [tha\(1\)](#) for details.

You can then use the Performance Analyzer to run the instrumented program with `collect -r races` to create a data-race-detection experiment. You can run the instrumented code standalone but it runs more slowly.

You can specify `-xinstrument=no%datarace` to turn off preparation of source code for the thread analyzer. This is the default.

It is illegal to specify `-xinstrument` without an argument.

If you compile and link in separate steps, you must specify `-xinstrument=datarace` in both the compilation and linking steps.

This option defines the preprocessor token `__THA_NOTIFY`. You can specify `#ifdef __THA_NOTIFY` to guard calls to [libtha\(3\)](#) routines.

This option also sets `-g`.

A.2.131 `-xipo[={0|1|2}]`

Performs interprocedural optimizations.

The `-xipo` option performs partial-program optimizations by invoking an interprocedural analysis pass. It performs optimizations across all object files in the link step, and the optimizations are not limited to just the source files on the compile command. However, whole-program optimizations performed with `-xipo` do not include assembly (`.s`) source files.

The `-xipo` option is particularly useful when compiling and linking large multifile applications. Object files compiled with this flag have analysis information compiled within them that enables interprocedural analysis across source and precompiled program files. However, analysis and optimization is limited to the object files compiled with `-xipo`, and does not extend to object files or libraries.

A.2.131.1 Values

The `-xipo` option can have the following values.

TABLE A-34 The `-xipo` Values

Value	Meaning
0	Do not perform interprocedural optimizations
1	Perform interprocedural optimizations
2	Perform interprocedural aliasing analysis as well as optimizations of memory allocation and layout to improve cache performance

Defaults

If `-xipo` is not specified, `-xipo=0` is assumed.

If only `-xipo` is specified, `-xipo=1` is assumed.

Examples

The following example compiles and links in the same step.

```
example% CC -xipo -x04 -o prog part1.cc part2.cc part3.cc
```

The optimizer performs crossfile inlining across all three source files. This is done in the final link step, so the compilation of the source files need not all take place in a single compilation and could be over a number of separate compilations, each specifying the `-xipo` option.

The following example compiles and links in separate steps.

```
example% CC -xipo -x04 -c part1.cc part2.cc
example% CC -xipo -x04 -c part3.cc
example% CC -xipo -x04 -o prog part1.o part2.o part3.o
```

The object files created in the compile steps have additional analysis information compiled within them to permit crossfile optimizations to take place at the link step.

Interactions

The `-xipo` option requires at least optimization level `-x04`.

You cannot use both the `-xipo` option and the `-xcrossfile` option in the same compiler command line.

Warnings

When compiling and linking are performed in separate steps, `-xipo` must be specified in both steps to be effective.

Objects that are compiled without `-xipo` can be linked freely with objects that are compiled with `-xipo`.

Libraries do not participate in crossfile interprocedural analysis, even when they are compiled with `-xipo`, as shown in this example.

```
example% CC -xipo -xO4 one.cc two.cc three.cc
example% CC -xar -o mylib.a one.o two.o three.o
...
example% CC -xipo -xO4 -o myprog main.cc four.cc mylib.a
```

In this example, interprocedural optimizations will be performed between `one.cc`, `two.cc` and `three.cc`, and between `main.cc` and `four.cc`, but not between `main.cc` or `four.cc` and the routines in `mylib.a`. (The first compilation may generate warnings about undefined symbols, but the interprocedural optimizations will be performed because it is a compile and link step.)

The `-xipo` option generates significantly larger object files due to the additional information needed to perform optimizations across files. However, this additional information does not become part of the final executable binary file. Any increase in the size of the executable program will be due to the additional optimizations performed.

A.2.131.2 When Not To Use `-xipo` Interprocedural Analysis

The compiler tries to perform whole-program analysis and optimizations as it works with the set of object files in the link step. The compiler makes the following two assumptions for any function (or subroutine) `foo()` defined in this set of object files:

- `foo()` is not called explicitly by another routine that is defined outside this set of object files at runtime.
- The calls to `foo()` from any routine in the set of object files are not interposed upon by a different version of `foo()` defined outside this set of object files.

Do not compile with `-xipo=2`, if assumption 1 is not true for the given application.

Do not compile with either `-xipo=1` or `-xipo=2`, if assumption 2 is not true.

As an example, consider interposing on the function `malloc()` with your own version and compiling with `-xipo=2`. Consequently, all the functions in any library that reference `malloc()` that are linked with your code have to be compiled with `-xipo=2` also and their object files need to participate in the link step. Since this might not be possible for system libraries, do not compile your version of `malloc` with `-xipo=2`.

As another example, suppose that you build a shared library with two external calls, `foo()` and `bar()` inside two different source files. Furthermore, suppose that `bar()` calls `foo()`. If there is a possibility that `foo()` could be interposed at runtime, then do not compile the source file for `foo()` or for `bar()` with `-xipo=1` or `-xipo=2`. Otherwise, `foo()` could be inlined into `bar()`, which could cause incorrect results.

See Also

`-xjobs`

A.2.132 `-xipo_archive=[a]`

The `-xipo_archive` option enables the compiler to optimize object files that are passed to the linker with object files that were compiled with `-xipo` and that reside in the archive library (`.a`) before producing an executable. Any object files contained in the library that were optimized during the compilation are replaced with their optimized version.

a is one of the following:

TABLE A-35 The `-xipo_archive` Flags

Value	Meaning
<code>writeback</code>	<p>The compiler optimizes object files passed to the linker with object files compiled with <code>-xipo</code> that reside in the archive library (<code>.a</code>) before producing an executable. Any object files contained in the library that were optimized during the compilation are replaced with an optimized version.</p> <p>For parallel links that use a common set of archive libraries, each link should create its own copy of archive libraries to be optimized before linking.</p>
<code>readonly</code>	<p>The compiler optimizes object files passed to the linker with object files compiled with <code>-xipo</code> that reside in the archive library (<code>.a</code>) before producing an executable.</p> <p>The option <code>-xipo_archive=readonly</code> enables cross-module inlining and interprocedural data flow analysis of object files in an archive library specified at link time. However, it does not enable cross-module optimization of the archive library's code except for code that has been inserted into other modules by cross module inlining.</p> <p>To apply cross-module optimization to code within an archive library, <code>-xipo_archive=writeback</code> is required. Note that doing so modifies the contents of the archive library from which the code was extracted.</p>

TABLE A-35 The `-xipo_archive` Flags (Continued)

Value	Meaning
none	This is the default. There is no processing of archive files. The compiler does not apply cross-module inlining or other cross-module optimizations to object files compiled using <code>-xipo</code> and extracted from an archive library at link time. To do that, both <code>-xipo</code> and either <code>-xipo_archive=readonly</code> or <code>-xipo_archive=writeback</code> must be specified at link time.

If you do not specify a setting for `-xipo_archive`, the compiler sets it to `-xipo_archive=none`.

It is illegal to specify `-xipo_archive` without a flag.

A.2.133 `-xjobs=n`

Specify the `-xjobs` option to set how many processes the compiler creates to complete its work. This option can reduce the build time on a multi-cpu machine. Currently, `-xjobs` works only with the `-xipo` option. When you specify `-xjobs=n`, the interprocedural optimizer uses n as the maximum number of code generator instances it can invoke to compile different files.

A.2.133.1 Values

You must always specify `-xjobs` with a value. Otherwise an error diagnostic is issued and compilation aborts.

Generally, a safe value for n is 1.5 multiplied by the number of available processors. Using a value that is many times the number of available processors can degrade performance because of context switching overheads among spawned jobs. Also, using a very high number can exhaust the limits of system resources such as swap space.

Defaults

Multiple instances of `-xjobs` on the command line override each other until the right-most instance is reached.

Examples

The following example compiles more quickly on a system with two processors than the same command without the `-xjobs` option.

```
example% CC -xipo -x04 -xjobs=3 t1.cc t2.cc t3.cc
```

A.2.134 **-xkeepframe**=[*%all*, *%none*, *name*, *no%name*]

Prohibit stack related optimizations for the named functions (*name*).

%all - prohibit stack related optimizations for all the code.

%none - allow stack related optimizations for all the code.

If not specified on the command line, the compiler assumes `-xkeepframe=%none` as the default. If specified but without a value, the compiler assumes `-xkeepframe=%all`

A.2.135 **-xlang**=*language*[, *language*]

Includes the appropriate runtime libraries and ensures the proper runtime environment for the specified language.

A.2.135.1 **Values**

language must be either *f77*, *f90*, *f95*, or *c99*.

The *f90* and *f95* arguments are equivalent. The *c99* argument invokes ISO 9899:1999 C programming language behavior for objects that were compiled with `cc -xc99=%all` and are being linked with `CC`.

Interactions

The `-xlang=f90` and `-xlang=f95` options imply `-library=f90`, and the `-xlang=f77` option implies `-library=f77`. However, the `-library=f77` and `-library=f90` options are not sufficient for mixed-language linking because only the `-xlang` option ensures the proper runtime environment.

To determine which driver to use for mixed-language linking, use the following language hierarchy:

1. C++
2. Fortran 95 (or Fortran 90)
3. Fortran 77
4. C or C99

When linking Fortran 95, Fortran 77, and C++ object files together, use the driver of the highest language. For example, use the following C++ compiler command to link C++ and Fortran 95 object files.

```
example% CC -xlang=f95...
```

To link Fortran 95 and Fortran 77 object files, use the Fortran 95 driver, as follows.

```
example% f95 -xlang=f77...
```

You cannot use the `-xlang` option and the `-xlic_lib` option in the same compiler command. If you are using `-xlang` and you need to link in the Sun Performance Libraries, use `-library=sunperf` instead.

Warnings

Do not use `-xnolib` with `-xlang`.

If you are mixing parallel Fortran objects with C++ objects, the link line must specify the `-mt` flag.

See also

`-library`, `-staticlib`

A.2.136 -xldscope={v}

Specify the `-xldscope` option to change the default linker scoping for the definition of extern symbols. Changing the default can result in faster and safer shared libraries and executables because the implementation are better hidden.

A.2.136.1 Values

`v` must be one of the following:

TABLE A-36 The `-xldscope` Values

Value	Meaning
global	Global linker scoping is the least restrictive linker scoping. All references to the symbol bind to the definition in the first dynamic load module that defines the symbol. This linker scoping is the current linker scoping for extern symbols.
symbolic	Symbolic linker scoping and is more restrictive than global linker scoping. All references to the symbol from within the dynamic load module being linked bind to the symbol defined within the module. Outside of the module, the symbol appears as though it is global. This linker scoping corresponds to the linker option <code>-Bsymbolic</code> . Although you cannot use <code>-Bsymbolic</code> with C++ libraries, you can use the <code>-xldscope=symbolic</code> without causing problems. See <code>ld(1)</code> for more information on the linker.
hidden	Hidden linker scoping is more restrictive than symbolic and global linker scoping. All references within a dynamic load module bind to a definition within that module. The symbol will not be visible outside of the module.

Defaults

If you do not specify `-xldscope`, the compiler assumes `-xldscope=global`. If you specify `-xldscope` without any values, the compiler issues an error. Multiple instances of this option on the command line override each other until the right most instance is reached.

Warning

If you intend to allow a client to override a function in a library, you must be sure that the function is not generated inline during the library build. The compiler inlines a function if you specify the function name with `-xinline`, if you compile at `-xO4` or higher in which case inlining can happen automatically, if you use the inline specifier, or if you are using cross-file optimization.

For example, suppose library ABC has a default allocator function that can be used by library clients, and is also used internally in the library:

```
void* ABC_allocator(size_t size) { return malloc(size); }
```

If you build the library at `-xO4` or higher, the compiler inlines calls to `ABC_allocator` that occur in library components. If a library client wants to replace `ABC_allocator` with a customized version, the replacement will not occur in library components that called `ABC_allocator`. The final program will include different versions of the function.

Library functions declared with the `__hidden` or `__symbolic` specifiers can be generated inline when building the library. They are not supposed to be overridden by clients. See [“4.1 Linker Scoping” on page 61](#).

Library functions declared with the `__global` specifier, should not be declared inline, and should be protected from inlining by use of the `-xinline` compiler option.

See Also

`-xinline`, `-xO`, `-xcrossfile`

A.2.137 `-xlibmieee`

Causes `libm` to return IEEE 754 values for math routines in exceptional cases.

The default behavior of `libm` is XPG-compliant.

A.2.137.1 See also

Numerical Computation Guide

A.2.138 `-xlibmil`

Inlines selected `libm` library routines for optimization.

Note – This option does not affect C++ inline functions.

There are inline templates for some of the `libm` library routines. This option selects those inline templates that produce the fastest executables for the floating-point option and platform currently being used.

A.2.138.1 **Interactions**

This option is implied by the `-fast` option.

See also

`-fast`, *Numerical Computation Guide*

A.2.139 `-xlibmopt`

Uses library of optimized math routines. You must use default rounding mode by specifying `-fround=nearest` when you use this option.

This option uses a math routine library optimized for performance and usually generates faster code. The results might be slightly different from those produced by the normal math library; if so, they usually differ in the last bit.

The order on the command line for this library option is not significant.

A.2.139.1 **Interactions**

This option is implied by the `-fast` option.

See also

`-fast`, `-xno libmopt`, `-fround`

A.2.140 `-xlic_lib=sunperf`

Deprecated, do not use. Specify `-library=sunperf` instead. See “[A.2.49 -library=l\[,l...\]](#)” on [page 242](#) for more information.

A.2.141 `-xlicinfo`

This option is silently ignored by the compiler.

A.2.142 `-xlinkopt[=level]`

Instructs the compiler to perform link-time optimization on the resulting executable or dynamic library over and above any optimizations in the object files. These optimizations are performed at link time by analyzing the object binary code. The object files are not rewritten but the resulting executable code may differ from the original object codes.

You must use `-xlinkopt` on at least some of the compilation commands for `-xlinkopt` to be useful at link time. The optimizer can still perform some limited optimizations on object binaries that are not compiled with `-xlinkopt`.

`-xlinkopt` optimizes code coming from static libraries that appear on the compiler command line, but it skips and does not optimize code coming from shared (dynamic) libraries that appear on the command line. You can also use `-xlinkopt` when you build shared libraries (compiling with `-G`).

A.2.142.1 Values

level sets the level of optimizations performed, and must be 0, 1, or 2. The optimization levels are:

TABLE A-37 The `-xlinkopt` Values

Value	Meaning
0	The link optimizer is disabled. (This is the default.)
1	Perform optimizations based on control flow analysis, including instruction cache coloring and branch optimizations, at link time.
2	Perform additional data flow analysis, including dead-code elimination and address computation simplification, at link time.

If you compile in separate steps, `-xlinkopt` must appear on both compile and link steps:

```
example% cc -c -xlinkopt a.c b.c
example% cc -o myprog -xlinkopt=2 a.o
```

Note that the level parameter is only used when the compiler is linking. In the example above, the link optimizer level is 2 even though the object binaries are compiled with an implied level of 1.

Defaults

Specifying `-xlinkopt` without a level parameter implies `-xlinkopt=1`.

Interactions

This option is most effective when you use it to compile the whole program, and with profile feedback. Profiling reveals the most and least used parts of the code and building directs the optimizer to focus its effort accordingly. This is particularly important with large applications where optimal placement of code performed at link time can reduce instruction cache misses. Typically, this compiles as follows:

```
example% cc -o prog -x05 -xprofile=collect:prog file.c
example% prog
example% cc -o prog -x05 -xprofile=use:prog -xlinkopt file.c
```

For details on using profile feedback, see “[A.2.170 `-xprofile=p`](#)” on page 327.

Warnings

Do not use the `-zcombreloc` linker option when you compile with `-xlinkopt`.

Note that compiling with this option increases link time slightly. Object file sizes also increase, but the size of the executable remains the same. Compiling with `-xlinkopt` and `-g` increases the size of the executable by including debugging information.

A.2.143 `-xloopinfo`

This option shows which loops are parallelized and which are not. It is normally for use with the `-xautopar` option.

A.2.144 `-xM`

Runs only the C++ preprocessor on the named C++ programs, requesting that the preprocessor generate makefile dependencies and send the result to the standard output (see `make(1)` for details about make files and dependencies).

However, `-xM` only reports dependencies of the included headers and not the associated template definition files. You can use the `.KEEP_STATE` feature in your makefile to generate all the dependencies in the `.make.state` file which the make utility creates.

A.2.144.1 Examples

For example:

```
#include <unistd.h>
void main(void)
{}
```

generates this output:

```
e.o: e.c
e.o: /usr/include/unistd.h
e.o: /usr/include/sys/types.h
e.o: /usr/include/sys/machtypes.h
e.o: /usr/include/sys/select.h
e.o: /usr/include/sys/time.h
e.o: /usr/include/sys/types.h
e.o: /usr/include/sys/time.h
e.o: /usr/include/sys/unistd.h
```

Interactions

If you specify `-xM` and `-xMF`, the compiler writes all makefile dependency information to the file specified with `-xMF`. This file is overwritten each time the preprocessor writes to it.

See also

`make(1S)` (for details about makefiles and dependencies)

A.2.145 `-xM1`

Generates makefile dependencies like `-xM`, except that it does not report dependencies for the `/usr/include` header files and it does not report dependencies for compiler-supplied header files.

If you specify `-xM1` and `-xMF`, the compiler writes all makefile dependency information to the file specified with `-xMF`. This file is overwritten each time the preprocessor writes to it.

A.2.146 `-xMD`

Generates makefile dependencies like `-xM` but compilation continues. `-xMD` generates an output file for the makefile-dependency information derived from the `-o` output filename, if specified, or the input source filename, replacing (or adding) the filename suffix with `.d`. If you specify `-xMD` and `-xMF`, the preprocessor writes all makefile dependency information to the file specified with `-xMF`. Compiling with `-xMD -xMF` or `-xMD -o filename` with more than one source file is not allowed and generates an error. The dependency file is overwritten if it already exists.

A.2.147 -xMF

Use this option to specify a file for the makefile-dependency output. There is no way to specify individual filenames for multiple input files with `-xMF` on one command line. Compiling with `-xMD -xMF` or `-xMMD -xMF` with more than one source file is not allowed and generates an error. The dependency file is overwritten if it already exists.

A.2.148 -xMMD

Use this option to generate makefile dependencies excluding system header files. This is the same functionality as `-xM1`, but compilation continues. `-xMMD` generates an output file for the makefile-dependency information derived from the `-o` output filename, if specified, or the input source filename, replacing (or adding) the filename suffix with `.d`. If you specify `-xMF`, the compiler uses the filename you provide instead. Compiling with `-xMMD -xMF` or `-xMMD -o filename` with more than one source file is not allowed and generates an error. The dependency file is overwritten if it already exists.

A.2.149 -xMerge

SPARC: Merges the data segment with the text segment.

The data in the object file is read-only and is shared between processes, unless you link with `ld -N`.

The three options `-xMerge -ztext -xprofile=collect` should not be used together. While `-xMerge` forces statically initialized data into read-only storage, `-ztext` prohibits position-dependent symbol relocations in read-only storage, and `-xprofile=collect` generates statically initialized, position-dependent symbol relocations in writable storage.

A.2.149.1 See also

`ld(1)` man page

A.2.150 -xmaxopt[=*v*]

This command limits the level of `pragma opt` to the level specified. *v* is one of `off`, `1`, `2`, `3`, `4`, `5`. The default value is `-xmaxopt=off` which causes `pragma opt` to be ignored. If you specify `-xmaxopt` without supplying an argument, that is the equivalent of specifying `-xmaxopt=5`.

If you specify both `-x0` and `-xmaxopt`, the optimization level set with `-x0` must not exceed the `-xmaxopt` value.

A.2.151 -xmemalign=ab

(SPARC) Use the `-xmemalign` option to control the assumptions the compiler makes about the alignment of data. By controlling the code generated for potentially misaligned memory accesses and by controlling program behavior in the event of a misaligned access, you can more easily port your code to SPARC.

Specify the maximum assumed memory alignment and behavior of misaligned data accesses. There must be a value for both *a* (alignment) and *b* (behavior). *a* specifies the maximum assumed memory alignment and *b* specifies the behavior for misaligned memory accesses.

For memory accesses where the alignment is determinable at compile time, the compiler generates the appropriate load/store instruction sequence for that alignment of data.

For memory accesses where the alignment cannot be determined at compile time, the compiler must assume an alignment to generate the needed load/store sequence.

If actual data alignment at runtime is less than the specified alignment, the misaligned access attempt (a memory read or write) generates a trap. The two possible responses to the trap are

- The OS converts the trap to a SIGBUS signal. If the program does not catch the signal, the program aborts. Even if the program catches the signal, the misaligned access attempt will not have succeeded.
- The OS handles the trap by interpreting the misaligned access and returning control to the program as if the access had succeeded normally.

A.2.151.1 Values

The following table lists the alignment and behavior values for `-xmemalign`

TABLE A-38 The `-xmemalign` Alignment and Behavior Values

<i>a</i>		<i>b</i>	
1	Assume at most 1 byte alignment.	i	Interpret access and continue execution.
2	Assume at most 2 byte alignment.	s	Raise signal SIGBUS.
4	Assume at most 4 byte alignment.	f	For variants of <code>-xarch=v9</code> only: Raise signal SIGBUS for alignments less or equal to 4, otherwise interpret access and continue execution. For all other <code>-xarch</code> values, the <code>f</code> flag is equivalent to <code>i</code> .
8	Assume at most 8 byte alignment.		
16	Assume at most 16 byte alignment		

You must specify `-xmalign` whenever you want to link to an object file that was compiled with the value of `b` set to either `i` or `f`. For a complete list of all compiler options that must be specified at both compile time and at link time, see “3.3.3 Compile-Time and Link-Time Options” on page 48.

Defaults

The following default values only apply when no `-xmalign` option is present:

- `-xmalign=8i` for all v8 architectures.
- `-xmalign=8s` for all v9 architectures.

Here is the default when the `-xmalign` option is present but no value is given:

- `-xmalign=1i` for all `-xarch` values.

Examples

The following table shows how you can use `-xmalign` to handle different alignment situations.

TABLE A-39 Examples of `-xmalign`

Command	Situation
<code>-xmalign=1s</code>	All memory accesses are misaligned so trap handling is too slow.
<code>-xmalign=8i</code>	There are occasional, intentional, misaligned accesses in code that is otherwise correct.
<code>-xmalign=8s</code>	There should be no misaligned accesses in the program.
<code>-xmalign=2s</code>	You want to check for possible odd-byte accesses.
<code>-xmalign=2i</code>	You want to check for possible odd-byte access and you want the program to work.

A.2.152 `-xmodel=[a]`

(x86) The `-xmodel` option enables the compiler to modify the form of 64-bit objects for the Solaris x86 platforms and should only be specified for the compilation of such objects.

This option is valid only when `-m64` is also specified on 64-bit enabled x64 processors.

`a` must be one of the following:

TABLE A-40 The `-xmodel` Flags

Value	Meaning
<code>small</code>	This option generates code for the small model in which the virtual address of code executed is known at link time and all symbols are known to be located in the virtual addresses in the range from 0 to $2^{31} - 2^{24} - 1$.
<code>kernel</code>	Generates code for the kernel model in which all symbols are defined to be in the range from $2^{64} - 2^{31}$ to $2^{64} - 2^{24}$.
<code>medium</code>	Generates code for the medium model in which no assumptions are made about the range of symbolic references to data sections. Size and address of the text section have the same limits as the small code model. Applications with large amounts of static data might require <code>-xmodel=medium</code> when compiling with <code>-m64</code> .

This option is not cumulative so the compiler sets the model value according to the rightmost instance of `-xmodel` on the command-line.

If you do not specify `-xmodel`, the compiler assumes `-xmodel=small`. Specifying `-xmodel` without an argument is an error.

It is not necessary to compile all translation units with this option. You can compile select files as long as you ensure the object you are accessing is within reach.

Be aware that not all Linux system support the medium model.

A.2.153 `-xnoLib`

Disables linking with default system libraries.

Normally (without this option), the C++ compiler links with several system support libraries to support C++ programs. With this option, the `-l lib` options to link the default system support libraries are not passed to `ld`.

Normally, the compiler links with the system support libraries in the following order:

- Standard mode (default mode):

```
-lCstd -lCrun -lm -lc
```

- Compatibility mode (`-compat`):

```
-lC -lm -lc
```

The order of the `-l` options is significant. The `-lm` option must appear before `-lc`.

Note – If the `-mt` compiler option is specified, the compiler normally links with `-lthread` just before it links with `-lm`.

To determine which system support libraries will be linked by default, compile with the `-dryrun` option. For example, the output from the following command:

```
example% CC foo.cc -xarch=v9 -dryrun
```

Includes the following in the output:

```
-lcstd -lCrun -lm -lc
```

A.2.153.1 Examples

For minimal compilation to meet the C application binary interface (that is, a C++ program with only C support required), use:

```
example% CC- xnoLib test.cc -lc
```

To link `libm` statically into a single-threaded application with the generic architecture instruction set, use:

Interactions

If you specify `-xnoLib`, you must manually link all required system support libraries in the given order. You must link the system support libraries last.

If `-xnoLib` is specified, `-library` is ignored.

Warnings

Many C++ language features require the use of `libC` (compatibility mode) or `libCrun` (standard mode).

This set of system support libraries is not stable and might change from release to release.

See also

`-library`, `-staticlib`, `-l`

A.2.154 `-xnoLibmil`

Cancels `-xlibmil` on the command line.

Use this option with `-fast` to override linking with the optimized math library.

A.2.155 **-xno libmopt**

Does not use the math routine library.

A.2.155.1 **Examples**

Use this option after the `-fast` option on the command line, as in this example:

```
example% CC -fast -xno libmopt
```

A.2.156 **-xnorunpath**

Same as [“A.2.62 -norunpath” on page 250](#)

A.2.157 **-xOlevel**

Specifies optimization level; note the uppercase letter O followed by the digit 1, 2, 3, 4, or 5. In general, program execution speed depends on the level of optimization. The higher the level of optimization, the better the runtime performance. However, higher optimization levels can result in increased compilation time and larger executable files.

In a few cases, `-x02` might perform better than the others, and `-x03` might outperform `-x04`. Try compiling with each level to see if you have one of these rare cases.

If the optimizer runs out of memory, it tries to recover by retrying the current procedure at a lower level of optimization. The optimizer resumes subsequent procedures at the original level specified in the `-xOlevel` option.

There are five levels that you can use with `-x0`. The following sections describe how they operate on the SPARC platform and the x86 platform.

A.2.157.1 **Values**

On the SPARC Platform:

- `-x01` does only the minimum amount of optimization (peephole), which is post-pass, assembly-level optimization. Do not use `-x01` unless using `-x02` or `-x03` results in excessive compilation time, or you are running out of swap space.
- `-x02` does basic local and global optimization, which includes:
 - Induction-variable elimination
 - Local and global common-subexpression elimination
 - Algebraic simplification
 - Copy propagation

- Constant propagation
- Loop-invariant optimization
- Register allocation
- Basic block merging
- Tail recursion elimination
- Dead-code elimination
- Tail-call elimination
- Complicated expression expansion

This level does not optimize references or definitions for external or indirect variables.

–x03, in addition to optimizations performed at the –x02 level, also optimizes references and definitions for external variables. This level does not trace the effects of pointer assignments. When compiling either device drivers that are not properly protected by `volatile` or programs that modify external variables from within signal handlers, use –x02. In general, this level results in increased code size unless combined with the `-xspace` option.

- –x04 does automatic inlining of functions contained in the same file in addition to performing –x03 optimizations. This automatic inlining usually improves execution speed but sometimes makes it worse. In general, this level results in increased code size unless combined with the `-xspace` option.
- –x05 generates the highest level of optimization. It is suitable only for the small fraction of a program that uses the largest fraction of computer time. This level uses optimization algorithms that take more compilation time or that do not have as high a certainty of improving execution time. Optimization at this level is more likely to improve performance if it is done with profile feedback. See “[A.2.170 –xprofile=p](#)” on page 327.

On the x86 Platform:

- –x01 does basic optimization. This includes algebraic simplification, register allocation, basic block merging, dead code and store elimination, and peephole optimization.
- –x02 performs local common subexpression elimination, local copy and constant propagation, and tail recursion elimination, as well as the optimization done by level 1.
- –x03 performs global common subexpression elimination, global copy and constant propagation, loop strength reduction, induction variable elimination, and loop-variant optimization, as well as the optimization done by level 2.
- –x04 does automatic inlining of functions contained in the same file as well as the optimization done by level 3. This automatic inlining usually improves execution speed, but sometimes makes it worse. This level also frees the frame pointer registration (ebp) for general purpose use. In general this level results in increased code size.
- –x05 generates the highest level of optimization. It uses optimization algorithms that take more compilation time or that do not have as high a certainty of improving execution time.

Interactions

If you use `-g` or `-g0` and the optimization level is `-x03` or lower, the compiler provides best-effort symbolic information with almost full optimization.

If you use `-g` or `-g0` and the optimization level is `-x04` or higher, the compiler provides best-effort symbolic information with full optimization.

Debugging with `-g` does not suppress `-x0level`, but `-x0level` limits `-g` in certain ways. For example, the `-x0level` options reduce the utility of debugging so that you cannot display variables from `dbx`, but you can still use the `dbx where` command to get a symbolic traceback. For more information, see *Debugging a Program With dbx*.

The `-xipo` option is effective only if it is used with `-x04` or `-x05`.

The `-xinline` option has no effect for optimization levels below `-x03`. At `-x04`, the optimizer decides which functions should be inlined, and does so regardless of whether you specify the `-xinline` option. At `-x04`, the compiler also attempts to determine which functions will improve performance if they are inlined. If you force the inlining of a function with `-xinline`, you might actually diminish performance.

Defaults

The default is no optimization. However, this is only possible if you do not specify an optimization level. If you specify an optimization level, there is no option for turning optimization off.

If you are trying to avoid setting an optimization level, be sure not to specify any option that implies an optimization level. For example, `-fast` is a macro option that sets optimization at `-x05`. All other options that imply an optimization level give a warning message that optimization has been set. The only way to compile without any optimization is to delete all options from the command line or make file that specify an optimization level.

Warnings

If you optimize at `-x03` or `-x04` with very large procedures (thousands of lines of code in a single procedure), the optimizer might require an unreasonable amount of memory. In such cases, machine performance can be degraded.

To prevent this degradation from taking place, use the `limit` command to limit the amount of virtual memory available to a single process (see the `csh(1)` man page). For example, to limit virtual memory to 4 gigabytes:

```
example% limit datasize 4G
```

This command causes the optimizer to try to recover if it reaches 4 gigabytes of data space.

The limit cannot be greater than the total available swap space of the machine, and should be small enough to permit normal use of the machine while a large compilation is in progress.

The best setting for data size depends on the degree of optimization requested, the amount of real memory, and virtual memory available.

To find the actual swap space, type: **swap- l**

To find the actual real memory, type: **dmesg | grep mem**

See also

-xldscope -fast, -xcrossfile=*n*, -xprofile=*p*, csh(1) man page

A.2.158 -xopenmp[=*i*]

Use the `-xopenmp` option to enable explicit parallelization with OpenMP directives. To run a parallelized program in a multithreaded environment, you must set the `OMP_NUM_THREADS` environment variable prior to execution.

To enable nested parallelism, you must set the `OMP_NESTED` environment variable to `TRUE`. Nested parallelism is disabled by default.

A.2.158.1 Values

The following table lists the values for *i*:

TABLE A-41 The `-xopenmp` Values

Values	Meaning
parallel	Enables recognition of OpenMP pragmas. The minimum optimization level under <code>-xopenmp=parallel</code> is <code>-x03</code> . The compiler changes the optimization from a lower level to <code>-x03</code> if necessary and issues a warning. This flag also defines the preprocessor token <code>_OPENMP</code> .
noopt	Enables recognition of OpenMP pragmas. The compiler does not raise the optimization level if it is lower than <code>-03</code> . If you explicitly set the optimization lower than <code>-03</code> , as in <code>CC -02 -xopenmp=noopt</code> , the compiler issues an error. If you do not specify an optimization level with <code>-xopenmp=noopt</code> , the OpenMP pragmas are recognized, the program is parallelized accordingly, but no optimization is done. This flag also defines the preprocessor token <code>_OPENMP</code> .
none	This flag is the default and disables recognition of OpenMP pragmas, does not change the optimization level of your program, and does not predefine any preprocessor tokens.

Defaults

If you do not specify `-xopenmp`, the compiler sets the option to `-xopenmp=none`.

If you specify `-xopenmp`, but without an argument, the compiler sets the option to `-xopenmp=parallel`.

Interactions

If you are debugging an OpenMP program with `dbx`, compile with `-g` and `-xopenmp=noopt` so you can breakpoint within parallel regions and display the contents of variables.

Warnings

The default for `-xopenmp` might change in future releases. You can avoid warning messages by explicitly specifying an appropriate optimization.

If you compile and link in separate steps, specify `-xopenmp` in both the compilation step and the link step. This is important if you are building a shared object. The compiler which was used to compile the executable must not be any older than the compiler that built the `.so` with `-xopenmp`. This is especially important when you compile libraries that contain OpenMP directives. See “[3.3.3 Compile-Time and Link-Time Options](#)” on page 48 for a complete list of options that must be specified at both compile time and link time.

Make sure that the latest patch of the OpenMP runtime library, `libmstk.so`, is installed on the system for best performance.

See also

For a complete summary of the OpenMP Fortran 95, C, and C++ application program interface (API) for building multiprocessing applications, see the *Solaris Studio OpenMP API User's Guide*.

A.2.159 `-xpagesize=n`

Sets the preferred page size for the stack and the heap.

A.2.159.1 Values

The following values are valid for SPARC: 4K, 8K, 64K, 512K, 2M, 4M, 32M, 256M, 2G, 16G, or `default`.

The following values are valid on x86/x64: 4K, 2M, 4M, 1G, or `default`.

You must specify a valid page size for the target platform. If you do not specify a valid `pagesize`, the request is silently ignored at run-time.

Use the `getpagesize(3C)` command on the Solaris operating system to determine the number of bytes in a page. The Solaris operating system offers no guarantee that the page size request will be honored. You can use `pmap(1)` or `meminfo(2)` to determine page size of the target platform.

Defaults

If you specify `-xpagesize=default`, the Solaris operating system sets the page size.

Expansions

This option is a macro for `-xpagesize_heap` and `-xpagesize_stack`. These two options accept the same arguments as `-xpagesize`: 4k, 8K, 64K, 512K, 2M, 4M, 32M, 256M, 2G, 16G, or `default`. You can set them both with the same value by specifying `-xpagesize` or you can specify them individually with different values.

Warnings

The `-xpagesize` option has no effect unless you use it at compile time and at link time. See [“3.3.3 Compile-Time and Link-Time Options” on page 48](#) for a complete list of options that must be specified at both compile time and link time.

See Also

Compiling with this option has the same effect as setting the `LD_PRELOAD` environment variable to `mpss.so.1` with the equivalent options, or running the Solaris command `ppgsz(1)` with the equivalent options before running the program. See the Solaris man pages for details.

A.2.160 `-xpagesize_heap=n`

Set the page size in memory for the heap.

A.2.160.1 Values

`n` can be 4k, 8K, 64K, 512K, 2M, 4M, 32M, 256M, 2G, 16G, or `default`. You must specify a valid page size for the target platform. If you do not specify a valid page size, the request is silently ignored at run-time.

Use the `getpagesize(3C)` command on the Solaris operating system to determine the number of bytes in a page. The Solaris operating system offers no guarantee that the page size request will be honored. You can use `pmap(1)` or `meminfo(2)` to determine page size of the target platform.

Defaults

If you specify `-xpagesize_heap=default`, the Solaris operating system sets the page size.

Warnings

The `-xpagesize_heap` option has no effect unless you use it at compile time and at link time.

See Also

Compiling with this option has the same effect as setting the `LD_PRELOAD` environment variable to `mpss.so.1` with the equivalent options, or running the Solaris command `ppgsz(1)` with the equivalent options before running the program. See the Solaris man pages for details.

A.2.161 `-xpagesize_stack=n`

Set the page size in memory for the stack.

A.2.161.1 Values

`n` can be `4k`, `8K`, `64K`, `512K`, `2M`, `4M`, `32M`, `256M`, `2G`, `16G`, or `default`. You must specify a valid page size for the target platform. If you do not specify a valid page size, the request is silently ignored at run-time.

Use the `getpagesize(3C)` command on the Solaris operating system to determine the number of bytes in a page. The Solaris operating system offers no guarantee that the page size request will be honored. You can use `pmap(1)` or `meminfo(2)` to determine page size of the target platform.

Defaults

If you specify `-xpagesize_stack=default`, the Solaris operating system sets the page size.

Warnings

The `-xpagesize_stack` option has no effect unless you use it at compile time and at link time.

See Also

Compiling with this option has the same effect as setting the `LD_PRELOAD` environment variable to `mpss.so.1` with the equivalent options, or running the Solaris command `ppgsz(1)` with the equivalent options before running the program. See the Solaris man pages for details.

A.2.162 `-xpch=v`

This compiler option activates the precompiled-header feature. The precompiled-header feature may reduce compile time for applications whose source files share a common set of include files containing a large amount of source code. The compiler collects information about

a sequence of header files from one source file, and then uses that information when recompiling that source file, and when compiling other source files that have the same sequence of headers. The information that the compiler collects is stored in a precompiled-header file. You can take advantage of this feature through the `-xpch` and `-xpchstop` options in combination with the `#pragma hdrstop` directive.

See Also:

- “A.2.163 `-xpchstop=file`” on page 319
- “B.2.9 `#pragma hdrstop`” on page 354

A.2.162.1 Creating a Precompiled-Header File

When you specify `-xpch=v`, `v` can be `collect:pch_filename` or `use:pch_filename`. The first time you use `-xpch`, you must specify the `collect` mode. The compilation command that specifies `-xpch=collect` must only specify one source file. In the following example, the `-xpch` option creates a precompiled-header file called `myheader.Cpch` based on the source file `a.cc`:

```
CC -xpch=collect:myheader a.cc
```

A valid precompiled-header filename always has the suffix `.Cpch`. When you specify `pch_filename`, you can add the suffix or let the compiler add it for you. For example, if you specify `cc -xpch=collect:foo a.cc`, the precompiled-header file is called `foo.Cpch`.

When you create a precompiled-header file, pick a source file that contains the common sequence of include files across all the source files with which the precompiled-header file is to be used. The common sequence of include files must be identical across these source files. Remember, only one source filename value is legal in `collect` mode. For example, `CC -xpch=collect:foo bar.cc` is valid, whereas `CC -xpch=collect:foo bar.cc foobar.cc` is invalid because it specifies two source files.

Using A Precompiled-Header File

Specify `-xpch=use:pch_filename` to use a precompiled-header file. You can specify any number of source files with the same sequence of include files as the source file that was used to create the precompiled-header file. For example, your command in `use` mode could look like this: `CC -xpch=use:foo.Cpch foo.c bar.cc foobar.cc`.

You should only use an existing precompiled-header file if the following is true. If any of the following is not true, you should recreate the precompiled-header file:

- The compiler that you are using to access the precompiled-header file is the same as the compiler that created the precompiled-header file. A precompiled-header file created by one version of the compiler may not be usable by another version of the compiler, including differences caused by installed patches.
- Except for the `-xpch` option, the compiler options you specify with `-xpch=use` must match the options that were specified when the precompiled-header file was created.

- The set of included headers you specify with `-xpch=use` is identical to the set of headers that were specified when the precompile header was created.
- The contents of the included headers that you specify with `-xpch=use` is identical to the contents of the included headers that were specified when the precompiled header was created.
- The current directory (that is, the directory in which the compilation is occurring and attempting to use a given precompiled-header file) is the same as the directory in which the precompiled-header file was created.
- The initial sequence of pre-processing directives, including `#include` directives, in the file you specify with `-xpch=collect` are the same as the sequence of pre-processing directives in the files you specify with `-xpch=use`.

In order to share a precompiled-header file across multiple source files, those source files must share a common set of include files as their initial sequence of tokens. This initial sequence of tokens is known as the viable prefix. The viable prefix must be interpreted consistently across all the source files that use the same precompiled-header file.

The viable prefix of a source file can only be comprised of comments and any of the following pre-processor directives:

```
#include
#if/ifdef/ifndef/else/elif/endif
#define/undef
#ident (if identical, passed through as is)
#pragma (if identical)
```

Any of these may reference macros. The `#else`, `#elif`, and `#endif` directives must match within the viable prefix.

Within the viable prefix of each file that shares a precompiled-header file, each corresponding `#define` and `#undef` directive must reference the same symbol (in the case of `#define`, each one must reference the same value). Their order of appearance within each viable prefix must be the same as well. Each corresponding `pragma` must also be the same and appear in the same order across all the files sharing a precompiled header.

A header file that is incorporated into a precompiled-header file must not violate the following. The results of compiling a program that violate any of these constraints is undefined.

- The header file must not contain function and variable definitions.
- The header file must not use `__DATE__` and `__TIME__`. Use of these pre-processor macros can generate unpredictable results.
- The header file must not contain `#pragma hdrstop`.
- The header file must not use `__LINE__` and `__FILE__` in the viable prefix. It is allowed to use `__LINE__` and `__FILE__` in included headers.

How to Modify make Files

Here are possible approaches to modifying your make files in order to incorporate `-xpch` into your builds.

- You can use the implicit make rules by using an auxiliary `CCFLAGS` variable and the `KEEP_STATE` facility of both `make` and `dmake`. The precompiled header is produced as a separate, independent step.

```
.KEEP_STATE:
CCFLAGS_AUX = -O etc
CCFLAGS = -xpch=use:shared $(CCFLAGS_AUX)
shared.Cpch: foo.cc
    $(CCC) -xpch=collect:shared $(CCFLAGS_AUX) foo.cc
a.out: foo.o ping.o pong.o
    $(CCC) foo.o ping.o pong.o
```

You can also define your own compilation rule instead of trying to use an auxiliary `CCFLAGS`.

```
.KEEP_STATE:
.SUFFIXES: .o .cc
%.o:%.cc shared.Cpch
    $(CCC) -xpch=use:shared $(CCFLAGS) -c $<
shared.Cpch: foo.cc
    $(CCC) -xpch=collect:shared $(CCFLAGS) foo.cc -xe
a.out: foo.o ping.o pong.o
    $(CCC) foo.o ping.o pong.o
```

- You can produce the precompiled header as a side effect of regular compilation, and without using `KEEP_STATE`, but this approach requires explicit compilation commands.

```
shared.Cpch + foo.o: foo.cc bar.h
    $(CCC) -xpch=collect:shared foo.cc $(CCFLAGS) -c
ping.o: ping.cc shared.Cpch bar.h
    $(CCC) -xpch=use:shared ping.cc $(CCFLAGS) -c
pong.o: pong.cc shared.Cpch bar.h
    $(CCC) -xpch=use:shared pong.cc $(CCFLAGS) -c
a.out: foo.o ping.o pong.o
    $(CCC) foo.o ping.o pong.o
```

A.2.163 `-xpchstop=file`

Use the `-xpchstop=file` option to specify the last include file to be considered in creating the precompile-header file with the `-xpch` option. Using `-xpchstop` on the command line is equivalent to placing a `hdrstop` pragma after the first include-directive that references `file` in each of the source files that you specify with the `cc` command.

In the following example, the `-xpchstop` option specifies that the viable prefix for the precompiled header file ends with the include of `projectheader.h`. Therefore, `privateheader.h` is not a part of the viable prefix.

```
example% cat a.cc
#include <stdio.h>
#include <strings.h>
#include "projectheader.h"
#include "privateheader.h"
.
.
.
example% CC -xpch=collect:foo.Cpch a.cc -xpchstop=projectheader.h -c
```

A.2.163.1 See also

-xpch, pragma hdrstop

A.2.164 -xpec [= {yes | no}]

Generates a Portable Executable Code (PEC) binary. PEC binaries can be used with the Automatic Tuning System (ATS) which works by rebuilding the compiled PEC binary for tuning and troubleshooting - the original source code is not required. More information about the ATS is available at [opensparc.net \(http://www.opensparc.net/sunsource/cooltools/www/ats/\)](http://www.opensparc.net/sunsource/cooltools/www/ats/).

A binary that is built with -xpec is usually five to ten times larger than if it is built without -xpec.

If you do not specify -xpec, the compiler sets it to -xpec=no. If you specify -xpec, but do not supply a flag, the compiler sets it to -xpec=yes.

A.2.165 -xpg

Compiles for profiling with the gprof profiler.

The -xpg option compiles self-profiling code to collect data for profiling with gprof. This option invokes a runtime recording mechanism that produces a gmon.out file when the program normally terminates.

Note – There is no advantage for -xprofile if you specify -xpg. The two do not prepare or use data provided by the other.

Profiles are generated by using prof(1) or gprof(1) on 64 bit Solaris platforms or just gprof on 32 bit Solaris platforms and include approximate user CPU times. These times are derived from PC sample data (see pcsample(2)) for routines in the main executable and routines in shared libraries specified as linker arguments when the executable is linked. Other shared libraries (libraries opened after process startup using dlopen(3DL)) are not profiled.

On 32 bit Solaris systems, profiles generated using `prof(1)` are limited to routines in the executable. 32 bit shared libraries can be profiled by linking the executable with `-xpg` and using `gprof(1)`.

On x86 systems, `-xpg` is incompatible with `-xregs=frameptr`, and these two options should not be used together. Note also that `-xregs=frameptr` is included in `-fast`.

The Solaris 10 software does not include system libraries compiled with `-p`. As a result, profiles collected on Solaris 10 platforms do not include call counts for system library routines.

A.2.165.1 Warnings

If you compile and link separately, and you compile with `-xpg`, be sure to link with `-xpg`. See “3.3.3 Compile-Time and Link-Time Options” on page 48 for a complete list of options that must be specified at both compile time and link time.

See also

`-xprofile=p`, the `analyzer(1)` man page, and the *Performance Analyzer* manual.

A.2.166 -xport64 [= (v)]

Use this option to help you debug code you are porting to a 64-bit environment. Specifically, this option warns against problems such as truncation of types (including pointers), sign extension, and changes to bit-packing that are common when code is ported from a 32-bit architecture such as V8 to a 64-bit architecture such as V9.

A.2.166.1 Values

The following table lists the valid values for `v`:

TABLE A-42 The `-xport64` Values

Values	Meaning
<code>no</code>	Generate no warnings related to the porting of code from a 32 bit environment to a 64 bit environment.
<code>implicit</code>	Generate warning only for implicit conversions. Do not generate warnings when an explicit cast is present.
<code>full</code>	Generate all warnings related to the porting of code from a 32 bit environment to a 64 bit environment. This includes warnings for truncation of 64-bit values, sign-extension to 64 bits under ISO value-preserving rules, and changes to packing of bitfields.

Defaults

If you do not specify `-xport64`, the default is `-xport64=no`. If you specify `-xport64`, but do not specify a flag, the default is `-xport64=full`.

Examples

This section provides examples of code that can cause truncation of type, sign extension and changes to bit-packing.

Checking for the Truncation of 64-bit Values

When you port to a 64-bit architecture such as V9, your data may be truncated. The truncation could happen implicitly, by assignment, at initialization, or by an explicit cast. The difference of two pointers is the typedef `ptrdiff_t`, which is a 32-bit integer type in 32-bit mode, and a 64-bit integer type in 64-bit mode. The truncation of a long to a smaller size integral type generates a warning as in the following example.

```
example% cat test1.c
int x[10];

int diff = &x[10] - &x[5]; //warn

example% CC -c -xarch=v9 -Qoption ccfe -xport64=full test1.c
"test1.c", line 3: Warning: Conversion of 64-bit type value to "int" causes truncation.
1 Warning(s) detected.
example%
```

Use `-xport64=implicit` to disable truncation warnings in 64bit compilation mode when an explicit cast is the cause of data truncation.

```
example% CC -c -xarch=v9 -Qoption ccfe -xport64=implicit test1.c
"test1.c", line 3: Warning: Conversion of 64-bit type value to "int" causes truncation.
1 Warning(s) detected.
example%
```

Another common issue that arises from porting to a 64-bit architecture is the truncation of a pointer. This is always an error in C++. An operation such as casting a pointer to an int which causes such a truncation results in an error diagnostic in V9 when you specify `-xport64`.

```
example% cat test2.c
char* p;
int main() {
    p=(char*) (((unsigned int)p) & 0xFF); // -xarch=v9 error
    return 0;
}
example% CC -c -xarch=v9 -Qoption ccfe -xport64=full test2.c
"test2.c", line 3: Error: Cannot cast from char* to unsigned.
1 Error(s) detected.
example%
```

Checking for Sign Extension

You can also use the `-xport64` option to check for situations in which the normal ISO C value-preserving rules allow for the extension of the sign of a signed-integral value in an expression of unsigned-integral type. Such sign extensions can cause subtle run-time bugs.

```
example% cat test3.c
int i= -1;
void promo(unsigned long l) {}

int main() {
    unsigned long l;
    l = i; // warn
    promo(i); // warn
}
example% CC -c -xarch=v9 -Qoption ccfe -xport64=full test3.c
"test3.c", line 6: Warning: Sign extension from "int" to 64-bit integer.
"test3.c", line 7: Warning: Sign extension from "int" to 64-bit integer.
2 Warning(s) detected.
```

Checking for Changes to Packing of Bitfields

Use `-xport64` to generate warnings against long bitfields. In the presence of such bitfields, packing of the bitfields might drastically change. Any program which relies on assumptions regarding the way bitfields are packed needs to be reviewed before a successful port can take place to a 64-bit architecture.

```
example% cat test4.c
#include <stdio.h>

union U {
    struct S {
        unsigned long b1:20;
        unsigned long b2:20;
    } s;

    long buf[2];
} u;

int main() {
    u.s.b1 = 0xFFFFF;
    u.s.b2 = 0xFFFFF;
    printf(" u.buf[0] = %lx u.buf[1] = %lx\n", u.buf[0], u.buf[1]);
    return 0;
}
example%
```

Output in V9:

```
example% u.buf[0] = ffffffff000000 u.buf[1] = 0
```

Warnings

Note that warnings are generated only when you compile in 64-bit mode by specifying options such as `-m64`.

See Also

[“A.2.50 -m32|-m64” on page 246](#)

A.2.167 `-xprefetch[=a[, a...]]`

Enable prefetch instructions on those architectures that support prefetch.

Explicit prefetching should only be used under special circumstances that are supported by measurements.

a must be one of the following values.

TABLE A-43 The `-xprefetch` Values

Value	Meaning
<code>auto</code>	Enable automatic generation of prefetch instructions
<code>no%auto</code>	Disable automatic generation of prefetch instructions
<code>explicit</code>	(SPARC) Enable explicit prefetch macros
<code>no%explicit</code>	(SPARC) Disable explicit prefetch macros
<code>latx:factor</code>	Adjust the compiler's assumed prefetch-to-load and prefetch-to-store latencies by the specified factor. You can only combine this flag with <code>-xprefetch=auto</code> . The factor must be a positive floating-point or integer number.
<code>yes</code>	Obsolete, do not use. Use <code>-xprefetch=auto,explicit</code> instead.
<code>no</code>	Obsolete, do not use. Use <code>-xprefetch=no%auto,no%explicit</code> instead.

With `-xprefetch` and `-xprefetch=auto` the compiler is free to insert prefetch instructions into the code it generates. This may result in a performance improvement on architectures that support prefetch.

If you are running computationally intensive codes on large multiprocessors, you might find it advantageous to use `-xprefetch=latx:factor`. This option instructs the code generator to adjust the default latency time between a prefetch and its associated load or store by the specified factor.

The prefetch latency is the hardware delay between the execution of a prefetch instruction and the time the data being prefetched is available in the cache. The compiler assumes a prefetch latency value when determining how far apart to place a prefetch instruction and the load or store instruction that uses the prefetched data.

Note – The assumed latency between a prefetch and a load may not be the same as the assumed latency between a prefetch and a store.

The compiler tunes the prefetch mechanism for optimal performance across a wide range of machines and applications. This tuning may not always be optimal. For memory-intensive applications, especially applications intended to run on large multiprocessors, you may be able to obtain better performance by increasing the prefetch latency values. To increase the values, use a factor that is greater than 1 (one). A value between .5 and 2.0 will most likely provide the maximum performance.

For applications with data sets that reside entirely within the external cache, you may be able to obtain better performance by decreasing the prefetch latency values. To decrease the values, use a factor that is less than 1 (one).

To use the `-xprefetch=latx:factor` option, start with a factor value near 1.0 and run performance tests against the application. Then increase or decrease the factor, as appropriate, and run the performance tests again. Continue adjusting the factor and running the performance tests until you achieve optimum performance. When you increase or decrease the factor in small steps, you will see no performance difference for a few steps, then a sudden difference, then it will level off again.

A.2.167.1 Defaults

The default is `-xprefetch=auto,explicit`. This default adversely affects applications that have essentially non-linear memory access patterns. Specify `-xprefetch=no%auto,no%explicit` to override the default.

The default of `auto` is assumed unless explicitly overridden with an argument of `no%auto` or an argument of `no`. For example, `-xprefetch=explicit` is the same as `-xprefetch=explicit,auto`.

The default of `explicit` is assumed unless explicitly overridden with an argument of `no%explicit` or an argument of `no`. For example, `-xprefetch=auto` is the same as `-xprefetch=auto,explicit`.

If only `-xprefetch` is specified, `-xprefetch=auto,explicit` is assumed.

If automatic prefetching is enabled, but a latency factor is not specified, then `-xprefetch=latx:1.0` is assumed.

Interactions

This option accumulates instead of overrides.

The `sun_prefetch.h` header file provides the macros for specifying explicit prefetch instructions. The prefetches will be approximately at the place in the executable that corresponds to where the macros appear.

To use the explicit prefetch instructions, you must be on the correct architecture, include `sun_prefetch.h`, and either exclude `-xprefetch` from the compiler command or use `-xprefetch`, `-xprefetch=auto,explicit` or `-xprefetch=explicit`.

If you call the macros and include the `sun_prefetch.h` header file, but specify `-xprefetch=no%explicit`, the explicit prefetches will not appear in your executable.

The use of `latx:factor` is valid only when automatic prefetching is enabled. That is, `latx:factor` is ignored unless you use it in conjunction with `-xprefetch=auto, latx:factor`.

Warnings

Explicit prefetching should only be used under special circumstances that are supported by measurements.

Because the compiler tunes the prefetch mechanism for optimal performance across a wide range of machines and applications, you should only use `-xprefetch=latx:factor` when the performance tests indicate there is a clear benefit. The assumed prefetch latencies may change from release to release. Therefore, retesting the effect of the latency factor on performance whenever switching to a different release is highly recommended.

A.2.168 `-xprefetch_auto_type=a`

Where *a* is `[no%]indirect_array_access`.

Use this option to determine whether or not the compiler generates indirect prefetches for the loops indicated by the option `-xprefetch_level` in the same fashion the prefetches for direct memory accesses are generated.

If you do not specify a setting for `-xprefetch_auto_type`, the compiler sets it to `-xprefetch_auto_type=no%indirect_array_access`.

Options such as `-xdepend`, `-xrestrict`, and `-xalias_level` can affect the aggressiveness of computing the indirect prefetch candidates and therefore the aggressiveness of the automatic indirect prefetch insertion due to better memory alias disambiguation information.

A.2.169 `-xprefetch_level[=i]`

Use the `-xprefetch_level=i` option to control the aggressiveness of the automatic insertion of prefetch instructions as determined with `-xprefetch=auto`. The compiler becomes more aggressive, or in other words, introduces more prefetches, with each higher, level of `-xprefetch_level`.

The appropriate value for `-xprefetch_level` depends on the number of cache misses your application has. Higher `-xprefetch_level` values have the potential to improve the performance of applications with a high number of cache misses.

A.2.169.1 Values

i must be one of 1, 2, or 3.

TABLE A-44 `-xprefetch_level` Values

Value	Meaning
1	Enables automatic generation of prefetch instructions.
2	Targets additional loops, beyond those targeted at <code>-xprefetch_level=1</code> , for prefetch insertion. Additional prefetches may be inserted beyond those that were inserted at <code>-xprefetch_level=1</code> .
3	Targets additional loops, beyond those targeted at <code>-xprefetch_level=2</code> , for prefetch insertion. Additional prefetches may be inserted beyond those that were inserted at <code>-xprefetch_level=2</code> .

Defaults

The default is `-xprefetch_level=1` when you specify `-xprefetch=auto`.

Interactions

This option is effective only when it is compiled with `-xprefetch=auto`, with optimization level 3 or greater (`-xO3`), and on a platform that supports prefetch (v9, v9a, v9b, generic64, native64).

A.2.170 `-xprofile=p`

Collects data for a profile or uses a profile to optimize.

p must be `collect[:profdir]`, `use[:profdir]`, or `tcov[:profdir]`.

This option causes execution frequency data to be collected and saved during execution, then the data can be used in subsequent runs to improve performance. Profile collection is safe for multithreaded applications. That is, profiling a program that does its own multitasking (`-mt`)

produces accurate results. This option is only valid when you specify `-xO2` or greater level of optimization. If compilation and linking are performed in separate steps, the same `-xprofile` option must appear on the link step as well as the compile step.

`collect[:profdir]` Collects and saves execution frequency for later use by the optimizer with `-xprofile=use`. The compiler generates code to measure statement execution-frequency.

`-xMerge`, `-ztext`, and `-xprofile=collect` should not be used together. While `-xMerge` forces statically initialized data into read-only storage, `-ztext` prohibits position-dependent symbol relocations in read-only storage, and `-xprofile=collect` generates statically initialized, position-dependent symbol relocations in writable storage.

The profile directory name *profdir*, if specified, is the pathname of the directory where profile data are to be stored when a program or shared library containing the profiled object code is executed. If the *profdir* pathname is not absolute, it is interpreted relative to the current working directory when the program is compiled with the option `-xprofile=use:profdir`. If no profile directory name is specified, profile data are stored in a directory named *program.profile* where *program* is the basename of the profiled process's main program.

Example[1]: to collect and use profile data in the directory `myprof.profile` located in the same directory where the program is built:

```
demo: CC -xprofile=collect:myprof.profile -xO5 prog.cc -o prog
demo: ./prog
demo: CC -xprofile=use:myprof.profile -xO5 prog.cc -o prog
```

Example[2]: to collect profile data in the directory `/bench/myprof.profile` and later use the collected profile data in a feedback compilation at optimization level `-xO5`:

```
demo: CC -xprofile=collect:/bench/myprof.profile
\   -xO5 prog.cc -o prog
...run prog from multiple locations..
demo: CC -xprofile=use:/bench/myprof.profile
\   -xO5 prog.cc -o prog
```

You can set the environment variables `SUN_PROFDATA` and `SUN_PROFDATA_DIR` to control where a program compiled with `-xprofile=collect` stores the profile data. If set, the `-xprofile=collect` data is written to `$SUN_PROFDATA_DIR/$SUN_PROFDATA`.

These environment variables similarly control the path and names of the profile data files written by `tcov`, as described in the `tcov(1)` man page.

If these environment variables are not set, the profile data is written to the directory *profdir*.profile in the current directory, where *profdir* is the name of the executable or the name specified in the `-xprofile=collect:profdir` flag. `-xprofile` does not append .profile to *profdir* if *profdir* already ends in .profile. If you run the program several times, the execution frequency data accumulates in the *profdir*.profile directory; that is output from prior executions is not lost.

If you are compiling and linking in separate steps, make sure that any object files compiled with `-xprofile=collect` are also linked with `-xprofile=collect`.

`use[:profdir]`

Uses execution frequency data collected from code compiled with `-xprofile=collect[:profdir]` to optimize for the work performed when the profiled code was executed. *profdir* is the pathname of a directory containing profile data collected by running a program that was compiled with `-xprofile=collect[:profdir]`.

The *profdir* pathname is optional. If *profdir* is not specified, the name of the executable binary is used. `a.out` is used if `-o` is not specified. The compiler looks for *profdir*.profile/feedback, or `a.out.profile/feedback` when *profdir* is not specified. For example:

```
demo: CC -xprofile=collect -o myexe prog.cc
demo: CC -xprofile=use:myexe -xO5 -o myexe prog.cc
```

The program is optimized by using the execution frequency data previously generated and saved in the feedback files written by a previous execution of the program compiled with `-xprofile=collect`.

Except for the `-xprofile` option, the source files and other compiler options must be exactly the same as those used for the compilation that created the compiled program that generated the feedback file. The same version of the compiler must be used for both the `collect` build and the `use` build as well.

If compiled with `-xprofile=collect:profdir`, the same profile directory name *profdir* must be used in the optimizing compilation:
`-xprofile=use:profdir`.

See also `-xprofile_ircache` for speeding up compilation between `collect` and `use` phases.

`tcov[:profdir]`

Instrument object files for basic block coverage analysis using `tcov(1)`.

If the optional *profdir* argument is specified, the compiler will create a profile directory at the specified location. The data stored in the profile directory can be used either by `tcov(1)` or by the compiler with `-xprofile=use:profdir`. If the optional *profdir* pathname is omitted, a profile directory will be created when the profiled program is executed. The data stored in the profile directory can only be used by `tcov(1)`. The location of the profile directory can be controlled using environment variables `SUN_PROFDATA` and `SUN_PROFDATA_DIR`.

If the location specified by *profdir* is not an absolute pathname, it is interpreted at compilation time relative to the directory in which the current object file is to be written. If *profdir* is specified for any object file, the same location must be specified for all object files in the same program. The directory whose location is specified by *profdir* must be accessible from all machines where the profiled program is to be executed. The profile directory should not be deleted until its contents are no longer needed, because data stored there by the compiler cannot be restored except by recompilation.

Example [1]: if object files for one or more programs are compiled with `-xprofile=tcov:/test/profdata`, a directory named `/test/profdata.profile` will be created by the compiler and used to store data describing the profiled object files. The same directory will also be used at execution time to store execution data associated with the profiled object files.

Example [2]: if a program named `myprog` is compiled with `-xprofile=tcov` and executed in the directory `/home/joe`, the directory `/home/joe/myprog.profile` will be created at run time and used to store runtime profile data.

A.2.171 **-xprofile_ircache[=*path*]**

(SPARC) Use `-xprofile_ircache[=path]` with `-xprofile=collect|use` to improve compilation time during the use phase by reusing compilation data saved from the collect phase.

With large programs, compilation time in the use phase can improve significantly because the intermediate data is saved. Note that the saved data could increase disk space requirements considerably.

When you use `-xprofile_ircache[=path]`, *path* overrides the location where the cached files are saved. By default, these files are saved in the same directory as the object file. Specifying a path is useful when the `collect` and `use` phases happen in two different directories. Here's a typical sequence of commands:

```
example% CC -xO5 -xprofile=collect -xprofile_ircache t1.cc t2.cc
example% a.out // run collects feedback data
example% CC -xO5 -xprofile=use -xprofile_ircache t1.cc t2.cc
```

A.2.172 `-xprofile_pathmap`

(SPARC) Use the `-xprofile_pathmap=collect_prefix:use_prefix` option when you are also specifying the `-xprofile=use` command. Use `-xprofile_pathmap` when both of the following are true and the compiler is unable to find profile data for an object file that is compiled with `-xprofile=use`.

- You are compiling the object file with `-xprofile=use` in a directory that is different from the directory in which the object file was previously compiled with `-xprofile=collect`.
- Your object files share a common basename in the profile but are distinguished from each other by their location in different directories.

The *collect-prefix* is the prefix of the UNIX pathname of a directory tree in which object files were compiled using `-xprofile=collect`.

The *use-prefix* is the prefix of the UNIX pathname of a directory tree in which object files are to be compiled using `-xprofile=use`.

If you specify multiple instances of `-xprofile_pathmap`, the compiler processes them in the order of their occurrence. Each *use-prefix* specified by an instance of `-xprofile_pathmap` is compared with the object file pathname until either a matching *use-prefix* is identified or the last specified *use-prefix* is found not to match the object file pathname.

A.2.173 `-xreduction`

Analyzes loops for reduction in automatic parallelization. This option is valid only if `-xautopar` is also specified. Otherwise the compiler issues a warning.

When reduction recognition is enabled, the compiler parallelizes reductions such as dot products, maximum and minimum finding. These reductions yield different roundoffs from those obtained by unparallelized code.

A.2.174 `-xregs=r[,r...]`

Specifies the usage of registers for the generated code.

`r` is a comma-separated list that consists of one or more of the following suboptions: `appl`, `float`, `frameptr`.

Prefixing a suboption with `no%` disables that suboption.

Note that `-xregs` suboptions are restricted to specific hardware platforms.

Example: `-xregs=appl,no%float`

TABLE A-45 The `-xregs` Suboptions

Value	Meaning
<code>appl</code>	<p>(SPARC) Allow the compiler to generate code using the application registers as scratch registers. The application registers are:</p> <p><code>g2, g3, g4</code> (on 32-bit platforms)</p> <p><code>g2, g3</code> (on 64-bit platforms)</p> <p>It is strongly recommended that all system software and libraries be compiled using <code>-xregs=no%appl</code>. System software (including shared libraries) must preserve these registers' values for the application. Their use is intended to be controlled by the compilation system and must be consistent throughout the application.</p> <p>In the SPARC ABI, these registers are described as <i>application</i> registers. Using these registers can improve performance because fewer load and store instructions are needed. However, such use can conflict with some old library programs written in assembly code.</p>
<code>float</code>	<p>(SPARC) Allow the compiler to generate code by using the floating-point registers as scratch registers for integer values. Use of floating-point values may use these registers regardless of this option. If you want your code to be free of all references to floating point registers, you need to use <code>-xregs=no%float</code> and also make sure your code does not in any way use floating point types.</p>

TABLE A-45 The `-xregs` Suboptions (Continued)

Value	Meaning
<code>frameptr</code>	<p>(x86) Allow the compiler to use the frame-pointer register (<code>%ebp</code> on IA32, <code>%rbp</code> on AMD64) as a general-purpose register.</p> <p>The default is <code>-xregs=no%frameptr</code>.</p> <p>The C++ compiler ignores <code>-xregs=frameptr</code> unless exceptions are also disabled with <code>-features=no%except</code>. Note that <code>-xregs=frameptr</code> is part of <code>-fast</code>, but is ignored by the C++ compiler unless <code>-features=no%except</code> is also specified.</p> <p>With <code>-xregs=frameptr</code> the compiler is free to use the frame-pointer register to improve program performance. However, some features of the debugger and performance measurement tools may be limited as a result. Stack tracing, debuggers, and performance analyzers cannot report on functions compiled with <code>-xregs=frameptr</code>.</p> <p>Also, C++ calls to <code>Posix pthread_cancel()</code> will fail to find cleanup handlers.</p> <p>Mixed C, Fortran, and C++ code should not be compiled with <code>-xregs=frameptr</code> if a C++ function, called directly or indirectly from a C or Fortran function, can throw an exception. If compiling such mixed source code with <code>-fast</code>, add <code>-xregs=no%frameptr</code> after the <code>-fast</code> option on the command line.</p> <p>With more available registers on 64-bit platforms, compiling with <code>-xregs=frameptr</code> has a better chance of improving 32-bit code performance than 64-bit code.</p> <p>The compiler ignores <code>-xregs=frameptr</code> and issues a warning if you also specify <code>-xpg</code>.</p>

The SPARC default is `-xregs=appl, float`.

The x86 default is `-xregs=no%frameptr`.

On x86 systems, `-xpg` is incompatible with `-xregs=frameptr`, and these two options should not be used together. Note also that `-xregs=frameptr` is included in `-fast`.

It is strongly recommended that you compile code intended for shared libraries that will link with applications, with `-xregs=no%appl, float`. At the very least, the shared library should explicitly document how it uses the application registers so that applications linking with those libraries are aware of these register assignments.

For example, an application using the registers in some global sense (such as using a register to point to some critical data structure) would need to know exactly how a library with code compiled without `-xregs=no%appl` is using the application registers in order to safely link with that library.

A.2.175 -xrestrict[=*f*]

Treats pointer-valued function parameters as restricted pointers. *f* must be one of the following values:

TABLE A-46 The -xrestrict Values

Value	Meaning
%all	All pointer parameters in the entire file are treated as restricted.
%none	No pointer parameters in the file are treated as restricted.
%source	Only functions defined within the main source file are restricted. Functions defined within included files are not restricted.
<i>fn[,fn...]</i>	A comma-separated list of one or more function names. If you specify a function list, the compiler treats pointer parameters in the specified functions as restricted; Refer to the following section, “ A.2.175.1 Restricted Pointers ” on page 334, for more information.

This command-line option can be used on its own, but it is best used with optimization. For example, the command:

```
%CC -xO3 -xrestrict=%all prog.cc
```

treats all pointer parameters in the file `prog.c` as restricted pointers. The command:

```
%CC -xO3 -xrestrict=agc prog.cc
```

treats all pointer parameters in the function `agc` in the file `prog.c` as restricted pointers.

Note that C99 standard for the C programming language introduced the `restrict` keyword, but the keyword is not part of the current C++ standard. Some compilers have a C++ language extension for the C99 `restrict` keyword, sometimes spelled `__restrict` or `__restrict__`, however the Solaris Studio C++ compiler does not currently have this extension. The `-xrestrict` option is a partial substitute for the `restrict` keyword in source code. (With the keyword, not all of the pointer arguments of a function need to be declared `restrict`.) The keyword primarily affects optimization opportunities, and limits the arguments that can be passed to a function. Removing all instances of `restrict` or `__restrict` from source code does not affect the observable behavior of a program.

The default is `%none`; specifying `-xrestrict` is equivalent to specifying `-xrestrict=%source`.

A.2.175.1 Restricted Pointers

In order for a compiler to effectively perform parallel execution of a loop, it needs to determine if certain lvalues designate distinct regions of storage. Aliases are lvalues whose regions of

storage are not distinct. Determining if two pointers to objects are aliases is a difficult and time consuming process because it could require analysis of the entire program. Consider function `vsq()` below:

EXAMPLE A-3 A Loop With Two Pointers

```
extern "C"
void vsq(int n, double *a, double *b) {
    int i;
    for (i=0; i<n; i++) {
        b[i] = a[i] * a[i];
    }
}
```

The compiler can parallelize the execution of the different iterations of the loops if it knows that pointers `a` and `b` access different objects. If there is an overlap in objects accessed through pointers `a` and `b` then it would be unsafe for the compiler to execute the loops in parallel.

At compile time, the compiler does not know if the objects accessed by `a` and `b` overlap by simply analyzing the function `vsq()`; the compiler may need to analyze the whole program to get this information. You can specify that pointer-valued function parameters be treated as restricted pointers by using the following command line option: `-xrestrict[=func1,...,funcn]`. If a function list is specified, pointer parameters in the specified functions are treated as restricted; otherwise, all pointer parameters in the entire source file are treated as restricted (not recommended). For example, `-xrestrict=vsq` qualifies the pointers `a` and `b` given in the example of the function `vsq()`.

Declaring the pointer arguments as restricted states that the pointers designate distinct objects. The compiler can assume that `a` and `b` point to distinct regions of storage. With this alias information, the compiler is able to parallelize the loop.

It is critical that you use `-xrestrict` correctly. If pointers qualified as restricted pointers point to objects that are not distinct, the compiler can incorrectly parallelize loops resulting in undefined behavior. For example, assume that pointers `a` and `b` of function `vsq()` point to objects that overlap, such that `b[i]` and `a[i+1]` are the same object. If `a` and `b` are not declared as restricted pointers the loops will be executed serially. If `a` and `b` are incorrectly qualified as restricted pointers the compiler may parallelize the execution of the loops, which is not safe, because `b[i+1]` should only be computed after `b[i]` is computed.

A.2.176 `-xs`

Allows debugging by `dbx` without object (`.o`) files.

This option causes all the debug information to be copied into the executable. This has little impact on `dbx` performance or the run-time performance of the program, but it does take more disk space.

This option has an effect only with `-xdebugformat=stabs`, where the default is not to copy debug data into the executable. With the default debug format `-xdebugformat=dwarf`, debug data is always copied into the executable, and there is no option to prevent the copying.

A.2.177 **`-xsafe=mem`**

SPARC: Allows the compiler to assume that no memory protection violations occur.

This option allows the compiler to use the non-faulting load instruction in the SPARC V9 architecture.

A.2.177.1 **Interactions**

This option takes effect only when used with optimization level `-xO5` and one of the following `-xarch` values: `sparc`, `sparcvis`, `sparcvis2`, or `sparcvis3` for both `-m32` and `-m64`.

A.2.177.2 **Warnings**

Because non-faulting loads do not cause a trap when a fault such as address misalignment or segmentation violation occurs, you should use this option only for programs in which such faults cannot occur. Because few programs incur memory-based traps, you can safely use this option for most programs. Do not use this option for programs that explicitly depend on memory-based traps to handle exceptional conditions.

A.2.178 **`-xsb`**

Deprecated - do not use. The source browser functionality is obsolete. This options is silently ignored.

A.2.179 **`-xsbfast`**

Deprecated - do not use. The source browser functionality is obsolete. This option is silently ignored.

A.2.180 **`-xspace`**

SPARC: Does not allow optimizations that increase code size.

A.2.181 **`-xtarget=t`**

Specifies the target platform for instruction set and optimization.

The performance of some programs can benefit by providing the compiler with an accurate description of the target computer hardware. When program performance is critical, the proper specification of the target hardware could be very important. This is especially true when running on the newer SPARC processors. However, for most programs and older SPARC processors, the performance gain is negligible and a generic specification is sufficient.

The value of *t* must be one of the following: `native`, `generic`, `native64`, `generic64`, *system-name*.

Each specific value for `-xtarget` expands into a specific set of values for the `-xarch`, `-xchip`, and `-xcache` options. Use the `-xdryrun` option to determine the expansion of `-xtarget=native` on a running system.

For example, `-xtarget=ultraT2` is equivalent to: `-xarch=sparcvist2 -xchip=ultraT2 -xcache=8/16/4:4096/64/16`.

Note – The expansion of `-xtarget` for a specific host platform might not expand to the same `-xarch`, `-xchip`, or `-xcache` settings as `-xtarget=native` when compiling on that platform.

A.2.181.1 -xtarget Values By Platform

This section provides descriptions of the `-xtarget` values by platform. The following table lists the `-xtarget` values for all platforms.

TABLE A-47 -xtarget Values for All Platforms

Value	Meaning
<code>native</code>	Gets the best performance on the host system. The compiler generates code optimized for the host system. It determines the available architecture, chip, and cache properties of the machine on which the compiler is running.
<code>native64</code>	Gets the best performance for 64-bit object binaries on the host system. The compiler generates 64-bit object binaries optimized for the host system. It determines the available 64-bit architecture, chip, and cache properties of the machine on which the compiler is running.
<code>generic</code>	This is the default value. Gets the best performance for generic architecture, chip, and cache.
<code>generic64</code>	Sets the parameters for the best performance of 64-bit object binaries over most 64-bit platform architectures.
<i>system-name</i>	Gets the best performance for the specified platform. Select a system name from the following lists for which represents the actual system you are targeting.

-xtarget Values on SPARC Platforms

Compiling for 64-bit Solaris software on SPARC or UltraSPARC V9 is indicated by the `-m64` option. If you specify `-xtarget` with a flag other than `native64` or `generic64`, you must also specify the `-m64` option as follows: `-xtarget=ultra...` `-m64` otherwise the compiler uses a 32-bit memory model.

TABLE A-48 `-xtarget` Expansions on SPARC Architecture

<code>-xtarget=</code>	<code>-xarch</code>	<code>-xchip</code>	<code>-xcache</code>
generic	generic	generic	generic
ultra	v8plusa	ultra	16/32/1:512/64/1
ultra1/140	v8plusa	ultra	16/32/1:512/64/1
ultra1/170	v8plusa	ultra	16/32/1:512/64/1
ultra1/200	v8plusa	ultra	16/32/1:512/64/1
ultra2	v8plusa	ultra2	16/32/1:512/64/1
ultra2/1170	v8plusa	ultra	16/32/1:512/64/1
ultra2/1200	v8plusa	ultra	16/32/1:1024/64/1
ultra2/1300	v8plusa	ultra2	16/32/1:2048/64/1
ultra2/2170	v8plusa	ultra	16/32/1:512/64/1
ultra2/2200	v8plusa	ultra	16/32/1:1024/64/1
ultra2/2300	v8plusa	ultra2	16/32/1:2048/64/1
ultra2e	v8plusa	ultra2e	16/32/1:256/64/4
ultra2i	v8plusa	ultra2i	16/32/1:512/64/1
ultra3	sparcvis2	ultra3	64/32/4:8192/512/1
ultra3cu	sparcvis2	ultra3cu	64/32/4:8192/512/2
ultra3i	sparcvis2	ultra3i	64/32/4:1024/64/4
ultra4	sparcvis2	ultra4	64/32/4:8192/128/2
ultra4plus	sparcvis2	ultra4plus	64/32/4:2048/64/4:32768/64/4
ultraT1	sparcvis2	ultraT1	8/16/4/4:3072/64/12/32
ultraT2	sparc	ultraT2	8/16/4:4096/64/16
ultraT2plus	sparcvis2	ultraT2plus	8/16/4:4096/64/16
ultraT3	sparcvis3	ultraT3	8/16/4:6144/64/24

TABLE A-48 -xtarget Expansions on SPARC Architecture (Continued)

-xtarget=	-xarch	-xchip	-xcache
sparc64vi	sparcfmaf	sparc64vi	128/64/2:5120/64/10
sparc64vii	sparcima	sparc64vii	64/64/2:5120/256/10

See “A.2.113 -xcache=c” on page 276 for more information on the cache properties of the UltraSPARC IVplus, UltraSPARC T1, and UltraSPARC T2 chips.

-xtarget Values on x86 Platforms

Compiling for 64-bit Solaris software on 64-bit x86 platforms is indicated by the -m64 option. If you specify -xtarget with a flag other than native64 or generic64, you must also specify the -m64 option as follows: -xtarget=opteron ... -m64 otherwise the compiler uses a 32-bit memory model.

TABLE A-49 -xtarget Values on x86 Platforms

-xtarget=	-xarch	-xchip	-xcache
generic	generic	generic	generic
opteron	sse2	opteron	64/64/2:1024/64/16
pentium	386	pentium	generic
pentium_pro	pentium_pro	pentium_pro	generic
pentium3	sse	pentium3	16/32/4:256/32/4
pentium4	sse2	pentium4	8/64/4:256/128/8
nehalem	sse4_2	nehalem	32/64/8:256/64/8: 8192/64/16
penryn	sse4_1	penryn	2/64/8:4096/64/16
woodcrest	ssse3	core2	32/64/8:4096/64/16
barcelona	amdsse4a	amdfam10	64/64/2:512/64/16

Defaults

On both SPARC and x86 devices, if -xtarget is not specified, -xtarget=generic is assumed.

Expansions

The -xtarget option is a macro that permits a quick and easy specification of the -xarch, -xchip, and -xcache combinations that occur on commercially purchased platforms. The only meaning of -xtarget is in its expansion.

Examples

`-xtarget=sun4/15` means `-xarch=v8a -xchip=micro -xcache=2/16/1`.

Interactions

Compilation for SPARC V9 architecture indicated by the `-xarch=v9|v9a|v9b` option. Setting `-xtarget=ultra` or `ultra2` is not necessary or sufficient. If `-xtarget` is specified, the `-xarch=v9, v9a, or v9b` option must appear after the `-xtarget`. For example:

```
-xarch=v9 -xtarget=ultra
```

expands to the following and reverts the `-xarch` value to `v8`.

```
-xarch=v9 -xarch=v8 -xchip=ultra -xcache=16/32/1:512/64/1
```

The correct method is to specify `-xarch` after `-xtarget`. For example:

```
-xtarget=ultra -xarch=v9
```

Warnings

When you compile and link in separate steps, you must use the same `-xtarget` settings in the compile step and the link step.

A.2.182 -xthreadvar[=o]

Specify `-xthreadvar` to control the implementation of thread local variables. Use this option in conjunction with the `__thread` declaration specifier to take advantage of the compiler's thread-local storage facility. After you declare the thread variables with the `__thread` specifier, specify `-xthreadvar` to enable the use of thread-local storage with position dependent code (non-PIC code) in dynamic (shared) libraries. For more information on how to use `__thread`, see [“4.2 Thread-Local Storage” on page 63](#).

A.2.182.1 Values

`o` must be one of the following:

TABLE A-50 The `-xthreadvar` Values

Value	Meaning
[no%]dynamic	[Do not] Compile variables for dynamic loading. Access to thread variables is significantly faster when <code>-xthreadvar=no%dynamic</code> but you cannot use the object file within a dynamic library. That is, you can only use the object file in an executable file.

Defaults

If you do not specify `-xthreadvar`, the default used by the compiler depends upon whether or not position-independent code is enabled. If position-independent code is enabled, the option is set to `-xthreadvar=dynamic`. If position-independent code is disabled, the option is set to `-xthreadvar=no%dynamic`.

If you specify `-xthreadvar` but do not specify any arguments, the option is set to `-xthreadvar=dynamic`.

Interactions

The `-mt` option must be used when compiling and linking files that use `__thread`.

Warnings

If there is non-position-independent code within a dynamic library, you must specify `-xthreadvar`.

The linker cannot support the thread-variable equivalent of non-PIC code in dynamic libraries. Non-PIC thread variables are significantly faster, and hence should be the default for executables.

See Also

`-xcode`, `-KPIC`, `-Kpic`

A.2.183 `-xtime`

Causes the CC driver to report execution time for the various compilation passes.

A.2.184 `-xtrigraphs[={yes|no}]`

Enables or disables recognition of trigraph sequences as defined by the ISO/ANSI C standard.

If your source code has a literal string containing question marks (?) that the compiler is interpreting as a trigraph sequence, you can use the `-xtrigraph=no` suboption to turn off the recognition of trigraph sequences.

A.2.184.1 Values

You can specify one of the following two values for `-xtrigraphs`:

TABLE A-51 The `-xtrigraphs` Values

Value	Meaning
yes	Enables recognition of trigraph sequences throughout the compilation unit
no	Disables recognition of trigraph sequences throughout the compilation unit

Defaults

When you do not include the `-xtrigraphs` option on the command line, the compiler assumes `-xtrigraphs=yes`.

If only `-xtrigraphs` is specified, the compiler assumes `-xtrigraphs=yes`.

Examples

Consider the following example source file named `trigraphs_demo.cc`.

```
#include <stdio.h>

int main ()
{
    (void) printf("(\\?\\?) in a string appears as (??)\\n");
    return 0;
}
```

Here is the output if you compile this code with `-xtrigraphs=yes`.

```
example% CC -xtrigraphs=yes trigraphs_demo.cc
example% a.out
(??) in a string appears as []
```

Here is the output if you compile this code with `-xtrigraphs=no`.

```
example% CC -xtrigraphs=no trigraphs_demo.cc
example% a.out
(??) in a string appears as (??)
```

See also

For information on trigraphs, see the *C User's Guide* chapter about transitioning to ANSI/ISO C.

A.2.185 `-xunroll=n`

Enables unrolling of loops where possible.

This option specifies whether or not the compiler optimizes (unrolls) loops.

A.2.185.1 Values

When n is 1, it is a suggestion to the compiler to not unroll loops.

When n is an integer greater than 1, `-unroll= n` causes the compiler to unroll loops n times.

A.2.186 `-xustr={ascii_utf16_ushort|no}`

Use this option if your code contains string or character literals that you want the compiler to convert to UTF-16 strings in the object file. Without this option, the compiler neither produces nor recognizes sixteen-bit character string literals. This option enables recognition of the `U"ASCII_string"` string literals as an array of unsigned short int. Since such strings are not yet part of any standard, this option enables recognition of non-standard C++.

Not all files have to be compiled with this option.

A.2.186.1 Values

Specify `-xustr=ascii_utf16_ushort` if you need to support an internationalized application that uses ISO10646 UTF-16 string literals. You can turn off compiler recognition of `U"ASCII_string"` string or character literals by specifying `-xustr=no`. The right-most instance of this option on the command line overrides all previous instances.

You can specify `-xustr=ascii_utf16_ushort` without also specifying a `U"ASCII_string"` string literal. It is not an error to do so.

Defaults

The default is `-xustr=no`. If you specify `-xustr` without an argument, the compiler won't accept it and instead issues a warning. The default can change if the C or C++ standards define a meaning for the syntax.

Example

The following example shows a string literal in quotes that is prepended by U. It also shows a command line that specifies `-xustr`

```
example% cat file.cc
const unsigned short *foo = U"foo";
const unsigned short bar[] = U"bar";
const unsigned short *fun() {return foo;}
example% CC -xustr=ascii_utf16_ushort file.cc -c
```

An 8-bit character literal can be prepended with U to form a 16-bit UTF-16 character of type unsigned short. Examples:

```
const unsigned short x = U'x';
const unsigned short y = U'\x79';
```

A.2.187 -xvector[=*a*]

Enables automatic generation of calls to the vector library functions and/or the generation of the SIMD (Single Instruction Multiple Data) instructions. You must use default rounding mode by specifying `-fround=nearest` when you use this option.

The `-xvector` option requires optimization level `-xO3` or greater. Compilation will not proceed if the optimization level is unspecified or lower than `-xO3`, and a message is issued.

a is the equivalent of the following:

TABLE A-52 The `-xvector` Flags

Value	Meaning
[no%]lib	<i>(Solaris only)</i> Does [not] enable the compiler to transform math library calls within loops into single calls to the equivalent vector math routines when such transformations are possible. This could result in a performance improvement for loops with large loop counts.
[no%]simd	Does [not]direct the compiler to use the native x86 SSE SIMD instructions to improve performance of certain loops. Streaming extensions are used on x86 by default at optimization level 3 and above where beneficial. The suboption <code>no%simd</code> can be used to disable it. The compiler will use SIMD only if streaming extensions exist in the target architecture; that is, if target ISA is at least SSE2. For example, you can specify <code>-xtarget=woodcrest</code> , <code>-xarch=generic64</code> , <code>-xarch=sse2</code> , <code>-xarch=sse3</code> , or <code>-fast</code> on a modern platform to use it. If the target ISA has no streaming extensions, the suboption will have no effect.
yes	This option is deprecated, specify <code>-xvector=lib</code> instead.
no	This option is deprecated, specify <code>-xvector=none</code> instead.

A.2.187.1 Defaults

The default is `-xvector=simd` on x86 and `-xvector=%none` on SPARC platforms. If you specify `-xvector` without a suboption, the compiler assumes `-xvector=simd,lib` on x86, `-xvector=lib` on SPARC (Solaris), and `-xvector=simd` (Linux).

Interactions

The compiler includes the `libmvec` libraries in the load step.

If you compile and link with separate commands, be sure to use `-xvector` in the linking CC command. See “[3.3.3 Compile-Time and Link-Time Options](#)” on page 48 for a complete list of options that must be specified at both compile time and link time.

A.2.188 -xvis[={yes|no}]

(SPARC) Use the `-xvis=[yes|no]` command when you are using the assembly-language templates defined in the VIS instruction-set Software Developers Kit (VSDK).

The VIS instruction set is an extension to the SPARC v9 instruction set. Even though the UltraSPARC processors are 64-bit, there are many cases, especially in multimedia applications, when the data are limited to eight or 16 bits in size. The VIS instructions can process four 16-bit data with one instruction so they greatly improve the performance of applications that handle new media such as imaging, linear algebra, signal processing, audio, video and networking.

A.2.188.1 Defaults

The default is `-xvis=no`. Specifying `-xvis` is equivalent to specifying `-xvis=yes`.

A.2.189 -xvpara

Issues warnings about potential parallel-programming related problems that may cause incorrect results when using OpenMP. Use with `-xopenmp` and OpenMP API directives.

The compiler issues warnings when it detects the following situations:

- Loops are parallelized using MP directives with data dependencies between different loop iterations
- OpenMP data-sharing attributes-clauses are problematic. For example, declaring a variable "shared" whose accesses in an OpenMP parallel region may cause a data race, or declaring a variable "private" whose value in a parallel region is used after the parallel region.

No warnings appear if all parallelization directives are processed without problems.

Example:

```
CC -xopenmp -xvpara any.cc
```

Note – Solaris Studio compilers support OpenMP 2.5 API parallelization. Consequently, the MP pragmas directives are deprecated and are no longer supported. See the *OpenMP API User's Guide* for information on migrating to the OpenMP API.

A.2.190 -xwe

Converts all warnings to errors by returning nonzero exit status.

A.2.190.1 See Also

“A.2.16 -errwarn[=t]” on page 214

A.2.191 *-Yc,path*

Specifies a new path for the location of component *c*.

If the location of a component is specified, then the new path name for the component is `path/component_name`. This option is passed to `ld`.

A.2.191.1 Values

c must be one of the following values:

TABLE A-53 The `-Y` Flags

Value	Meaning
P	Changes the default directory for <code>cpp</code> .
0	Changes the default directory for <code>ccfe</code> .
a	Changes the default directory for <code>fbe</code> .
2	Changes the default directory for <code>iropt</code> .
c (SPARC)	Changes the default directory for <code>cg</code> .
O	Changes the default directory for <code>ipo</code> .
k	Changes the default directory for <code>CCLink</code> .
l	Changes the default directory for <code>ld</code> .
f	Changes the default directory for <code>c++filt</code> .
m	Changes the default directory for <code>mcs</code> .
u (x86)	Changes the default directory for <code>ube</code> .
h (x86)	Changes the default directory for <code>ir2hf</code> .
A	Specifies a directory to search for all compiler components. If a component is not found in <code>path</code> , the search reverts to the directory where the compiler is installed.
P	Adds <code>path</code> to the default library search path. This path will be searched before the default library search paths.
S	Changes the default directory for startup object files

Interactions

You can have multiple `-Y` options on a command line. If more than one `-Y` option is applied to any one component, then the last occurrence holds.

See also

Solaris Linker and Libraries Guide

A.2.192 **-z[]arg**

Link editor option. For more information, see the `ld(1)` man page and the Solaris *Linker and Libraries Guide*.

Pragmas

This appendix describes the C++ compiler pragmas. A *pragma* is a compiler directive that allows you to provide additional information to the compiler. This information can change compilation details that are not otherwise under your control. For example, the `pack` pragma affects the layout of data within a structure. Compiler pragmas are also called *directives*.

The preprocessor keyword `pragma` is part of the C++ standard, but the form, content, and meaning of pragmas is different for every compiler. No pragmas are defined by the C++ standard.

Note – Code that depends on pragmas is not portable.

B.1 Pragma Forms

The various forms of a C++ compiler pragma are:

```
#pragma keyword  
#pragma keyword ( a [ , a ] ... ) [ , keyword ( a [ , a ] ... ) ] , ...  
#pragma sun keyword
```

The variable *keyword* identifies the specific directive; *a* indicates an argument.

B.1.1 Overloaded Functions as Pragma Arguments

Several pragmas listed in this appendix take function names as arguments. In the event that the function is overloaded, the pragma uses the function declaration immediately preceding the pragma as its argument. Consider the following example:

```
int bar(int);  
int foo(int);  
int foo(double);  
#pragma does_not_read_global_data(foo, bar)
```

In this example, `foo` means `foo(double)`, the declaration of `foo` immediately preceding the pragma, and `bar` means `bar(int)`, the only declared `bar`. Now, consider this following example in which `foo` is again overloaded:

```
int foo(int);
int foo(double);
int bar(int);
#pragma does_not_read_global_data(foo, bar)
```

In this example, `bar` means `bar(int)`, the only declared `bar`. However, the pragma will not know which version of `foo` to use. To correct this problem, you must place the pragma immediately following the definition of `foo` that you want the pragma to use.

The following pragmas use the selection method described in this section:

- `does_not_read_global_data`
- `does_not_return`
- `does_not_write_global_data`
- `no_side_effect`
- `opt`
- `rarely_called`
- `returns_new_memory`

B.2 Pragma Reference

This section describes the pragma keywords that are recognized by the C++ compiler.

B.2.1 `#pragma align`

```
#pragma align integer(variable [,variable...])
```

Use `align` to make the listed variables memory-aligned to *integer* bytes, overriding the default. The following limitations apply:

- *integer* must be a power of 2 between 1 and 128; valid values are 1, 2, 4, 8, 16, 32, 64, and 128.
- *variable* is a global or static variable; it cannot be a local variable or a class member variable.
- If the specified alignment is smaller than the default, the default is used.
- The pragma line must appear before the declaration of the variables that it mentions; otherwise, it is ignored.
- Any variable mentioned on the pragma line but not declared in the code following the pragma line is ignored. Variables in the following example are properly declared.

```
#pragma align 64 (aninteger, astring, astruct)
int aninteger;
static char astring[256];
struct S {int a; char *b;} astruct;
```

When `#pragma align` is used inside a namespace, mangled names must be used. For example, in the following code, the `#pragma align` statement will have no effect. To correct the problem, replace `a`, `b`, and `c` in the `#pragma align` statement with their mangled names.

```
namespace foo {
    #pragma align 8 (a, b, c)
    static char a;
    static char b;
    static char c;
}
```

B.2.2 `#pragma does_not_read_global_data`

```
#pragma does_not_read_global_data(funcname [, funcname])
```

This pragma asserts that the specified routines do not read global data directly or indirectly. This allows for better optimization of code around calls to such routines. In particular, assignment statements or stores could be moved around such calls.

This pragma is permitted only after the prototype for the specified functions are declared. If the assertion about global access is not true, then the behavior of the program is undefined.

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see [“B.1.1 Overloaded Functions as Pragma Arguments” on page 349](#).

B.2.3 `#pragma does_not_return`

```
#pragma does_not_return(funcname [, funcname])
```

This pragma is an assertion to the compiler that the calls to the specified routines will not return. This allows the compiler to perform optimizations consistent with that assumption. For example, register life-times terminate at the call sites which in turn allows more optimizations.

If the specified function does return, then the behavior of the program is undefined.

This pragma is permitted only after the prototype for the specified functions are declared as the following example shows:

```
extern void exit(int);
#pragma does_not_return(exit)

extern void __assert(int);
#pragma does_not_return(__assert)
```

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see [“B.1.1 Overloaded Functions as Pragma Arguments” on page 349](#).

B.2.4 #pragma does_not_write_global_data

```
#pragma does_not_write_global_data(funcname [, funcname])
```

This pragma asserts that the specified list of routines do not write global data directly or indirectly. This allows for better optimization of code around calls to such routines. In particular, assignment statements or stores could be moved around such calls.

This pragma is permitted only after the prototype for the specified functions are declared. If the assertion about global access is not true, then the behavior of the program is undefined.

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see “[B.1.1 Overloaded Functions as Pragma Arguments](#)” on page 349.

B.2.5 #pragma dumpmacros

```
#pragma dumpmacros (value[,value...])
```

Use this pragma when you want to see how macros are behaving in your program. This pragma provides information such as macro defines, undefines, and instances of usage. It prints output to the standard error (`stderr`) based on the order macros are processed. The `dumpmacros` pragma is in effect through the end of the file or until it reaches a `#pragma end_dumpmacros`. See “[B.2.6 #pragma end_dumpmacros](#)” on page 353. You can substitute the following arguments in place of *value*:

Value	Meaning
<code>defs</code>	Print all macro defines
<code>undefs</code>	Print all macro undefines
<code>use</code>	Print information about the macros used
<code>loc</code>	Print location (path name and line number) also for <code>defs</code> , <code>undefs</code> , and <code>use</code>
<code>conds</code>	Print use information for macros used in conditional directives
<code>sys</code>	Print all macros defines, undefines, and use information for macros in system header files

Note – The sub-options `loc`, `conds`, and `sys` are qualifiers for `defs`, `undefs` and `use` options. By themselves, `loc`, `conds`, and `sys` have no effect. For example, `#pragma dumpmacros=loc,conds,sys` has no effect.

The `dumpmacros` pragma has the same effect as the command line option, however, the pragma overrides the command line option. See “A.2.122 `-xdumpmacros[=value[, value...]]`” on page 285.

The `dumpmacros` pragma does not nest so the following lines of code stop printing macro information when the `#pragma end_dumpmacros` is processed:

```
#pragma dumpmacros (defs, undefs)
#pragma dumpmacros (defs, undefs)
...
#pragma end_dumpmacros
```

The effect of the `dumpmacros` pragma is cumulative. The following lines

```
#pragma dumpmacros(defs, undefs)
#pragma dumpmacros(loc)
```

have the same effect as

```
#pragma dumpmacros(defs, undefs, loc)
```

If you use the option `#pragma dumpmacros=use, no%loc`, the name of each macro that is used is printed only once. If you use the option `#pragma dumpmacros=use, loc` the location and macro name is printed every time a macro is used.

B.2.6 `#pragma end_dumpmacros`

```
#pragma end_dumpmacros
```

This pragma marks the end of a `dumpmacros` pragma and stops printing information about macros. If you do not use an `end_dumpmacros` pragma after a `dumpmacros` pragma, the `dumpmacros` pragma continues to generate output through the end of the file.

B.2.7 `#pragma error_messages`

```
#pragma error_messages (on|off|default, tag... tag)
```

The error message pragma provides control within the source program over the messages issued by the compiler. The pragma has an effect on warning messages only. The `-w` command-line option overrides this pragma by suppressing all warning messages.

- `#pragma error_messages (on, tag... tag)`
The `on` option ends the scope of any preceding `#pragma error_messages` option, such as the `off` option, and overrides the effect of the `-eroff` option.
- `#pragma error_messages (off, tag... tag)`

The `off` option prevents the compiler program from issuing the given messages beginning with the token specified in the pragma. The scope of the pragma for any specified error message remains in effect until overridden by another `#pragma error_messages`, or the end of compilation.

- `#pragma error_messages` (default, *tag... tag*)

The default option ends the scope of any preceding `#pragma error_messages` directive for the specified tags.

B.2.8 `#pragma fini`

`#pragma fini` (*identifier[, identifier...]*)

Use `fini` to mark *identifier* as a finalization function. Such functions are expected to be of type `void`, to accept no arguments, and to be called either when a program terminates under program control or when the containing shared object is removed from memory. As with initialization functions, finalization functions are executed in the order processed by the link editor.

In a source file, the functions specified in `#pragma fini` are executed after the static destructors in that file. You must declare the identifiers before using them in the pragma.

Such functions are called once for every time they appear in a `#pragma fini` directive.

B.2.9 `#pragma hdrstop`

Embed the `hdrstop` pragma in your source-file headers to identify the end of the viable source prefix. For example, consider the following files:

```
example% cat a.cc
#include "a.h"
#include "b.h"
#include "c.h"
#include <stdio.h>
#include "d.h"
.
.
.
example% cat b.cc
#include "a.h"
#include "b.h"
#include "c.h"
```

The viable source prefix ends at `c.h` so you would insert a `#pragma hdrstop` after `c.h` in each file.

`#pragma hdrstop` must only appear at the end of the viable prefix of a source file that is specified with the `CC` command. Do not specify `#pragma hdrstop` in any include file.

See “A.2.162 -xpch=v” on page 316 and “A.2.163 -xpchstop=file” on page 319.

B.2.10 #pragma ident

```
#pragma ident string
```

Use `ident` to place *string* in the `.comment` section of the executable.

B.2.11 #pragma init

```
#pragma init(identifier[, identifier...])
```

Use `init` to mark *identifier* as an initialization function. Such functions are expected to be of type `void`, to accept no arguments, and to be called while constructing the memory image of the program at the start of execution. Initializers in a shared object are executed during the operation that brings the shared object into memory, either at program start up or during some dynamic loading operation, such as `dlopen()`. The only ordering of calls to initialization functions is the order in which they are processed by the link editors, both static and dynamic.

Within a source file, the functions specified in `#pragma init` are executed after the static constructors in that file. You must declare the identifiers before using them in the pragma.

Such functions are called once for every time they appear in a `#pragma init` directive.

B.2.12 #pragma must_have_frame

```
#pragma must_have_frame(funcname [, funcname])
```

This pragma requests that the specified list of functions always be compiled to have a complete stack frame (as defined in the System V ABI). You must declare the prototype for a function before listing that function with this pragma.

```
extern void foo(int);
extern void bar(int);
#pragma must_have_frame(foo, bar)
```

This pragma is permitted only after the prototype for the specified functions is declared. The pragma must precede the end of the function.

```
void foo(int) {
    .
    #pragma must_have_frame(foo)
    .
    return;
}
```

See “B.1.1 Overloaded Functions as Pragma Arguments” on page 349

B.2.13 **#pragma no_side_effect**

```
#pragma no_side_effect(name[,name...])
```

Use `no_side_effect` to indicate that a function does not change any persistent state. The pragma declares that the named functions have no side effects of any kind. This means that the functions return result values that depend on the passed arguments only. In addition, the functions and their called descendants:

- Do not access for reading or writing any part of the program state visible in the caller at the point of the call.
- Do not perform I/O.
- Do not change any part of the program state not visible at the point of the call.

The compiler can use this information when doing optimizations.

If the function does have side effects, the results of executing a program which calls this function are undefined.

The *name* argument specifies the name of a function within the current translation unit. The pragma must be in the same scope as the function and must appear after the function declaration. The pragma must be before the function definition.

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see “B.1.1 Overloaded Functions as Pragma Arguments” on page 349.

B.2.14 **#pragma opt**

```
#pragma opt level (funcname[,funcname])
```

funcname specifies the name of a function defined within the current translation unit. The value of *level* specifies the optimization level for the named function. You can assign optimization levels 0, 1, 2, 3, 4, 5. You can turn off optimization by setting *level* to 0. The functions must be declared with a prototype or empty parameter list prior to the pragma. The pragma must proceed the definitions of the functions to be optimized.

The level of optimization for any function listed in the pragma is reduced to the value of `-xmaxopt`. The pragma is ignored when `-xmaxopt=off`.

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see “B.1.1 Overloaded Functions as Pragma Arguments” on page 349.

B.2.15 #pragma pack (*n*)

```
#pragma pack([n])
```

Use `pack` to affect the packing of structure members.

If present, *n* must be 0 or a power of 2. A value of other than 0 instructs the compiler to use the smaller of *n*-byte alignment and the platform's natural alignment for the data type. For example, the following directive causes the members of all structures defined after the directive (and before subsequent `pack` directives) to be aligned no more strictly than on 2-byte boundaries, even if the normal alignment would be on 4- or 8-byte boundaries.

```
#pragma pack(2)
```

When *n* is 0 or omitted, the member alignment reverts to the natural alignment values.

If the value of *n* is the same as or greater than the strictest alignment on the platform, the directive has the effect of natural alignment. The following table shows the strictest alignment for each platform.

TABLE B-1 Strictest Alignment by Platform

Platform	Strictest Alignment
x86	4
SPARC generic, V8, V8a, V8plus, V8plusa, V8plusb	8
SPARC V9, V9a, V9b	16

A `pack` directive applies to all structure definitions which follow it, until the next `pack` directive. If the same structure is defined in different translation units with different packing, your program may fail in unpredictable ways. In particular, you should not use a `pack` directive prior to including a header defining the interface of a precompiled library. The recommended usage is to place the `pack` directive in your program code, immediately before the structure to be packed, and to place `#pragma pack()` immediately after the structure.

When using `#pragma pack` on a SPARC platform to pack denser than the type's default alignment, the `-misalign` option must be specified for both the compilation and the linking of the application. The following table shows the storage sizes and default alignments of the integral data types.

TABLE B-2 Storage Sizes and Default Alignments in Bytes

Type	SPARC V8 Size, Alignment	SPARC V9 Size, Alignment	x86 Size, Alignment
bool	1, 1	1, 1	1, 1

TABLE B-2 Storage Sizes and Default Alignments in Bytes (Continued)

Type	SPARC V8 Size, Alignment	SPARC V9 Size, Alignment	x86 Size, Alignment
char	1, 1	1, 1	1, 1
short	2, 2	2, 2	2, 2
wchar_t	4, 4	4, 4	4, 4
int	4, 4	4, 4	4, 4
long	4, 4	8, 8	4, 4
float	4, 4	4, 4	4, 4
double	8, 8	8, 8	8, 4
long double	16, 8	16, 16	12, 4
pointer to data	4, 4	8, 8	4, 4
pointer to function	4, 4	8, 8	4, 4
pointer to member data	4, 4	8, 8	4, 4
pointer to member function	8, 4	16, 8	8, 4

B.2.16 #pragma rarely_called

```
#pragms rarely_called(funcname[, funcname])
```

This pragma provides a hint to the compiler that the specified functions are called infrequently. This allows the compiler to perform profile-feedback style optimizations on the call-sites of such routines without the overhead of a profile-collections phase. Since this pragma is a suggestion, the compiler may not perform any optimizations based on this pragma.

The #pragma rarely_called preprocessor directive is only permitted after the prototype for the specified functions are declares. The following is an example of #pragma rarely_called:

```
extern void error (char *message);
#pragma rarely_called(error)
```

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see “[B.1.1 Overloaded Functions as Pragma Arguments](#)” on page 349.

B.2.17 #pragma returns_new_memory

```
#pragma returns_new_memory(name[, name...])
```

This pragma asserts that each named function returns the address of newly allocated memory and that the pointer does not alias with any other pointer. This information allows the optimizer to better track pointer values and to clarify memory location. This results in improved scheduling and pipelining.

If the assertion is false, the results of executing a program which calls this function are undefined.

The *name* argument specifies the name of a function within the current translation unit. The pragma must be in the same scope as the function and must appear after the function declaration. The pragma must be before the function definition.

For a more detailed explanation of how the pragma treats overloaded function names as arguments, see “[B.1.1 Overloaded Functions as Pragma Arguments](#)” on page 349.

B.2.18 `#pragma unknown_control_flow`

```
#pragma unknown_control_flow(name[, name...])
```

Use `unknown_control_flow` to specify a list of routines that violate the usual control flow properties of procedure calls. For example, the statement following a call to `setjmp()` can be reached from an arbitrary call to any other routine. The statement is reached by a call to `longjmp()`.

Because such routines render standard flowgraph analysis invalid, routines that call them cannot be safely optimized; hence, they are compiled with the optimizer disabled.

If the function name is overloaded, the most recently declared function is chosen.

B.2.19 `#pragma weak`

```
#pragma weak name1 [= name2]
```

Use `weak` to define a weak global symbol. This pragma is used mainly in source files for building libraries. The linker does not warn you if it cannot resolve a weak symbol.

The `weak` pragma can specify symbols in one of two forms:

- **String form.** The string must be the mangled name for a C++ variable or function. The behavior for an invalid mangled name reference is unpredictable. The back end may or may not produce an error for invalid mangled name references. Regardless of whether it produces an error, the behavior of the back end when invalid mangled names are used is unpredictable.
- **Identifier form.** The identifier must be an unambiguous identifier for a C++ function that was previously declared in the compilation unit. The identifier form cannot be used for variables. The front end (`ccfe`) will produce an error message if it encounters an invalid identifier reference.

B.2.19.1 **#pragma weak** *name*

In the form `#pragma weak name`, the directive makes *name* a weak symbol. The linker will not complain if it does not find a symbol definition for *name*. It also does not complain about multiple weak definitions of the symbol. The linker simply takes the first one it encounters.

If another compilation unit has a strong definition for the function or variable, *name* will be linked to that. If there is no strong definition for *name*, the linker symbol will have a value of 0.

The following directive defines `ping` to be a weak symbol. No error messages are generated if the linker cannot find a definition for a symbol named `ping`.

```
#pragma weak ping
```

```
#pragma weak name1 = name2
```

In the form `#pragma weak name1 = name2`, the symbol *name1* becomes a weak reference to *name2*. If *name1* is not defined elsewhere, *name1* will have the value *name2*. If *name1* is defined elsewhere, the linker uses that definition and ignores the weak reference to *name2*. The following directive instructs the linker to resolve any references to `bar` if it is defined anywhere in the program, and to `foo` otherwise.

```
#pragma weak bar = foo
```

In the identifier form, *name2* must be declared and defined within the current compilation unit. For example:

```
extern void bar(int) {...}
extern void _bar(int);
#pragma weak _bar=bar
```

When you use the string form, the symbol does not need to be previously declared. If both `_bar` and `bar` in the following example are `extern "C"`, the functions do not need to be declared. However, `bar` must be defined in the same object.

```
extern "C" void bar(int) {...}
#pragma weak "_bar" = "bar"
```

Overloading Functions

When you use the identifier form, there must be exactly one function with the specified name in scope at the pragma location. Attempting to use the identifier form of `#pragma weak` with an overloaded function is an error. For example:

```
int bar(int);
float bar(float);
#pragma weak bar           // error, ambiguous function name
```

To avoid the error, use the string form, as shown in the following example.


```
int bar(int);  
float bar(float);  
#pragma weak "__lDbar6Fi_i_" // make float bar(int) weak
```

See the Solaris *Linker and Libraries Guide* for more information.

Glossary

ABI	See Application Binary Interface.
abstract class	A class that contains one or more abstract methods, and therefore can never be instantiated. Abstract classes are defined so that other classes can extend them and make them concrete by implementing the abstract methods.
abstract method	A method that has no implementation.
ANSI C	American National Standards Institute's definition of the C programming language. It is the same as the ISO definition. See ISO.
ANSI/ISO C++	The American National Standards Institute and the ISO standard for the C++ programming language. See ISO.
application binary interface	The binary system interface between compiled applications and the operating system on which they run.
array	A data structure that stores a collection of values of a single data type consecutively in memory. Each value is accessed by its position in the array.
base class	See <i>inheritance</i> .
binary compatibility	The ability to link object files that are compiled by one release while using a compiler of a different release.
binding	Associating a function call with a specific function definition. More generally, associating a name with a particular entity.
cfront	A C++ to C compiler program that translates C++ to C source code, which in turn can be compiled by a standard C compiler.
class	A user-defined data type consisting of named data elements (which may be of different types), and a set of operations that can be performed with the data.
class template	A template that describes a set of classes or related data types.
class variable	A data item associated with a particular class as a whole, not with particular instances of the class. Class variables are defined in class definitions. Also called static field. See also instance variable.
compiler option	An instruction to the compiler that changes its behavior. For example, the <code>-g</code> option tells the compiler to generate data for the debugger. Synonyms: <i>flag</i> , <i>switch</i> .

constructor	A special class member function that is automatically called by the compiler whenever a class object is created to ensure the initialization of that object's instance variables. The constructor must always have the same name as the class to which it belongs. See <i>destructor</i> .
data member	An element of a class that is <i>data</i> , as opposed to a function or type definition.
data type	The mechanism that allows the representation of, for example, characters, integers, or floating-point numbers. The type determines the storage that is allocated to a variable and the operations that can be performed on the variable.
derived class	See <i>inheritance</i> .
destructor	A special class member function that is automatically called by the compiler whenever a class object is destroyed or the operator <code>delete</code> is applied to a class pointer. The destructor must always have the same name as the class to which it belongs, preceded by a tilde (~). See <i>constructor</i> .
dynamic binding	Connection of the function call to the function body at runtime. Occurs only with virtual functions. Also called <i>late binding</i> , <i>runtime binding</i> .
dynamic cast	A safe method of converting a pointer or reference from its declared type to any type that is consistent with the dynamic type to which it refers.
dynamic type	The actual type of an object that is accessed by a pointer or reference that might have a different declared type.
early binding	See static binding.
ELF file	Executable and Linking Format file, which is produced by the compiler.
exception	An error occurring in the normal flow of a program that prevents the program from continuing. Some reasons for errors include memory exhaustion or division by zero.
exception handler	Code specifically written to deal with errors, and that is invoked automatically when an exception occurs for which the handler has been registered.
exception handling	An error recovery process that is designed to intercept and prevent errors. During the execution of a program, if a synchronous error is detected, control of the program returns to an exception handler that was registered at an earlier point in the execution, and the code containing the error is bypassed.
flag	See compiler option.
function overloading	Giving the same name, but different argument types and numbers, to different functions. Also called <i>functional polymorphism</i> .
function prototype	A declaration that describes the function's interface with the rest of the program.
function template	A mechanism that allows you to write a single function that you can then use as a model, or pattern, for writing related functions.
functional polymorphism	See function overloading.

idempotent	The property of a header file that including it many times in one translation unit has the same effect as including it once.
incremental linker	A linker that creates a new executable file by linking only the changed .o files to the previous executable.
inheritance	A feature of object-oriented programming that allows the programmer to derive new classes (derived classes) from existing ones (base classes). There are three kinds of inheritance: public, protected, and private.
inline function	A function that replaces the function call with the actual function code.
instance variable	Any item of data that is associated with a particular object. Each instance of a class has its own copy of the instance variables defined in the class. Also called field. See also class variable.
instantiation	The process by which a C++ compiler creates a usable function or object (instance) from a template.
ISO	International Organization for Standardization.
K&R C	The de facto C programming language standard that was developed by Brian Kernighan and Dennis Ritchie before ANSI C.
keyword	A word that has unique meaning in a programming language, and that can be used only in a specialized context in that language.
late binding	See dynamic binding.
linker	The tool that connects object code and libraries to form a complete, executable program.
local variable	A data item known within a block, but inaccessible to code outside the block. For example, any variable defined within a method is a local variable and cannot be used outside the method.
locale	A set of conventions that are unique to a geographical area and/or language, such as date, time, and monetary format.
lvalue	An expression that designates a location in memory at which a variable's data value is stored. Also, the instance of a variable that appears to the left of the assignment operator.
mangle	See name mangling.
member function	An element of a class that is a function, as opposed to a data definition or type definition.
method	In some object-oriented languages, another name for a member function.
multiple inheritance	Inheritance of a derived class directly from more than one base class.
multithreading	The software technology that enables the development of parallel applications, whether on single- or multiple-processor systems.
name mangling	In C++, many functions can share the same name, so name alone is not sufficient to distinguish different functions. The compiler solves this problem by name mangling—creating a unique name for the function that consists of some combination of the function name and its parameters—to enable type-safe linkage. Also called <i>name decoration</i> .

namespace	A mechanism that controls the scope of global names by allowing the global space to be divided into uniquely named scopes.
operator overloading	The ability to use the same operator notation to produce different outcomes. A special form of function overloading.
optimization	The process of improving the efficiency of the object code that is generated by the compiler.
option	See compiler option.
overloading	To give the same name to more than one function or operator.
polymorphism	The ability of a pointer or reference to refer to objects whose dynamic type is different from the declared pointer or reference type.
pragma	A compiler preprocessor directive, or special comment, that instructs the compiler to take a specific action.
runtime binding	See dynamic binding.
runtime type identification (RTTI)	A mechanism that provides a standard method for a program to determine an object type during runtime.
rvalue	The variable that is located to the right of an assignment operator. The rvalue can be read but not altered.
scope	The range over which an action or definition applies.
stab	A symbol table entry that is generated in the object code. The same format is used in both a.out files and ELF files to contain debugging information.
stack	A data storage method by which data can be added to or removed from only the top of the stack, using a last-in, first-out strategy.
static binding	Connection of a function call to a function body at compile time. Also called <i>early binding</i> .
subroutine	A function. In Fortran, a function that does not return a value.
switch	See compiler option.
symbol	A name or label that denotes some program entity.
symbol table	A list of all identifiers that are present when a program is compiled, their locations in the program, and their attributes. The compiler uses this table to interpret uses of identifiers.
template database	A directory containing all configuration files that are needed to handle and instantiate the templates that are required by a program.
template options file	A user-provided file containing options for the compilation of templates, as well as source location and other information. The template options file is deprecated and should not be used.
template specialization	A specialized instance of a class template member function that overrides the default instantiation when the default cannot handle a given type adequately.

trapping	Interception of an action, such as program execution, in order to take other action. The interception causes the temporary suspension of microprocessor operations and transfers program control to another source.
type	A description of the ways in which a symbol can be used. The basic types are <code>integer</code> and <code>float</code> . All other types are constructed from these basic types by collecting them into arrays or structures, or by adding modifiers such as <code>pointer-to</code> or <code>constant</code> attributes.
variable	An item of data named by an identifier. Each variable has a type, such as <code>int</code> or <code>void</code> , and a scope. See also <code>class variable</code> , <code>instance variable</code> , <code>local variable</code> .
VTABLE	A table that is created by the compiler for each class that contains virtual functions.

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