



# Configuring and Maintaining a Storage Array Using the Command Line Interface

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## Chapter 1: About the Command Line Interface

The command line interface (CLI) is a software application that provides a way for installers, developers, and engineers to configure and monitor storage arrays. Using the CLI, you can run commands from an operating system prompt, such as the DOS `C:` prompt, a Linux operating system path, or a Solaris operating system path.

Each command performs a specific action for managing a storage array or returning information about the status of a storage array. You can enter individual commands, or you can run script files when you need to perform operations more than once. For example, you can run script files when you want to install the same configuration on several storage arrays. The CLI enables you to load a script file from a disk and run the script file. The CLI provides a way to run storage management commands on more than one network storage array. You can use the CLI both in installation sites and in development environments.

### Structure of a CLI Command

The CLI commands are in the form of a command wrapper and elements embedded into the wrapper. A CLI command consists of these elements:

- A command wrapper identified by the term `SMcli`
- The storage array identifier
- Terminals that define the operation to be performed
- Script commands

The CLI command wrapper is a shell that identifies storage array controllers, embeds operational terminals, embeds script commands, and passes these values to the script engine.

All CLI commands have the following structure:

```
SMcli storageArray terminal script-commands;
```

- `SMcli` invokes the command line interface.
- `storageArray` is the name or the IP address of the storage array.
- `terminal` are CLI values that define the environment and the purpose for the command.
- `script-commands` are one or more script commands or the name of a script file that contains script commands. (The script commands configure and manage the storage array.)

If you enter an incomplete or inaccurate `SMcli` string that does not have the correct syntax, parameter names, options, or terminals, the script engine returns usage information.

### Interactive Mode

If you enter `SMcli` and a storage array name but do not specify CLI parameters, script commands, or a script file, the command line interface runs in interactive mode. Interactive mode lets you run individual commands without prefixing the commands with `SMcli`.

In interactive mode, you can enter a single command, view the results, and enter the next command without typing the complete `SMcli` string. Interactive mode is useful for determining configuration errors and quickly testing configuration changes.

To end an interactive mode session, type the operating system-specific command for terminating a program, such as **Control-C** on the UNIX operating system or the Windows operating system. Typing the termination command (**Control-C**) while in interactive mode turns off interactive mode and returns operation of the command prompt to an input mode that requires you to type the complete `SMcli` string.

## CLI Command Wrapper Syntax

General syntax forms of the CLI command wrappers are listed in this section. The general syntax forms show the terminals and the parameters that are used in each command wrapper. The conventions used in the CLI command wrapper syntax are listed in the following table.

Convention	Definition
a   b	Alternative ("a" or "b")
<i>italicized-words</i>	A terminal that needs user input to fulfill a parameter (a response to a variable)
[ ... ] (square brackets)	Zero or one occurrence (square brackets are also used as a delimiter for some command parameters)
{ ... } (curly braces)	Zero or more occurrences
(a   b   c)	Choose only one of the alternatives
<b>bold</b>	A terminal that needs a command parameter entered to start an action

```
SMcli host-name-or-IP-address [host-name-or-IP-address]
[-c "command; {command2};"]
[-n storage-system-name | -w wwID]
[-o outputfile] [-p password] [-e ] [-S ] [-quick]
SMcli host-name-or-IP-address [hostname-or-IP-address]
[-f scriptfile]
[-n storage-system-name | -w wwID]
[-o outputfile] [-p password] [-e] [-S] [-quick]
SMcli (-n storage-system-name | -w wwID)
[-c "command; {command2};"]
[-o outputfile] [-p password] [-e] [-S] [-quick]
SMcli (-n storage-system-name -w wwID)
[-f scriptfile]
[-o outputfile] [-p password] [-e] [-S] [-quick]
SMcli -a email: email-address [host-name-or-IP-address1
[host-name-or-IP-address2]]
[-n storage-system-name | -w wwID | -h host-name]
[-I information-to-include] [-q frequency] [-S]
SMcli -x email: email-address [host-name-or-IP-address1
[host-name-or-IP-address2]]
[-n storage-system-name | -w wwID | -h host-name] [-S]
SMcli (-a | -x) trap: community, host-name-or-IP-address
[host-name-or-IP-address1 [host-name-or-IP-address2]]
[-n storage-system-name | -w wwID | -h host-name] [-S]
SMcli -d [-w] [-i] [-s] [-v] [-S]
SMcli -m host-name-or-IP-address -F email-address
[-g contactInfoFile] [-S]
SMcli -A [host-name-or-IP-address [host-name-or-IP-address]]
[-S]
SMcli -X (-n storage-system-name | -w wwID | -h host-name)
SMcli -?
```



## Command Line Terminals

Terminal	Definition
<i>host-name-or-IP-address</i>	<p>Specifies either the host name or the Internet Protocol (IP) address (<i>xxx.xxx.xxx.xxx</i>) of an in-band managed storage array or an out-of-band managed storage array.</p> <ul style="list-style-type: none"> <li>■ If you are managing a storage array by using a host through in-band storage management, you must use the <i>-n</i> terminal or the <i>-w</i> terminal if more than one storage array is connected to the host.</li> <li>■ If you are managing a storage array by using out-of-band storage management through the Ethernet connection on each controller, you must specify the <i>host-name-or-IP-address</i> of the controllers.</li> <li>■ If you have previously configured a storage array in the Enterprise Management Window, you can specify the storage array by its user-supplied name by using the <i>-n</i> terminal.</li> <li>■ If you have previously configured a storage array in the Enterprise Management Window, you can specify the storage array by its World Wide Identifier (WWID) by using the <i>-w</i> terminal.</li> </ul>
<i>-A</i>	Adds a storage array to the configuration file. If you do not follow the <i>-A</i> terminal with a <i>host-name-or-IP-address</i> , auto-discovery scans the local subnet for storage arrays.
<i>-a</i>	<p>Adds a Simple Network Management Protocol (SNMP) trap destination or an email address alert destination.</p> <ul style="list-style-type: none"> <li>■ When you add an SNMP trap destination, the SNMP community is automatically defined as the community name for the trap, and the <i>host</i> is the IP address or Domain Name Server (DNS) host name of the system to which the trap should be sent.</li> <li>■ When you add an email address for an alert destination, the <i>email-address</i> is the email address to which you want the alert message to be sent.</li> </ul>
<i>-c</i>	Indicates that you are entering one or more script commands to run on the specified storage array. End each command with a semicolon (;). You cannot place more than one <i>-c</i> terminal on the same command line. You can include more than one script command after the <i>-c</i> terminal.
<i>-d</i>	Shows the contents of the script configuration file. The file content has this format: <i>storage-system-name host-name1 host-name2</i>
<i>-e</i>	Runs the commands without performing a syntax check first.
<i>-F</i> (uppercase)	Specifies the email address from which all alerts will be sent.
<i>-f</i> (lowercase)	<p>Specifies a file name that contains script commands that you want to run on the specified storage array. The <i>-f</i> terminal is similar to the <i>-c</i> terminal in that both terminals are intended for running script commands. The <i>-c</i> terminal runs individual script commands. The <i>-f</i> terminal runs a file of script commands.</p> <p>By default, any errors that are encountered when running the script commands in a file are ignored, and the file continues to run. To override this behavior, use the <i>set session errorAction=stop</i> command in the script file.</p>
<i>-g</i>	Specifies an ASCII file that contains email sender contact information that will be included in all email alert notifications. The CLI assumes that the ASCII file is text only, without delimiters or any expected format. Do not use the <i>-g</i> terminal if a <i>userdata.txt</i> file exists.

Terminal	Definition
-h	Specifies the host name that is running the SNMP agent to which the storage array is connected. Use the -h terminal with these terminals: <ul style="list-style-type: none"> <li>■ -a</li> <li>■ -x</li> </ul>
-I (uppercase)	Specifies the type of information to be included in the email alert notifications. You can select these values: <ul style="list-style-type: none"> <li>■ eventOnly – Only the event information is included in the email.</li> <li>■ profile – The event and array profile information is included in the email.</li> <li>■ supportBundle – The event and support bundle information information is included in the email.</li> </ul> You can specify the frequency for the email deliveries using the -q terminal.
-i (lowercase)	Shows the IP address of the known storage arrays. Use the -i terminal with the -d terminal. The file contents has this format: <pre>storage-system-name IP-address1 IPaddress2</pre>
-m	Specifies the host name or the IP address of the email server from which email alert notifications are sent.
-n	Specifies the name of the storage array on which you want to run the script commands. This name is optional when you use a <i>host-name-or-IP-address</i> . If you are using the in-band method for managing the storage array, you must use the -n terminal if more than one storage array is connected to the host at the specified address. The storage array name is required when the <i>host-name-or-IP-address</i> is not used. The name of the storage array that is configured for use in the Enterprise Management Window (that is, the name is listed in the configuration file) must not be a duplicate name of any other configured storage array.
-o	Specifies a file name for all output text that is a result of running the script commands. Use the -o terminal with these terminals: <ul style="list-style-type: none"> <li>■ -c</li> <li>■ -f</li> </ul> If you do not specify an output file, the output text goes to standard output (stdout). All output from commands that are not script commands is sent to stdout, regardless of whether this terminal is set.
-p	Specifies the password for the storage array on which you want to run commands. A password is not necessary under these conditions: <ul style="list-style-type: none"> <li>■ A password has not been set on the storage array.</li> <li>■ The password is specified in a script file that you are running.</li> <li>■ You specify the password by using the -c terminal and this command: <pre>set session password=password</pre> </li> </ul>

Terminal	Definition
-q	<p>Specifies the frequency that you want to receive event notifications and the type of information returned in the event notifications. An email alert notification containing at least the basic event information is always generated for every critical event.</p> <p>These values are valid for the -q terminal:</p> <ul style="list-style-type: none"> <li>■ everyEvent – Information is returned with every email alert notification.</li> <li>■ 2 – Information is returned no more than once every two hours.</li> <li>■ 4 – Information is returned no more than once every four hours.</li> <li>■ 8 – Information is returned no more than once every eight hours.</li> <li>■ 12 – Information is returned no more than once every 12 hours.</li> <li>■ 24 – Information is returned no more than once every 24 hours.</li> </ul> <p>Using the -I terminal you can specify the type of information in the email alert notifications.</p> <ul style="list-style-type: none"> <li>■ If you set the -I terminal to eventOnly, the only valid value for the -q terminal is everyEvent.</li> <li>■ If you set the -I terminal to either the profile value or the supportBundle value, this information is included with the emails with the frequency specified by the -q terminal.</li> </ul>
-quick	<p>Reduces the amount of time that is required to run a single-line operation. An example of a single-line operation is the recreate snapshot volume command. This terminal reduces time by not running background processes for the duration of the command.</p> <p>Do not use this terminal for operations that involve more than one single-line operation. Extensive use of this command can overrun the controller with more commands than the controller can process, which causes operational failure. Also, status updates and configuration updates that are collected usually from background processes will not be available to the CLI. This terminal causes operations that depend on background information to fail.</p>
-S (uppercase)	<p>Suppresses informational messages describing the command progress that appear when you run script commands. (Suppressing informational messages is also called silent mode.) This terminal suppresses these messages:</p> <ul style="list-style-type: none"> <li>■ Performing syntax check</li> <li>■ Syntax check complete</li> <li>■ Executing script</li> <li>■ Script execution complete</li> <li>■ SMcli completed successfully</li> </ul>
-s (lowercase)	Shows the alert settings in the configuration file when used with the -d terminal.
-v	Shows the current global status of the known devices in a configuration file when used with the -d terminal.
-w	<p>Specifies the WWID of the storage array. This terminal is an alternate to the -n terminal. Use the -w terminal with the -d terminal to show the WWIDs of the known storage arrays. The file content has this format:</p> <pre>storage-system-name world-wide-ID IP-address1 IP-address2</pre>
-X (uppercase)	Deletes a storage array from a configuration.
-x (lowercase)	Removes an SNMP trap destination or an email address alert destination. The community is the SNMP community name for the trap, and the host is the IP address or DNS host name of the system to which you want the trap sent.
-?	Shows usage information about the CLI commands.

---

## Formatting CLI Commands

Double quotation marks ( " ") that are used as part of a name or label require special consideration when you run the CLI commands and the script commands on a Microsoft Windows operating system.

When double quotation marks ( " ") are part of a name or value, you must insert a backslash (\) before each double quotation mark character. For example:

```
-c "set storageArray userLabel=\"Engineering\";"
```

In this example, "Engineering" is the storage array name. A second example is:

```
-n \"My\"_Array
```

In this example, "My"\_Array is the name of the storage array.

You cannot use double quotation marks ( " ") as part of a character string (also called string literal) within a script command. For example, you cannot enter the following string to set the storage array name to "Finance" Array:

```
-c "set storageArray userLabel=\"\"Finance\"Array\";"
```

In the Linux operating system and the Solaris operating system, the delimiters around names or labels are single quotation marks ( ' '). The UNIX versions of the previous examples are as follows:

```
-c 'set storageArray userLabel="Engineering";'
```

```
-n "My"_Array
```

In a Windows operating system, if you do not use double quotation marks ( " ") around a name, you must insert a caret ( ^ ) before each special script character. Special characters are ^, |, <, and >.

Insert a caret before each special script character when used with the terminals -n, -o, -f, and -p. For example, to specify storage array CLI>CLIENT, enter this string:

```
-n CLI^>CLIENT
```

Insert one caret (^) before each special script character when used within a string literal in a script command. For example, to change the name of a storage array to FINANCE\_>\_PAYROLL, enter the following string:

```
-c "set storageArray userLabel=\"FINANCE_^|_PAYROLL\";"
```

## Usage Examples

This example shows how to change the name of a storage array. The original name of the storage array is Payroll\_Array. The new name is Finance\_Array.

### Windows operating system:

```
SMcli ICTSANT -n "Payroll_Array" -c "set storageArray  
userLabel=\"Finance_Array\";"
```

### UNIX operating system:

```
SMcli ICTSANT -n 'Payroll_Array' -c 'set storageArray userLabel="Finance_Array";'
```

This example shows how to delete an existing volume and create a new volume on a storage array. The existing volume name is Stocks\_<\_Bonds. The new volume name is Finance. The controller host names are finance1 and finance2. The storage array is protected, requiring the password TestArray.

### Windows operating system:

```
SMcli finance1 finance2 -c "set session password=\"TestArray\";
delete volume [\"Stocks_<Bonds\"];
create volume driveCount[3] RAIDLEVEL=3 capacity=10GB userLabel=\"Finance\";
show storageArray healthStatus;"
```

#### UNIX operating system:

```
SMcli finance1 finance2 -c 'set session password="TestArray";
delete volume ["Stocks_<Bonds"]';
create volume driveCount[3] RAIDLEVEL=3 capacity=10GB userLabel="Finance";
show storageArray healthStatus;"
```

This example shows how to run commands in a script file named `scriptfile.scr` on a storage array named Example. The `-e` terminal causes the file to run without checking the syntax. Running a script file without checking the syntax lets the file run more quickly; however, the file might not run correctly because the syntax for a command might be incorrect.

```
SMcli -n Example -f scriptfile.scr -e
```

This example shows how to run commands in a script file named `scriptfile.scr` on a storage array named Example. In this example, the storage array is protected by the password `MyArray`. Output, as a result of commands in the script file, goes to file `output.txt`.

#### Windows operating system:

```
SMcli -n Example -f scriptfile.scr -p "My_Array" -o output.txt
```

#### UNIX operating system:

```
SMcli -n Example -f scriptfile.scr -p 'My_Array' -o output.txt
```

This example shows how to show all of the storage arrays in the current configuration. The command in this example returns the host name of each storage array.

```
SMcli -d
```

If you want to know the IP address of each storage array in the configuration, add the `-i` terminal to the command.

```
SMcli -d -i
```

## Exit Status

This table lists the exit statuses that might be returned and the meaning of each status.

Status Value	Meaning
0	The command terminated without an error.
1	The command terminated with an error. Information about the error also appears.
2	The script file does not exist.
3	An error occurred while opening an output file.
4	A storage array was not at the specified address.
5	Addresses specify different storage arrays.
6	A storage array name does not exist for the host agent that is connected.

---

Status Value	Meaning
7	The storage array name was not at the specified address.
8	The storage array name was not unique.
9	The storage array name was not in the configuration file.
10	A management class does not exist for the storage array.
11	A storage array was not found in the configuration file.
12	An internal error occurred.
13	Invalid script syntax was found.
14	The controller was unable to communicate with the storage array.
15	A duplicate argument was entered.
16	An execution error occurred.
17	A host was not at the specified address.
18	The WWID was not in the configuration file.
19	The WWID was not at the address.
20	An unknown IP address was specified.
21	The Event Monitor configuration file was corrupted.
22	The storage array was unable to communicate with the Event Monitor.
23	The controller was unable to write alert settings.
24	The wrong organizer node was specified.
25	The command was not available.
26	The device was not in the configuration file.
27	An error occurred while updating the configuration file.
28	An unknown host error occurred.
29	The sender contact information file was not found.
30	The sender contact information file could not be read.
31	The <code>userdata.txt</code> file exists.
32	An invalid <code>-I</code> value in the email alert notification was specified.
33	An invalid <code>-f</code> value in the email alert notification was specified.

## Chapter 2: About the Script Commands

You can use the script commands to configure and manage a storage array. The script commands are distinct from the command line interface (CLI) command wrappers. You can enter individual script commands, or you can run a file of script commands. When you enter an individual script command, you embed the script command in a CLI command wrapper. When you run a file of script commands, you embed the file name in the CLI command wrapper. The script commands are processed by a script engine that performs the following functions:

- Verifies the command syntax
- Interprets the commands
- Converts the commands to the appropriate protocol-compliant commands
- Passes the commands to the storage array

At the storage array, the storage array controllers run the script commands.

**Table 1 Configuration and Management Operations**

Operation	Activities
General storage array configuration	Resetting a configuration to defaults, labeling, checking the health status, setting the time of day, clearing the Event Log, and setting the media scan rate
Volume configuration and pool configuration	Creating, deleting, and setting the reconstruction priority control; labeling; setting drive composition when creating volumes; setting the segment size; and setting the media scan control
Drive configuration	Assigning hot spares
Controller configuration	Defining volume ownership, changing mode settings, defining network settings, and setting host channel IDs
Firmware management	Downloading controller firmware, the environmental services monitor (ESM) firmware, and the drive firmware
NVSRAM configuration	Downloading and modifying the user configuration region at the bit level and the byte level, showing nonvolatile static random access memory (NVSRAM) values
Cache configuration	Controlling all cache parameters, both at the storage array level and the individual volume level
Product identification	Retrieving the module profile display data
Battery management	Setting the battery installation date

### Structure of a Script Command

All script commands have the following structure:

*command operand-data (statement-data)*

- *command* identifies the action to be performed.
- *operand-data* represents the objects associated with a storage array that you want to configure or manage.
- *statement-data* provides the information needed to perform the command.

The syntax for *operand-data* has the following structure:

```
(object-type | allobject-types | [qualifier]
(object-type [identifier] {object-type [identifier]} | object-types
[identifier-list]))
```

An object can be identified in four ways:

- Object type – Use when the command is not referencing a specific object.
- all parameter prefix – Use when the command is referencing all of the objects of the specified type in the storage array (for example, `allVolumes`).
- Square brackets – Use when performing a command on a specific object to identify the object (for example, `volume [engineering]`).
- A list of identifiers – Use to specify a subset of objects. Enclose the object identifiers in square brackets (for example, `volumes [sales engineering marketing]`).

A qualifier is required if you want to include additional information to describe the objects.

The object type and the identifiers that are associated with each object type are listed in this table.

**Table 2 Script Command Object Type Identifiers**

Object Type	Identifier
controller	a or b
drive	Module ID and slot ID
replacementDrive	Module ID and slot ID
driveChannel	Drive channel identifier
host	User label
hostChannel	Host channel identifier
hostGroup	User label
hostPort	User label
iscsiInitiator	User label or iSCSI Qualified Name (IQN)
iscsiTarget	User label or IQN
remoteMirror	Primary volume user label
snapshot	Volume user label
storageArray	Not applicable
module	Module ID
volume	Volume user label or volume World Wide Identifier (WWID) ( <code>set</code> command only)
volumeCopy	Target volume user label and, optionally, the source volume user label
pool	User label Valid characters are alphanumeric, a hyphen, and an underscore.

Statement data is in the form of:

- Parameter = value (such as `raidLevel=5`)
- Parameter-name (such as `batteryInstallDate`)
- Operation-name (such as `redundancyCheck`)

A user-defined entry (such as user label) is called a variable. In the syntax, it is shown in italic (such as *trayID* or *poolName*).



## Synopsis of the Script Commands

Because you can use the script commands to define and manage the different aspects of a storage array (such as host topology, drive configuration, controller configuration, volume definitions, and pool definitions), the actual number of commands is extensive. The commands, however, fall into general categories that are reused when you apply the commands to the different to configure or maintain a storage array. The following table lists the general form of the script commands and a definition of each command.

**Table 3 General Form of the Script Commands**

Syntax	Description
<code>activate object</code> {statement-data}	Sets up the environment so that an operation can take place or performs the operation if the environment is already set up correctly.
<code>autoConfigure storageArray</code> {statement-data}	Automatically creates a configuration that is based on the parameters that are specified in the command.
<code>check object</code> {statement-data}	Starts an operation to report on errors in the object, which is a synchronous operation.
<code>clear object</code> {statement-data}	Discards the contents of some attributes of an object. This operation is destructive and cannot be reversed.
<code>create object</code> {statement-data}	Creates an object of the specified type.
<code>deactivate object</code> {statement-data}	Removes the environment for an operation.
<code>delete object</code>	Deletes a previously created object.
<code>diagnose object</code> {statement-data}	Runs a test and shows the results.
<code>disable object</code> {statement-data}	Prevents a feature from operating.
<code>download object</code> {statement-data}	Transfers data to the storage array or to the hardware that is associated with the storage array.
<code>enable object</code> {statement-data}	Sets a feature to operate.
<code>load object</code> {statement-data}	Transfers data to the storage array or to the hardware that is associated with the storage array. This command is functionally similar to the <code>download</code> command.
<code>recopy object</code> {statement-data}	Restarts a volume copy operation by using an existing volume copy pair. You can change the parameters before the operation is restarted.
<code>recover object</code> {statement-data}	Re-creates an object from saved configuration data and the statement parameters. (This command is similar to the <code>create</code> command.)
<code>recreate object</code> {statement-data}	Restarts a snapshot operation by using an existing snapshot volume. You can change the parameters before the operation is restarted.
<code>remove object</code> {statement-data}	Removes a relationship from between objects.
<code>repair object</code> {statement-data}	Repairs errors found by the <code>check</code> command.

Syntax	Description
<code>reset object</code> <code>{statement-data}</code>	Returns the hardware or an object to an initial state.
<code>resume object</code>	Starts a suspended operation. The operation starts where it left off when it was suspended.
<code>revive object</code>	Forces the object from the Failed state to the Optimal state. Use this command only as part of an error recovery procedure.
<code>save object</code> <code>{statement-data}</code>	Writes information about the object to a file.
<code>set object</code> <code>{statement-data}</code>	Changes object attributes. All changes are completed when the command returns.
<code>show object</code> <code>{statement-data}</code>	Shows information about the object.
<code>start object</code> <code>{statement-data}</code>	Starts an asynchronous operation. You can stop some operations after they have started. You can query the progress of some operations.
<code>stop object</code> <code>{statement-data}</code>	Stops an asynchronous operation.
<code>suspend object</code> <code>{statement-data}</code>	Stops an operation. You can then restart the suspended operation, and it continues from the point where it was suspended.

## Recurring Syntax Elements

Recurring syntax elements are a general category of parameters and options that you can use in the script commands. The [Recurring Syntax Elements](#) table lists the recurring syntax parameters and the values that you can use with the recurring syntax parameters. The conventions used in the recurring syntax elements are listed in the following table.

Convention	Definition
<code>a   b</code>	Alternative ("a" or "b")
<i>italicized-words</i>	A terminal that needs user input to fulfill a parameter (a response to a variable)
<code>[ ... ]</code> (square brackets)	Zero or one occurrence (square brackets are also used as a delimiter for some command parameters)
<code>{ ... }</code> (curly braces)	Zero or more occurrences
<code>(a   b   c)</code>	Choose only one of the alternatives
<b>bold</b>	A terminal that needs a command parameter entered to start an action

**Table 4** Recurring Syntax Elements

Recurring Syntax	Syntax Value
<i>raid-level</i>	(0   1   3   5   6)
<i>repository-raid-level</i>	(1   3   5   6)
<i>capacity-spec</i>	<i>integer-literal</i> [KB   MB   GB   TB   Bytes]
<i>segment-size-spec</i>	<i>integer-literal</i>
<i>boolean</i>	(TRUE   FALSE)
<i>user-label</i>	<i>string-literal</i> Valid characters are alphanumeric, the dash, and the underscore.
<i>user-label-list</i>	<i>user-label</i> { <i>user-label</i> }
<i>create-raid-vol-attr-value-list</i>	<i>create-raid-volume-attribute-value-pair</i> { <i>create-raid-volume-attribute-value-pair</i> }
<i>create-raid-volume-attribute-value-pair</i>	<i>capacity=capacity-spec</i>   <i>owner=(a   b)</i>   <i>cacheReadPrefetch=(TRUE   FALSE)</i>   <i>segmentSize=integer-literal</i>   <i>usageHint=usage-hint-spec</i>
<i>noncontroller-moduleID</i>	(0-99)
<i>slotID</i>	(1-32)
<i>portID</i>	(0-127)
<i>drive-spec</i>	<i>moduleID</i> , <i>slotID</i> or <i>moduleID</i> , <i>drawerID</i> , <i>slotID</i> A drive is defined as two or three interger literal values separated by a comma. Low-density modules require two values. High-density modules, those modules that have drawers, require three values.
<i>drive-spec-list</i>	<i>drive-spec drive-spec</i>
<i>moduleID-list</i>	<i>moduleID</i> { <i>moduleID</i> }
<i>esm-spec-list</i>	<i>esm-spec</i> { <i>esm-spec</i> }
<i>esm-spec</i>	<i>moduleID</i> , (left   right)
<i>hex-literal</i>	<i>0xhexadecimal-literal</i>
<i>pool-number</i>	<i>integer-literal</i>
<i>filename</i>	<i>string-literal</i>
<i>error-action</i>	(stop   continue)
<i>drive-channel-identifier</i> (four drive ports per module)	(1   2   3   4)
<i>drive-channel-identifier</i> (eight drive ports per module)	(1   2   3   4   5   6   7   8)
<i>drive-channel-identifier-list</i>	<i>drive-channel-identifier</i> { <i>drive-channel-identifier</i> }
<i>host-channel-identifier</i> (four host ports per module)	(a1   a2   b1   b2)
<i>host-channel-identifier</i> (eight host ports per module)	(a1   a2   a3   a4   b1   b2   b3   b4)
<i>host-channel-identifier</i> (16 host ports per module)	(a1   a2   a3   a4   a5   a6   a7   a8   b1   b2   b3   b4   b5   b6   b7   b8)
<i>drive-type</i>	(fibre   SATA   SAS)

Recurring Syntax	Syntax Value
<i>drive-media-type</i>	(HDD   SSD   unknown   allMedia) <i>HDD</i> means hard disk drive. <i>SSD</i> means solid state disk.
<i>feature-identifier</i>	(storagePartition2   storagePartition4   storagePartition8   storagePartition16   storagePartition64   storagePartition96   storagePartition128   storagePartition256   storagePartitionMax   snapshot   snapshot2   snapshot4   snapshot8   snapshot16   remoteMirror8   remoteMirror16   remoteMirror32   remoteMirror64   remoteMirror128   volumeCopy   goldKey   mixedDriveTypes   highPerformanceTier   SSDSupport   safeStoreSecurity   safeStoreExternalKeyMgr   protectionInformation) To use the High Performance Tier premium feature, you must configure a storage array as one of these: <ul style="list-style-type: none"> <li>■ SHIPPED_ENABLED</li> <li>■ SHIPPED_ENABLED=FALSE; KEY_ENABLED=TRUE</li> </ul>
<i>repository-spec</i>	<i>instance-based-repository-spec</i>   <i>count-based-repository-spec</i>
<i>instance-based-repository-spec</i>	(repositoryRAIDLevel = <i>repository-raid-level</i> repositoryDrives= ( <i>drive-spec-list</i> ) [repositoryPoolUserLabel = <i>user-label</i> ] [moduleLossProtect=(TRUE   FALSE) <sup>1</sup> ]   [drawerLossProtect=(TRUE   FALSE) <sup>2</sup> ]   (repositoryPool= <i>user-label</i> [freeCapacityArea= <i>integer-literal</i> <sup>3</sup> ]) Specify the repositoryRAIDLevel parameter with the repositoryDrives parameter. Do not specify the RAID level or the drives with the pool. Do not set a value for the moduleLossProtect parameter when you specify a pool.
<i>count-based-repository-spec</i>	repositoryRAIDLevel = <i>repository-raid-level</i> repositoryDriveCount= <i>integer-literal</i> [repositoryPoolUserLabel = <i>user-label</i> ] [driveType= <i>drive-type</i> <sup>4</sup> ] [moduleLossProtect=(TRUE   FALSE) <sup>1</sup> ]   [drawerLossProtect=(TRUE   FALSE) <sup>2</sup> ]   [protectionInformation=(none   enabled) <sup>5</sup> ] 

Recurring Syntax	Syntax Value
<i>wwID</i>	<i>string-literal</i>
<i>gid</i>	<i>string-literal</i>
<i>host-type</i>	<i>string-literal</i>   <i>integer-literal</i>
<i>host-card-identifier</i>	(1   2   3   4)
<i>backup-device-identifier</i>	(1   n   all) n is a specific slot number. Specifying all includes all of the cache backup devices available to the entire storage array.
<i>nvsram-offset</i>	<i>hex-literal</i>
<i>nvsram-byte-setting</i>	<i>nvsram-value</i> = <i>0hexadecimal</i>   <i>integer-literal</i> The <i>0hexadecimal</i> value is typically a value from 0x0000 to 0xFFFF.
<i>nvsram-bit-setting</i>	<i>nvsram-mask</i> , <i>nvsram-value</i> = <i>0hexadecimal</i> , <i>0hexadecimal</i>   <i>integer-literal</i> The <i>0hexadecimal</i> value is typically a value from 0x0000 to 0xFFFF.
<i>ip-address</i>	(0-255).(0-255).(0-255).(0-255)
<i>ipv6-address</i>	(0-FFFF):(0-FFFF):(0-FFFF):(0-FFFF): (0-FFFF):(0-FFFF):(0-FFFF):(0-FFFF) You must enter all 32 hexadecimal characters.
<i>autoconfigure-vols-attr-value-list</i>	<i>autoconfigure-vols-attr-value-pair</i> { <i>autoconfigure-vols-attr-value-pair</i> }
<i>autoconfigure-vols-attr-value-pair</i>	<i>driveType</i> = <i>drive-type</i>   <i>driveMediaType</i> = <i>drive-media-type</i>   <i>raidLevel</i> = <i>raid-level</i>   <i>poolWidth</i> = <i>integer-literal</i>   <i>poolCount</i> = <i>integer-literal</i>   <i>volumesPerGroupCount</i> = <i>integer-literal</i> <sup>6</sup>   <i>hotSpareCount</i> = <i>integer-literal</i>   <i>segmentSize</i> = <i>segment-size-spec</i>   <i>cacheReadPrefetch</i> =(TRUE   FALSE) <i>securityType</i> =(none   capable   enabled) <sup>7</sup>   <i>protectionInformation</i> =(none   enabled) <sup>5</sup>
<i>create-volume-copy-attr-value-list</i>	<i>create-volume-copy-attr-value-pair</i> { <i>create-volume-copy-attr-value-pair</i> }
<i>create-volume-copy-attr-value-pair</i>	<i>copyPriority</i> =(highest   high   medium   low   lowest)   <i>targetReadOnlyEnabled</i> =(TRUE   FALSE)   <i>copyType</i> =(offline   online)   <i>repositoryPercentOfBase</i> =(20   40   60   120   default)   <i>repositoryGroupPreference</i> =(sameAsSource   otherThanSource   default)
<i>recover-raid-volume-attr-value-list</i>	<i>recover-raid-volume-attr-value-pair</i> { <i>recover-raid-volume-attr-value-pair</i> }
<i>recover-raid-volume-attr-value-pair</i>	<i>owner</i> =(a   b)   <i>cacheReadPrefetch</i> =(TRUE   FALSE)   <i>protectionInformation</i> =(none   enabled)

Recurring Syntax	Syntax Value
<i>cache-flush-modifier- setting</i>	immediate, 0, .25, .5, .75, 1, 1.5, 2, 5, 10, 20, 60, 120, 300, 1200, 3600, infinite
<i>serial-number</i>	string-literal
<i>usage-hint-spec</i>	usageHint=(multiMedia   database   fileSystem)
<i>iscsiSession</i>	[ <i>session-identifier</i> ]
<i>iscsi-host-port</i>	(1   2   3   4) The host port number might be 2, 3, or 4 depending on the type of controller you are using.
<i>ethernet-port-options</i>	enableIPv4=(TRUE   FALSE)   enableIPv6=(TRUE   FALSE)   IPv6LocalAddress= <i>ipv6-address</i>   IPv6RoutableAddress= <i>ipv6-address</i>   IPv6RouterAddress= <i>ipv6-address</i>   IPv4Address= <i>ip-address</i>   IPv4ConfigurationMethod=(static   dhcp)   IPv4GatewayIP= <i>ip-address</i>   IPv4SubnetMask= <i>ip-address</i>   duplexMode=(TRUE   FALSE)   portSpeed=(autoNegotiate   10   100   1000)
<i>iscsi-host-port-options</i>	IPv4Address= <i>ip-address</i>   IPv6LocalAddress= <i>ipv6-address</i>   IPv6RoutableAddress= <i>ipv6-address</i>   IPv6RouterAddress= <i>ipv6-address</i>   enableIPv4=(TRUE   FALSE)   enableIPv6=(TRUE   FALSE)   enableIPv4Priority=(TRUE   FALSE)   enableIPv6Priority=(TRUE   FALSE)   IPv4ConfigurationMethod=(static   dhcp)   IPv6ConfigurationMethod=(static   auto)   IPv4GatewayIP= <i>ip-address</i>   IPv6HopLimit= <i>integer</i>   IPv6NdDetectDuplicateAddress= <i>integer</i>   IPv6NdReachableTime= <i>time-interval</i>   IPv6NdRetransmitTime= <i>time-interval</i>   IPv6NdTimeOut= <i>time-interval</i>   IPv4Priority= <i>integer</i>   IPv6Priority= <i>integer</i>   IPv4SubnetMask= <i>ip-address</i>   IPv4VlanId= <i>integer</i>   IPv6VlanId= <i>integer</i>   maxFramePayload= <i>integer</i>   tcpListeningPort= <i>tcp-port-id</i>   portSpeed=(autoNegotiate   1   10)
<i>test-devices-list</i>	<i>test-devices</i> { <i>test-devices</i> }

Recurring Syntax	Syntax Value
<i>test-devices</i>	controller=(a   b) esms=( <i>esm-spec-list</i> ) drives=( <i>drive-spec-list</i> )
<i>snapshot-schedule-attribute-value-list</i>	<i>snapshot-schedule-attribute-value-pair</i> { <i>snapshot-schedule-attribute-value-pair</i> }
<i>time-zone-spec</i>	(GMT+HH:MM   GMT-HH:MM) [dayLightSaving=HH:MM]
<i>snapshot-schedule-attribute-value-pair</i>	startDate=MM:DD:YY scheduleDay=( <i>dayOfWeek</i>   all) startTime=HH:MM scheduleInterval= <i>interger</i> endDate=(MM:DD:YY   noEndDate) timesPerDay= <i>interger</i>

<sup>1</sup>For module loss protection to work, each drive in a pool must be in a separate module. If you set the `moduleLossProtect` parameter to `TRUE` and you have selected more than one drive from any one module, the storage array returns an error. If you set `moduleLossProtect` parameter to `FALSE`, the storage array performs operations, but the pool that you create might not have module loss protection.

If you set the `moduleLossProtect` parameter to `TRUE`, the storage array returns an error if the controller firmware cannot find drives that will enable the new pool to have module loss protection. If you set the `moduleLossProtect` parameter to `FALSE`, the storage array performs the operation even if it means that the pool might not have module loss protection.

<sup>2</sup>In modules that have drawers for holding the drives, drawer loss protection determines whether data on a volume is accessible or inaccessible if a drawer fails. To help make sure that your data is accessible, set the `drawerLossProtect` parameter to `TRUE`. For drawer loss protection to work, each drive in a pool must be in separate drawers. If you have a storage array configuration in which a pool spans several modules, you must make sure that the setting for drawer loss protection works with the setting for module loss protection. If you set the `moduleLossProtect` parameter to `TRUE`, you must set the `drawerLossProtect` parameter to `TRUE`. If you set the `trayLossProtect` parameter to `TRUE`, and you set the `drawerLossProtect` parameter to `FALSE`, the storage array returns an error message and a storage array configuration will not be created.

<sup>3</sup>To determine if a free capacity area exists, run the `show pool` command.

<sup>4</sup>The default drive (drive type) is `fibre` (Fibre Channel).

The `driveType` parameter is not required if only one type of drive is in the storage array. If you use the `driveType` parameter, you also must use the `hotSpareCount` parameter and the `poolWidth` parameter. If you do not use the `driveType` parameter, the configuration defaults to Fibre Channel drives.

<sup>5</sup>The `protectionInformation` parameter applies to the drives in a volume group. Using the `protectionInformation` parameter, you can specify that protected drives must be selected for a pool. If you want to set the `protectionInformation` parameter to `enabled`, all of the drives in the pool must be capable of T10 protection information. You cannot have a mix of drives that are capable of T10 protection information and drives that are not capable of T10 protection information in the pool.

<sup>6</sup>The `volumesPerGroupCount` parameter is the number of equal-capacity volumes per pool.

<sup>7</sup>The `securityType` parameter enables you to specify the security setting for a pool that you are creating. All of the volumes are also set to the security setting that you choose. Available options for setting the security setting include:

- `none` – The pool is not secure.
- `capable` – The pool is security capable, but security has not been enabled.
- `enabled` – The pool is security enabled.

---

**NOTE** A storage array security key must already be created for the storage array if you want to set `securityType=enabled`. (To create a storage array security key, use the `create storageArray securityKey` command).

---

## Usage Guidelines

This list provides guidelines for writing script commands on the command line:

- You must end all commands with a semicolon (;).
- You can enter more than one command on a line, but you must separate each command with a semicolon (;).
- You must separate each base command and its associated primary parameters and secondary parameters with a space.
- The script engine is not case sensitive. You can enter commands by using uppercase letters, lowercase letters, or mixed-case letters.
- Add comments to your scripts to make it easier for you and future users to understand the purpose of the script commands. (For information about how to add comments, see "[Adding Comments to a Script File](#).")

---

**NOTE** While the CLI commands and the script commands are not case sensitive, user labels (such as for volumes, hosts, or host ports) are case sensitive. If you try to map to an object that is identified by a user label, you must enter the user label exactly as it is defined, or the CLI commands and the script commands will fail.

---

## Adding Comments to a Script File

The script engine looks for certain characters or a command to show comments. You can add comments to a script file in three ways:

1. Add text after two forward slashes (//) as a comment until an end-of-line character is reached. If the script engine does not find an end-of-line character in the script after processing a comment, an error message appears, and the script operation is terminated. This error usually occurs when a comment is placed at the end of a script and you have forgotten to press the **Enter** key.

```
// Deletes the existing configuration.  
set storageArray resetConfiguration=true;
```

2. Add text between /\* and \*/ as a comment. If the script engine does not find both a starting comment notation and an ending comment notation, an error message appears, and the script operation is terminated.

```
/* Deletes the existing configuration */  
set storageArray resetConfiguration=true;
```

3. Use the `show` statement to embed comments in a script file that you want to appear while the script file is running. Enclose the text that you want to appear by using double quotation marks (" ").

```
show "Deletes the existing configuration";  
set storageArray resetConfiguration=true;
```



---

## Chapter 3: Configuring a Storage Array

This chapter explains how to run script commands from the command line to create a volume from a collection of drives and how to configure a redundant array of independent disks (RAID) storage array. This chapter assumes that you have a basic understanding of RAID concepts and terminology. Before you begin to configure your storage array, become familiar with these concepts:

- Controllers
- Drives
- Hot spares
- Pools
- Volumes
- RAID technology
- Hosts
- Host groups
- Host bus adapter (HBA) host ports
- Logical unit numbers (LUNs)

Configuring a RAID storage array requires caution and planning to make sure that you define the correct RAID level and configuration for your storage array. The main purpose in configuring a storage array is to create volumes, which are addressable by the hosts, from a collection of drives. The commands described in this chapter enable you to set up and run a RAID storage array. Additional commands are also available to provide you with more control and flexibility in managing and maintaining your storage array.

---

**NOTE** Many of these commands require a thorough understanding of the firmware as well as an understanding of the network components that need to be mapped. Use the CLI commands and the script commands with caution.

---

The sections in this chapter show some, but not all, of the CLI wrapper commands and the script commands. The commands in this chapter show how you can use the commands to configure a storage array. These presentations do not describe all possible usage and syntax for the commands. For complete definitions of the commands, including syntax, parameters, and usage notes, refer to the *Command Line Interface and Script Commands*.

This chapter contains examples of CLI command usage and script command usage. The command syntax that is used in the examples is for a host running a Microsoft operating system. As part of the examples, the complete `C:\` prompt and the DOS path for the commands are shown. Depending on your operating system, the prompt and path construct will vary.

For most commands, the syntax is the same for all Windows operating systems and UNIX operating systems, as well as for a script file. Windows operating systems, however, have an additional requirement when entering names on a command line. On Windows operating systems, you must enclose the name between two back slashes (`\ \`) in addition to other delimiters. For example, the following name is used in a command running under a Windows operating system:

```
[ \ "Engineering\ " ]
```

For a UNIX operating system, and when used in a script file, the name appears as follows:

```
[ "Engineering" ]
```

## Configuration Concepts

When you configure a storage array, you organize drives into a logical structure that provides storage capacity and data protection so that one or more hosts can safely store data in the storage array. This section provides definitions of the physical and logical components required to organize the physical disks into a storage array configuration. This section also describes how the components relate to each other.

### Controllers

All storage arrays have one or two controllers. The controllers are circuit-board assemblies that manage data and communication between the hosts and the storage array. The controller manages the data flow between the hosts and the drives, keeping track of the logical address of where the data resides. In general, each controller has a processor for performing control operations, NVSRAM for storing the firmware code that operates the storage array, and the buses along which the data flows.

The controllers are located in a controller module or an array module. The controller module or an array module has two positions for controllers: slot A and slot B. The script commands identify each controller by the slot in which the controller is installed. If controller module or an array module has only one controller, the controller must be in slot A. A controller module or an array module with two controllers is called a *duplex* module. A controller module or an array module with one controller is called a *simplex* module.

Early controller models D178 and FLX280 used minihubs; two connected to each controller. When viewed from the rear of the controller module, the host-side minihubs are numbered from left-to-right a1, b1, a2, and b2. The script commands identify the host channels by using these identifiers. Minihubs also support the drive-side, where each minihub represents a single channel to the drives. When viewed from the rear of the controller module, the drive minihubs are numbered from left to right 4, 3, 2, and 1. The script commands use these numbers to identify the drive channels.

Controller models SAT2700 and 6130 are used in an early array module that has a slot where either a controller or an environmental services monitor (ESM) can be used. When an ESM is used, the module is called a drive module.

Controllers manage the interface by running controller firmware to transmit and receive commands between the hosts and the drives. Host bus adapters facilitate the communication through whichever interface is selected. Typically, two host bus adapters and two paths are used to optimize redundancy.

The array modules and controller modules incorporate all host connections and drive module connections into each controller. The host ports must be identified in your command statements to let you complete their network configurations.

The more recent models of controllers do not use minihubs. These controllers have host ports that are integrated into the controller circuit boards or auxiliary circuit boards that are directly connected to the controller circuit boards.

The following table lists the array modules that do not use minihubs, the type of host port, and the number of host ports.

**Table 1 Host Ports and Host Interfaces for Controllers**

Model	Available Host Ports	Type of Host Interface
AM1331 array module	1	SAS
ST2530 array module	3	SAS
ST2510 array module	2	iSCSI
ST2540 array module	2	Fibre Channel

Model	Available Host Ports	Type of Host Interface
ST2500 M2 array module	2 or 4	SAS
	4	Fibre Channel
	4	iSCSI
6140 array module	2	Fibre Channel
6140 array module	4	Fibre Channel
6540 controller module	4	Fibre Channel
6580/6780 controller module	16	Fibre Channel
	4	iSCSI The four iSCSI host connections are used with eight Fibre Channel host connections.

The ST2530 array module has three host ports that are numbered from left to right: host port 1, host port 2, and host port 3 as seen from the rear of the array module.

The ST2510 and ST2540 array modules have two host ports on each controller, which are numbered from left to right: host port 1 and host port 2 as seen from the rear of the array module.

The host ports on the 6140 array module are numbered from left-to-right on controller B as Ch 1, Ch 2, Ch 3, and Ch 4. Controller A, which is installed upside-down in the array module, is numbered from right-to-left in the same sequence.

The controller in the 6540 controller module can have up to four host channels with one port for each channel; up to two drive channels with two ports per channel (for a total of four drive ports); and up to two Ethernet ports. In the 6540 controller module, the controllers are stacked one above the other. The top controller is A. The bottom controller is B.

For controller A, the host channel identifiers are a1, a2, a3, and a4, and the host bus adapter (HBA) host ports are labeled 1, 2, 3, and 4. For controller B, the host channel identifiers are b1, b2, b3, and b4, and the HBA host ports are labeled 1, 2, 3, and 4.

Controller A has drive channels 1 and 2. Drive ports labeled 3 and 4 connect to drive channel 1. Drive ports labeled 1 and 2 connect to Drive Channel 2. Controller B has drive channels 3 and 4. Drive ports labeled 1 and 2 connect to drive channel 3. Drive ports labeled 3 and 4 connect to drive channel 4. Each Ethernet port on a controller can have a unique IP address; however, both Ethernet ports share the same gateway IP address, subnet mask, and remote login settings.

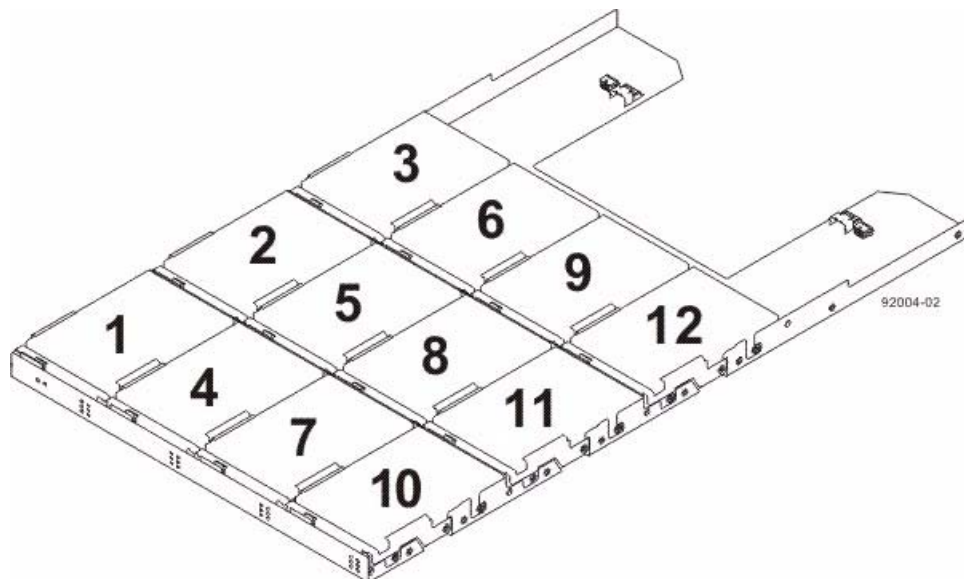
Each of the two controllers in the 6580/6780 controller module can have two host cards with four host ports on each card. Some 6580/6780 controller modules can have controllers with only one host card each. Controller A is inverted from controller B, which means that its host channels are upside-down.

## Drives

The drives store the data that is sent to the storage array. The drives are mounted in either an array module or a drive module. The array module has drives and controllers in one module. A drive module has only drives, and is connected to a controller through an environmental services monitor (ESM). In addition to the drives and ESMs, the drive module contains power supplies and fans. These components support drive module operation and can be maintained through the CLI.

Drives are located in a storage array by module ID and slot ID. Module ID values are 0 to 99. In older modules, module ID values are set during installation by switches on the rear of the modules. In newer modules, module ID values are set automatically when the power is applied.

The slot ID is the drive position in the drive module. A drive module can contain 12, 14, 16, 24, or 60 drives. In drive modules with fewer than 60 drives, slot ID values range from 1 to 32. In drive modules with 60 drives, slot ID values are defined by the drawer number and the position of the drive in the drawer. The drawer numbers range from 1 to 5, counting from top to bottom. The position of each drive in a drawer is shown in the following figure.



**Figure 1 Drive Drawer with Drives**

The total number of drives in a storage array depends on the model of the controller module or array module and the capacity of the drives. The following table lists, by controller module or array module model and drive module capacity, the maximum number of drives in a storage array.

**Table 2 Maximum Number of Drives Supported**

Controller Model	12-Drive Drive Module	14-Drive Drive Module	16-Drive Drive Module	24-Drive Drive Module	60-Drive Drive Module
AM1331 ST2530	48				
ST2510	48				
ST2540	48				
ST2500 M2 (simplex controller)	96			96	
ST2500 M2 (duplex controller)	192			192	
6140		112	112		
6140		112	112		
6180		112	112		
6540		224	224		
6580/6780			256		480

**NOTE** A maximum of seven drive modules can be on a channel when mixing 14-slot drive modules and 16-slot drive modules.

The maximum capacity in a storage array depends on the number of the drives in the and storage array the capacity of each drive in the storage array. The following table lists the maximum storage for each controller model based on the capacity of the drives.

**Table 3 Maximum Capacity with Supported Drives**

Drive Capacity	AM1331 ST2530 ST2510 ST2540	ST2500 M2	6140/6140	6180	6540	6580/6780
73-GB FC			8.0 TB		16.4 TB	
73-GB SAS	3.5 TB					
146-GB FC			16.0 TB		32.7 TB	
146-GB SAS	7.0 TB	28.0 TB				
150-GB SAS		28.8 TB				
300-GB FC			34.0 TB		67.2 TB	
300-GB SAS	14.4 TB	57.6 TB				
450-GB FC				50.0 TB		201.0 TB
450-GB SAS		86.4 TB				
500-GB SATA	24.0 TB		56.0 TB		112.0 TB	
500-GB SAS		96.0 TB				
600-GB SAS		115.2 TB				
750-GB SATA	36.0 TB					
1.0-TB SAS		192.0 TB				
1.0-TB SATA	48.0 TB			112.0 TB		480.0 TB

## Hot Spare Drives

A hot spare is a drive that acts as a standby in the event that a drive containing data fails. The hot spare is a drive that has not been assigned to a particular pool and, as such, can be used in any pool. You can use the hot spare feature with RAID Level 1, RAID Level 3, RAID Level 5, or RAID Level 6. If a drive in a pool fails, the controllers automatically replace the failed drive with a hot spare. The controllers use redundancy data to reconstruct the data from the failed drive onto the hot spare. To be most effective, the drive that you assign as a hot spare must have a capacity equal to or greater than the capacity of the largest drive in the storage array. The hot spare must be the same type of drive as the drive that failed (for example, a Serial Advanced Technology Attachment [SATA] hot spare cannot replace a Fibre Channel hot spare).

You can assign drives to act as hot spares manually or have the script commands automatically assign hot spares. If you manually assign a drive to be a hot spare, you must identify the drive by module ID and slot ID. When you let the script commands automatically assign hot spares, you must enter the number of hot spares that you want in the storage array.

## Drive Security with Encryption Services

Drive Security is a premium feature that prevents unauthorized access to the data on a drive that is physically removed from the storage array. Controllers in the storage array have a *security key*. Secure drives provide access to data only through a controller that has the correct security key. Drive Security is a premium feature of the storage management software and must be enabled either by you or your storage vendor.

The Drive Security premium feature requires *security capable* drives. A security capable drive encrypts data during writes and decrypts data during reads. Each security capable drive has a unique drive encryption key.

When you create a *secure pool* from security capable drives, the drives in that pool become security enabled. When a security capable drive has been security enabled, the drive requires the correct security key from a controller to read or write the data. All of the drives and controllers in a storage array share the same security key. The shared security key provides read and write access to the drives, while the drive encryption key on each drive is used to encrypt the data. A security capable drive works like any other drive until it is security enabled.

Whenever the power is turned off and turned on again, all of the security-enabled drives change to a *security locked* state. In this state, the data is inaccessible until the correct security key is provided by a controller.

You can view the Drive Security status of any drive in the storage array from the **Drive Properties** dialog. The drive can have one of these capabilities:

- Security Capable
- Secure – Security enabled or disabled
- Read/Write Accessible – Security locked or unlocked

You can view the Drive Security status of any volume group in the storage array by using the `show volume group` command. The pool can have one of these capabilities:

- Security Capable
- Secure

The following table shows how to interpret the security properties status of a pool.

**Table 4 Pool Security Properties**

	Security Capable – yes	Security Capable – no
<b>Secure – yes</b>	The pool is composed of all Encryption Services (ES) drives and is in a Secure state.	Not applicable. Only ES drives can be in a Secure state.
<b>Secure – no</b>	The pool is composed of all ES drives and is in a Non-Secure state.	The pool is not entirely composed of ES drives.

You can erase security-enabled drives so that you can reuse the drives in another volume group or in another storage array. Use the `start secure erase` command to completely erase any data on a security-enabled drive. Using the `start secure erase` command results in the loss of all of the data on a drive, and is irreversible. You can never recover the data.

The storage array password protects a storage array from potentially destructive operations by unauthorized users. The storage array password is independent from the Drive Security premium feature and should not be confused with the pass phrase that is used to protect copies of a security key. However, it is good practice to set a storage array password before you create, change, or save a security key or unlock secure drives.

### **Commands for ES Drives**

You can use these commands to enable security in the ES drives and manage the drives.

- `activate hostPort`
- `activate iscsiInitiator`

- `create volume – Automatic drive select`
- `create volume – Free extent based select`
- `create volume – Manual drive select`
- `create storageArray securityKey`
- `create volumeGroup`
- `enable volumeGroup security`
- `export storageArray securityKey`
- `import storageArray securityKey`
- `set controller`
- `set storageArray securityKey`
- `show drive`
- `start secure erase`

## Pools

A pool is a set of drives that are logically grouped together by the controllers in a storage array. After you create a pool, you can create one or more volumes in the pool. A pool is identified by a sequence number that is defined by the controller firmware when you created the pool.

**NOTE** Some storage arrays permit different drive types in the same module; however, you cannot have a combination of different drives in the same pool.

To create a pool, you must define the capacity and the RAID level.

Capacity is the size of the pool. Capacity is determined by the number of drives that you assign to the pool. You can use only unassigned drives to create a pool. (In this programming guide, the storage space on unassigned drives constitutes the *unconfigured capacity* of a storage array.)

*Free capacity* is a contiguous region of unassigned capacity in a designated pool. Before you create a new volume in a pool, you need to know the free capacity space so that you can determine the size of the volume.

The RAID level is the level of data protection that you want to define for your storage array. The RAID level that you choose affects storage capacity. When you configure your storage array, you must consider this compromise between data protection and storage capacity. In general, the more protection that you need, the less storage capacity is available in your storage array.

The following table lists the minimum number of drives and the maximum number of drives that you can use in a pool based on the RAID level that you want to assign to the pool.

**Table 5 Maximum Number of Drives in a Pool Based on RAID Level**

RAID Level	Minimum Number of Drives	Maximum Number of Drives	Redundancy
0	1	All	None
1	1	All	Mirrored pairs
3	3	30	1 drive
5	3	30	1 drive
6	5	30	2 drives

You can determine the size of the pool by multiplying the maximum number of drives in the pool by the capacity of the smallest drive in the pool.

---

## Volumes

A volume is a logical component (object) that is the basic structure that is created on the storage array to store data. A volume is a contiguous subsection of a pool that is configured to meet application needs for data availability and I/O performance. The storage management software administers a volume as if the volume is one “drive” for data storage. Volumes are identified by names or labels that users choose. The volume names can be any combination of alphanumeric characters, hyphens (-), and underscores (\_). The maximum length of a volume name is 30 characters.

The script commands support the following types of volumes:

- **Standard volume** – A logical structure that is the principal type of volume for data storage. A standard volume is the most common type of volume in a storage array.
- **Access volume** – A factory-configured volume in a storage area network (SAN) environment that is used for communication between the storage management software and the storage array controller. The access volume uses a logical unit number (LUN) address and consumes 20 MB of storage space. The 20 MB of access volume storage space is not available for data storage.

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**NOTE** Use the access volume only for in-band-managed storage arrays.

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- **Snapshot volume** – A logical point-in-time image of another volume. A snapshot volume is the logical equivalent of a complete physical copy; however, it is not an actual, physical copy. Instead, the firmware tracks only the data blocks that are overwritten and copies those blocks to a snapshot repository volume.
- **Snapshot repository volume** – A special volume in the storage array that is created as a resource for a snapshot volume. A snapshot repository volume contains snapshot data and copy-on-write data for a particular snapshot volume.
- **Base volume** – A standard volume from which you create a snapshot volume. The term “base volume” is used only to show the relationship between a standard volume from which you are taking the point-in-time image and a snapshot volume.
- **Primary volume** – A standard volume in a Data Replicator Software relationship. The primary volume accepts host data transfers and stores application data. When you first create the mirror relationship, data from the primary volume is copied in its entirety to the associated secondary volume.
- **Secondary volume** – A standard volume in a Data Replicator Software relationship that maintains a mirror (or copy) of the data from its associated primary volume. The secondary volume remains unavailable to host applications while mirroring is underway. In the event of a disaster or a catastrophic failure of the primary site, a system administrator can promote the secondary volume to a primary role.
- **Mirror repository volume** – A special volume in a Data Replicator Software configuration that is created as a resource for each controller in both the local storage array and the remote storage array. The controller stores mirroring information on this volume, including information about remote writes that are not yet complete. A controller can use this information to recover from controller resets and accidental power shutdown of the storage arrays.

---

**NOTE** Snapshot Volume and Data Replicator Software are premium features that you must activate before you can use them. For more information about snapshot volumes, see [Chapter 4 “Using the Snapshot Premium Feature.”](#) For more information about Data Replicator Software, see [Chapter 5 “Using the Data Replicator Software Premium Feature.”](#)

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The number and capacity of the volumes in your storage array depends on the type of controller in the storage array. The following table lists the maximum number of volumes in a storage array that each controller model supports.



**Table 6 Maximum Number of Volumes Each Controller Model Supports**

Specification	AM1331 ST2530 ST2510 ST2540	ST2500 M2	6140 or 6140	6180	6540 or 6580/6780
Maximum number of volumes per storage array	256	256	1024	1024	2048
Maximum number of volumes per pool	256	256	256	256	256
Maximum volume size	Number of drives supported by array x (capacity of largest supported drive by array – 512 MB)				
Maximum number of drives per pool using RAID Level 5	30	30	30	30	30
Maximum number of remote mirrors	16	16	64	64	128

**NOTE** The maximum volume size is limited by the size of the drives and the configuration of the storage array. The last 512 MB on each drive is reserved for storage array configuration database and potential future expansion. For practical considerations, you want to constrain the maximum volume size so that drive replacement and volume reconstruction does not take an excessive amount of time.

## RAID Levels

The RAID level defines a storage architecture in which the storage capacity on the drives in a pool is separated into two parts: part of the capacity stores the user data, and the remainder stores redundant or parity information about the user data. The RAID level that you choose determines how user data is written to and retrieved from the drives. Using the script commands, you can define five RAID levels: RAID Level 0, RAID Level 1, RAID Level 3, RAID Level 5, and RAID Level 6. Each level provides different performance and protection features.

RAID Level 0 provides the fastest storage access but does not provide any redundant information about the stored data. RAID Level 1, RAID Level 3, RAID Level 5, and RAID Level 6 write redundancy information to the drives to provide fault tolerance. The redundancy information might be a copy of the data or an error-correcting code that is derived from the data. In RAID Level 1, RAID Level 3, RAID Level 5, or RAID Level 6 configurations, if a drive fails, the redundancy information can be used to reconstruct the lost data. Regardless of the RAID level that you choose, you can configure only one RAID level across each pool. All redundancy information for a pool is stored within the pool. The following table lists the RAID levels and describes the configuration capabilities of each level.

**Table 7 RAID Level Configurations**

RAID Level	Configuration
0	<b>Non-redundant striping mode</b> – Use this level for high-performance needs. RAID Level 0 does not provide any data redundancy. RAID Level 0 stripes data across all of the drives in the pool. If a single drive fails, all of the associated volumes fail and all data is lost. RAID Level 0 is suited for noncritical data. It is not recommended for high-availability needs.
1	<b>Striping mirroring mode</b> – RAID Level 1 uses drive mirroring to create an exact copy from one drive to another drive. A minimum of two drives are required; one for the user data, and one for the mirrored data. RAID Level 1 offers high performance and the best data availability.  Data is written to two drives simultaneously. If one drive in a drive pair fails, the system can instantly switch to the other drive without any loss of data or service. Only half of the drives in the pool are available for user data. If a single drive fails in a RAID Level 1 pool, all of the associated volumes become degraded, but the mirror drive provides access to the data. RAID Level 1 can survive multiple drive failures as long as no more than one failure occurs per mirrored pair. If a drive pair fails, all of the associated volumes fail, and all data is lost.
3	<b>High-bandwidth mode</b> – RAID Level 3 stripes both user data and redundancy data (in the form of parity) across the drives. The equivalent of the capacity of one drive is used for the redundancy data. RAID Level 3 works well for large data transfers in applications, such as multimedia or medical imaging, that write and read large sequential chunks of data.  If a single drive fails in a RAID Level 3 pool, all of the associated volumes become degraded, but the redundancy data lets the data be reconstructed. If two or more drives fail, all of the associated volumes fail, and all data is lost.
5	<b>High I/O mode</b> – RAID Level 5 stripes both user data and redundancy data (in the form of parity) across the drives. The equivalent of the capacity of one drive is used for the redundancy data. RAID Level 5 works well for multiuser environments, such as databases or file system storage, where typical I/O size is small, and a high proportion of read activity exists.  If a single drive fails in a RAID Level 5 pool, all of the associated volumes become degraded, and the redundancy data permits the data to be reconstructed. If two or more drives fail, all of the associated volumes fail, and all data is lost.
6	<b>Data protection or continuous access mode</b> – RAID Level 6 stripes both user data and redundancy data (in the form of parity) across the drives. A minimum of five drives are required for a RAID Level 6 pool. The equivalent capacity of two drives is used for the redundancy data. Two different algorithms calculate redundancy data, which are in the form of both a P parity and a Q parity.  RAID Level 6 works well for larger drive sizes. Recovery from a second drive failure in the same pool is possible. If two drives fail in a RAID Level 6 pool, all of the associated volumes become degraded, but the redundancy data permits the data to be reconstructed. If three or more drives fail, all of the associated volumes fail, and all data is lost.

**NOTE** RAID Level 6 is only available to those controllers that are capable of supporting the P+Q calculation. The model 6540 controller does not support RAID Level 6. The ST2500 M2, 6140, 6140, 6180, and 6580/6780, controllers support RAID Level 6. A premium feature key enables customers to use RAID Level 6 and to use dynamic RAID-level migration. Refer to the "Set Volume Group" command in *Command Line Interface and Script Commands for Version 10.75* for information explaining how to set your pool to RAID Level 6.

## Hosts

A host is a computer that is attached to the storage array for accessing the volumes in the storage array. The host is attached to the storage array through HBA host ports, which are connectors on host bus adapter circuit boards. You can define specific volume-to-LUN mappings to an individual host or assign the host to a host group that shares access to one or more volumes. Hosts are identified by names or labels that users choose. The host name can be any combination of alphanumeric characters, hyphens, and underscores. The maximum length of the host name is 30 characters.

In addition to a host name, some script commands require you to identify a host by its “type.” A host type identifies the operating system under which the host is running (such as Windows, Solaris, or Linux). Specifying the host type lets the controllers in the storage array adapt their behavior (such as LUN reporting and error conditions) to the operating system of the host that is sending the information. Host types are identified by a label or an index number that is generated by the controller firmware.

## Host Groups

A host group is a topological element that you can define if you want to designate a collection of hosts that will share access to the same volumes. A host group is a logical entity. Host groups are identified by names or labels that users choose. The host group name can be any combination of alphanumeric characters with a maximum length of 30 characters.

## Host Bus Adapter Host Ports

A host bus adapter (HBA) provides the physical connection from the host to the storage array. The host port is a physical connector on an HBA. The HBA is a circuit board that is installed in the host. The HBA can have one or more host ports. Each host port is identified by a unique, 16-byte World Wide Identifier (WWID). If the HBA has more than one host port, each host port has a unique ID.

When you first turn on the power to a storage array, the storage management software automatically detects the HBA host ports. Initially, all detected host ports belong to a default group. You can use script commands to identify the WWIDs on a storage array and, if you choose, change them. If you move an HBA host port, you must remap any volume-to-LUN mappings. Access to your data is lost until you remap the volumes.

The maximum number of HBA host ports that you can logically define for your storage array depends on the type of controller in the storage array. The following table lists the maximum number of HBA host ports that you can define.

**Table 8 Maximum Number of HBA Host Ports per Controller**

Controller Models	Maximum Number of Host Ports
1331, 1333, 1532, 1932	256
ST2500 M2	256
6140 or 6140	256
6180	256
6540	512
6580/6780	1024

## Logical Unit Numbers

In the context of the CLI commands and the script commands, a logical unit number (LUN) is a unique value that identifies the volumes in a storage array. The hosts identify the volumes that they want to access using the LUN values. When you create a volume, the firmware assigns the LUN values, or you can assign LUN values when you enable the Storage Domains premium feature. A volume can have only one LUN and can be mapped to only one host or host group. Each host has unique addressing capability. That is, when more than one host accesses a storage array, each host might use the same LUN to access different volumes. The LUNs might be the same, but the volumes are different. If you are mapping to a host group, the LUN that you specify must be available on every host in the host group.

---

## Configuring a Storage Array

When you configure a storage array, you want to maximize the data availability by making sure that the data is quickly accessible while maintaining the highest level of data protection possible. The speed by which a host can access data is affected by these items:

- The RAID level for the pool
- The settings for the segment size and the cache size
- Whether the cache read prefetch capability is turned on or turned off

Data protection is determined by the RAID level, hardware redundancy (such as global hot spares), and software redundancy (such as the Data Replicator Software premium feature and the Snapshot Volume premium feature).

In general, you configure a storage array by defining a pool and its associated RAID level, defining the volumes, and defining which hosts have access to the volumes. This section explains how to use the script commands to perform the general steps to create a configuration from an array of drives.

### Determining What Is on Your Storage Array

Even when you create a configuration on a storage array that has never been configured, you still need to determine the hardware features and software features that are to be included with the storage array. When you configure a storage array that has an existing configuration, you must make sure that your new configuration does not inadvertently alter the existing configuration, unless you are reconfiguring the entire storage array. For example, consider the case where you want to create a new pool on unassigned drives. Before you create a new pool, you must determine which drives are available. The commands that are described in this section help you to determine the components and the features in your storage array.

The command that returns general information about the storage array is the `show storageArray` command. This command returns information about the components and properties of your storage array, including these items:

- A detailed profile of the components and features in the storage array
- The age of the battery
- The default host type (which is the current host type)
- Other host types that you can select
- The hot spare locations
- The identifiers for enabled premium features
- The logical component profiles and the physical component profiles
- The time to which both controllers are set
- The controller that currently owns each volume in the storage array

To return the most information about the storage array, run the `show storageArray` command with the `profile` parameter. This example shows the complete CLI command and script command running on a Windows operating system:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "show storageArray profile;"
```

This example identifies the storage array by the IP addresses 123.45.67.88 123.45.67.89. These addresses are the IP addresses of the controllers in the storage array. You can also identify the storage array by name.

The `show storageArray profile` command returns detailed information about the storage array. The information appears in several display screens. You might need to increase the size of your display buffer to see all of the information. Because this information is so detailed, you might want to save the output to a file. To save the output to a file, enter the command as shown in this example:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "show storageArray profile;" -o
c:\folder\storagearrayprofile.txt
```

In this example, the name `folder` is the folder in which you choose to place the profile file, and `storagearrayprofile.txt` is the name of the file. You can choose any folder and any file name.

---

**ATTENTION Possible loss of data** – When you write information to a file, the script engine does not check to determine if the file name already exists. If you choose the name of a file that already exists, the script engine writes over the information in the file without warning.

---

To return a brief list of the storage array features and components, use the `summary` parameter. The command looks like this example:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "show storageArray summary;"
SUMMARY_ _ _ _ _
Number of controllers: 1
Number of volume groups: 2
Total number of volumes (includes access volume): 3 of 2048      used
    Number of standard volumes: 5
    Number of access volumes: 1
    Number of snapshot repositories: 0
Number of snapshot volumes: 0
Number of copies: 0
Number of drives: 9
Supported drive types: Fibre (9)
Total hotspare drives: 1
    Standby: 1
    In use: 0
Access volume: LUN 7 (see Mappings section for details)
Default host type: Linux (host type index 6)
Current configuration
    Firmware version: PkgInfo ww.xx.yy.zz
    NVSRAM version: N1111-234567-001
Pending configuration
    Staged firmware download supported: Yes
    Firmware version: Not applicable
    NVSRAM version: Not applicable
    Transferred on: Not applicable
NVSRAM configured for batteries: Yes
Start cache flushing at (in percentage): 80
Stop cache flushing at (in percentage): 80
Cache block size (in KB): 4
Media scan frequency (in days): Disabled
Failover alert delay (in minutes): 5
Feature enable identifier: 1234567891011121314151617181ABCD
```

The summary information is also returned as the first section of information when you use the `profile` parameter.

The `show` commands return information about the specific components of a storage array. The information returned by each of the `show` commands is the same as the information returned by the `show storageArray profile` command, but the information is constrained to the specific component. Following is a list of the `show` commands.

- `show controller`
- `show drive`

- 
- `show driveChannels stats`
  - `show storageArray hostTopology`
  - `show storageArray lunMappings`
  - `show allVolumes`
  - `show volumeGroup`
  - `show volume reservations`
  - `show controller NVSRAM`
  - `show storageArray autoConfigure`
  - `show storageArray unreadableSectors`
  - `show volumeCopy sourceCandidates`
  - `show volumeCopy targetCandidates`
  - `show volume performanceStat`

## Clearing the Configuration

If you want to create a completely new configuration on a storage array that already has an existing configuration, use the `clear storageArray configuration` command. This command deletes all of the existing configuration information, including all of the pools, volumes, and hot spare definitions from the controller memory.

---

**ATTENTION Possible damage to the storage array configuration** – As soon as you run this command, the existing storage array configuration is deleted.

---

The command has this form:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "clear storageArray configuration;"
```

This command has two parameters that you can use to limit the amount of configuration information removed:

- `all` – Removes the entire configuration of the storage array, including security information and identification information. Removing all of the configuration information returns the storage array to its initial state.
- `volumeGroups` – Removes the volume configuration and the pool configuration, but leaves the rest of the configuration intact.

If you want to create new pools and volumes within the storage array, you can use the `clear storageArray configuration` command with the `volumeGroups` parameter to remove existing pools in a pre-existing configuration. This action destroys the pre-existing configuration. Use the `clear storageArray configuration` command only when you create a new configuration.

## Using the Auto Configure Command

The `autoConfigure storageArray` command creates the pools on a storage array, the volumes in the pools, and the hot spares for the storage array. When you use the `autoConfigure storageArray` command, you define these parameters:

- The type of drives (Fibre, SATA, or SAS)
- The RAID level
- The number of drives in a pool
- The number of pools
- The number of volumes in each pool
- The number of hot spares

- The size of each segment on the drives
- A read ahead multiplier

After you define these parameters, the SANtricity ES Storage Manager software creates the pools, the volumes, and the hot spares. The controllers assign pool numbers and volume numbers as they are created. After the SANtricity ES Storage Manager software creates the initial configuration, you can use the `set volume` command to define volume labels.

Before you run the `autoConfigure storageArray` command, run the `show storageArray autoConfigure` command. The latter command returns a list of parameter values that the SANtricity ES Storage Manager software uses to automatically create a storage array. If you would like to change any of the parameter values, you can do so by entering new values for the parameters when you run the `autoConfigure storageArray` command. If you are satisfied with the parameter values that the `show storageArray autoConfiguration` command returns, run the `autoConfigure storageArray` command without new parameter values.

The `autoConfigure storageArray` command has this form:

When you use the `autoConfigure storageArray` command, two symbol functions (`getAutoConfigCandidates` and `createAutoConfig`) are used that let the client retrieve default settings for the various automatic configuration parameters, change the settings, query what the results of those changes would be and, finally, apply the desired parameters to create a configuration. The configurability portion of this feature provides enhancements to the automatic pool creation algorithms, which produce pools with improved performance and more information about drive and volume attributes so the user can make better choices when configuring volumes manually.

The `volumeGroupWidth` parameter defines the number of unassigned drives that you want to use for each new pool.

The `volumeGroupCount` parameter defines the number of new pools that you want in the storage array.

The `volumesPerGroupCount` parameter defines the number of volumes that you want in each pool.

The `hotSpareCount` parameter defines the number of hot spares that you want in each pool.

The `segmentSize` parameter defines the amount of data, in KB, that the controller writes on a single drive in a volume before writing data on the next drive. The smallest units of storage are data blocks. A data block stores 512 bytes of data. The size of a segment determines how many data blocks that it contains. An 8-KB segment holds 16 data blocks. A 64-KB segment holds 128 data blocks.

---

**NOTE** For optimal performance in a multiuser database or file system storage environment, set the segment size to minimize the number of drives that are needed to satisfy an I/O request.

---

Using a single drive for a single request leaves other drives available to simultaneously service other requests. Valid segment size values are 8, 16, 32, 64, 128, 256, and 512.

---

**NOTE** If you set the cache block size to 16, you cannot create a volume with a segment size of 8.

---

If the volume is for a single user with large I/O requests (such as multimedia), performance is maximized when a single I/O request can be serviced with a single data stripe. A data stripe is the segment size multiplied by the number of drives in the pool that are used for data storage. In this environment, multiple drives are used for the same request, but each drive is accessed only once.

The `cacheReadPrefetch` parameter turns on or turns off the ability of the controller to read additional data blocks into the cache. When you turn on cache read prefetch, the controller copies additional data blocks into the cache while it is reading requested data blocks from a drive into the cache. This action increases the chance that a future request for data can be fulfilled from the cache, which improves the speed with which data is accessed. The number of additional data blocks that the controller reads into the cache is determined by the configuration settings for the storage array that you use. Cache read prefetch is important for applications that use sequential I/O, such as multimedia applications.

Valid values for the `cacheReadPrefetch` parameter are `TRUE` or `FALSE`. If you want to turn on cache read prefetch, set the `cacheReadPrefetch` parameter to `TRUE`. If you want to turn off cache read prefetch, set the `cacheReadPrefetch` parameter to `FALSE`.

The following table lists the default values for the segment size and cache read prefetch settings for different storage array uses.

**Table 9 Default Values for Segment Size and Cache Read Prefetch**

Storage Array Use	Segment Size (KB)	Cache Read Prefetch
File system	128	TRUE
Database	128	TRUE
Multimedia	256	TRUE

Use the `securityType` parameter when you have security-capable drives that can support the Drive Security premium feature. This parameter enables you to specify the security level when you create the pool that uses the security-capable drives. The settings for the `securityType` parameter are:

- `none` – The pool and volumes are not secure.
- `capable` – The pool and volumes are capable of having security set, but security has not been enabled.
- `enabled` – The pool and volumes have security enabled.

After you have finished creating the pools and the volumes by using the `autoConfigure storageArray` command, you can further define the properties of the volumes in a configuration by using the `set volume` command.

#### **Example of the Auto Configuration Command**

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "autoConfigure storageArray driveType=fibre
raidLevel=5 volumeGroupWidth=8 volumeGroupCount=3
volumesPerGroupCount=4 hotSpareCount=2
segmentSize=8 cacheReadPrefetch=TRUE;"
```

The command in this example creates a storage array configuration by using Fibre Channel drives set to RAID Level 5. Three pools are created, and each pool consists of eight drives, which are configured into four volumes. The storage array has two hot spares. The segment size for each volume is 8 KB. The cache read prefetch is turned on, which causes additional data blocks to be written into the cache.

## **Using the Create Volume Command**

Use the `create volume` command to create new storage array volumes in three ways:

- Create a new volume while simultaneously creating a new pool to which you assign the drives
- Create a new volume while simultaneously creating a new pool to which the storage management software assigns the drives
- Create a new volume in an existing pool



---

You must have unassigned drives in the pool. You do not need to assign the entire capacity of the pool to a volume.

### Creating Volumes with User-Assigned Drives

When you create a new volume and assign the drives you want to use, the storage management software creates a new pool. The controller firmware assigns a pool number to the new pool. The command has this form:

```
create volume drives=(moduleID1, slotID1... moduleIDn, slotIDn)
raidLevel=(0 | 1 | 3 | 5 | 6) userLabel="volumeName"
[pool=[poolName]
capacity=volumeCapacity owner=(a | b)
cacheReadPrefetch=(TRUE | FALSE)
segmentSize=segmentSizeValue
moduleLossProtect=(TRUE | FALSE)]
```

---

**NOTE** The `capacity` parameter, the `owner` parameter, the `cacheReadPrefetch` parameter, the `segmentSize` parameter, the `trayLossProtect` parameter, the `drawerLossProtect` parameter, the `dssPreAllocate` parameter, and the `securityType` parameter are optional parameters (indicated by the placement inside the square brackets). You can use one or all of the optional parameters as needed to define your configuration. If you choose not to use any of the optional parameters, the default values of the parameters are used for your configuration.

---

The `userLabel` parameter is the name that you want to give to the volume. The volume name can be any combination of alphanumeric characters, hyphens, and underscores. The maximum length of the volume name is 30 characters. You must enclose the volume name with double quotation marks (" ").

The `drives` parameter is a list of the drives that you want to use for the pool. Enter the module ID and the slot ID of each drive that you want to use. Enclose the list in parentheses, separate the module ID value and the slot ID value of a drive with a comma, and separate each tray ID and slot ID pair with a space. This example shows you how to enter module ID values and slot ID values:

```
(1,1 1,2 1,3 1,4 1,5)
```

The `capacity` parameter defines the size of the volume. You do not need to assign the entire capacity of the drives to the volume. Later, you can assign any unused space to another volume.

The `owner` parameter defines the controller to which you want to assign the volume. If you do not specify a controller, the controller firmware determines the volume owner.

The `cacheReadPrefetch` parameter and the `segmentSize` parameter are the same as those described for the `autoConfigure storageArray` command.

The `trayLossProtect` parameter turns on or turns off module loss protection for the pool. (For a description of how module loss protection works, see "[Module Loss Protection](#).")

#### **Example of Creating Volumes with User-Assigned Drives**

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create volume drives=(1,1 1,2 1,3 2,1 2,2 2,3)
raidLevel=5 userLabel=\"Engineering_1\" capacity=20GB
owner=a cacheReadPrefetch=TRUE segmentSize=128;"
```

The command in this example automatically creates a new pool and a volume with the name `Engineering_1`. The pool uses RAID Level 5. The command uses six drives to construct the pool. The capacity of the volume will be 20 GB, which is distributed across all six drives. If each drive has a capacity of 73 GB, the total capacity of all the assigned disks is 438 GB.

73 GB x 6 drives = 438 GB

Because only 20 GB is assigned to the volume, 418 GB remains available (as unconfigured capacity) for other volumes that a user can add to this pool later.

---

438 GB - 20 GB pool size = 418 GB

Cache read prefetch is turned on, which causes additional data blocks to be written into the cache. The segment size for each volume is 128 KB. Module loss protection is set to `TRUE`, which prevents any operation to drives in the drive module if the drive module fails. Hot spares are not created for this new pool. You must create hot spares after you run this command.

## Creating Volumes with Software-Assigned Drives

If you choose to let the storage management software assign the drives when you create the volume, you need only to specify the number of drives that you want to use. The storage management software then assigns the drives. The controller firmware assigns a pool number to the new pool. To manually create pools and volumes, use the `create volume` command:

```
create volume driveCount=numberOfDrives
raidLevel=(0 | 1 | 3 | 5 | 6) userLabel=volumeName
[driveType=(fibre | SATA | SAS | PATA)]
[capacity=volumeCapacity | owner=(a | b) |
cacheReadPrefetch=(TRUE | FALSE) |
segmentSize=segmentSizeValue]
[trayLossProtect=(TRUE | FALSE)]
```

This command is similar to the previous `create volume` command in which users assign the drives. The difference between this command and the previous one is that this version of the command requires only the number and the type of drives you want to use in the pool. You do not need to enter a list of drives. All of the other parameters are the same. Module loss protection is performed differently when the storage management software assigns the drives than when a user assigns the drives. (For a description of the difference, see the topic "[Module Loss Protection](#).")

### Example of Creating Volumes with Software-Assigned Drives

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create volume driveCount=6 raidLevel=5
userLabel=\"Engineering_1\"
capacity=20GB owner=a cacheReadPrefetch=TRUE segmentSize=128;"
```

The command in this example creates the same volume as the example for the previous `create volume` command in which a user assigns the drives. The difference is that a user does not know which drives are assigned to this pool.

## Creating Volumes in an Existing Pool

If you want to add a new volume to an existing pool, use this command:

```
create volume volumeGroup=volumeGroupNumber
userLabel=volumeName
[freeCapacityArea=freeCapacityIndexNumber |
capacity=volumeCapacity | owner=(a | b) |
cacheReadPrefetch=(TRUE | FALSE) |
segmentSize=segmentSizeValue]
```

---

**NOTE** Parameters wrapped in square brackets or curly brackets are optional. You can use one or all of the optional parameters as needed to define your configuration. If you choose not to use any of the optional parameters, the default values of the parameter are provided for your configuration.

---

The `volumeGroup` parameter is the number of the pool in which you want to create a new volume. If you do not know the pool numbers on the storage array, you can use the `show allVolumes` summary command to get a list of the volumes and the pools to which the volumes belong.

The `userLabel` parameter is the name that you want to give to the volume. The volume name can be any combination of alphanumeric characters, hyphens, and underscores. The maximum length of the volume name is 30 characters. You must enclose the volume name with double quotation marks (" ").

The `freeCapacityArea` parameter defines the free capacity area to use for the volume. If a pool has several free capacity areas, you can use this parameter to identify which free capacity area to use for volume creation. You do not have to assign the entire capacity of the drives to the volume. Later, you can assign any unused space to another volume.

The usage of the `capacity` parameter, the `owner` parameter, the `cacheReadPrefetch` parameter, and the `segmentSize` parameter is the same as described in the previous examples of the `create volume` command.

## Module Loss Protection

The `trayLossProtect` parameter is a boolean switch that you set to turn on or turn off module loss protection. For module loss protection to work, each drive in a pool must be on a separate module. The way in which module loss protection works depends on the method that you choose to assign the drives for a pool.

When you assign the drives, if you set `trayLossProtect=TRUE` and have selected more than one drive from any one module, the storage array returns an error. If you set `trayLossProtect=FALSE`, the storage array performs operations, but the pool that you create does not have module loss protection.

When the controller firmware assigns the drives, if `trayLossProtect=TRUE`, the storage array posts an error if the controller firmware cannot provide drives that result in the new pool having module loss protection. If `trayLossProtect=FALSE`, the storage array performs the operation even if it means that the pool might not have module loss protection.

Module loss protection is not valid when creating volumes on existing pools.

## Modifying Your Configuration

For most configurations, after you have created your initial configuration by using the `autoConfigure storageArray` command or the `create volume` command, you must modify the properties of your configuration to make sure that it performs to meet the requirements for data storage. Use the `set` commands to modify a storage array configuration. This section describes how to modify these properties:

- The controller clocks
- The storage array password
- The storage array host type
- The storage array cache
- The global hot spares

## Setting the Controller Clocks

To synchronize the clocks on the controllers with the host, use the `set storageArray time` command. Run this command to make sure that event time stamps that are written by the controllers to the Event Log match the event time stamps that are written to the host log files. The controllers stay available during synchronization. This example shows the command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set storageArray time;"
```

---

## Setting the Storage Array Password

Use the `set storageArray` command to define a password for a storage array. The command has this form:

```
set storageArray password="password"
```

The `password` parameter defines a password for the storage array. Passwords provide added security to a storage array to help reduce the possibility of implementing destructive commands.

---

**ATTENTION Possible data corruption or data loss** – Implementing destructive commands can cause serious damage, including data loss.

---

Unless you define a password for the storage array, you can run all of the script commands. A password protects the storage array from any command that the controllers consider destructive. A destructive command is any command that can change the state of the storage array, such as volume creation; cache modification; or reset, delete, rename, or change commands.

If you have more than one storage array in a storage configuration, each storage array has a separate password. Passwords can have a maximum length of 30 alphanumeric characters. You must enclose the password in double quotation marks (" "). This example shows how to use the `set storageArray` command to define a password:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set storageArray password="1a2b3c4d5e";"
```

## Setting the Storage Array Host Type

Use the `set storageArray` command to define the default host type. The command has this form:

```
set storageArray defaultHostType=(hostTypeName | hostTypeIdentifier)
```

The `defaultHostType` parameter defines how the controllers in the storage array will communicate with the operating system on undefined hosts that are connected to the storage array SAN. This parameter defines the host type only for data I/O activities of the storage array. This parameter does not define the host type for the management station. The operating system can be Windows, Linux, or Solaris.

For example, if you set the `defaultHostType` parameter to `Linux`, the controller communicates with any undefined host if the undefined host is running a Linux operating system. Typically, you would need to change the host type only when you are setting up the storage array. The only time that you might need to use this parameter is if you need to change how the storage array behaves relative to the hosts that are connected to it.

Before you can define the default host type, you need to determine what host types are connected to the storage array. To return information about host types that are connected to the storage array, use the `show storageArray` command with the `defaultHostType` parameter or the `hostTypeTable` parameter. This command returns a list of the host types with which the controllers can communicate. This command does not return a list of the hosts. These examples show the use of the `show storageArray` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "show storageArray defaultHostType;"  
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "show storageArray hostTypeTable;"
```

This example shows how to define a specific default host type:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set storageArray defaultHostType=11;"
```

The value 11 is the host type index value from the host type table that appears after entering the previous command.

---

## Setting the Storage Array Cache

The cache is high-speed memory that holds data that is either written to the drives or read by the host. A controller has two memory areas that are used for intermediate storage of read data and write data. The read cache contains data that has been read from the drives but not yet transferred to the host. The write cache contains data from the host but not yet written to the drives.

The cache acts as a buffer so that data transfers between the host and the drive do not need to be synchronized. In read caching, the data for a read operation from the host might already be in the cache from a previous operation, which eliminates the need to access the drives. The data stays in the read cache until it is flushed. For write caching, a write operation stores data from the host in cache until it can be written to the drives.

The script command set provides two commands to define cache properties:

- `set storageArray`
- `set volume`

Use the `set storageArray` command to change the cache block size, the cache flush start value, and the cache stop value. The command has this form:

```
set storageArray cacheBlockSize=cacheBlockSizeValue |  
cacheFlushStart=cacheFlushStartSize |  
cacheFlushStop=cacheFlushStopSize
```

You can enter one, two, or all three of the parameters on the command line.

The cache block size value defines the size of the data block that is used by the controller in transferring data into or out of the cache. You can set the cache block size to either 4KB, 8KB, or 16KB. The value that you use applies to the entire storage array and all of the volumes in the storage array. For redundant controller configurations, this value includes all volumes owned by both controllers. Use smaller cache block sizes for systems that require transaction processing requests or I/O streams that are typically small and random. Use larger cache block sizes for large I/O, sequential, high-bandwidth applications. The choice of block size affects read/write performance. Large data transfers take longer in 4-KB block sizes than 16-KB block sizes. This example shows how to set the `cacheBlockSize` parameter:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set storageArray cacheBlockSize=16;"
```

To prevent data loss or corruption, the controller periodically writes cache data to the drives (flushes the cache) when the amount of unwritten data in the cache reaches a predefined level, called a start percentage. The controller also writes cache data to the drives when data has been in the cache for a predetermined amount of time. The controller writes data to the drives until the amount of data in the cache drops to a stop percentage level. Use the `set storageArray` command to set the start value and the stop value as percentages of the filled capacity of the cache. For example, you can specify that the controller start flushing the cache when it reaches 80-percent full and stop flushing the cache when it reaches 16-percent full. This example shows how to set these parameters:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set storageArray cacheFlushStart=80 cacheFlushStop=16;"
```

Low start percentages and low stop percentages provide for maximum data protection. For both low start percentages and low stop percentages, the chance that data requested by a read command is not in the cache is increased. When the data is not in the cache, the cache hit percentage for writes and I/O requests decreases. Low start values and low stop values also increase the number of writes that are necessary to maintain the cache level. Increasing the number of writes increases the system overhead and further decreases performance.

Use the `set volume` command to change settings for the cache flush modifier, cache without batteries enabled, mirror cache enabled, the read ahead multiplier, read cache enabled, and write cache enabled. Use this command to set properties for all of the volumes or for a specific volume in a pool. The command has this form:

```
set (allVolumes | volume [volumeName] |
volumes [volumeName1 ... volumeNameN]
volume <wwID>) |
cacheFlushModifier=cacheFlushModifierValue |
cacheWithoutBatteryEnabled=(TRUE | FALSE) |
mirrorCacheEnabled=(TRUE | FALSE) |
readCacheEnabled=(TRUE | FALSE) |
writeCacheEnabled=(TRUE | FALSE) |
cacheReadPrefetch=(TRUE | FALSE)
```

The `cacheFlushModifier` parameter defines the amount of time that data stays in the cache before it is written to the drives. The following table lists the values for the `cacheFlushModifier` parameter.

**Table 10 Values for the `cacheFlushModifier` Parameter**

Value	Meaning
Immediate	Data is flushed as soon as it is placed into the cache.
250	Data is flushed after 250 ms.
500	Data is flushed after 500 ms.
750	Data is flushed after 750 ms.
1	Data is flushed after 1 s.
1500	Data is flushed after 1500 ms.
2	Data is flushed after 2 s.
5	Data is flushed after 5 s.
10	Data is flushed after 10 s.
20	Data is flushed after 20 s.
60	Data is flushed after 60 s (1 min.).
120	Data is flushed after 120 s (2 min.).
300	Data is flushed after 300 s (5 min.).
1200	Data is flushed after 1200 s (20 min.).
3600	Data is flushed after 3600 s (1 hr.).
Infinite	Data in cache is not subject to any age or time constraints. The data is flushed based on other criteria managed by the controller.

This example shows how to set this parameter value for all of the volumes in the storage array:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set allvolumes cacheFlushModifier=10;"
```

**NOTE** Do not set the value of the `cacheFlushModifier` parameter above 10 seconds. An exception is for testing purposes. After running any tests in which you have set the values of the `cacheFlushModifier` parameter above 10 seconds, return the value of the `cacheFlushModifier` parameter to 10 or fewer seconds.

The `cacheWithoutBatteryEnabled` parameter turns on or turns off the ability of a host to perform write caching without backup batteries in a controller. To enable write caching without batteries, set this parameter to `TRUE`. To disable write caching without batteries, set this parameter to `FALSE`. If you set this parameter to `TRUE`, write caching continues, even when the controller batteries are completely discharged, not fully charged, or not present. If you do not have an uninterruptible power supply (UPS) and you enable this parameter, you can lose data if power to the storage array fails. This example shows how to set this parameter value:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set volume [\"Engineering\"]
cacheWithoutBatteryEnabled=FALSE;"
```

The `mirrorCacheEnabled` parameter turns on or turns off write caching with mirroring. Write caching with mirroring permits cached data to be mirrored across redundant controllers that have the same cache size. Data written to the cache memory of one controller also is written to the cache memory of the second controller. If one controller fails, the second controller can complete all outstanding write operations. To use this option, these conditions must exist:

- The controller pair must be an active/active pair.
- The controllers must have the same size cache.

To enable write caching with mirroring, set this parameter to `TRUE`. To disable write caching with mirroring, set this parameter to `FALSE`. This example shows how to set this parameter:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set volume [\"Accounting\"] mirrorCacheEnabled=TRUE;"
```

The `readCacheEnabled` parameter turns on or turns off the ability of the host to read data from the cache. Read caching enables read operations from the host to be stored in controller cache memory. If a host requests data that is not in the cache, the controller reads the needed data blocks from the drives and places them in the cache. Until the cache is flushed, all of the other requests for this data are fulfilled with cache data rather than from a read, which increases throughput. To enable read caching, set this parameter to `TRUE`. To disable read caching, set this parameter to `FALSE`. This example shows how to set this parameter:

```
c:\...\sm9\client>smcli 123.45.67.88 123.45.67.89
-c "set volume [\"Balance_04\"] readCacheEnabled=TRUE;"
```

The `writeCacheEnabled` parameter turns on or turns off the ability of the host to write data to the cache. Write caching enables write operations from the host to be stored in cache memory. The volume data in the cache is automatically written to the drives every 10 seconds. To enable write caching, set this parameter to `TRUE`. To disable write caching, set this parameter to `FALSE`. This example shows how to set this parameter:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set allVolumes writeCacheEnabled=TRUE;"
```

The `cacheReadPrefetch` parameter turns on or turns off the ability of the controller to read additional data blocks into cache. When you turn on cache read prefetch, the controller copies additional data blocks into cache while it is reading requested data blocks from a drive into cache. This action increases the chance that a future request for data can be fulfilled from the cache, which improves the speed with which data is accessed. The number of additional data blocks that the controller reads into cache is determined by the storage array configuration settings that you use. Cache read prefetch is important for applications that use sequential I/O, such as multimedia applications.

Valid values for the `cacheReadPrefetch` parameter are `TRUE` or `FALSE`. If you want to turn on cache read prefetch, set the `cacheReadPrefetch` parameter to `TRUE`. If you want to turn off cache read prefetch, set the `cacheReadPrefetch` parameter to `FALSE`. This example shows how to set this parameter:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set volume [\"Engineering_1\" \"Engineering_2\"]
cacheReadPrefetch=TRUE;"
```

## Setting the Modification Priority

Modification priority defines how much processing time is allocated for volume modification operations. Time allocated for volume modification operations affects system performance. Increases in volume modification priority can reduce read/write performance. The modification priority affects these operations:

- Copyback



- Reconstruction
- Initialization
- Changing the segment size
- Defragmentation of a pool
- Adding free capacity to a pool
- Changing the RAID level of a pool

The lowest priority rate favors system performance, but the modification operation takes longer. The highest priority rate favors the modification operation, but the system performance might be degraded.

Use the `set volume` command to define the modification priority for a volume. The command has this form:

```
set (allVolumes | volume [volumeName] |  
volumes [volumeName1 ... volumeNameN] volume <wwID> |  
accessVolume)  
modificationPriority=(highest | high | medium | low | lowest)
```

This example shows how to use this command to set the modification priority for volumes named `Engineering_1` and `Engineering_2`:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set volume [\"Engineering_1\" \"Engineering_2\"]  
modificationPriority=lowest;"
```

The modification rate is set to `lowest` so that system performance is not significantly reduced by modification operations.

## Assigning Global Hot Spares

You can assign or unassign global hot spares by using the `set drive` command. To use this command, you must identify the location of the drives by the module ID and the slot ID. Then, you set the `hotSpare` parameter to `TRUE` to enable the hot spare or `FALSE` to disable an existing hot spare. The command has this form:

```
set (drive [trayID,slotID] | drives  
[trayID1,slotID1 ... trayIDn,slotIDn]) hotSpare=(TRUE | FALSE)
```

This example shows how to set hot spare drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set drives [1,2 1,3] hotSpare=TRUE;"
```

Enter the module ID and the slot ID of each drive that you want to use. Enclose the list in square brackets, separate the module ID value and the slot ID value of a drive with a comma, and separate each module ID and slot ID pair with a space.

## Saving a Configuration to a File

After you have created a new configuration or if you want to copy an existing configuration for use on other storage arrays, you can save the configuration to a file by using the `save storageArray configuration` command. Saving the configuration creates a script file that you can run on the command line. The command has this form:

```
save storageArray configuration file="filename"  
[(allconfig | globalSettings=(TRUE | FALSE)) |  
volumeConfigAndSettings=(TRUE | FALSE) |  
hostTopology=(TRUE | FALSE) | lunMappings=(TRUE | FALSE)]
```



---

**ATTENTION Possible loss of data** – When information is written to a file, the script engine does not check to determine if the file name already exists. If you choose the name of a file that already exists, the script engine writes over the information in the file without warning.

---

You can choose to save the entire configuration or specific configuration features. This example shows how to set this parameter value:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "save storagearray configuration  
file=\"c:\\folder\\storagearrayconfig1.scr\";"
```

In this example, the name `folder` is the folder in which you want to place the profile file and `storagearrayconfig1.scr` is the name of the file. You can choose any folder and any file name. The file extension for a configuration file is `.scr`. The storage management software uses this extension when it creates the configuration file.

## Chapter 4: Using the Snapshot Premium Feature

The Snapshot premium feature creates a snapshot volume that you can use as a backup of your data. A snapshot volume is a logical point-in-time image of a standard volume. Because it is not a physical copy, a snapshot volume is created more quickly than a physical copy and requires less storage space on the drive. Typically, you create a snapshot volume so that an application, such as a backup application, can access the snapshot volume and read the data while the base volume stays online and user accessible. You can also create several snapshot volumes of a base volume and write data to the snapshot volumes to perform testing and analysis.

Snapshot volumes provide these capabilities:

- Create a complete image of the data on a base volume at a particular point in time
- Use only a small amount of storage space
- Provide for quick, frequent, non-disruptive backups, or testing new versions of a database system without affecting real data
- Provide for snapshot volumes to be read, written, and copied
- Use the same availability characteristics of the base volume (such as RAID protection and redundant path failover)
- Map the snapshot volume and make it accessible to any host on a storage area network (SAN). You can make snapshot data available to secondary hosts for read access and write access by mapping the snapshot to the hosts
- Create up to 16 snapshots per volume and up to 1024 snapshots per storage array. The maximum number of snapshots depends on the model of the controller. The maximum number of snapshot volumes is one-half of the total number of volumes that are supported by the controller.
- Increase the capacity of a snapshot volume

### How Snapshot Works

Three components comprise a snapshot volume: the base volume, the snapshot volume, and the snapshot repository volume. The following table lists the components and briefly describes what they do.

**Table 1 Components of a Snapshot Volume**

Component	Description
Base volume	A standard volume from which the snapshot is created
Snapshot volume	A logical point-in-time image of a standard volume
Snapshot repository volume	A volume that contains snapshot metadata and copy-on-write data for a particular snapshot volume

Based on information that you provide through the script commands, the storage management software creates an empty snapshot repository volume and defines the mapping from a base volume to the snapshot repository volume. The snapshot repository volume holds changed data that a host writes to the base volume. When the snapshot repository volume is first created, it holds only the metadata about the snapshot volume with which it is associated.

**NOTE** When you first create a snapshot repository volume, briefly stop all of the write operations to the base volume so that a stable image of the base volume is available.

When the host writes to the base volume, the new data is also copied to the snapshot repository volume. This action is called *copy-on-write*. A snapshot is constructed by combining the updated data in the snapshot repository volume with data in the base volume that has not been altered. This action creates a complete copy of the base volume at a specific point in time. The snapshot appears as a volume that contains the original data at the time of creation, but the snapshot is actually an image that is the combination of the snapshot repository volume and the original base volume. The snapshot repository volume, which houses original data that has been changed, is the only additional drive space that is needed for the snapshot volume. The additional drive space is typically 10 percent to 20 percent of the drive space of the base volume and varies depending on the amount of changes to the data. The longer a snapshot volume is active, the larger the snapshot repository volume must be. The default size of the snapshot repository volume is 20 percent of the base volume; however, you can set the size of the snapshot repository volume to other values.

You can read, write, and copy a snapshot volume. Data written by a host to the snapshot volume is handled in the snapshot repository volume. When a write occurs to the base volume of a snapshot volume, the new data also overwrites the appropriate snapshot repository volume data.

**Table 2 Snapshot Volume Commands**

Command	Description
<code>create snapshotVolume</code>	This command creates a snapshot volume.
<code>recreate snapshot</code>	This command starts a fresh copy-on-write operation by using an existing snapshot volume.
<code>recreate snapshot collection</code>	This command restarts multiple snapshot volumes as one batch operation by using one or many existing snapshot volumes.
<code>set (snapshotVolume)</code>	This command defines the properties for a snapshot volume and lets you rename a snapshot volume.
<code>stop snapshot</code>	This command stops a copy-on-write operation.

## Creating a Snapshot Volume

The `create snapshotVolume` command provides three methods for defining the drives for your snapshot repository volume:

- Defining the drives for the snapshot repository volume by their module IDs and their slot IDs.
- Defining a pool in which the snapshot repository volume resides. In addition, you can define the capacity of the snapshot repository volume.
- Defining the number of drives, but not specific drives, for the snapshot repository volume.

When you use the `create snapshotVolume` command to create a snapshot volume, the minimum information that you need to provide is the standard volume that you want to use for the base volume. When you create a snapshot volume by using minimum information, the storage management software provides default values for the other property parameters that are required for a completely defined snapshot volume.

### Creating a Snapshot Volume with User-Assigned Drives

Creating a snapshot volume by assigning the drives provides flexibility in defining your configuration by letting you choose from the available drives in your storage array. When you choose the drives for your snapshot volume, you automatically create a new pool. You can specify which drives to use and the RAID level for the new pool. The command has this form:

```
create snapshotVolume baseVolume="baseVolumeName"  
[repositoryRAIDLevel=(1 | 3 | 5 | 6)  
(repositoryDrives=(trayID1,slotID1 ... trayIDn,slotIDn)  
userLabel="snapshotVolumeName"  
warningThresholdPercent=percentValue  
repositoryPercentOfBase=percentValue  
repositoryUserLabel="repositoryName"  
repositoryFullPolicy=(failBaseWrites | failSnapShot)]  
[trayLossProtect=(TRUE | FALSE)]
```

This example shows a command in which users assign the drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "create snapshotVolume baseVolume=\"Mars_Spirit_4\"  
repositoryRAIDLevel=5 repositoryDrives=(1,1 1,2 1,3 1,4 1,5);"
```

The command in this example creates a new snapshot of the base volume Mars\_Spirit\_4. The snapshot repository volume consists of five drives that form a new pool. The new pool has RAID Level 5. This command also takes a snapshot of the base volume, which starts the copy-on-write operation.

This example shows how to use the command in a script file:

```
create snapshotVolume baseVolume="Mars_Spirit_4" repositoryRAIDLevel=5  
repositoryDrives=(1,1 1,2 1,3 1,4 1,5);
```

This example shows a minimal version of the command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "create snapshotVolume baseVolume=\"Mars_Spirit_4\";"
```

The command in this example creates a new snapshot for the base volume Mars\_Spirit\_4. The snapshot repository volume is created in the same pool as the base volume, which means that the snapshot repository volume has the same RAID level as the base volume. This command starts the copy-on-write operation.

This example shows how to use the command in a script file:

```
create snapshotVolume baseVolume="Mars_Spirit_4";
```

## Creating a Snapshot Volume with Software-Assigned Drives

With this version of the `create snapshotVolume` command, you choose an existing pool in which to place the snapshot repository volume. The storage management software determines which drives to use. You can also define how much space to assign to the snapshot repository volume. Because you are using an existing pool, the RAID level for the snapshot volume defaults to the RAID level of the pool in which you place it. You cannot define the RAID level for the snapshot volume. The command has this form:

```
create snapshotVolume baseVolume="baseVolumeName"  
[repositoryVolumeGroup=volumeGroupNumber  
freeCapacityArea=freeCapacityIndexNumber  
userLabel="snapshotVolumeName"  
warningThresholdPercent=percentValue  
repositoryPercentOfBase=percentValue  
repositoryUserLabel=repositoryName  
repositoryFullPolicy=(failBaseWrites | failSnapShot)]  
[trayLossProtect=(TRUE | FALSE)]
```

This example shows a command in which the storage management software assigns the drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create snapshotVolume baseVolume=\"Mars_Spirit_4\"
repositoryVolumeGroup=2 freeCapacityArea=2;"
```

The command in this example creates a new snapshot repository volume in pool 2. The base volume is Mars\_Spirit\_4. The size of the snapshot repository volume is 4 GB. This command also takes a snapshot of the base volume, starting the copy-on-write operation.

When you define the capacity of a snapshot repository volume, specify a size that is 20 percent of the size of the base volume. In the previous example, the size of the snapshot repository volume is set to 4 GB. The underlying assumption is that the base volume size is 20 GB (0.2 x 20 GB= 4 GB).

This example shows how to use the command in a script file:

```
create snapshotVolume baseVolume="Mars_Spirit_4"
repositoryVolumeGroup=2 freeCapacityArea=2;
```

## Creating a Snapshot Volume by Specifying a Number of Drives

With this version of the `create snapshotVolume` command, you must specify the number of drives and the RAID level that you want for the snapshot repository volume. This version of the `create snapshotVolume` command creates a new pool. You must have drives in the storage array that are not assigned to a pool for this command to work.

```
create snapshotVolume baseVolume="baseVolumeName"
[repositoryRAIDLevel=(1 | 3 | 5 | 6)
repositoryDriveCount=numberOfDrives
driveType=(fibre | SATA | SAS)
userLabel="snapshotVolumeName"
warningThresholdPercent=percentValue
repositoryPercentOfBase=percentValue
repositoryUserLabel="repositoryName"
repositoryFullPolicy=(failBaseWrites | failSnapShot)]
[trayLossProtect=(TRUE | FALSE)]
```

This example shows how to use a command in which users specify the number of drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create snapshotVolume baseVolume=\"Mars_Spirit_4\"
repositoryRAIDLevel=5 repositoryDriveCount=3;"
```

The command in this example creates a new snapshot repository volume that consists of three drives. Three drives comprise a new pool that has RAID Level 5. This command also takes a snapshot of the base volume, which starts the copy-on-write operation.

This example shows how to use the command in a script file:

```
create snapshotVolume baseVolume= "Mars_Spirit_4"
repositoryRAIDLevel=5 repositoryDriveCount=3;
```

## User-Defined Parameters

Use the parameters in the `create snapshotVolume` command to define the snapshot volume to suit the requirements of your storage array. The following table lists the parameters and briefly describes what the parameters do.

**Table 3 Snapshot Volume Parameters**

Parameter	Description
driveType	The type of drive that you want to use for the snapshot repository volume. The choice is <code>fibre</code> (Fibre Channel), <code>SATA</code> , or <code>SAS</code> . This parameter works only with the count-based repository method of defining a snapshot volume.
repositoryPool	The pool in which you want to build the snapshot repository volume. The default value is to build the snapshot repository volume in the same pool as the base volume.
freeCapacityArea	The amount of storage space that you want to use for the snapshot repository volume. Free storage space is defined in units of bytes, KB, MB, GB, or TB.
userLabel	The name that you want to give to the snapshot volume. If you do not choose a name for the snapshot volume, the software creates a default name by using the base volume name. For example, with a base volume name of <code>Mars_Spirit_4</code> : <ul style="list-style-type: none"> <li>When the base volume does not have a snapshot volume, the default snapshot volume name is <code>Mars_Spirit_4-1</code>.</li> <li>When the base volume already has <i>n-1</i> number of snapshot volumes, the default name is <code>Mars_Spirit_4-n</code>.</li> </ul>
repositoryUserLabel	The name that you want to give to the snapshot repository volume. If you do not choose a name for the snapshot repository volume, the software creates a default name by using the base volume name. For example, if the base volume name is <code>Mars_Spirit_4</code> and does not have an associated snapshot repository volume, the default snapshot repository volume name is <code>Mars_Spirit_4-R1</code> . If the base volume already has <i>n-1</i> number of snapshot repository volumes, the default name is <code>Mars_Spirit_4-Rn</code> .
warningThresholdPercent	The percentage of the capacity that you will permit the snapshot repository volume to get before you receive a warning that the snapshot repository volume is nearing full. The warning value is a percentage of the total capacity of the snapshot repository volume. The default value is 50, which represents 50 percent of the total capacity. (You can change this value later by using the <code>set snapshotVolume</code> command.)
repositoryPercentOfBase	The size of the snapshot repository volume as a percentage of the base volume size. The default value is 20, which represents 20 percent of the base volume size.
repositoryFullPolicy	The type of snapshot processing that you want to continue if the snapshot repository volume is full. You can choose to fail writes to the base volume ( <code>failBaseWrites</code> ) or fail writes to the snapshot volume ( <code>failSnapshot</code> ). The default value is <code>failSnapshot</code> .

This example shows the `create snapshotVolume` command that includes user-defined parameters:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create snapshotVolume baseVolume=\"Mars_Spirit_4\"
repositoryRAIDLevel=5 repositoryDriveCount=5
driveType=fibre userLabel=\"Mars_Spirit_4_snap1\"
repositoryUserLabel=\"Mars_Spirit_4rep1\"
warningThresholdPercent=75 repositoryPercentOfBase=40
repositoryFullPolicy=failSnapshot;"
```

This example shows how to use the command in a script file:

```
create snapshotVolume baseVolume="Mars_Spirit_4"  
repositoryRAIDLevel=5 repositoryDriveCount=5 driveType=fibre  
userLabel="Mars_Spirit_4_snap1"  
repositoryUserLabel="Mars_Spirit_4_rep1"  
warningThresholdPercent=75 repositoryPercentOfBase=40  
repositoryFullPolicy=failSnapshot;
```

## Snapshot Volume Names and Snapshot Repository Volume Names

The snapshot volume names and the snapshot repository volume names can be any combination of alphanumeric characters, hyphens, and underscores. The maximum length of the volume names is 30 characters. You must enclose the volume name in double quotation marks. The character string cannot contain a new line. Make sure that you use unique names; if you do not use unique names, the controller firmware returns an error.

One technique for naming the snapshot volume and the snapshot repository volume is to add a hyphenated suffix to the original base volume name. The suffix distinguishes between the snapshot volume and the snapshot repository volume. For example, if you have a base volume with a name of Engineering Data, the snapshot volume can have a name of Engineering Data-S1, and the snapshot repository volume can have a name of Engineering Data-R1.

If you do not choose a unique name for either the snapshot volume or the snapshot repository volume, the controllers create a default name by using the base volume name. These examples are snapshot volume names that the controllers might create:

- If the base volume name is *aaa* and does not have a snapshot volume, the default snapshot volume name is *aaa1*.
- If the base volume already has *n-1* number of snapshot volumes, the default name is *aaa-n*.
- If the base volume name is *aaa* and does not have a snapshot repository volume, the default snapshot repository volume name is *aaa-R1*.
- If the base volume already has *n-1* number of snapshot repository volumes, the default name is *aaa-Rn*.

In the examples from the previous section, the user-defined snapshot volume name was *Mars\_Spirit\_4\_snap1*, and the user-defined snapshot repository volume name was *Mars\_Spirit\_4\_rep1*. The default name that was provided by the controller for the snapshot volume was *Mars\_Spirit\_4-1*. The default name that was provided by the controller for the snapshot repository volume was *Mars\_Spirit\_4-R1*.

## Changing Snapshot Volume Settings

Use the `set (snapshot) volume` command to change these property settings for a snapshot volume:

- The snapshot volume name
- The warning threshold percent
- The snapshot repository full policy

This example shows how to change a snapshot volume name.

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "set volume ["Mars_Spirit_4-1"]  
userLabel="Mars_Odyssey_3-2";"
```

This example shows how to use the command in a script file:

```
set volume ["Mars_Spirit_4-1"] userLabel="Mars_Odyssey_3-2";
```

When you change the warning threshold percent and the snapshot repository full policy, you can apply the changes to one or several snapshot volumes with this command. This example shows how to use the `set (snapshot) volume` command to change these properties on more than one snapshot volume:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set volume
[\"Mars_Spirit_4-1\" \"Mars_Spirit_4-2\" \"Mars_Spirit_4-3\"
warningThresholdPercent=50
repositoryFullPolicy=failBaseWrites;"
```

This example shows how to use the command in a script file:

```
set volume [\"Mars_Spirit_4-1\" \"Mars_Spirit_4-2\"
\"Mars_Spirit_4-3\"] warningThresholdPercent=50
repositoryFullPolicy=failBaseWrites;
```

## Stopping, Restarting, and Deleting a Snapshot Volume

When you create a snapshot volume, copy-on-write starts running immediately. As long as a snapshot volume is enabled, storage array performance is impacted by the copy-on-write operations to the associated snapshot repository volume.

If you no longer want copy-on-write operations to run, you can use the `stop snapshot volume` command to stop the copy-on-write operations. When you stop a snapshot volume, the snapshot volume and the snapshot repository volume are still defined for the base volume. Only copy-on-write has stopped. This example shows how to stop a snapshot volume:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "stop snapshot volumes
[\"Mars_Spirit_4-2\" \"Mars_Spirit_4-3\"];"
```

This example shows how to use the command in a script file:

```
stop snapshot volumes
[\"Mars_Spirit_4-2\" \"Mars_Spirit_4-3\"];
```

When you stop the copy-on-write operations for a specific snapshot volume, only that snapshot volume is disabled. All of the other snapshot volumes stay in operation.

When you want to restart a copy-on-write operation, use the `recreate snapshot volume` command or the `recreate snapshot collection` command. The `recreate snapshot volume` command starts a fresh copy-on-write operation by using an existing snapshot volume.

---

**NOTE** The snapshot volume must be in either an Optimal state or a Disabled state.

---

When you restart a snapshot volume, these actions occur:

- All copy-on-write data previously on the snapshot repository volume is overwritten.
- Snapshot volume parameters and snapshot repository volume parameters stay the same as the previously disabled snapshot volume and the previously disabled snapshot repository volume. You can also change the `userLabel` parameter, the `warningThresholdPercent` parameter, and the `repositoryFullPolicy` parameter when you restart the snapshot volume.
- The original names for the snapshot repository volume are retained.

This example shows how to restart a snapshot volume:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "recreate snapshot volumes
[\"Mars_Spirit_4-2\" \"Mars_Spirit_4-3\"];"
```

This example shows how to use the command in a script file:



---

```
recreate snapshot volumes  
["Mars_Spirit_4-2" "Mars_Spirit_4-3"];
```

If you do not intend to use a snapshot volume again, you can delete the snapshot volume by using the `delete volume` command. When you delete a snapshot volume, the associated snapshot repository volume also is deleted.

## Chapter 5: Using the Data Replicator Software Premium Feature

The Data Replicator Software premium feature provides for online, real-time replication of data between storage arrays over a remote distance. In the event of a disaster or a catastrophic failure on one storage array, you can promote the second storage array to take over responsibility for computing services. Data Replicator Software is designed for extended storage environments in which the storage arrays that are used for Data Replicator Software are maintained at separate sites. Volumes on one storage array are mirrored to volumes on another storage array across a fabric SAN. Data transfers can be synchronous or asynchronous. You choose the method when you set up the remote mirrored pair. The data transfers occur at Fibre Channel speeds to maintain data on the different storage arrays. Because Data Replicator Software is storage based, it does not require any server overhead or application overhead.

You can use Data Replicator Software for these functions:

- **Disaster recovery** – Data Replicator Software lets you replicate data from one site to another site, which provides an exact duplicate at the remote (secondary) site. If the primary site fails, you can use mirrored data at the remote site for failover and recovery. You can then shift storage operations to the remote site for continued operation of all of the services that are usually provided by the primary site.
- **Data vaulting and data availability** – Data Replicator Software lets you send data off site where it can be protected. You can then use the off-site copy for testing or to act as a source for a full backup to avoid interrupting operations at the primary site.
- **Two-way data protection** – Data Replicator Software provides the ability to have two storage arrays back up each other by duplicating critical volumes on each storage array to volumes on the other storage array. This action lets each storage array recover data from the other storage array in the event of any service interruptions.

### How Data Replicator Software Works

When you create a remote-mirror pair, the remote-mirror pair consists of a *primary volume* on a local storage array and a *secondary volume* on a storage array at another site. A standard volume might only be included in one mirrored volume pair.

**Table 1 Maximum Number of Defined Mirrors per Storage Array**

Controller Model	Maximum Number of Defined Mirrors
AM1331, ST2530, ST2510, ST2540	Only supported in a co-existence storage environment
ST2500 M2	16
6140, 6140	64
6180	64
6540, 6580/6780	128

The primary volume is the volume that accepts host I/O activity and stores application data. When the mirror relationship is first created, data from the primary volume is copied in its entirety to the secondary volume. This process is known as a *full synchronization* and is directed by the controller owner of the primary volume. During a full synchronization, the primary volume remains fully accessible for all normal I/O operations.

The controller owner of the primary volume initiates remote writes to the secondary volume to keep the data on the two volumes synchronized.

The secondary volume maintains a mirror (or copy) of the data on its associated primary volume. The controller owner of the secondary volume receives remote writes from the controller owner of the primary volume but will not accept host write requests. Hosts are able to read from the secondary volume, which appears as read-only.

In the event of a disaster or a catastrophic failure at the primary site, you can perform a role reversal to promote the secondary volume to a primary role. Hosts then are able to read from and write to the newly promoted volume, and business operations can continue.

## Mirror Repository Volumes

A mirror repository volume is a special volume in the storage array that is created as a resource for the controller owner of the primary volume in a remote mirrored pair. The controller stores mirror information on this volume, including information about remote writes that are not yet complete. The controller can use this information to recover from controller resets and the accidental powering down of the storage arrays.

When you activate the Data Replicator Software premium feature on the storage array, you create two mirror repository volumes, one for each controller in the storage array. An individual mirror repository volume is not needed for each remote mirror.

When you create the mirror repository volumes, you specify the location of the volumes. You can either use existing free capacity, or you can create a pool for the volumes from unconfigured capacity and then specify the RAID level.

Because of the critical nature of the data being stored, do not use RAID Level 0 as the RAID level of mirror repository volumes. The required size of each volume is 128 MB, or 256 MB total for both mirror repository volumes of a dual-controller storage array. In previous versions of the Data Replicator Software premium feature, the mirror repository volumes required less disk storage space and needed to be upgraded to use the maximum amount of mirror relationships.

## Mirror Relationships

Before you create a mirror relationship, you must enable the Data Replicator Software premium feature on both the primary storage array and the secondary storage array. You must also create a secondary volume on the secondary site if one does not already exist. The secondary volume must be a standard volume of equal or greater capacity than the associated primary volume.

When secondary volumes are available, you can establish a mirror relationship in the storage management software by identifying the primary volume and the storage array that contains the secondary volume.

When you first create the mirror relationship, a full synchronization automatically occurs, with data from the primary volume copied in its entirety to the secondary volume.

## Data Replication

The controllers manage data replication between the primary volume and the secondary volume. This process is transparent to host machines and applications. This section describes how data is replicated between the storage arrays that are participating in Data Replicator Software. This section also describes the actions taken by the controller owner of the primary volume if a link interruption occurs between storage arrays.

### **Write Modes**

When the controller owner of the primary volume receives a write request from a host, the controller first logs information about the write to a mirror repository volume, and then writes the data to the primary volume. The controller then initiates a remote write operation to copy the affected data blocks to the secondary volume at the secondary storage array.

---

The Data Replicator Software premium feature provides two write mode options that affect when the I/O completion indication is sent back to the host: Synchronous and Asynchronous.

### **Synchronous Write Mode**

Synchronous write mode provides the highest level security for full data recovery from the secondary storage array in the event of a disaster. Synchronous write mode does reduce host I/O performance. When this write mode is selected, host write requests are written to the primary volume and then copied to the secondary volume. After the host write request has been written to the primary volume and the data has been successfully copied to the secondary volume, the controller removes the log record on the mirror repository volume. The controller then sends an I/O completion indication back to the host system. Synchronous write mode is selected as the default value and is the recommended write mode.

### **Asynchronous Write Mode**

Asynchronous write mode offers faster host I/O performance but does not guarantee that a copy operation has successfully completed before processing the next write request. When you use Asynchronous write mode, host write requests are written to the primary volume. The controller then sends an "I/O complete" indication back to the host system, without acknowledging that the data has been successfully copied to the secondary (remote) storage array.

When using Asynchronous write mode, write requests are not guaranteed to be completed in the same order on the secondary volume as they are on the primary volume. If the order of write requests is not retained, data on the secondary volume might become inconsistent with the data on the primary volume. This event could jeopardize any attempt to recover data if a disaster occurs on the primary storage array.

### **Write Consistency Mode**

When multiple mirror relationships exist on a single storage array and have been configured to use Asynchronous write mode and to preserve consistent write order, they are considered to be an interdependent group that is in the *Write consistency mode*. The data on the secondary, remote storage array cannot be considered fully synchronized until all of the remote mirrors that are in the Write consistency mode are synchronized.

If one mirror relationship in the group becomes unsynchronized, all of the mirror relationships in the group become unsynchronized. Any write activity to the remote, secondary storage arrays is prevented to protect the consistency of the remote data set.

## **Link Interruptions or Secondary Volume Errors**

When processing write requests, the primary controller might be able to write to the primary volume, but a link interruption might prevent communication with the remote (secondary) controller.

In this case, the remote write operation cannot be completed to the secondary volume, and the primary volume and the secondary volume are no longer correctly mirrored. The primary controller transitions the mirrored pair into an Unsynchronized state and sends an I/O completion to the primary host. The primary host can continue to write to the primary volume, but remote writes do not take place.

When communication is restored between the controller owner of the primary volume and the controller owner of the secondary volume, a resynchronization takes place. This resynchronization happens automatically, or it must be started manually, depending on which write mode you chose when setting up the mirror relationship. During the resynchronization, only the blocks of data that have changed on the primary volume during the link interruption are copied to the secondary volume. After the resynchronization starts, the mirrored pair transitions from an Unsynchronized status to a Synchronization in Progress status.

The primary controller also marks the mirrored pair as unsynchronized when a volume error on the secondary side prevents the remote write from completing. For example, an offline secondary volume or a failed secondary volume can cause the remote mirror to become unsynchronized. When the volume error is corrected (the secondary volume is placed online or recovered to an Optimal status), then synchronization is required. The mirrored pair then transitions to a Synchronization in Progress status.

---

## Resynchronization

Data replication between the primary volume and the secondary volume in a mirror relationship is managed by the controllers and is transparent to host machines and applications. When the controller owner of the primary volume receives a write request from a host, the controller first logs information about the write to a mirror repository volume. The controller then writes the data to the primary volume. The controller then initiates a write operation to copy the affected data to the secondary volume on the remote storage array.

If a link interruption or a volume error prevents communication with the secondary storage array, the controller owner of the primary volume transitions the mirrored pair into an Unsynchronized status. The controller owner then sends an I/O completion to the host sending the write request. The host can continue to issue write requests to the primary volume, but remote writes to the secondary volume do not take place.

When connectivity is restored between the controller owner of the primary volume and the controller owner of the secondary volume, the volumes must be resynchronized by copying the blocks of data that changed during the interruption to the secondary volume. Only the blocks of data that have changed on the primary volume during the link interruption are copied to the secondary volume.

---

**ATTENTION Possible loss of data access** – Any communication disruptions between the primary storage array and the secondary storage array while resynchronization is underway could result in a mix of new data and old data on the secondary volume. This condition would render the data unusable in a disaster recovery situation.

---

## Creating a Remote Mirrored Pair

Before you create any mirror relationships, volumes must exist at both the primary site and the secondary site. The volume that resides on the local storage array is the primary volume. Similarly, the volume that resides on the remote storage array is the secondary volume. If neither the primary volume nor the secondary volume exist, you must create these volumes. Keep these guidelines in mind when you create the secondary volume:

- The secondary volume must be of equal or greater size than the primary volume.
- The RAID level of the secondary volume does not have to be the same as the primary volume.

Use these steps to create the volume.

1. Enable the Data Replicator Software premium feature.
2. Activate the Data Replicator Software premium feature.
3. Determine candidates for a remote mirrored pair.
4. Create the remote- relationship.

## Performance Considerations

Keep these performance considerations in mind when you create mirror relationships:

- The controller owner of a primary volume performs a full synchronization in the background while processing local I/O writes to the primary volume and associated remote writes to the secondary volume. Because the full synchronization diverts controller processing resources from I/O writes, full synchronization can have a performance impact to the host application.
- To reduce the performance impact, you can set the synchronization priority level to determine how the controller owner will prioritize the full synchronization relative to other I/O activity. To set the synchronization priority level, consider these guidelines:

- A full synchronization at the lowest synchronization priority level takes approximately eight times as long as a full synchronization at the highest synchronization priority level.
- A full synchronization at the low synchronization priority level takes approximately six times as long as a full synchronization at the highest synchronization priority level.
- A full synchronization at the medium synchronization priority level takes approximately three-and-a-half times as long as a full synchronization at the highest synchronization priority level.
- A full synchronization at the high synchronization priority level takes approximately twice as long as a full synchronization at the highest synchronization priority level.
- When the mirrored volume pair is in a Synchronization in Progress state, all host write data is copied to the remote system. Both controller I/O bandwidth and I/O latency can affect host write performance. Host read performance is not affected by the mirror relationship.
- The time that it takes for data to be copied from the primary volume to the secondary volume might impact overall performance. This impact is primarily caused by the delay and system resource required for copying data to the remote mirror. Some delay might also occur because of the limit to the number of simultaneous writes.

## Enabling the Data Replicator Software Premium Feature

The first step in creating a remote mirror is to make sure that the Data Replicator Software premium feature is enabled on both storage arrays. Because Data Replicator Software is a premium feature, you need a feature key file to enable the premium feature. The command for enabling the feature key file is as follows:

```
enable storageArray feature file="filename"
```

In this command, the `file` parameter is the complete file path and file name of a valid feature key file. Enclose the file path and the file name in double quotation marks (" "). Valid file names for feature key files end with a `.key` extension.

## Activating the Data Replicator Software Premium Feature

Activating the Data Replicator Software premium feature prepares the storage arrays to create and configure mirror relationships. After you activate the premium feature, the secondary ports for each controller are reserved and dedicated to remote mirror use. In addition, a mirror repository volume is automatically created for each controller in the storage array. As part of the activation process, you can decide where the mirror repository volumes will reside, free capacity on an existing pool or in a newly created pool, and the RAID level for the mirror repository volumes.

The free capacity that you select for the mirror repository volume must have a total of 256 MB of capacity available. Two mirror repository volumes are created on this capacity, one for each controller. If you enter a value for the repository storage space that is too small for the mirror repository volumes, the firmware returns an error message that gives the amount of space needed for the mirror repository volumes. The command does not try to activate the Data Replicator Software premium feature. You can re-enter the command using the value from the error message for the repository storage space value.

The RAID level that you choose for the mirror repository volume has these constraints:

- **RAID Level 0** – You cannot use RAID Level 0.
- **RAID Level 1** – The number of drives must be an even number. If you select an odd number of drives, the controller firmware returns an error.
- **RAID Level 5** – You must have a minimum of three drives in the pool.
- **RAID Level 6** – You must have a minimum of five drives in the pool.

To activate the Data Replicator Software premium feature, use this command:

```
activate storageArray feature=remoteMirror
```

The `activate storageArray feature=remoteMirror` command provides three methods for defining the drives for your mirror repository volume:

- You define each drive for the mirror repository volume by its module ID and its slot ID.
- You define a pool in which the mirror repository volume resides. You can optionally define the capacity of the mirror repository volume.
- You define the number of drives, but not specific drives, for the mirror repository volume.

### **Activating the Data Replicator Software Premium Feature with User-Assigned Drives**

Activating the Data Replicator Software premium feature by assigning the drives provides flexibility in defining your configuration by letting you choose from the available drives in your storage array. Choosing the drives for your remote mirror automatically creates a new pool. You can specify which drives to use and the RAID level for the new pool.

The command takes this form:

```
activate storageArray feature=remoteMirror
repositoryRAIDLevel=(1 | 3 | 5 | 6)
repositoryDrives=(moduleID1,slotID1 ... moduleIDn,slotIDn)
moduleLossProtect=(TRUE | FALSE)
```

This example shows a command in which you assign the drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "activate storageArray feature=remoteMirror
repositoryRAIDLevel=5
repositoryDrives=(1,1 1,2 1,3 1,4 1,5);"
```

The command in this example creates a new mirror repository volume consisting of five drives that form a new pool. The new pool has RAID Level 5.

This example shows how to use the command in a script file:

```
activate storageArray feature=remoteMirror
repositoryRAIDLevel=5
repositoryDrives=(1,1 1,2 1,3 1,4 1,5);
```

### **Activating the Data Replicator Software Premium Feature with Software-Assigned Drives**

With this version of the `activate storageArray feature=remoteMirror` command, you choose an existing pool in which to place the mirror repository volume. The storage management software then determines which drives to use. You can also define how much space to assign to the mirror repository volume. Because you are using an existing pool, the RAID level for the mirror repository volume defaults to the RAID level of the pool in which you place it. You cannot define the RAID level for the mirror repository volume.

The command takes this form:

```
activate storageArray feature=remoteMirror
repositoryPool=poolNumber
[freeCapacityArea=freeCapacityIndexNumber]
```

This example shows a command in which the software assigns the drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "activate storageArray feature=remoteMirror
repositoryPool=2 freeCapacityArea=2;"
```

The command in this example creates a new mirror repository volume in pool 2 using the second free capacity area.

This example shows how to use the command in a script file:

```
activate storageArray feature=remoteMirror
repositoryPool=2 freeCapacityArea=2;
```

---

### **Activating the Data Replicator Software Premium Feature by Specifying a Number of Drives**

With this version of the `activate storageArray feature=remoteMirror` command, you must specify the number of drives and the RAID level that you want for the mirror repository volume. This version of the command creates a new pool. For this command to work, you must have drives in the storage array that are not assigned to a pool.

```
activate storageArray feature=remoteMirror
repositoryRAIDLevel=(1 | 3 | 5 | 6)
repositoryDriveCount=numberOfDrives
[driveType=(fibre | SATA | SAS)]
[moduleLossProtect=(TRUE | FALSE)]
```

This example shows a command in which you specify the number of drives:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "activate storageArray feature=remoteMirror
repositoryRAIDLevel=5 repositoryDriveCount=5
driveType=SAS;"
```

The command in this example creates a new mirror repository volume by using five software-selected drives for the mirror repository volume. The mirror repository volume has RAID Level 5. The type of drive for the mirror repository volume is SAS.

This example shows how to use the command in a script file:

```
activate storageArray feature=remoteMirror
repositoryRAIDLevel=5 repositoryCount=5
driveType=SAS;
```

## **Determining Candidates for a Remote Mirrored Pair**

All of the volumes and drives on the remote storage array might not be available for use as secondary volumes. To determine which volumes on a remote storage array that you can use as candidates for secondary volumes, use the `show remoteMirror candidates` command. This command returns a list of the volumes that you can use when creating a remote mirror.

The command takes this form:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "show remoteMirror candidates primary=\"volumeName\"
remoteStorageArrayName=\"storageArrayName\";"
```

where *volumeName* is the name of the volume that you want to use for the primary volume, and *storageArrayName* is the remote storage array that contains possible candidates for the secondary volume. Enclose both the volume name and the storage array name in double quotation marks (" ").

## **Creating a Remote Mirrored Pair**

When you create a new remote mirror, you must define which volumes that you want to use for the primary (local) volume and the secondary (remote) volume. You define the primary volume by the name of the volume. You define the secondary volume by name with either the name or the World Wide Identifier (WWID) of the storage array on which the secondary volume resides. The primary volume name, the secondary volume name, and the remote storage array name (or WWID) are the minimum information that you need to provide. Using this command, you can also define synchronization priority, write order, and write mode.

The command takes this form:



```
create remoteMirror primary="primaryVolumeName"
secondary="secondaryVolumeName"
(remoteStorageArrayName="storageArrayName" |
remoteStorageArrayWwn="wwID") remotePassword=password
syncPriority=(highest | high | medium | low | lowest)
writeOrder=(preserved | notPreserved)
writeMode=(synchronous | asynchronous)
```

---

**NOTE** You can use the optional parameters as needed to help define your configuration.

---

This example shows the `create remoteMirror` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create remoteMirror primary=\"Jan_04_Account\"
secondary=\"Jan_04_Account_B\" remoteStorageArrayName=\"Tabor\"
remotePassword=\"jdw2ga05\" syncPriority=highest
writeMode=synchronous;"
```

The command in this example creates a remote mirror in which the primary volume is named `Jan_04_Account` on the local storage array. The secondary volume is named `Jan_04_Account_B` on the remote storage array that is named `Tabor`. The names used in this example are similar, but that is not a requirement for the volume names in a remote mirrored pair. In this example, the remote storage array has a password that you must enter when making any change to the storage array configuration. Creating a remote mirrored pair is a significant change to a storage array configuration. Setting the write mode to `synchronous` and the synchronization priority to `highest` means that host write requests are written to the primary volume and then immediately copied to the secondary volume. These actions help to make sure that the data on the secondary volume is as accurate a copy of the data on the primary volume as possible. The highest synchronization priority does, however, use more system resources, which can reduce system performance.

This example shows how to use the command in a script file:

```
create remoteMirror primary="Jan_04_Account"
secondary="Jan_04_Account_B" remoteStorageArrayName="Tabor"
remotePassword="jdw2ga05" syncPriority=highest
writeMode=synchronous;
```

After you have created a remote mirror, you can see the progress of data synchronization between the primary volume and the secondary volume by running the `show remoteMirror synchronizationProgress` command. This command shows the progress as a percentage of data synchronization that has completed.

## Changing Data Replicator Software Settings

The `set remoteMirror` command lets you change the property settings for a remote mirrored pair. Use this command to change these property settings:

- The volume role (either primary or secondary)
- The synchronization priority
- The write order
- The write mode

You can apply the changes to one or several remote mirrored pairs by using this command. Use the primary volume name to identify the remote mirrored pairs for which you are changing the properties.

This example shows how to use the `set remoteMirror` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set remoteMirror localVolume [Jan_04_Account]
syncPriority=medium
writeOrder=notpreserved
writeMode=asynchronous;"
```

This example shows how to use the command in a script file:

```
set remoteMirror localVolume [Jan_04_Account]
syncPriority=medium
writeOrder=notpreserved
writeMode=asynchronous;
```

## Suspending and Resuming a Mirror Relationship

Use the `suspend remoteMirror` command to stop data transfer between a primary volume and a secondary volume in a mirror relationship without disabling the mirror relationship. Suspending a mirror relationship lets you control when the data on the primary volume and data on the secondary volume are synchronized. Suspending a mirror relationship helps to reduce any performance impact to the host application that might occur while any changed data on the primary volume is copied to the secondary volume. Suspending a mirror relationship is particularly useful when you want to run a backup of the data on the secondary volume.

When a mirror relationship is in a suspended state, the primary volume does not make any attempt to contact the secondary volume. Any writes to the primary volume are persistently logged in the mirror repository volumes. After the mirror relationship resumes, any data that is written to the primary volume is automatically written to the secondary volume. Only the modified data blocks on the primary volume are written to the secondary volume. Full synchronization is not required.

---

**NOTE** If you suspend a remote mirror that is set up in the Write consistency mode, you suspend all remote mirrored pairs within the group. You can then resume mirror operations for any of the individual remote mirrored pairs that are in the group.

---

This example shows the `suspend remoteMirror` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "suspend remoteMirror primary Jan_04_Account
writeConsistency=false;"
```

The `writeConsistency` parameter defines whether the volumes identified in this command are in a write-consistency group or are separate. For the volumes in a write-consistency group, set this parameter to `TRUE`. For the volumes that are not in a write-consistency group, set this parameter to `FALSE`.

This example shows how to use the command in a script file:

```
suspend remoteMirror volume Jan_04_Account
writeConsistency=false;
```

The mirror relationship remains suspended until you use the `resume remoteMirror` command to restart synchronization activities. This command restarts data transfers between a primary volume and a secondary volume in a mirror relationship after the mirror has been suspended or unsynchronized.

This example shows the `resume remoteMirror` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "resume remoteMirror volume Jan_04_Account
writeConsistency=false;"
```

---

The `writeConsistency` parameter in this command operates the same as in the previous command.

This example shows how to use the command in a script file:

```
resume remoteMirror volume Jan_04_Account  
writeConsistency=false;
```

## Removing a Mirror Relationship

Use the `remove remoteMirror` command to remove the link between a primary volume and a secondary volume. (Removing a mirror relationship is similar to deleting a mirror relationship.) Removing the link between a primary volume and a secondary volume does not affect any of the existing data on either volume. The link between the volumes is removed, but the primary volume still continues normal I/O operations. Later, you can establish the mirror relationship between the two volumes and resume normal mirror operations. You can remove the mirror relationship for one or several remote mirrored pairs with this command.

This example shows the `remove remoteMirror` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "remove remoteMirror localVolume [Jan_04_Account];"
```

When you run this command, use the name of the primary volume of the remote mirrored pair.

This example shows how to use the command in a script file:

```
remove remoteMirror localVolume [Jan_04_Account];
```

To re-establish the link between a primary volume and a secondary volume, use the `create remoteMirror` command.

## Deleting a Primary Volume or a Secondary Volume

Use the `delete volume` command to remove a primary volume or a secondary volume from a storage array. Deleting a volume in a mirror relationship removes the mirror relationship and completely deletes the volume from the storage array. You cannot redefine the mirror relationship until you create a new volume or choose an alternate volume to replace the deleted volume.

---

**ATTENTION Possible loss of data access** – Deleting a primary volume or a secondary volume permanently removes the data from the storage array.

---

## Disabling the Data Replicator Software Premium Feature

You disable the Data Replicator Software premium feature to prevent the new mirror relationship from being created. When you disable the Data Replicator Software premium feature, the premium feature is in a Disabled/Active state. In this state, you can maintain and manage previously existing mirror relationships; however, you cannot create new relationships. To disable the Data Replicator Software premium feature, use this command:

```
disable storageArray feature=remoteMirror
```

---

## Deactivating the Data Replicator Software Premium Feature

If you no longer require the Data Replicator Software premium feature and you have removed all of the mirror relationships, you can deactivate the premium feature. Deactivating the premium feature re-establishes the normal use of dedicated ports on both storage arrays and deletes both mirror repository volumes. To deactivate the Data Replicator Software premium feature, use this command:

```
deactivate storageArray feature=remoteMirror
```

## Interaction with Other Premium Features

You can run the Data Replicator Software premium feature while running these premium features:

- Storage Domains
- Snapshot
- Volume Copy

When you run the Data Replicator Software premium feature with other premium features, you must consider the requirements of the other premium features to help make sure that you set up a stable storage array configuration.

In addition to running with the premium features, you can also run the Data Replicator Software premium feature while running Dynamic Volume Expansion (DVE).

## Storage Domains

Storage Domains is a premium feature that lets hosts share access to volumes in a storage array. You create a storage domain when you define any of these logical components in a storage array:

- A host
- A host group
- A volume-to-LUN mapping

The volume-to-LUN mapping lets you define which host group or host has access to a particular volume in the storage array.

When you create storage domains, define the storage domains after you have created the primary volume and the secondary volume in a Data Replicator Software configuration. The storage domain definitions for the primary storage array and the secondary storage array are independent of each other. If these definitions are put in place while the volume is in a secondary role, the administrative effort associated with the site recovery is reduced if it becomes necessary to promote the volume to a primary role.

## Snapshot Volumes

A snapshot is a point-in-time image of a volume. Typically, it is created so that an application, such as a backup application, can access the snapshot volume and read the data while the base volume stays online and is accessible to hosts.

The volume for which the point-in-time image is created is known as the base volume and must be a standard volume in the storage array. The snapshot repository volume stores information about all data that changed since the snapshot was created.

In this version of the storage management software, you can create snapshot volumes based on the primary volume or secondary volume of a remote mirror.

---

## Volume Copy

The Volume Copy premium feature copies data from one volume (the source volume) to another volume (the target volume) within a single storage array. You can use this premium feature to perform these functions:

- Copy data from pools that use smaller-capacity drives to pools that use larger-capacity drives
- Back up data
- Restore snapshot volume data to the base volume.

You can use a primary volume in a remote mirror as a source volume or a target volume in a volume copy. You cannot use a secondary volume as a source volume or a target volume.

---

**NOTE** If you start a role reversal during a copy-in-progress, the copy fails and cannot be restarted.

---

## Dynamic Volume Expansion

A Dynamic Volume Expansion (DVE) is a modification operation that increases the capacity of a standard volume or a snapshot repository volume. The increase in capacity is achieved by using the free capacity that is available in the pool of the standard volume or the snapshot repository volume.

This modification operation is considered to be “dynamic” because you can continually access data on pools, volumes, and drives throughout the entire operation.

A DVE operation can be performed on a primary volume or a secondary volume of a mirror relationship.

---

**NOTE** Although the storage management software indicates that the volume has increased capacity, its usable capacity is the size of the smaller of the primary volume or the secondary volume.

---

You cannot perform a DVE operation on a mirror repository volume.

---

## Chapter 6: Using the Volume Copy Premium Feature

The Volume Copy premium feature lets you copy data from one volume (the source) to another volume (the target) in a single storage array. You can use this premium feature to perform these tasks:

- Back up data
- Copy data from pools that use smaller-capacity drives to pools using greater-capacity drives
- Restore snapshot volume data to the associated base volume

### How Volume Copy Works

When you create a volume copy, you create a copy pair that consists of a source volume and a target volume. Both the source volume and the target volume are located on the same storage array. During a volume copy, the controllers manage copying the data from the source volume to the target volume. The volume copy is transparent to the host machines and applications, except that users cannot write to the source volume during a volume copy.

While a volume copy is In Progress, the same controller must own both the source volume and the target volume. If one controller does not own both the source volume and the target volume before creating the volume copy, ownership of the target volume is automatically transferred to the controller that owns the source volume. When the volume copy is finished or stopped, ownership of the target volume is restored to its preferred controller. If ownership of the source volume changes while a volume copy is running, ownership of the target volume also changes.

### Source Volume

The source volume is the volume that accepts host I/O and stores data. When you start a volume copy, data from the source volume is copied in its entirety to the target volume. While a volume copy has a status of In Progress, Pending, or Failed, the source volume is available only for read activity.

After the volume copy completes, the source volume becomes available to host applications for write requests. The target volume automatically becomes read only to hosts, and write requests to the target volume are rejected.

The following are valid source volumes:

- A standard volume
- A snapshot volume
- The base volume of a snapshot volume
- A primary volume that is participating in a remote-mirror pair

The following are not valid source volumes:

- A secondary volume that is participating in a remote-mirror pair
- A snapshot repository volume
- A mirror repository volume
- A failed volume
- A missing volume
- A volume currently in a modification operation
- A volume that is holding a Small Computer System Interface-2 (SCSI-2) reservation or a persistent reservation
- A volume that is a source volume or a target volume in another volume copy that has a status of In Progress, Pending, or Failed

---

## Target Volume

A target volume contains a copy of the data from the source volume. When a volume copy is started, data from the source volume is copied in its entirety to the target volume.

---

**ATTENTION Possible loss of data access** – A volume copy overwrites data on the target volume. Before you start a new operation, make sure that you no longer need the old data, or you have backed up the old data on the target volume.

---

While the volume copy has a status of In Progress, Pending, or Failed, the controllers reject read and write requests to the target volume. After the volume copy operation is finished, the target volume automatically becomes read only to the hosts, and write requests to the target volume are rejected. You can change the Read-Only attribute after the volume copy has completed or has been stopped. (For more information about the Read-Only attribute, see [“Viewing Volume Copy Properties.”](#))

The following volumes are valid target volumes:

- A standard volume
- The base volume of a disabled snapshot volume or failed snapshot volume
- A primary volume that is participating in a remote-mirror pair

The following volumes are not valid target volumes:

- The base volume of an active snapshot volume
- A snapshot volume
- A mirror repository volume
- A snapshot repository volume
- A secondary volume in a remote-mirror pair
- A failed volume
- A missing volume
- A volume with a status of Degraded
- A volume that is currently in a modification operation
- A volume that is holding a SCSI-2 reservation or a persistent reservation
- A volume that is a source volume or a target volume in another volume copy that has a status of In Progress, Pending, or Failed

## Volume Copy and Persistent Reservations

You cannot use volumes that hold persistent reservations for either a source volume or a target volume. Persistent reservations are configured and managed through the server cluster software and prevent other hosts from accessing the reserved volume. Unlike other types of reservations, a persistent reservation reserves host access to the volume across multiple HBA host ports, which provides various levels of access control.

To determine which volumes have reservations, run the `show (volume) reservations` command. To remove a reservation, run the `clear (volume) reservations` command.

## Storage Array Performance

During a volume copy operation, the resources of the storage array might be diverted from processing I/O activity to completing a volume copy, which might affect the overall performance of the storage array.

These factors contribute to the performance of the storage array:

- The I/O activity
- The volume RAID level
- The volume configuration (number of drives in the pools and cache parameters)
- The volume type (snapshot volumes might take more time to copy than standard volumes)

When you create a new volume copy, you define the copy priority to determine how much controller processing time is allocated for a volume copy compared with I/O activity.

Copy priority has five relative settings ranging from highest to lowest. The highest priority rate supports the volume copy, but I/O activity might be affected. The lowest priority rate supports I/O activity, but the volume copy takes longer. You define the copy priority when you create the volume copy pair. You can redefine the copy priority later by using the `set volumeCopy` command. You can also redefine the volume copy priority when you recopy a volume.

## Restrictions

These restrictions apply to the source volume, the target volume, and the storage array:

- While a volume copy operation has a status of In Progress, Pending, or Failed, the source volume is available for read activity only. After the volume copy finishes, read activity from and write activity to the source volume is permitted.
- A volume can be selected as a target volume for only one volume copy at a time.
- The maximum allowable number of volume copies per storage array depends upon the storage array configuration.
- A volume that is reserved by the host cannot be selected as a source volume or as a target volume.
- A volume with a status of Failed cannot be used as a source volume or as a target volume.
- A volume with a status of Degraded cannot be used as a target volume.
- You cannot select a volume that is participating in a modification operation as a source volume or as a target volume. Modification operations include Dynamic Capacity Expansion (DCE), Dynamic RAID Level Migration (DRM), Dynamic Segment Sizing (DSS), Dynamic Volume Expansion (DVE), and defragmenting a pool.

## Volume Copy Commands

The following table lists the Volume Copy commands and briefly describes what the commands do.

**Table 1 Volume Copy Commands**

Command	Description
<code>create volumeCopy</code>	Creates a volume copy and starts the volume copy operation.
<code>disable storageArray featurevolumeCopy</code>	Turns off the current volume copy operation.
<code>enable storageArray feature</code>	Activates the Volume Copy premium feature.
<code>recopy volumeCopy</code>	Re-initiates a volume copy operation using an existing volume copy pair.
<code>remove volumeCopy</code>	Removes a volume copy pair.
<code>set volumeCopy</code>	Defines the properties for a volume copy pair.
<code>show volumeCopy</code>	Returns information about volume copy operations. You can retrieve information about a specific volume copy pair, or all of the volume copy pairs in the storage array.



Command	Description
<code>show volumeCopy sourceCandidates</code>	Returns information about the candidate volumes that you can use as the source for a volume copy operation.
<code>show volumeCopy targetCandidates</code>	Returns information about the candidate volumes that you can use as the target for a volume copy operation.
<code>stop volumeCopy</code>	Stops a volume copy operation.

## Creating a Volume Copy

Before you create a volume copy, make sure that a suitable target volume exists on the storage array, or create a new target volume specifically for the volume copy. The target volume that you use must have a capacity equal to or greater than the source volume.

You can have a maximum of eight volume copies with a status of In Progress at one time. Any volume copy greater than eight has a status of Pending until one of the volume copies with a status of In Progress has completed the volume copy process.

To create a volume copy, perform these general steps:

1. Enable the Volume Copy premium feature.
2. Determine the candidates for a volume copy.
3. Create the target volume and the source volume for the volume copy.

## Enabling the Volume Copy Premium Feature

The first step in creating a volume copy is to make sure that the feature is enabled on the storage array. Because Volume Copy is a premium feature, you need a Feature Key file to enable the feature. This command enables the Feature Key file:

```
enable storageArray feature file="filename"
```

where the `file` parameter is the complete file path and file name of a valid Feature Key file. Enclose the file path and file name in double quotation marks (" "). Valid file names for Feature Key files usually end with a `.key` extension.

## Determining Volume Copy Candidates

All volumes and drives might not be available for use in volume copy operations. To determine which candidate volumes on the storage array that you can use as a source volume, use the commands in the following table.

Action	Use This CLI Command
Determine which candidate volumes on the storage array you can use as a source volume	<code>show volumeCopy sourceCandidates</code>
Determine which candidate volumes on the storage array you can use as a target volume	<code>show volumeCopy targetCandidates</code>

The `show volumeCopy sourceCandidates` command and the `show volumeCopy targetCandidates` command return a list of the drive module, slot, and capacity information for the source volume candidates and the target volume candidates.

---

You can use the `show volumeCopy sourceCandidates` command and the `show volumeCopy targetCandidates` command only after you have enabled the Volume Copy premium feature.

## Creating a Volume Copy

---

**ATTENTION Possible loss of data access** – A volume copy overwrites data on the target volume. Make sure that you no longer need the data or have backed up the data on the target volume before you start a volume copy operation.

---

When you create a volume copy, you must define which volumes that you want to use for the source volume and the target volume. You define the source volume and the target volume by the name of each volume. You can also define the copy priority and choose whether you want the target volume to be read only after the data is copied from the source volume.

The command has this form:

```
create volumeCopy
source="sourceName" target="targetName"
[copyPriority=(highest | high | medium | low | lowest)
targetReadOnlyEnabled=(TRUE | FALSE)]
```

Before you run the `create volumeCopy` command, perform these actions:

- Stop all I/O activity to the source volume and the target volume.
- Dismount any file systems on the source volume and the target volume, if applicable.

This example shows the `create volumeCopy` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "create volumeCopy source=\"Jaba_Hut\" target=\"Obi_1\"
copyPriority=medium targetReadOnlyEnabled=TRUE;"
```

The command in this example copies the data from the source volume named `Jaba_Hut` to the target volume named `Obi_1`. Setting the copy priority to `medium` provides a compromise between how quickly the data is copied from the source volume to the target volume and the amount of processing resources that are required for data transfers to other volumes in the storage array. Setting the `targetReadOnlyEnabled` parameter to `TRUE` means that write requests cannot be made to the target volume, making sure that the data on the target volume stays unaltered.

This example shows how to use the command in a script file:

```
create volumeCopy source="Jaba_Hut" target="Obi_1"
copyPriority=medium targetReadOnlyEnabled=TRUE;
```

After the volume copy operation is completed, the target volume automatically becomes read only to hosts. Any write requests to the target volume are rejected, unless you disable the Read-Only attribute by using the `set volumeCopy` command.

To view the progress of a volume copy, use the `show volume actionProgress` command. This command returns information about the volume action, the percentage completed, and the time remaining until the volume copy is complete.

## Viewing Volume Copy Properties

Use the `show volumeCopy` command to view information about one or more selected source volumes or target volumes. This command returns these values:

- The role

- The copy status
- The start time stamp
- The completion time stamp
- The copy priority
- The Read-Only attribute setting for the target volume
- The source volume World Wide Identifier (WWID) or the target volume WWID

If a volume is participating in more than one volume copy (it can be a source volume for one volume copy operation and a target volume for another volume copy operation), the details are repeated for each associated copy pair.

The command has this form:

```
show volumeCopy (allVolumes | source [sourceName] |  
target [targetName])
```

This example shows the `show volumeCopy` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "show volumeCopy source [\"JabaHut\"];"
```

The command in this example is requesting information about the source volume `Jaba_Hut`. If you wanted information about all of the volumes, you would use the `allVolumes` parameter. You can also request information about a specific target volume.

This example shows how to use the command in a script file:

```
show volumeCopy source [\"Jaba_Hut\"];
```

## Changing Volume Copy Settings

The `set volumeCopy` command lets you change these property settings for a volume copy pair:

- The copy priority
- The target volume read/write permission

Copy priority has five relative settings ranging from highest to lowest. The highest priority supports the volume copy, but I/O activity might be affected. The lowest priority supports I/O activity, but the volume copy takes longer. You can change the copy priority at these times:

- Before the volume copy operation starts
- While the volume copy operation has a status of In Progress
- After the volume copy operation has completed when re-creating a volume copy operation by using the `recopy volumeCopy` command

When you create a volume copy pair and after the original volume copy has completed, the target volume is automatically defined as read-only to the hosts. The read-only status of the target volume helps to make sure that the copied data on the target volume is not corrupted by additional writes to the target volume after the volume copy is created. You want to maintain the read-only status when you are performing these tasks:

- Using the target volume for backup purposes
- Copying data from one pool to a larger pool for greater accessibility
- Planning to use the data on the target volume to copy back to the base volume in case of a disabled snapshot volume or failed snapshot volume

At other times, you might want to write additional data to the target volume. You can use the `set volumeCopy` command to reset the read/write permission for the target volume.

---

**NOTE** If you have set the volume copy parameters to enable host writes to the target volume, the read request and the write request to the target volume are rejected while the volume copy operation has a status of In Progress, Pending, or Failed.

---

The command has this form:

```
set volumeCopy target [targetName] [source [sourceName]]
copyPriority=(highest | high | medium | low | lowest)
targetReadOnlyEnabled=(TRUE | FALSE)
```

---

**NOTE** You can use the parameters as needed to help define your configuration.

---

This example shows the `set volumeCopy` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89
-c "set volumeCopy target [\"Obi_1\"]
copyPriority=highest
targetReadOnlyEnabled=FALSE;"
```

This example shows how to use the command in a script file:

```
set volumeCopy target ["Obi_1"] copyPriority=highest
targetReadOnlyEnabled=FALSE;
```

## Recopying a Volume

Use the `recopy volumeCopy` command to create a new volume copy for a previously defined copy pair that has a status of Stopped, Failed, or Completed. You can use the `recopy volumeCopy` command to create backups of the target volume. Then, you can copy the backup to tape for off-site storage. When you use the `recopy volumeCopy` command to make a backup, you cannot write to the source volume while the recopy operation is running. The recopy operation might take a long time.

When you run the `recopy volumeCopy` command, the data on the source volume is copied in its entirety to the target volume.

---

**ATTENTION Possible loss of data access** – The `recopy volumeCopy` command overwrites existing data on the target volume and makes the target volume read-only to hosts. The `recopy volumeCopy` command fails all of the snapshot volumes that are associated with the target volume, if any exist.

---

You can also reset the copy priority by using the `recopy volumeCopy` command if you want to change the copy priority for the recopy operation. The higher priorities allocate storage array resources to the volume copy at the expense of storage array performance.

The command has this form:

```
recopy volumeCopy target [targetName] [source [sourceName]]
copyPriority=(highest | high | medium | low | lowest)
targetReadOnlyEnabled=(TRUE | FALSE)]
```

---

**NOTE** You can use the optional parameters as needed to help define your configuration.

---

This example shows the `show volumeCopy` command:

---

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "recopy volumeCopy target [\"Obi_1\"] copyPriority=highest;"
```

The command in this example copies data from the source volume that is associated with the target volume `Obi_1` to the target volume again. The copy priority is set to the highest value to complete the volume copy as quickly as possible. The underlying consideration for using this command is that you have already created the volume copy pair, which has already created one volume copy. By using this command, you are copying the data from the source volume to the target volume with the assumption that the data on the source volume has changed since the previous copy was made.

This example shows you how to use the command in a script file:

```
recopy volumeCopy target [\"Obi_1\"] copyPriority=highest;
```

## Stopping a Volume Copy

The `stop volumeCopy` command lets you stop a volume copy that has a status of In Progress, Pending, or Failed. After you have stopped a volume copy, you can use the `recopy volumeCopy` command to create a new volume copy by using the original volume copy pair. After you stop a volume copy operation, all of the mapped hosts will have write access to the source volume.

The command has this form:

```
stop volumeCopy target [targetName] [source [sourceName]]
```

This example shows the `show volumeCopy` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "stop volumeCopy target [\"Obi_1\"];"
```

This example shows how to use the command in a script file:

```
stop volumeCopy target [\"Obi_1\"];
```

## Removing Copy Pairs

The `remove volumeCopy` command lets you remove a volume copy pair from the storage array configuration. All of the volume copy-related information for the source volume and the target volume is removed from the storage array configuration. The data on the source volume or the target volume is not deleted. Removing a volume copy from the storage array configuration also removes the Read-Only attribute for the target volume.

---

**NOTE** If the volume copy has a status of In Progress, you must stop the volume copy before you can remove the volume copy pair from the storage array configuration.

---

The command has this form:

```
remove volumeCopy target [targetName] [source [sourceName]]
```

This example shows the `remove volumeCopy` command:

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-c "remove volumeCopy target [\"Obi_1\"];"
```

This example shows how to use the command in a script file:

```
remove volumeCopy target [\"Obi_1\"];
```

---

---

## Interaction with Other Premium Features

You can run the Volume Copy premium feature while running the following premium features:

- Storage Domains
- Snapshot
- Data Replicator Software

When you are running the Volume Copy premium feature with other premium features, you must consider the requirements of other premium features to help make sure that you set up a stable storage array configuration.

In addition to the premium features, you also can run the Volume Copy premium feature while running Dynamic Volume Expansion (DVE).

### Storage Domains

Storage Domains is a premium feature that lets hosts share access to volumes in a storage array. You create a storage domain when you define any of these logical components in a storage array:

- A host
- A host group
- A volume-to-LUN mapping

The volume-to-LUN mapping lets you define which host group or host has access to a particular volume in the storage array.

After you create a volume copy, the target volume automatically becomes read only to hosts to make sure that the data is preserved. Hosts that have been mapped to a target volume do not have write access to the volume, and any attempt to write to the read-only target volume results in a host I/O error.

If you want hosts to have write access to the data on the target volume, use the `set volumeCopy` command to disable the Read-Only attribute for the target volume.

### Snapshot Volumes

A snapshot is a point-in-time image of a volume. It is usually created so that an application, such as a backup application, can access the snapshot volume and read the data while the base volume stays online and is accessible to hosts.

The volume for which the point-in-time image is created is known as the base volume and must be a standard volume in the storage array. The snapshot repository volume stores information about all of the data that changed since the snapshot was created.

You can select snapshot volumes as the source volumes for a volume copy. This selection is a good use of this premium feature, because it performs complete backups without significant impact to the storage array I/O. Some I/O processing resources are lost to the copy operation.

---

**NOTE** If you choose the base volume of a snapshot volume as your target volume, you must disable all of the snapshot volumes that are associated with the base volume before you can select it as a target volume.

---

When you create a snapshot volume, a snapshot repository volume is automatically created. The snapshot repository volume stores information about the data that has changed since the snapshot volume was created. You cannot select a snapshot repository volume as a source volume or a target volume in a volume copy.

---

You can use the Snapshot Volume premium feature with the Volume Copy premium feature to back up data on the same storage array and to restore the data on the snapshot volume back to its original base volume.

## Data Replicator Software

The Data Replicator Software premium feature provides for online, real-time replication of data between storage arrays over a remote distance. In the event of a disaster or a catastrophic failure of one storage array, you can promote a secondary storage array to take over responsibility for data storage.

When you create a remote mirror, a remote-mirror pair is created, which consists of a primary volume at the primary storage array and a secondary volume at a remote storage array.

The primary volume is the volume that accepts host I/O and stores data. When the mirror relationship is initially created, data from the primary volume is copied in its entirety to the secondary volume. This process is known as a full synchronization and is directed by the controller owner of the primary volume. During a full synchronization, the primary volume remains fully accessible for all normal I/O activity.

The controller owner of the primary volume starts remote writes to the secondary volume to keep the data on the two volumes synchronized. Whenever the data on the primary volume and the secondary volume becomes unsynchronized, the controller owner of the primary volume starts a resynchronization, where only the data that changed during the interruption is copied.

The secondary volume maintains a mirror of the data on its associated primary volume. The controller owner of the secondary volume receives remote writes from the controller owner of the primary volume but does not accept host write requests.

The secondary volume stays available to host applications as read-only while mirroring is underway. In the event of a disaster or a catastrophic failure at the primary site, you can perform a role reversal to promote the secondary volume to a primary role. Hosts are then able to access the newly promoted volume, and business operations can continue.

You can select a primary volume that is participating in a remote-mirror pair to be used as the source volume or a target volume for a volume copy. A secondary volume that is participating in a remote-mirror pair cannot be selected as a source volume or a target volume.

### Role Reversals

A role reversal is the act of promoting the secondary volume to be the primary volume of the remote-mirror pair, and demoting the primary volume to be the secondary volume.

In the event of a disaster at the storage array that contains the primary volume, you can fail over to the secondary site by performing a role reversal to promote the secondary volume to the primary volume role. This action lets hosts continue to access data, and business operations can continue.

Trying a role reversal in which the original primary volume is the source volume for an active volume copy (the status is In Progress or Pending) causes the volume copy to fail. The failure occurs when the original primary volume becomes the new secondary volume. You cannot restart the volume copy until you return the roles of the volumes back to their original state; that is, the volume that was originally the primary volume is set once again to be the primary volume.

If the primary storage array is recovered but is unreachable due to a link failure, a forced promotion of the secondary volume will result in both the primary volume and the secondary volume viewing themselves in the primary volume role (dual-primary condition). If this condition occurs, the volume copy in which the primary volume is participating is unaffected by the role change.

You can perform a role reversal by using the `set remoteMirror` command.

- To change a secondary volume to a primary volume, use this command, which promotes the selected secondary volume to become the primary volume of the remote-mirror pair. Use this command after a catastrophic failure has occurred.

---

```
set remoteMirror role=primary
```

- To change a primary volume to a secondary volume, use this command, which demotes the selected primary volume to become the secondary volume. Use this command after a catastrophic failure has occurred.

```
set remoteMirror role=secondary
```



---

## Chapter 7: Maintaining a Storage Array

Maintenance covers a broad spectrum of activity with the goal of keeping a storage array operational and available to all hosts. This chapter provides descriptions of commands you can use to perform storage array maintenance. The commands are organized into four sections:

- Routine maintenance
- Performance tuning
- Troubleshooting and diagnostics
- Recovery operations

The organization is not a rigid approach, and you can use the commands as appropriate for your storage array. The commands listed in this chapter do not cover the entire array of commands you can use for maintenance. Other commands, particularly the `set` commands, can provide diagnostic or maintenance capabilities.

### Routine Maintenance

Routine maintenance involves those tasks that you might perform periodically to make sure that the storage array is running as well as possible or to detect conditions before they become problems.

### Running a Media Scan

Media scan provides a way of detecting drive media errors before they are found during a normal read from or write to the drives. Any media scan errors that are detected are reported to the Event Log. The Event Log provides an early indication of an impending drive failure and reduces the possibility of encountering a media error during host operations. A media scan is performed as a background operation and scans all data and redundancy information in defined user volumes.

A media scan runs on all of the volumes in the storage array that have these conditions:

- Has Optimal status
- Has no modification operations in progress
- Has media scan enabled

Errors that are detected during a scan of a user volume are reported to the Major Event Log (MEL) and handled as follows:

- **Unrecovered media error** – The drive could not read the requested data on its first try or on any subsequent retries. The result of this action is that for volumes with redundancy protection, the data is reconstructed, rewritten to the drive, and verified, and the error is reported to the Event Log. For volumes without redundancy protection, the error is not corrected, but it is reported to the Event Log.
- **Recovered media error** – The drive could not read the requested data on its first attempt. The result of this action is that the data is rewritten to the drive and verified. The error is reported to the Event Log.
- **Redundancy mismatches** – Redundancy errors are found, and a media error is forced on the block stripe so that it is found when the drive is scanned again. If redundancy is repaired, this forced media error is removed. The result of this action is that the first 10 redundancy mismatches found on a volume are reported to the Event Log.
- **Unfixable error** – The data could not be read, and parity information or redundancy information could not be used to regenerate it. For example, redundancy information cannot be used to reconstruct data on a degraded volume. The result of this action is that the error is reported to the Event Log.

The script command set provides two commands to define media scan properties:

- `set volume`

---

- `set storageArray`

The `set volume` command enables a media scan for the volume. The command has this form:

```
set (allVolumes | volume [volumeName] |  
volumes [volumeName1 ... volumeNameN] |  
volume <wwID>)  
mediaScanEnabled=(TRUE | FALSE)
```

The `set storageArray` command defines how frequently a media scan is run on a storage array. The command has this form:

```
set storageArray mediaScanRate=(disabled | 1-30)
```

The `mediaScanRate` values define the number of days over which the media scan runs. Valid values are `disabled`, which turns off the media scan; or 1 day to 30 days, where 1 day is the fastest scan rate, and 30 days is the slowest. A value other than what is shown will not allow the media scan to function.

## Running a Redundancy Check

Redundancy checks are performed when media scans are run. (For a description about how to set up and run media scans, see [“Running a Media Scan.”](#)) During a redundancy check, all of the data blocks in a volume are scanned, and, depending on the RAID level, deteriorated data is corrected. Correction is performed as follows:

- For RAID Level 3, RAID Level 5, or RAID Level 6 volumes, redundancy is checked and repaired.
- For RAID Level 1 volumes, the data is compared between the mirrored drives and data inconsistencies are repaired.
- RAID Level 0 volumes have no redundancy.

Before you can run a redundancy check, you must enable redundancy checking by using the `set volume` command. The command has this form:

```
set (allVolumes | volume [volumeName] |  
volumes [volumeName1 ... volumeNameN] |  
volume <wwID>)  
redundancyCheckEnabled=(TRUE | FALSE)
```

## Resetting a Controller

---

**NOTE** When you reset a controller, the controller is no longer available for I/O operations until the reset is complete. If a host is using volumes that are owned by the controller being reset, the I/O that is directed to the controller is rejected. Before resetting the controller, either make sure that the volumes that are owned by the controller are not in use, or make sure that a multi-path driver is installed on all of the hosts that are using these volumes.

---

Resetting a controller is the same as rebooting the controller processors. To reset a controller, use this command:

```
reset controller [(a | b)]
```

## Enabling a Controller Data Transfer

At times, a controller might become quiescent while running diagnostics. If this condition occurs, the controller might become unresponsive. To revive a controller that has become quiescent while running diagnostics, use this command:

```
enable controller [(a | b)] dataTransfer
```

---

## Resetting the Battery Age

After you have replaced the batteries in the storage array, you must reset the age of the battery. You can reset either the batteries for an entire storage array or a battery in a specific controller. To reset the age of the batteries to zero days, use this command:

```
reset storageArray batteryInstallDate [controller=(a | b)]
```

---

**NOTE** This command is supported only by controller modules and array modules released before the 6540 controller module. The batteries in controller modules and array modules released after the 6540 controller module do not require that you reset the battery age after you have replaced the batteries.

---

## Removing Persistent Reservations

Persistent reservations preserve volume registrations, and they prevent hosts, other than the host defined for the volume, from accessing the volume. You must remove persistent reservations before you make these changes to your configuration:

- Change or delete LUN mappings on a volume holding a reservation
- Delete pools or volumes that have any reservations

To determine which volumes have reservations, use this command:

```
show (allVolumes | volume [volumeName] |  
volumes [volumeName1 ... volumeNameN]) reservations
```

To clear persistent volume reservations, use this command:

```
clear (allVolumes | volume [volumeName] |  
volumes [volumeName1 ... volumeNameN]) reservations
```

## Synchronizing the Controller Clocks

To synchronize the clocks on both controllers in a storage array with the host clock, use this command:

```
set storageArray time
```

## Locating Drives

At times, you might need to locate a specific drive. In very large storage array configurations, this task can sometimes be awkward. If you need to locate a specific drive, you can do so by turning on the indicator light on the front of the drive. To locate a drive, use this command:

```
start drive [trayID,slotID] locate
```

To turn off the indicator light after locating the drive, use this command:

```
stop drive locate
```

## Relocating a Pool

Pool relocation describes the action of moving drives within the same storage array. This is a supported capability; however, any relocation of storage array components must be completed under the guidance of your Sun Customer Care Center representative.

This section describes the commands that you use to remove a set of drives and then reinstall them into a different storage array.

### **Hot and Cold Pool Relocation**

There are two methods you can use to move pools: hot pool relocation and cold pool relocation.

- Hot pool relocation lets you add or move storage without reconfiguring the storage array and, in some cases, without rebooting. During hot pool relocation, the storage array power is not turned off.
- Cold pool relocation requires that the power to the source storage array and the destination storage array be turned off before moving the pools from one storage array to another. Then the power to the storage arrays can be turned on.

To make sure that any pool being moved to a different destination storage array is correctly recognized and managed by the new storage array, use hot pool relocation whenever possible.

---

**ATTENTION Possible loss of data access** – You must move a single pool at a time, and it must go into a storage array with the same level of controller firmware.

---

### **Basic Process Steps**

Relocating a pool includes these procedures:

1. Verifying the status of the storage array
2. Locating the drives in the pool
3. Placing the pool offline
4. Removing drives from the storage array
5. Replacing a pool into the new storage array

To perform these steps, you must be familiar with the following CLI commands. The command syntax is provided to assist in your use of these new commands.

### **Pool Relocation Commands**

Use the following command to place a specific storage array into an exported state so that its drives can be removed.

```
start pool [poolName] export
```

At this point you are allowed to remove the drives that comprise the pool, and physically reinstall them into a different storage array.

Use the following command to logically move a specific storage array from an exported state to the complete state.

```
start pool [poolName] import
```

Your relocated pool is now available for use.

For additional information, refer to these commands in the *Command Line Interface and Script Commands for Version 10.75*:

- `show pool exportDependencies`
- `show pool importDependencies`
- `show pool export`
- `show pool import`

## Performance Tuning

Over time, as a storage array exchanges data between the hosts and the drives, its performance can degrade. You can monitor the performance of a storage array and make adjustments to the operational settings on the storage array to help improve performance.

### Monitoring the Performance

You can monitor the performance of a storage array by using the `save storageArray performanceStats` command. This command saves performance information to a file that you can review to help determine how well the storage array is running. The following table lists the performance information that is saved to the file.

**Table 1 Information About Storage Array Performance**

Type of Information	Description
Devices	These devices are included in the file: <ul style="list-style-type: none"><li>■ <b>Controllers</b> – The controller in slot A or slot B and a list of the volumes that are owned by the controller</li><li>■ <b>Volumes</b> – A list of the volume names</li><li>■ <b>Storage array totals</b> – A list of the totals for both controllers in an active/active controller pair, regardless if one, both, or neither are selected for monitoring</li></ul>
Total I/Os	The number of total I/Os performed since the storage array was started
Read Percentage	The percentage of total I/Os that are read operations (calculate the write percentage by subtracting the read percentage from 100 percent)
Cache Hit Percentage	The percentage of reads that are fulfilled by data from the cache rather than requiring an actual read from a drive
Current KB per second	The current transfer rate in kilobytes per second (current means that the number of kilobytes per second since the last time that the polling interval elapsed, causing an update to occur)
Maximum KB per second	The highest data transfer value that is achieved in the current kilobyte-per-second statistic block
Current I/O per second (IOPS)	The current number of I/Os per second (current means the number of I/Os per second since the last time that the polling interval elapsed, causing an update to occur)
Maximum I/O per second	The highest number of I/Os achieved in the current I/O-per-second statistic block

The command takes this form:

```
save storageArray performanceStats file="filename"
```

where *filename* is the name of the file in which you want to save the performance statistics. You can use any file name that your operating system can support. The default file type is `.csv`. The performance information is saved as a comma-delimited file.

Before you use the `save storageArray performanceStats` command, run these commands to specify how often statistics are collected.

- `set session performanceMonitorInterval`
- `set session performanceMonitorIterations`

---

## Changing the RAID Levels

When you create a pool, you can define the RAID level for the volumes in that pool. You can change the RAID level later to improve performance or provide more secure protection for your data.

---

**NOTE** RAID Level 6 is a premium feature for the 6140 array module, 6140 array module, and the 6180 array module. You must enable RAID Level 6 with the feature key file before you can use the Dynamic RAID-level Migration feature.

---

To change the RAID level, use this command:

```
set volumeGroup [volumeGroupName]
raidLevel=(0 | 1 | 3 | 5 | 6)
```

In this command, *volumeGroupName* is the number of the pool for which you want to change the RAID level.

## Changing the Segment Size

When you create a new volume, you can define the segment size for that volume. In addition, you can change the segment size later to optimize performance. In a multiuser database or file system storage environment, set your segment size to minimize the number of drives that are needed to satisfy an I/O request. Use larger values for the segment size. Using a single drive for a single request leaves other drives available to simultaneously service other requests. If the volume is in a single-user large I/O environment, performance is maximized when a single I/O request is serviced with a single data stripe; use smaller values for the segment size. To change the segment size, use this command:

```
set volume ([volumeName] | <wwID>) segmentSize=segmentSizeValue
```

where *segmentSizeValue* is the new segment size that you want to set. Valid segment size values are 8, 16, 32, 64, 128, 256, and 512. You can identify the volume by name or by WWID. (For usage information, refer to the *set volume* command in the *Command Line Interface and Script Commands for Version 10.75*.)

## Changing the Cache Parameters

The script command *set* provides two commands that you can use to change cache parameter settings:

- `set storageArray`
- `set volume`

The `set storageArray` command lets you change settings for these items:

- The cache block size
- The cache flush start percentage
- The cache flush stop percentage

The `set volume` command lets you change settings for these items:

- The cache flush modifier
- The cache without batteries enabled or disabled
- The mirror cache enabled or disabled
- The read cache enabled or disabled
- The write cache enabled or disabled
- The read ahead multiplier
- The redundancy check enabled or disabled

---

## Defragmenting a Pool

When you defragment a pool, you consolidate the free capacity in the pool into one contiguous area. Defragmentation does not change the way in which the data is stored on the volumes. As an example, consider a pool with five volumes. If you delete volume 1 and volume 3, your pool is configured as follows:

space, volume 2, space, volume 4, volume 5, original unused space

When you defragment this pool, the space (free capacity) is consolidated into one contiguous location after the volumes. After being defragmented, the pool appears as follows:

volume 2, volume 4, volume 5, consolidated unused space

To defragment a pool, use this command:

```
start pool [poolNumber] defragment
```

where *poolNumber* is the identifier for the pool.

## Troubleshooting and Diagnostics

If a storage array exhibits abnormal operation or failures, you can use the commands that are described in this section to help determine the cause of the problem.

### Detailed Error Reporting

Data collected from an error encountered by the CLI is written to a file. Detailed error reporting under the CLI works as follows:

- If the CLI must abnormally end running CLI commands and script commands, error data is collected and saved before the CLI finishes.
- The CLI saves the error data by writing the data to a standard file name.
- The CLI automatically saves the data to a file. Special command line options are not required to save the error data.
- You are not required to perform any action to save the error data to a file.
- The CLI does not have any provision to avoid over-writing an existing version of the file that contains error data.

For error processing, errors appear as two types:

- Terminal errors or syntax errors that you might enter
- Exceptions that occur as a result of an operational error

When the CLI encounters either type of error, the CLI writes information that describes the error directly to the command line and sets a return code. Depending on the return code, the CLI also might write additional information about which terminal caused the error. The CLI also writes information about what it was expecting in the command syntax to help you identify any syntax errors that you might have entered.

When an exception occurs while a command is running, the CLI captures the error. At the end of processing the command (after the command processing information has been written to the command line), the CLI automatically saves the error information to a file.

The name of the file to which error information is saved is `excp rpt . txt`. The CLI tries to place the `excp rpt . txt` file in the directory that is specified by the system property `devmgr . datadir`. If for any reason the CLI cannot place the file in the directory specified by `devmgr . datadir`, the CLI saves the `excp rpt . txt` file in the same directory from which the CLI is running. You cannot change the file name or the location. The `excp rpt . txt` file is overwritten every time that an exception occurs. If you want to save the information in the `excp rpt . txt` file, you must copy the information to a new file or a new directory.

## Collecting All Support Data

To gather the most comprehensive information about a storage array, run the `save storageArray supportData` command. This command collects data for remote troubleshooting and analysis of problems with the storage management software. All of the files gathered are compressed into a single archive in a zipped file format. The following table lists the type of support data that is collected.

**Table 2 Support Data for the Storage Array**

Type of Data	Description and File Name
Storage array support data	A collection of all of the current support files for a storage array. <code>storageArraySupportData . zip</code> This file is not automatically generated. Create this file using the <code>save storageArray supportData</code> command.
Storage array profile	A list of all components and properties of a storage array. <code>storageArrayProfile . txt</code>
Major Event Log	A detailed list of errors that occur on the storage array. The list is stored in reserved areas on the drives in the storage array. The list records configuration events and failures with storage array components. <code>majorEventLog . txt</code>
NVSRAM	A controller file that specifies the default settings for the controllers. <code>NVSRAMdata . txt</code>
Object bundle	A detailed description of the status of the storage array and its components, which was valid at the time that the file was generated. The object bundle file is a binary file and does not contain human-readable information. <code>objectBundle</code>
Performance statistics	A detailed description of how a storage array is performing. Collected data includes the I/O activity of specific controllers or volumes, the transfer rate of the controller, the current I/Os per second, and the maximum I/Os per second. <code>performanceStatistics . csv</code>
Persistent reservations and persistent registrations	A detailed list of volumes on the storage array and persistent reservations and persistent registrations. <code>persistentRegistrations . txt</code>
Read link status	A detailed list of errors that have been detected in the traffic flow between the devices on the Fibre Channel loop. A file of historical read link status data might also be included in the archive. <code>readLinkStatus . csv</code>
SAS physical layer (SAS PHY)	A detailed list of errors that have been detected in the traffic flow between the devices on the SAS loop. A file of historical SAS PHY status data might also be included in the archive. <code>sasPHYStatus . csv</code>



Type of Data	Description and File Name
Recovery profile	A detailed description of the latest recovery profile record and historical data. <code>recoveryProfile.csv</code>
Switch-on-a-chip (SOC) error statistics	Information from the loop-switch ports that are connected to Fibre Channel devices. <code>socStatistics.csv</code>
Drive diagnostic data	A detailed list of log sense data from all of the drives in the storage array. <code>driveDiagnosticData.txt</code>
State capture data	A detailed description of the current state of the storage array. <code>stateCaptureData.txt</code>
Environmental services monitor (ESM) state capture	A detailed description of the current state of the ESMs in a storage array. <code>ESMStateCaptureData.zip</code>
Storage array	A detailed listing of the hardware components and the software components that comprise the storage array configuration. <code>storageArrayConfiguration.cfg</code>
Unreadable sectors	A detailed list of all of the unreadable sectors that have been logged to the storage array. <code>badBlocksData.txt</code>
Firmware inventory	A detailed list of all of the firmware running on the controllers, the drives, the drawers, and the environmental services monitors (ESMs) in the storage array. <code>firmwareInventory.txt</code>

## Collecting Drive Data

To gather information about all of the drives in a storage array, use the `save allDrives` command. This command collects sense data and saves the data to a file. The sense data consists of statistical information that is maintained by each of the drives in the storage array.

## Diagnosing a Controller

The `diagnose controller` command provides these tests that help you make sure that a controller is functioning correctly:

- The read test
- The write test
- The data-loopback test

The read test initiates a read command as it would be sent over an I/O data path. The read test compares data with a known, specific data pattern, and the read test checks for data integrity and errors. If the read command is unsuccessful or the data compared is not correct, the controller is considered to be in error and is placed offline.

The write test initiates a write command as it would be sent over an I/O data path to the diagnostics region on a specified drive. This diagnostics region is then read and compared to a specific data pattern. If the write fails or the data compared is not correct, the controller is considered to be in error, and it is failed and placed offline.

Run the data-loopback test only on controllers that have connections between the controller and the drives. The test passes data through each controller drive-side channel, out onto the loop, and back again. Enough data is transferred to determine error conditions on the channel. If the test fails on any channel, this status is saved so that it can be returned if all of the other tests pass.

For best results, run all three tests after you first install the storage array and any time that you that have made changes to the storage array or the components that are connected to the storage array (such as hubs, switches, and host adapters).

A custom data pattern file called `diagnosticsDataPattern.dpf` is included in the root directory of the installation CD. You can modify this file, but the file must have these properties to work correctly for the tests:

- The file values must be entered in hexadecimal format (00 to FF) with only one space between the values.
- The file must be no larger than 64 bytes in size. Smaller files will work, but larger files can cause an error.

The test results contain a generic, overall status message and a set of specific test results. Each test result contains these items:

- Test (read, write, or data loopback)
- Port (read or write)
- Level (internal or external)
- Status (pass or fail)

Events are written to the Event Log when the diagnostics are started and when testing is completed. These events help you to evaluate whether diagnostics testing was successful or failed and the reason for the failure.

## Running Read Link Status Diagnostics

Read link status (RLS) error counts refer to link errors that have been detected in the traffic flow of a Fibre Channel loop. The errors detected are represented as a count (32-bit field) of error occurrences that are accumulated over time. The counts provide coarse measure of the integrity of the components and devices on the loop. By analyzing the error counts that are retrieved, you can determine the components or devices within the Fibre Channel loop that might be experiencing problems communicating with the other devices on the loop. A high error count for a particular component or device indicates that it might be experiencing problems and should be given immediate attention.

Error counts are calculated from the current baseline. The baseline describes the error count values for each type of device in the Fibre Channel loop, either when the controller goes through its start-of-day sequence or when you reset the baseline. The baseline indicates the difference in error counts from the time the baseline was established to the time you request the read link status data.

The script command set provides two commands for running RLS diagnostics:

- `reset storageArray RLSBaseline` – Resets the RLS baseline for all devices by setting all of the counts to 0.
- `save storageArray RLSCounts` – Saves the RLS counters to a file that you can review later. The default file name is `readLinkStatus.csv`.

Run the `reset storageArray RLSBaseline` command before you run the `save storageArray RLSBaseline` command.

The following table lists the type of data contained by the file that is generated by the `save storageArray RLSBaseline` command.

**Table 3 RLS Baseline Data for the Storage Array**

Type of Data	Description
Devices	A list of all devices on the Fibre Channel loop. The devices appear in channel order. Within each channel, the devices are sorted according to the device position in the loop.
Baseline time	The date and time when the baseline was set.
Elapsed time	The time that has elapsed from when the baseline time was set to when the read link status was gathered.
Invalid transmission word (ITW)	The total number of ITW errors that were detected on the Fibre Channel loop from the baseline time to the current date and time. ITW might also be referred to as the Received Bad Character Count.  ITW counts indicate that in decoding a read/write transmission, the mapping did not exist and the running disparity of the transmission word is invalid. This data is the key error count to be used when analyzing the error count data.
Link failure (LF)	The total number of LF errors that were detected on the Fibre Channel loop from the baseline time to the current date and time.  An LF condition is either a link fault signal, a loss of signal, or a loss of synchronization condition. The LF signal indicates a failure with the media module laser operation.
Loss of synchronization (LOS)	The total number of LOS errors that were detected on the Fibre Channel loop from the baseline time to the current date and time.  LOS errors indicate that the receiver cannot acquire symbol lock with the incoming data stream due to a degraded input signal. If this condition persists, the number of LOS errors increases.

Type of Data	Description
Loss of signal (LOSG)	<p>The total number of LOSG errors that were detected on the Fibre Channel loop from the baseline date to the current date and time.</p> <p>LOSG errors typically indicate a loss of signal from the transmitting node or the physical component within the Fibre Channel loop. Physical components where a loss of signal typically occurs include the gigabit interface converters (GBICs), the Small Form-factor Pluggable (SFP) transceivers, and the Fibre Channel fiber-optic cable.</p>
Primitive sequence protocol (PSP)	<p>The total number of PSP errors that were detected on the Fibre Channel loop from the baseline date to the current date and time. PSP refers to the number of N_Port protocol errors that were detected and Link Reset Response (LRR) primitive sequences that were received while the link is up. An LRR is issued by another N_Port in response to a link reset.</p> <p>An N_Port is a Fibre Channel-defined port at the end of a link, such as a server or a workstation. Each port can act as an originator or a responder (or both) and contains a transmitter and receiver. Each port is given a unique name, called an N_Port or an N_Port identifier. If an N_Port is connected to a loop, it becomes an NL_Port. An NL_Port is a Fibre Channel controller ID in a hexadecimal number. The hexadecimal number varies depending on the topology:</p> <ul style="list-style-type: none"> <li>■ For a private arbitrated loop, the ID is a 1-byte arbitrated loop physical address (ALPA).</li> <li>■ For all other arbitrated loops, it appears as a single 24-bit hexadecimal number (a triplet of domain, area, and ALPA where each field is 1 byte).</li> <li>■ For fabric and point-to-point, the ID is a 3-byte hexadecimal number used in the DID and SID (destination identifier and source identifier) fields of Fibre Channel frames.</li> </ul>
Invalid cyclic redundancy check (ICRC)	<p>The total number of ICRC errors that were detected on the Fibre Channel loop from the baseline date to the current date and time.</p> <p>An ICRC count indicates that a frame has been received with an invalid cyclic redundancy check value. A cyclic redundancy check reads the data, calculates the cyclic redundancy check character, and compares the calculated cyclic redundancy check character with a cyclic check character already present in the data. If they are equal, the new data is presumed to be the same as the old data. If the calculated characters and the old characters do not match, an error is posted, and the data is re-sent.</p>

### Interpreting the RLS Results

The way that you interpret the RLS results is based on the concept that the device immediately following the problematic component will have the largest number of invalid transition word (ITW) error counts. The process is to obtain the ITW count for every component and device on the loop, analyze the data in loop order, and identify any large increases in the ITW counts.

**NOTE** The current error counting standard for when to calculate the ITW error count is not well defined. Different vendor devices calculate at different rates. Analysis of the data must take this discrepancy into consideration.

---

## Collecting Switch-on-a-Chip Error Statistics

Switch-on-a-chip (SOC) error statistics provide information about the loop-switch ports that are connected to the Fibre Channel devices in a storage array. (RLS counts provide information about the Fibre Channel devices.) Reporting SOC error statistics is available only on storage arrays that have SOC loop-switch devices that are incorporated into the controller drive channel or the ESM circuitry. SOC devices are integrated circuits that join together Fibre Channel devices in arbitrated loop topologies. SOC devices automatically collect statistical information for each SOC port that is connected to a controller port, an ESM port, a drive port, or an expansion connector. Your Sun Customer Care Center representative can use the statistical information with RLS counts to identify problems with Fibre Channel devices that are attached to the loop.

SOC error statics include this information:

- The port state
- The port insertion count
- The loop state
- The loop up count
- The CRC error count
- The relative frequency drift error average
- The loop cycle count
- The operating system (OS) error count
- The port connections attempted count
- The port connections held off count
- The port utilization

The method for collecting error statistics starts by establishing a baseline for the SOC error statistics. The baseline consists of SOC error statistics that are established at a set time for each SOC device on the loop. The baseline is set by clearing the error counters in each SOC device. You can set a device baseline by performing one of these actions:

- Turning on the power to the device or resetting the device
- Running the `reset storageArray SOCBaseline` command

In addition, each controller also initializes the SOC error counters in all of the drive modules that are attached to the controller following a cold boot (power-on or hot insertion). If you add a drive module while the power is turned on to the storage array, a new baseline is established for any device on the drive module.

After you have established the baseline for the SOC devices, you run the storage array for a predetermined amount of time (for example, two hours). At the end of the run time, you collect the SOC error statistics by saving the information to a file. To save the information, run the `save storageArray SOCCounts file filename` command. The default name of the file that contains the SOC error statistics is `socStatistics.csv`. You can use any file name that has the `.csv` extension.

Analyzing the SOC error statistics is beyond the scope of normal storage array management. After you have collected the SOC error statistics in a file, send the file to your Sun Customer Care Center representative.

## Recovery Operations

Recovery operations include repairing the storage array and returning it to an operational state. This might involve replacing a failed CRU, a failed controller, or a drive or restoring data or the storage array to operation. For information about when it is appropriate to replace a CRU, see ["Routine Maintenance."](#)

---

## Setting the Controller Operational Mode

A controller has three operational modes:

- Online
- Offline
- Service

Placing a controller online sets it to the Optimal state and makes it active and available for I/O operations. Placing a controller offline makes it unavailable for I/O operations and moves its pools to the other controller if failover protection is enabled.

Taking a controller offline can seriously impact data integrity and storage array operation.

- If you do not use write cache mirroring, data in the cache of the controller you place offline is lost.
- If you take a controller offline and you have controller failover protection through a host multi-path driver, the other controller in the pair takes over. Pools and their associated volumes that were assigned to the offline controller are automatically reassigned to the remaining controller. If you do not have a multi-path driver installed on the application host and you take a controller offline while the application is using associated volumes, application errors will occur.

---

**ATTENTION Possible loss of data access** – Placing a controller offline can cause loss of data.

---

Use Service mode to replace CRUs, such as a controller. Placing a controller in Service mode makes it unavailable for I/O operations and moves its pools to the second controller without affecting the preferred path of the pool. This action might significantly reduce performance. The pools are automatically transferred back to the preferred controller when it is placed back online.

If you change a controller to Service mode while an application is using the associated volumes on the controller, the change causes I/O errors unless a multi-path driver is installed on the host. Before you place a controller in Service mode, make sure that the volumes are not in use, or a multi-path driver is installed on all of the hosts that are using these volumes.

In addition, if you do not have a multi-path driver, you must make appropriate operating system-specific modifications to make sure that the pools moved are accessed on the new path when you change to Service mode.

---

**NOTE** Place a controller in Service mode only under the direction of a Sun Customer Care Center representative.

---

To change the operational mode of a controller, use this command:

```
set controller [(a | b)] availability=(online | offline | serviceMode)
```

## Changing the Controller Ownership

You can change which controller is the owner of a volume by using the `set volume` command. The command takes this form:

```
set (allVolumes | volume [volumeName] |  
volumes [volumeName1 ... volumeNameN] |  
volume <wwID>) owner=(a | b)
```

## Initializing a Drive

---

**ATTENTION Possible loss of data access** – When you initialize a drive, all data on the drive is lost.

---

You must initialize a drive when you have moved a drive that was previously part of a multidisk pool from one storage array to another. If you do not move the entire set of drives, the pool information and the volume information on the drives that you move are incomplete. Each drive that you move contains only part of the information that is defined for the volume and the pool. To be able to reuse the drives to create a new pool and volume, you must delete all of the old information from the drives by initializing the drive.

When you initialize a drive, all of the old pool information and volume information are deleted, and the drive is returned to an unassigned state. Returning a drive to an unassigned state adds unconfigured capacity to a storage array. You can use this capacity to create additional pools and volumes.

To initialize a drive, use this command:

```
start drive [trayID,slotID] initialize
```

In this command, *trayID* and *slotID* are the identifiers for the drive.

## Reconstructing a Drive

If two or more of the drives in a pool have failed, the volume shows a status of Failed. All of the volumes in the pool are no longer operating. To return the pool to an Optimal status, you must replace the failed drives. Then, you must reconstruct the data on the new drives. The data that you reconstruct is the data as it would appear on the failed drives.

---

**NOTE** You can use this command only when the drive is assigned to a RAID Level 1, RAID Level 3, RAID Level 5, or RAID Level 6 pool.

---

To reconstruct a drive, use this command:

```
start drive [trayID,slotID] reconstruct
```

In this command, *trayID* and *slotID* are the identifiers for the drive.

## Initializing a Volume

---

**ATTENTION Possible loss of data access** – When you initialize a volume, all data on the volume and all of the information about the volume are destroyed.

---

A volume is automatically initialized when you first create it. If the volume starts showing failures, you might be required to re-initialize the volume to correct the failure condition.

Consider these restrictions when you initialize a volume:

- You cannot cancel the operation after it begins.
- You cannot use this option if any modification operations are in progress on the volume or the pool.
- You cannot change the cache parameters of the volume while the initialization operation is in progress.

To initialize a volume, use this command:

```
start volume [volumeName] initialize
```

where *volumeName* is the identifier for the volume.

---

## Redistributing Volumes

When you redistribute volumes, you return the volumes to their preferred controller owners. The preferred controller ownership of a volume or a pool is the controller of an active-active pair that is designated to own the volumes. The preferred owner for a volume is initially designated when the volume is created. If the preferred controller is being replaced or undergoing a firmware download, ownership of the volumes is automatically shifted to the other controller. That controller becomes the current owner of the volumes. This change is considered to be a routine ownership change and is reported in the Event Log.

To redistribute volumes to their preferred controllers, use this command:

```
reset storageArray volumeDistribution
```

---

**NOTE** If you run this command without a multi-path driver on the hosts, stop I/O activity to the volumes to prevent application errors.

---

**NOTE** You cannot run this command if all of the volumes are currently owned by their preferred controller, or the storage array does not have defined volumes.

---

Under some host operating systems, you must reconfigure the multi-path host driver. You might also need to make operating system modifications to recognize the new I/O path to the volume.

## Replacing CRUs

Beginning with the 6540 controller module, components, such as the controller CRUs, the power-fan CRUs, and the interconnect-battery CRUs, have a Service Action Allowed indicator light. This indicator light is a blue LED. The Service Action Allowed indicator light helps to make sure that you do not remove a CRU before it is safe to do so.

---

**ATTENTION Possible loss of data access** – Never remove a component that has a Service Action Required indicator light on unless the Service Action Allowed indicator light is on.

---

If a component fails and must be replaced, the Service Action Required indicator light on that CRU comes on to indicate that service action is required, provided no data availability dependencies or other conditions exist that dictate the CRU should not be removed. The Service Action Allowed indicator light automatically comes on or goes off when conditions change. In most cases, the Service Action Allowed indicator light comes on steadily when the Service Action Required indicator light comes on for the CRU.

If the interconnect-battery CRU must be replaced, the Service Action Allowed indicator light does not come on automatically. Before the Service Action Allowed indicator light on the interconnect-battery CRU can come on, you must place controller CRU in slot B into Service mode. This action routes all control and I/O activity through one controller to help make sure that data access is maintained while the interconnect-battery CRU is removed. The Service Action Allowed indicator light comes on after the new CRU has been installed.

The ability to remove a CRU depends on the data availability dependencies of the controller module or the array module. The Service Action Allowed indicator light does not come on if removing a CRU jeopardizes data on the drive modules or current I/O activity. An example of limiting when you can remove a CRU is when one controller CRU has a Service Action Required indicator light on. You cannot remove the other controller CRU (the Service Action Allowed indicator light does not come on), because doing so would jeopardize the data either on the drive modules or transitioning through the controllers.

A less obvious example is when the power supply for the controller CRU in slot A has failed, and the controller CRU in slot B has failed. Removing the controller CRU in slot B before replacing the failed power-fan CRU causes the controller CRU in slot A to lose power, which results in a loss of data access. This action occurs because power distribution from each power-fan CRU is through the controller CRU that is physically connected to that power-fan CRU.



So, in the preceding example, these actions occur:

- The power-fan CRU has both its Service Action Required indicator light and its Service Action Allowed indicator light on.
- The controller CRU in slot B has only its Service Action Required indicator light on, but its Service Action Allowed indicator light is off.
- After the failed power-fan CRU has been replaced, the Service Action Allowed indicator light comes on for the controller CRU in slot B.

The following table shows when the Service Action Allowed indicator light does not come on for each CRU (the indicator light is suppressed). An **X** in a table cell indicates that service is not allowed, therefore the Service Action Allowed light does not come on. For example, if the power supply in the power-fan CRU in slot A has failed, then replacement of the controller CRU in slot B, the interconnect-battery CRU, or the power-fan CRU in slot B is not allowed, which is indicated when the Service Action Allowed indicator light stays off for those CRUs.

**Table 4 Service Action Not Allowed**

Description of Failure or Circumstance	CRU Description				
	Controller in Slot A	Controller in Slot B	Interconnect Battery	Power-Fan in Slot A	Power-Fan in Slot B
The controller CRU in slot A has failed or is locked down		X	X		
The controller CRU in slot B has failed or is locked down	X				
The controller CRU in the slot A drive path is unavailable		X	X		
The controller CRU in the slot B drive path is unavailable	X		X		
The power supply in the power-fan CRU in slot A has failed		X	X		X
A fan in the power-fan CRU in slot A has failed					
The power supply in the power-fan CRU in slot B has failed	X		X	X	
A fan in the power-fan CRU in slot B has failed					
The interconnect-battery CRU has been removed	X			X	
The controller CRU in slot A has been removed		X	X		X
The controller CRU in slot B has been removed	X			X	
The power-fan CRU in slot A has been removed		X	X		X
The power-fan CRU in slot B has been removed	X		X	X	
The battery pack has failed					
The battery pack has been removed					

---

## Appendix A: Examples of Information Returned by the Show Commands

This appendix provides examples of information that is returned by the `show` commands. These examples show the type of information and the information detail. This information is useful in determining the components, features, and identifiers that you might need when you configure or maintain a storage array.

### Show Storage Array

The `show storageArray` command returns information about the components and the features in a storage array. If you run the command with the `profile` parameter, the command returns information in the form shown by this example. This information is the most detailed report that you can receive about the storage array. After you have configured a storage array, save the configuration description to a file as a reference.

```
Storage array profile
PROFILE FOR STORAGE ARRAY: example9 (x/xx/xx 1:06:05 PM)

SUMMARY-----
Number of controllers: 1
Number of volume groups: 1
Total number of volumes (includes an access volume): 5 of 2048 used
    Number of standard volumes: 2
    Number of access volumes: 1
    Number of mirror repositories: 2
    Number of snapshot repositories: 0
Number of snapshot volumes: 0
Number of mirrored pairs: 0 of 64 used
Number of copies: 0
Number of drives: 9
Supported drive types: Fibre (9)
Total hot spare drives: 0
    Standby: 0
    In use: 0
Access volume: LUN 7 (see Mappings section for details)
Default host type: Linux (Host type index 6)
Current configuration
    Firmware version: PkgInfo 96.10.21.00
    NVSRAM version: N4884-610800-001
Pending configuration
    Staged firmware download supported?: No
    Firmware version: Not applicable
    NVSRAM version: Not applicable
    Transferred on: Not applicable
NVSRAM configured for batteries?: Yes
Start cache flushing at (in percentage): 80
Stop cache flushing at (in percentage): 80
Cache block size (in KB): 4
Media scan frequency (in days): Disabled
Failover alert delay (in minutes): 5
Feature enable identifier: 1234567891011121314151617181ABCD
```

```
CONTROLLERS-----
Number of controllers: 1

Controller in Slot A
Status: Online
Current configuration
  Firmware version: 96.10.21.00
  Appware version: 96.10.21.00
  Bootware version: 96.10.21.00
  NVSRAM version: N4884-610800-001
Pending configuration
  Firmware version: Not applicable
  Appware version: Not applicable
  Bootware version: Not applicable
  NVSRAM version: Not applicable
  Transferred on: Not applicable
Board ID: 4884
Product ID: INF-01-00
Product revision: 9610
Serial number: 1T14148766
Date of manufacture: October 14, 2001
Cache/processor size (MB): 1024/128
Date/Time: Fri Feb 13 13:06:05 MST 2004
Associated Volumes (* = Preferred Owner):
  1*, CTL 0 Mirror Repository*, Mirror Repository 1*, Primary_Volume*
Ethernet port: 1
  MAC address: 00:a0:b8:0c:c3:f5
  Host name: ausctlr9
  Network configuration: Static
  IP address: 172.22.4.249
  Subnet mask: 255.255.255.0
  Gateway: 172.22.4.1
  Remote login: Enabled

Drive interface: Fibre
  Channel: 1
  Current ID: 125/0x1
  Maximum data rate: 2 Gbps
  Current data rate: 1 Gbps
  Data rate control: Switch
  Link status: Up
Drive interface: Fibre
  Channel: 2
  Current ID: 125/0x1
  Maximum data rate: 2 Gbps
  Current data rate: 1 Gbps
  Data rate control: Switch
  Link status: Up
Drive interface: Fibre
  Channel: 3
  Current ID: 125/0x1
  Maximum data rate: 2 Gbps
  Current data rate: 1 Gbps
  Data rate control: Switch
  Link status: Up
Drive interface: Fibre
  Channel: 4
  Current ID: 125/0x1
  Maximum data rate: 2 Gbps
  Current data rate: 1 Gbps
  Data rate control: Switch
  Link status: Up
```

```
Host interface: Fibre
  Port: 1
  Current ID: Not applicable/0xFFFFFFFF
  Preferred ID: 126/0x0
  NL-Port ID: 0x011100
  Maximum data rate: 2 Gbps
  Current data rate: 1 Gbps
  Data rate control: Switch
  Link status: Up
  Topology: Fabric Attach
  World-wide port name: 20:2c:00:a0:b8:0c:c3:f6
  World-wide node name: 20:2c:00:a0:b8:0c:c3:f5
  Part type: HPFC-5200    revision 10
Host interface: Fibre
  Port: 2
  Current ID: Not applicable/0xFFFFFFFF
  Preferred ID: 126/0x0
  NL-Port ID: 0x011000
  Maximum data rate: 2 Gbps
  Current data rate: 1 Gbps
  Data rate control: Switch
  Link status: Up
  Topology: Fabric Attach
  World-wide port name: 20:2c:00:a0:b8:0c:c3:f7
  World-wide node name: 20:2c:00:a0:b8:0c:c3:f5
  Part type: HPFC-5200    revision 10

VOLUME GROUPS-----
  Number of volume groups: 1

  Volume Group 1 (RAID 5)
    Status: Online
    Drive type: Fibre Channel
    Tray loss protection: No
    Current owner: Controller in slot A
    Associated volumes and free capacities:
      CTL 0 Mirror Repository (0.125 GB), Mirror Repository 1 (0.125 GB),
      Primary_Volume (5 GB), 1 (1 GB), Free Capacity (129.113 GB)
    Associated drives (in piece order):
      Drive at Tray 0, Slot 1
      Drive at Tray 0, Slot 2
      Drive at Tray 0, Slot 3
      Drive at Tray 0, Slot 5
      Drive at Tray 0, Slot 6
      Drive at Tray 0, Slot 7
      Drive at Tray 0, Slot 10
      Drive at Tray 0, Slot 12
      Drive at Tray 0, Slot 14
```

---

STANDARD VOLUMES-----

SUMMARY

Number of standard volumes: 2  
See other Volumes sub-tabs for premium feature information.

NAME	STATUS	CAPACITY	RAID LEVEL	VOLUME GROUP
1	Optimal	1 GB	5	1
Primary_Volume	Optimal	5 GB	5	1

DETAILS

Volume name: 1  
Volume ID: 60:0a:0b:80:00:0c:c3:f5:00:00:00:23:40:22:86:ea  
Subsystem ID (SSID): 3  
Status: Optimal  
Drive type: Fibre Channel  
Tray loss protection: No  
Preferred owner: Controller in slot A  
Current owner: Controller in slot A  
Capacity: 1 GB  
RAID level: 5  
Segment size: 64 KB  
Modification priority: High  
Associated volume group: 1  
Read cache: Enabled  
Write cache: Enabled  
Write cache without batteries: Disabled  
Write cache with mirroring: Enabled  
Flush write cache after (in seconds): 10.00  
Cache read ahead multiplier: 1  
Enable background media scan: Disabled  
Media scan with redundancy check: Disabled

Volume name: Primary\_Volume  
Volume ID: 60:0a:0b:80:00:0c:c3:f5:00:00:00:1c:40:22:45:ca  
Subsystem ID (SSID): 2  
Status: Optimal  
Drive type: Fibre Channel  
Tray loss protection: No  
Preferred owner: Controller in slot A  
Current owner: Controller in slot A  
Capacity: 5 GB  
RAID level: 5  
Segment size: 64 KB  
Modification priority: High  
Associated volume group: 1  
Read cache: Enabled  
Write cache: Enabled  
Write cache without batteries: Disabled  
Write cache with mirroring: Enabled  
Flush write cache after (in seconds): 10.00  
Cache read ahead multiplier: 1  
Enable background media scan: Disabled  
Media scan with redundancy check: Disabled

```
SNAPSHOT REPOSITORY VOLUMES-----
Number of snapshot repositories: 0

MIRROR REPOSITORY VOLUMES-----
Number of mirror repositories: 0

SNAPSHOT VOLUMES-----
Number of snapshot volumes: 0

MIRRORED PAIRS-----

SUMMARY
Number of mirrored pairs: 0 of 64 used
See also Standard sub-tab for standard volume properties

COPIES-----

SUMMARY
Number of copies: 0
See also Standard sub-tab for standard volume properties

MISSING VOLUMES-----
Number of missing volumes: 0
See other Volumes sub-tabs for premium feature information

DRIVES-----

SUMMARY
Number of drives: 9
Supported drive types: Fibre (9)

BASIC:

TRAY, SLOT  STATUS  CAPACITY  CURRENT DATA RATE  PRODUCT ID  FIRMWARE VERSION
0, 1        Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 2        Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 3        Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 5        Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 6        Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 7        Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 10       Optimal  16.959 GB  1 Gbps              ST318451FC  F28D
0, 12       Optimal  16.959 GB  1 Gbps              ST318451FC  F28B
0, 14       Optimal  16.959 GB  1 Gbps              ST318451FC  F28B

DRIVE CHANNELS:

TRAY, SLOT  PREFERRED CHANNEL  REDUNDANT CHANNEL
0, 1        4                  2
0, 2        2                  4
0, 3        4                  2
0, 5        4                  2
0, 6        2                  4
0, 7        4                  2
0, 10       2                  4
0, 12       2                  4
0, 14       2                  4
```



---

```
HOT SPARE COVERAGE:
  The following volume groups are not protected: 1

  Total hot spare drives: 0
    Standby: 0
    In use: 0

DETAILS
  Drive at Tray 0, Slot 1
    Drive port: 1, Channel: 4, ID: 0/0xEF
    Drive port: 2, Channel: 2, ID: 0/0xEF
    Drive path redundancy: OK
    Status: Optimal
    Raw capacity: 16.959 GB
    Usable capacity: 16.92 GB
    Current data rate: 1 Gbps
    Product ID: ST318451FC
    Firmware version: F280
    Serial number: 3CC052RK00007116BMW7
    Vendor: SEAGATE
    Date of manufacture: July 19, 2001
    World-wide name: 20:00:00:20:37:f5:b3:b6
    Drive type: Fibre Channel
    Speed: 15015 RPM
    Mode: Assigned
    Associated volume group: volume group 1

  Drive at Tray 0, Slot 2
    Drive port: 1, Channel: 2, ID: 1/0xE8
    Drive port: 2, Channel: 4, ID: 1/0xE8
    Drive path redundancy: OK
    Status: Optimal
    Raw capacity: 16.959 GB
    Usable capacity: 16.92 GB
    Current data rate: 1 Gbps
    Product ID: ST318451FC
    Firmware version: F280
    Serial number: 3CC0Q06K0000720291J9
    Vendor: SEAGATE
    Date of manufacture: July 18, 2001
    World-wide name: 20:00:00:20:37:f5:ac:cd
    Drive type: Fibre Channel
    Speed: 15015 RPM
    Mode: Assigned
    Associated volume group: volume group 1

  Drive at Tray 0, Slot 3
    Drive port: 1, Channel: 4, ID: 2/0xE4
    Drive port: 2, Channel: 2, ID: 2/0xE4
    Drive path redundancy: OK
    Status: Optimal
    Raw capacity: 16.959 GB
    Usable capacity: 16.92 GB
    Current data rate: 1 Gbps
    Product ID: ST318451FC
    Firmware version: F280
    Serial number: 3CC052MA00007116DB89
    Vendor: SEAGATE
    Date of manufacture: July 19, 2001
    World-wide name: 20:00:00:20:37:f5:b3:fc
    Drive type: Fibre Channel
    Speed: 15015 RPM
    Mode: Assigned
    Associated volume group: volume group 1
```

---

---

```
Drive at Tray 0, Slot 5
  Drive port: 1, Channel: 4, ID: 4/0xE1
  Drive port: 2, Channel: 2, ID: 4/0xE1
  Drive path redundancy: OK
  Status: Optimal
  Raw capacity: 16.959 GB
  Usable capacity: 16.92 GB
  Current data rate: 1 Gbps
  Product ID: ST318451FC
  Firmware version: F28D
  Serial number: 3CC0526N000007143A10K
  Vendor: SEAGATE
  Date of manufacture: July 19, 2001
  World-wide name: 20:00:00:20:37:f5:b4:5b
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1

Drive at Tray 0, Slot 6
  Drive port: 1, Channel: 2, ID: 5/0xE0
  Drive port: 2, Channel: 4, ID: 5/0xE0
  Drive path redundancy: OK
  Status: Optimal
  Raw capacity: 16.959 GB
  Usable capacity: 16.92 GB
  Current data rate: 1 Gbps
  Product ID: ST318451FC
  Firmware version: F28D
  Serial number: 3CC03R58000007112JU2D
  Vendor: SEAGATE
  Date of manufacture: July 19, 2001
  World-wide name: 20:00:00:20:37:f5:b3:06
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1

Drive at Tray 0, Slot 7
  Drive port: 1, Channel: 4, ID: 6/0xDC
  Drive port: 2, Channel: 2, ID: 6/0xDC
  Drive path redundancy: OK
  Status: Optimal
  Raw capacity: 16.959 GB
  Usable capacity: 16.92 GB
  Current data rate: 1 Gbps
  Product ID: ST318451FC
  Firmware version: F28D
  Serial number: 3CC052J4000007116BSJV
  Vendor: SEAGATE
  Date of manufacture: July 19, 2001
  World-wide name: 20:00:00:20:37:f5:b3:0b
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1
```

---



---

```
Drive at Tray 0, Slot 10
  Drive port: 1, Channel: 2, ID: 96/0x3A
  Drive port: 2, Channel: 4, ID: 96/0x3A
  Drive path redundancy: OK
  Status: Optimal
  Raw capacity: 16.959 GB
  Usable capacity: 16.92 GB
  Current data rate: 1 Gbps
  Product ID: ST318451FC
  Firmware version: F28D
  Serial number: 3CC0P5Q80000711552CZ
  Vendor: SEAGATE
  Date of manufacture: June 30, 2001
  World-wide name: 20:00:00:20:37:f5:69:50
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1

Drive at Tray 0, Slot 12
  Drive port: 1, Channel: 2, ID: 72/0x67
  Drive port: 2, Channel: 4, ID: 72/0x67
  Drive path redundancy: OK
  Status: Optimal
  Raw capacity: 16.959 GB
  Usable capacity: 16.92 GB
  Current data rate: 1 Gbps
  Product ID: ST318451FC
  Firmware version: F28B
  Serial number: 3CC0P7TS00007116DL9D
  Vendor: LSILOGIC
  Date of manufacture: Not available
  World-wide name: 20:00:00:20:37:f5:68:76
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1

Drive at Tray 0, Slot 14
  Drive port: 1, Channel: 2, ID: 104/0x2E
  Drive port: 2, Channel: 4, ID: 104/0x2E
  Drive path redundancy: OK
  Status: Optimal
  Raw capacity: 16.959 GB
  Usable capacity: 16.92 GB
  Current data rate: 1 Gbps
  Product ID: ST318451FC
  Firmware version: F28B
  Serial number: 3CC03STH00007112JNM4
  Vendor: LSILOGIC
  Date of manufacture: Not available
  World-wide name: 20:00:00:20:37:f5:b3:69
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1
```

---

---

DRIVE CHANNEL INFORMATION - Channel 1

SUMMARY-----

Channel 1 status: Optimal  
Controller A link status: Up

CUMULATIVE ERROR COUNTS-----  
Controller A Cumulative Error Counts  
Baseline time set: 2/9/04 10:46:37 AM  
Sample period (days, hh:mm:ss): 4 days, 02:06:52  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: 3  
Total I/O count: 11

DRIVE CHANNEL INFORMATION - Channel 2

SUMMARY-----

Channel 2 status: Optimal  
Controller A link status: Up

CUMULATIVE ERROR COUNTS-----  
Controller A Cumulative Error Counts  
Baseline time set: 2/9/04 10:46:42 AM  
Sample period (days, hh:mm:ss): 4 days, 02:06:47  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: 2  
Total I/O count: 239075

DRIVE CHANNEL INFORMATION - Channel 3

SUMMARY-----

Channel 3 status: Optimal  
Controller A link status: Up

CUMULATIVE ERROR COUNTS-----  
Controller A Cumulative Error Counts  
Baseline time set: 2/9/04 10:46:42 AM  
Sample period (days, hh:mm:ss): 4 days, 02:06:47  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: 3  
Total I/O count: 11

DRIVE CHANNEL INFORMATION - Channel 4

SUMMARY-----

Channel 4 status: Optimal  
Controller A link status: Up

CUMULATIVE ERROR COUNTS-----  
Controller A Cumulative Error Counts  
Baseline time set: 2/9/04 10:46:42 AM  
Sample period (days, hh:mm:ss): 4 days, 02:06:47  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: 2  
Total I/O count: 45807

---

```
TRAYS-----
Controller Tray Overall Component Information
  Drive technology: Unknown
  Minihub data rate mismatch: No
  Fan canister: Optimal
  Fan canister: Optimal
  Battery status: Optimal
    Age: 0 day(s)
    Days until replacement: 719 day(s)
  Power supply canister
    Status: Optimal
  Power supply canister
    Status: Optimal
  Temperature: Optimal
  Host mini-hub canister
    Status: Optimal
    Location: Controller A - Port 1
    Serial number: SN 1T13742151
    Part number: PN 348-0043290
    Vendor: VN LSILOGIC
    Date of manufacture: Not available
  SFP
    Status: Optimal
    Location: In connection
    Supported data rate(s): 1 Gbps, 2 Gbps
    Link length: Intermediate
    Connector: LC
    Transmitter type: Shortwave Laser w/o OFC
    Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
    IEEE company ID: 08 00 5a
    Revision: AA10
    Part number: IBM42P21SNY
    Serial number: 21P7053000M6R
    Vendor: IBM
    Date of manufacture: July 1, 2001
  SFP
    Status: Optimal
    Location: Out connection
    Supported data rate(s): 1 Gbps, 2 Gbps
    Link length: Intermediate
    Connector: LC
    Transmitter type: Shortwave Laser w/o OFC
    Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
    IEEE company ID: 08 00 5a
    Revision: AA10
    Part number: IBM42P21SNY
    Serial number: 21P7053000M54
    Vendor: IBM
    Date of manufacture: July 1, 2001
```

---

---

```
Host mini-hub canister
Status: Optimal
Location: Controller A - Port 2
Serial number: SN 1T13742219
Part number: PN 348-0043290
Vendor: VN LSILOGIC
Date of manufacture: Not available
SFP
  Status: Optimal
  Location: In connection
  Supported data rate(s): 1 Gbps, 2 Gbps
  Link length: Intermediate
  Connector: LC
  Transmitter type: Shortwave Laser w/o OFC
  Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
  IEEE company ID: 08 00 5a
  Revision: AA10
  Part number: IBM42P21SNY
  Serial number: 21P7053000M3Z
  Vendor: IBM
  Date of manufacture: July 1, 2001
SFP
  Status: Optimal
  Location: Out connection
  Supported data rate(s): 1 Gbps, 2 Gbps
  Link length: Intermediate
  Connector: LC
  Transmitter type: Shortwave Laser w/o OFC
  Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
  IEEE company ID: 08 00 5a
  Revision: AA10
  Part number: IBM42P21SNY
  Serial number: 21P7053000M3J
  Vendor: IBM
  Date of manufacture: July 1, 2001
Drive mini-hub canister
Status: Optimal
Location: Channel 1
Serial number: SN 1T13438343
Part number: PN 348-0043290
Vendor: VN LSILOGIC
Date of manufacture: Not available
SFP
  Status: Optimal
  Location: Out connection
  Supported data rate(s): 1 Gbps, 2 Gbps
  Link length: Intermediate
  Connector: LC
  Transmitter type: Shortwave Laser w/o OFC
  Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
  IEEE company ID: 08 00 5a
  Revision: AA10
  Part number: IBM42P21SNY
  Serial number: 21P7053000M6Z
  Vendor: IBM
  Date of manufacture: July 1, 2001
```



---

```
Drive mini-hub canister
  Status: Optimal
  Location: Channel 2
  Serial number: SN 1T13844441
  Part number: PN 19K1270
  Vendor: VN IBM
  Date of manufacture: Not available
  SFP
    Status: Optimal
    Location: In connection
    Supported data rate(s): 1 Gbps, 2 Gbps
    Link length: Intermediate
    Connector: LC
    Transmitter type: Shortwave Laser w/o OFC
    Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
    IEEE company ID: 08 00 5a
    Revision: AA10
    Part number: IBM42P21SNY
    Serial number: 21P7053000M4E
    Vendor: IBM
    Date of manufacture: July 1, 2001
  SFP
    Status: Optimal
    Location: Out connection
    Supported data rate(s): 1 Gbps, 2 Gbps
    Link length: Intermediate
    Connector: LC
    Transmitter type: Shortwave Laser w/o OFC
    Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
    IEEE company ID: 08 00 5a
    Revision: AA10
    Part number: IBM42P21SNY
    Serial number: 21P7053000M40
    Vendor: IBM
    Date of manufacture: July 1, 2001
Drive mini-hub canister
  Status: Optimal
  Location: Channel 3
  Serial number: SN 1T13844373
  Part number: PN 348-0043290
  Vendor: VN LSILOGIC
  Date of manufacture: Not available
  SFP
    Status: Optimal
    Location: In connection
    Supported data rate(s): 1 Gbps, 2 Gbps
    Link length: Intermediate
    Connector: LC
    Transmitter type: Shortwave Laser w/o OFC
    Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
    IEEE company ID: 08 00 5a
    Revision: AA10
    Part number: IBM42P21SNY
    Serial number: 21P7053000M4R
    Vendor: IBM
    Date of manufacture: July 1, 2001
  SFP
    Status: Optimal
    Location: Out connection
    Supported data rate(s): 1 Gbps, 2 Gbps
    Link length: Intermediate
    Connector: LC
    Transmitter type: Shortwave Laser w/o OFC
    Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
    IEEE company ID: 08 00 5a
    Revision: AA10
    Part number: IBM42P21SNY
    Serial number: 21P7053000LXS
    Vendor: IBM
    Date of manufacture: July 1, 2001
```

---

---

```
Drive mini-hub canister
Status: Optimal
Location: Channel 4
Serial number: SN 1T13844386
Part number: PN 348-0043290
Vendor: VN LSILOGIC
Date of manufacture: Not available
SFP
  Status: Optimal
  Location: In connection
  Supported data rate(s): 1 Gbps, 2 Gbps
  Link length: Intermediate
  Connector: LC
  Transmitter type: Shortwave Laser w/o OFC
  Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
  IEEE company ID: 08 00 5a
  Revision: AA10
  Part number: IBM42P21SNY
  Serial number: 21P7053000M6E
  Vendor: IBM
  Date of manufacture: July 1, 2001
SFP
  Status: Optimal
  Location: Out connection
  Supported data rate(s): 1 Gbps, 2 Gbps
  Link length: Intermediate
  Connector: LC
  Transmitter type: Shortwave Laser w/o OFC
  Transmission media: TM Multi-mode 50m(M5) TM Multi-mode 62.5m(M6)
  IEEE company ID: 08 00 5a
  Revision: AA10
  Part number: IBM42P21SNY
  Serial number: 21P7053000M57
  Vendor: IBM
  Date of manufacture: July 1, 2001
```

---

```
Drive Tray 0 Overall Component Information
  Drive technology: Fibre channel
  Part number: PN 348-0042807
  Serial number: SN 0146001584
  Vendor: VN LSILOGIC
  Date of manufacture: November 1, 2001
  Tray path redundancy: OK
  Fan canister: Optimal
  Fan canister: Optimal
  Power supply canister
    Status: Optimal
  Power supply canister
    Status: Optimal
  Temperature: Optimal
  Temperature: Optimal
  ESM card
    Status: Optimal
    Firmware version: 9163
    Maximum data rate: 1 Gbps
    Current data rate: 1 Gbps
    Location: A (left canister)
    Card communication: OK
    Product ID: SYM2500-FC
    Part number: PN 348-0043832
    Serial number: SN 1T22941398
    Vendor: LSILOGIC
    Date of manufacture: July 1, 2002
  GBIC
    Status: Optimal
    Location: In connection
    Type: Optical Shortwave
  ESM card
    Status: Optimal
    Firmware version: 9163
    Maximum data rate: 1 Gbps
    Current data rate: 1 Gbps
    Location: B (right canister)
    Card communication: OK
    Product ID: SYM2500-FC
    Part number: PN 348-0043832
    Serial number: SN 1T13945863
    Vendor: LSILOGIC
    Date of manufacture: October 1, 2001
  GBIC
    Status: Optimal
    Location: In connection
    Type: Optical Shortwave
```

```
MAPPINGS (SANshare STORAGE PARTITIONING - ENABLED (0 of 64 used))-----
Volume-To-LUN Mappings
  Access Volume, LUN 7, Default Group

Topology
  [Undefined Host Ports]
    10:00:00:a0:b8:04:29:3f
    21:00:00:e0:8b:01:34:c1
    21:01:00:e0:8b:22:80:38

  [Default Group]

NVSRAM Host Type Internal Definitions
Index 0
  Name: Windows NT Non-Clustered (SP5 or higher)
  AVT status: Disabled
Index 1
  Name: Windows 2000/Server 2003 Non-Clustered
  AVT status: Disabled
Index 2
  Name: Solaris
  AVT status: Disabled
Index 3
  Name: HP-UX
  AVT status: Enabled
Index 4
  Name: AIX
  AVT status: Disabled
Index 5
  Name: Irix
  AVT status: Disabled
Index 6 (DEFAULT)
  Name: Linux
  AVT status: Disabled
Index 7
  Name: Windows NT Clustered (SP5 or higher)
  AVT status: Disabled
Index 8
  Name: Windows 2000/Server 2003 Clustered
  AVT status: Disabled
Index 9
  Name: Netware Non-Failover
  AVT status: Enabled
Index 10
  Name: PTX
  AVT status: Enabled
Index 11
  Name: Netware Failover
  AVT status: Enabled
Index 12
  Name: Solaris (with Veritas DMP)
  AVT status: Enabled
```

## Show Controller NVSRAM

The `show controller NVSRAM` command returns a table of values in the controller NVSRAM that is similar to that shown in this example. With the information from the table, you can modify the contents of the NVSRAM by using the `set controller` command. This example shows information for a controller in slot A in a controller module. You can produce a similar table for a controller in slot B, or you can produce a table for both controllers.



```

Controller "a":
Region 232:
  0000: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 233:
  0000: 0000 7f8e 0000 1384 ff01 0000 0000 0000 ...?...?.....
  0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0020: 0000 0308 8e08 8108 0000 0000 0000 0408 ....?.?.....
  0030: 0220 0220 8920 8820 8d00 0900 0308 0000 ....?.?.?.....
  0040: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0050: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 234:
  0000: 1020 3040 5060 0000 0000 0000 0000 0000 ..0.P.....
  0010: 1121 3141 5161 0000 0000 0000 0000 0000 ..1AQa.....
  0020: 1222 3242 5262 0000 0000 0000 0000 0000 ..2BRb.....
  0030: 1323 3343 5363 0000 0000 0000 0000 0000 ..3CSc.....
  0040: 1424 3444 5464 0000 0000 0000 0000 0000 ..4DTd.....
  0050: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0060: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0070: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 236:
  0000: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0040: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0050: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0060: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0070: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 237:
  0000: 0000 0000 0000 0000 0000 0000 0000 0000 .....
  0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 238:
  0000: 0000 ca32 0000 0000 0050 0600 0000 0000 ..?2.....P.....
  0010: 0000 0000 0000 0000 0000 f001 0000 8480 .....??..
  0020: 0000 0000 0000 0000 0000 0c04 008a 0000 .....?.....
  0030: 0020 8741 1300 0000 0f00 1400 0000 0000 ..?A.....

```

```

Region 240:
0000: fb01 80fa 0101 0104 ffff ff00 0304 ac16 ..?.....?.
0010: 0401 ab04 ac16 04f9 ac04 ac16 04c8 0c08 ..?..?..?..
0020: 6175 7363 746c 7239 a013 616e 7461 7265 ausctlr9?.antare
0030: 732e 6b73 2e6c 7369 6c2e 636f 6da1 076a s.ks.lsil.com?.j
0040: 6761 7469 6361 a20b 6171 7561 3a6d 6172 gatica?.aqua.mar
0050: 696e 6511 012f b101 0ab0 0218 47ff 0000 ine...?..?..G...
0060: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0070: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0080: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0090: 0000 0000 0000 0000 0000 0000 0000 0000 .....
00a0: 0000 0000 0000 0000 0000 0000 0000 0000 .....
00b0: 0000 0000 0000 0000 0000 0000 0000 0000 .....
00c0: 0000 0000 0000 0000 0000 0000 0000 0000 .....
00d0: 0000 0000 0000 0000 0000 0000 0000 0000 .....
00e0: 0000 0000 0000 0000 0000 0000 0000 0000 .....
00f0: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 241:
0000: 0000 ca32 0000 0000 0050 0600 0000 0000 ..?2.....P.....
0010: 0000 0000 0000 0000 0000 f001 0000 8480 0000 .....
0020: 0000 0000 0000 0000 0000 0c04 008a 0000 0000 .....
0030: 0020 8741 1300 0000 0f00 1400 0000 0000 ..?A.....
0040: 4465 6661 756c 7400 0000 0000 0000 0000 Default.....
0050: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0060: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0070: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0080: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0090: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 574e 544e 434c 5350 3500 0000 0000 0000 WNTNCLSP5.....
0010: 0000 0000 0100 0000 0000 0000 0000 0000 .....
0020: 0100 0000 0000 0002 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 5732 4b4e 4554 4e43 4c00 0000 0000 0000 W2KNETNCL.....
0010: 0020 0000 0100 0000 0000 0000 0000 0000 .....
0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 534f 4c00 0000 0000 0000 0000 0000 0000 SOL.....
0010: 0120 0000 0100 0000 0001 0000 0000 0000 .....
0020: 0000 0000 0000 0002 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 4850 5800 0000 0000 0000 0000 0000 0000 HPX.....
0010: 0120 0000 0100 0000 0101 0001 0101 0001 .....
0020: 0000 0000 0100 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 4149 5800 0000 0000 0000 0000 0000 0000 AIX.....
0010: 0120 0000 0100 2000 0101 0000 0001 0000 .....
0020: 0000 0100 0000 0001 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 4952 5800 0000 0000 0000 0000 0000 0000 IRX.....
0010: 007f 0000 0100 2000 0000 0000 0000 0000 .....
0020: 0000 0100 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

```



```

Region 242:
0000: 4c4e 5800 0000 0000 0000 0000 0000 0000 LNX.....
0010: 0120 0000 0100 0000 0001 0000 0000 0000 .....
0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 574e 5443 4c53 5035 0000 0000 0000 0000 WNTCLSP5.....
0010: 0000 0000 0100 0000 0001 0001 0000 0000 .....
0020: 0100 0000 0000 0002 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 5732 4b4e 4554 434c 0000 0000 0000 0000 W2KNETCL.....
0010: 0020 0000 0100 0000 0001 0001 0000 0000 .....
0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 4e57 5200 0000 0000 0000 0000 0000 0000 NWR.....
0010: 007f 0000 0100 2000 0000 0000 0000 0000 .....
0020: 0100 0100 0100 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 5054 5800 0000 0000 0000 0000 0000 0000 PTX.....
0010: 0120 0000 0100 0000 0001 0000 0000 0000 .....
0020: 0100 0000 0100 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 4e57 5246 4f00 0000 0000 0000 0000 0000 NWRFD.....
0010: 007f 0000 0100 0000 0000 0000 0000 0000 .....
0020: 0100 0100 0100 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 534f 4c41 5654 0000 0000 0000 0000 0000 SOLAVT.....
0010: 0120 0000 0100 0000 0001 0100 0000 0000 .....
0020: 0000 0001 0180 0000 0000 0000 0000 0000 .....?.....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

Region 242:
0000: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0010: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0020: 0000 0000 0000 0000 0000 0000 0000 0000 .....
0030: 0000 0000 0000 0000 0000 0000 0000 0000 .....

```

## Show Volume

The `show volume` command returns information about the volumes in a storage array.

---

STANDARD VOLUMES-----

SUMMARY

Number of standard volumes: 5

See other Volumes sub-tabs for premium feature information.

NAME	STATUS	CAPACITY	RAID LEVEL	VOLUME GROUP	LUN
1	Optimal	5,120.000 GB	10	6	13
2	Optimal	1.000 GB	1	Volume-Group-2	14
3	Optimal	10.000 GB	1	Volume-Group-2	15
4	Optimal	3.000 GB	1	Volume-Group-2	16
Unnamed	Optimal	100.004 MB	0	Volume-Group-1	0

DETAILS

Volume name: 1

Volume status: Optimal

Capacity: 5,120.000 GB

Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12:00:00

Subsystem ID (SSID): 14

Associated volume group: 6

RAID level: 10

LUN: 13

Accessible By: Default Group

Media type: Hard Disk Drive

Interface type: Serial ATA (SATA)

Tray loss protection: Yes

Secure: No

Preferred owner: Controller in slot A

Current owner: Controller in slot A

Segment size: 128 KB

Capacity reserved for future segment size changes: Yes

Maximum future segment size: 2,048 KB

Modification priority: High

Read cache: Enabled

Write cache: Enabled

Write cache without batteries: Disabled

Write cache with mirroring: Enabled

Flush write cache after (in seconds): 10.00

Dynamic cache read prefetch: Enabled

Enable background media scan: Disabled

Media scan with redundancy check: Disabled

Pre-Read redundancy check: Disabled

Volume name: 2

Volume status: Optimal

Capacity: 1.000 GB

Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12:00:00

Subsystem ID (SSID): 15

Associated volume group: Volume-Group-2

RAID level: 1

LUN: 14

Accessible By: Default Group

Media type: Hard Disk Drive

Interface type: Fibre Channel

Tray loss protection: Yes

Secure: No

Preferred owner: Controller in slot B

Current owner: Controller in slot B

---

```
Segment size:                                128 KB
Capacity reserved for future segment size changes: Yes
Maximum future segment size:                2,048 KB
Modification priority:                      High
Read cache:                                Enabled
Write cache:                                Enabled
  Write cache without batteries:            Disabled
  Write cache with mirroring:              Enabled
Flush write cache after (in seconds):      10.00
Dynamic cache read prefetch:              Enabled
Enable background media scan:              Disabled
Media scan with redundancy check:          Disabled
Pre-Read redundancy check:                 Disabled
Volume name:                               3
Volume status:                             Optimal
Capacity:                                  10.000 GB
Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12:00:00
Subsystem ID (SSID):                       16
Associated volume group:                   Volume-Group-2
RAID level:                                1
LUN:                                        15
Accessible By:                             Default Group
Media type:                                Hard Disk Drive
Interface type:                            Fibre Channel
Tray loss protection:                      Yes
Secure:                                    No
Preferred owner:                           Controller in slot A
Current owner:                             Controller in slot A
Segment size:                                128 KB
Capacity reserved for future segment size changes: Yes
Maximum future segment size:                2,048 KB
Modification priority:                      High
Read cache:                                Enabled
Write cache:                                Enabled
  Write cache without batteries:            Disabled
  Write cache with mirroring:              Enabled
Flush write cache after (in seconds):      10.00
Dynamic cache read prefetch:              Enabled
Enable background mediascan:               Disabled
Media scan with redundancy check:          Disabled
Pre-Read redundancy check:                 Disabled
Volume name:                               4
Volume status:                             Optimal
Capacity:                                  3.000 GB
Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12:00:00
Subsystem ID (SSID):                       17
Associated volume group:                   Volume-Group-2
RAID level:                                1
LUN:                                        16
Accessible By:                             Default Group
Media type:                                Hard Disk Drive
Interface type:                            Fibre Channel
Tray loss protection:                      Yes
Secure:                                    No
```

---

```

Preferred owner:           Controller in slot B
Current owner:             Controller in slot B
Segment size:              128 KB
Capacity reserved for future segment size changes: Yes
Maximum future segment size: 2,048 KB
Modification priority:     High
Read cache:                Enabled
Write cache:               Enabled
    Write cache without batteries: Disabled
    Write cache with mirroring:   Enabled
Flush write cache after (in seconds): 10.00
Dynamic cache read prefetch: Enabled
Enable background media scan: Disabled
Media scan with redundancy check: Disabled
Pre-Read redundancy check: Disabled
Volume name:               Unamed
Volume status:             Optimal
Capacity:                  100.004 GB
Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12:00:00
Subsystem ID (SSID):       0
Associated volume group:    Volume-Group-1
RAID level:                 0
LUN:                        0
Accessible By:              Default Group
Media type:                 Hard Disk Drive
Interface type:             Serial ATA (SATA)
Tray loss protection:       No
Secure:                     No
Preferred owner:           Controller in slot B
Current owner:             Controller in slot B
Segment size:              16 KB
Capacity reserved for future segment size changes: Yes
Maximum future segment size: Not Appl
Modification priority:     Low
Read cache:                Enabled
Write cache:               Disabled
    Write cache without batteries: Disabled
    Write cache with mirroring:   Disabled
Flush write cache after (in seconds): 10.00
Dynamic cache read prefetch: Disabled
Enable background media scan: Enabled
Media scan with redundancy check: Enabled

```

#### SNAPSHOT REPOSITORY VOLUMES-----

##### SUMMARY

```

Number of snapshot repositories: 1
NAME      CAPACITY USAGE(%)  THRESHOLD WARNING  FULL POLICY
DAE1-1    0                    50% full           Fail snapshot

```

##### DETAILS

#### SNAPSHOT REPOSITORY VOLUME NAME: DAE1-1

```

Snapshot repository volume status: Optimal
Capacity usage (%):                 0
Notify when capacity reaches:       50% full
Snapshot repository full policy:     Fail snapshot volume

```

---

Associated base volume (standard): Unnamed  
Associated snapshot volume: DAE1  
Volume name: DAE1-1  
Volume status: Optimal  
Capacity: 20.000 MB  
Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12  
Subsystem ID (SSID): 11  
RAID level: 0  
Media type: Hard Disk Drive  
Interface type: Serial ATA (SATA)  
Tray loss protection: No  
Secure: No  
Preferred owner: Controller in slot B  
Current owner: Controller in slot B  
Segment size: 64 KB  
Capacity reserved for future segment size changes: No  
Maximum future segment size: Not ap  
Modification priority: High  
Read cache: Enabled  
Write cache: Enabled  
Write cache without batteries: Disabled  
Write cache with mirroring: Enabled  
Flush write cache after (in seconds): 10.00  
Dynamic cache read prefetch: Disabled  
Enable background media scan: Disabled  
Media scan with redundancy check: Disabled

MIRROR REPOSITORY VOLUMES-----

SUMMARY

Number of mirror repositories: 2

NAME	STATUS	CAPACITY	RAID LEVEL	VOLUME
Mirror Repository 2	Optimal	129.093 MB	10	6
Mirror Repository 1	Optimal	129.093 MB	10	6

DETAILS

MIRROR REPOSITORY VOLUME NAME: Mirror Repository 2

Mirror repository volume status: Optimal

Volume name: Mirror Repository 2  
Volume status: Optimal  
Capacity: 129.093 MB  
Volume world-wide identifier: 60:0a:0b:80:00:29:ed  
Subsystem ID (SSID): 12  
Associated volume group: 6  
RAID level: 10  
Media type: Hard Disk Drive  
Interface type: Serial ATA (SATA)  
Tray loss protection: Yes  
Secure: No  
Preferred owner: Controller in slot B  
Current owner: Controller in slot B  
Segment size: 32 KB  
Capacity reserved for future segment size changes: No  
Maximum future segment size: Not applicable  
Modification priority: High

MIRROR REPOSITORY VOLUME NAME: Mirror Repository 1

---

Mirror repository volume status: Optimal  
Volume name: Mirror Repository 1  
Volume status: Optimal  
Capacity: 129.093 MB  
Volume world-wide identifier: 60:0a:0b:80:00:29:ed  
Subsystem ID (SSID): 13  
Associated volume group: 6  
RAID level: 10  
Media type: Hard Disk Drive  
Interface type: Serial ATA (SATA)  
Tray loss protection: Yes  
Secure: No  
Preferred owner: Controller in slot A  
Current owner: Controller in slot A  
Segment size: 32 KB  
Capacity reserved for future segment size changes: No  
Maximum future segment size: Not applicable  
Modification priority: High

SNAPSHOT VOLUMES-----

SUMMARY

Number of snapshot volumes: 1

NAME	STATUS	CREATION	TIMESTAMP
DAE1	Optimal	9/24/10	8:54 AM

DETAILS

SNAPSHOT VOLUME NAME: DAE1

Snapshot status: Optimal  
Creation timestamp: 9/24/10 8:54 AM  
Associated base volume (standard): Unnamed  
Associated snapshot repository volume: DAE1-1  
Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12:00  
Capacity: 100.004 MB  
Preferred owner: Controller in slot B  
Current owner: Controller in slot B

COPIES-----

SUMMARY

Number of copies: 10

S = Source volume

T = Target volume

COPY PAIR	STATUS	COMPLETION	TIMESTAMP
5 (S), 10 (T)	Completed	10/14/10	3:16:27 PM
5 (S), 8 (T)	Completed	10/18/10	9:46:45 AM
10 (S), 9 (T)	Stopped	None	
(S), 7 (T)	Completed	10/14/10	3:13:37 PM
5 (S), 4 (T)	Completed	10/14/10	3:18:23 PM
1 (S), 3 (T)	Completed	10/14/10	3:22:56 PM
Unnamed (S), 5 (T)	Completed	9/16/10	2:30:06 PM
Unnamed (S), 11 (T)	Stopped	None	
Unnamed (S), 6 (T)	Completed	9/2/10	10:03:56 AM
Unnamed (S), 1 (T)	Completed	9/16/10	12:41:14 PM

DETAILS

Copy pair: Unnamed and 4

Copy status: Copy pair: Unnamed and 4



---

```
Copy status: Completed
Start timestamp: 9/16/10 2:29:23 PM
Completion timestamp: 9/16/10 2:30:06 PM
Copy priority: Lowest
Source volume: Unnamed
  Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12
Target volume: 5
  Volume world-wide identifier: 60:0a:0b:80:00:47:5b:8a
Read-only: Disabled
Copy pair: Unnamed and 3
Copy status: Stopped
Start timestamp: None
Completion timestamp: None
Copy priority: Lowest
Source volume: Unnamed
  Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12
Target volume: 11
  Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12
Read-only: Enabled
Copy pair: Unnamed and 2
Copy status: Completed
Start timestamp: 9/2/10 10:03:41 AM
Completion timestamp: 9/2/10 10:03:56 AM
Copy priority: Medium
Source volume: Unnamed
  Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12
Target volume: 6
  Volume world-wide identifier: 60:0a:0b:80:00:29:ed:12
Read-only: Enabled
Copy pair: Unnamed and 1
Copy status: Completed
Start timestamp: 9/16/10 12:40:58 PM
Completion timestamp: 9/16/10 12:41:14 PM
Copy priority: Medium
Source volume: Unnamed
  Volume world-wide identifier: 60:0a:0b:80:00:29:ed:1
Target volume: 1
  Volume world-wide identifier: 60:0a:0b:80:00:47:5b:8
Read-only: Enabled
```

MIRRORED PAIRS-----

Number of mirrored pairs: 0 of 64 used

MISSING VOLUMES-----

Number of missing volumes: 0

## Show Drive Channel Stat

The `show drive channel stat` command returns information about the drive channels in a storage array. Use this information to determine how well the channels are running and errors that might be occurring on the channels.

---

DRIVE CHANNELS-----

SUMMARY

CHANNEL	PORT	STATUS
1	8,7,ESM A 1A,ESM A 1B,ESM A 1A,ESM A 1B,ESM A 1B	Optimal
2	6,5	Optimal
3	4,3	Optimal
4	2,1	Optimal
5	1,2,ESM B 1B,ESM B 1A,ESM B 1B,ESM B 1A,ESM B 1B	Optimal
6	3,4	Optimal
7	5,6	Optimal
8	7,8	Optimal

DETAILS

DRIVE CHANNEL 1

Port: 8, 7, ESM A 1A, ESM A 1B, ESM A 1A, ESM A 1B, ESM A 1B  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 4 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

Total # of attached drives: 44  
Connected to: Controller A, Port 8  
Attached drives: 44  
Drive tray: 3 (14 drives)  
Drive tray: 1 (15 drives)  
Drive tray: 2 (15 drives)

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set: 10/30/10 1:15:59 PM  
Sample period (days, hh:mm:ss): 32 days, 00:55:04  
Controller detected errors: 0  
Drive detected errors: 48  
Timeout errors: 1  
Link down errors: N/A  
Total I/O count: 199070838

Controller B

Baseline time set: 10/30/10 1:15:59 PM  
Sample period (days, hh:mm:ss): 32 days, 00:53:22  
Controller detected errors: 0  
Drive detected errors: 52  
Timeout errors: 0  
Link down errors: N/A  
Total I/O count: 198778804

---

DRIVE CHANNEL 2

Port: 6, 5  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 4 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

Total # of attached drives: 0

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:55:04
Controller detected errors:	0
Drive detected errors:	0
Timeout errors:	2
Link down errors:	N/A
Total I/O count:	14238433

Controller B

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:53:22
Controller detected errors:	0
Drive detected errors:	0
Timeout errors:	0
Link down errors:	N/A
Total I/O count:	13470436

DRIVE CHANNEL 3

Port: 6, 5  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 4 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

Total # of attached drives: 0

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:55:04
Controller detected errors:	0
Drive detected errors:	0

---

Timeout errors:	0
Link down errors:	N/A
Total I/O count:	13414513

Controller B

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:53:22
Controller detected errors:	0
Drive detected errors:	0
Timeout errors:	0
Link down errors:	N/A
Total I/O count:	13201515

DRIVE CHANNEL 4

Port: 2, 1  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 2 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

Total # of attached drives: 0

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:55:04
Controller detected errors:	111
Drive detected errors:	0
Timeout errors:	0
Link down errors:	N/A
Total I/O count:	13093814

Controller B

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:53:22
Controller detected errors:	54
Drive detected errors:	0
Timeout errors:	0
Link down errors:	N/A
Total I/O count:	13039285

DRIVE CHANNEL 5

Port: 1, 2, ESM B 1B, ESM B 1A, ESM B 1B, ESM B 1A, ESM B 1B  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 4 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up

---

Trunking active: No

DRIVE COUNTS

Total # of attached drives: 44  
Connected to: Controller B, Port 1  
Attached drives: 44  
Drive tray: 3 (14 drives)  
Drive tray: 1 (15 drives)  
Drive tray: 2 (15 drives)

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:55:04
Controller detected errors:	0
Drive detected errors:	49
Timeout errors:	1
Link down errors:	N/A
Total I/O count:	183366503

Controller B

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:53:22
Controller detected errors:	1
Drive detected errors:	52
Timeout errors:	0
Link down errors:	N/A
Total I/O count:	182512319

DRIVE CHANNEL 6

Port: 3, 4  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 2 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

Total # of attached drives: 0

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:55:04
Controller detected errors:	0
Drive detected errors:	0
Timeout errors:	0
Link down errors:	0
Total I/O count:	13296480

---

Controller B

Baseline time set: 10/30/10 1:15:59 PM  
Sample period (days, hh:mm:ss): 32 days, 00:53:22  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: N/A  
Total I/O count: 13275865

DRIVE CHANNEL 7

Port: 5, 6  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 2 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

Total # of attached drives: 0

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set: 10/30/10 1:15:59 PM  
Sample period (days, hh:mm:ss): 32 days, 00:55:04  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: 0  
Total I/O count: 131818784

Controller B

Baseline time set: 10/30/10 1:15:59 PM  
Sample period (days, hh:mm:ss): 32 days, 00:53:22  
Controller detected errors: 0  
Drive detected errors: 0  
Timeout errors: 0  
Link down errors: N/A  
Total I/O count: 13171844

DRIVE CHANNEL 8

Port: 7, 8  
Status: Optimal  
Max. Rate: 4 Gbps  
Current Rate: 4 Gbps  
Rate Control: Auto  
Controller A link status: Up  
Controller B link status: Up  
Trunking active: No

DRIVE COUNTS

---

Total # of attached drives: 0

CUMULATIVE ERROR COUNTS

Controller A

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:55:04
Controller detected errors:	44
Drive detected errors:	0
Timeout errors:	0
Link down errors:	0
Total I/O count:	13067464

Controller B

Baseline time set:	10/30/10 1:15:59 PM
Sample period (days, hh:mm:ss):	32 days, 00:53:22
Controller detected errors:	25
Drive detected errors:	0
Timeout errors:	0
Link down errors:	N/A
Total I/O count:	12987004

## Show Drive

The `show drive` command returns information about the drives in a storage array.

```
DRIVES-----
SUMMARY
  Number of drives: 14
  Supported drive types: Fibre (14)

BASIC:

TRAY, SLOT  STATUS  CAPACITY  CURRENT DATA RATE  PRODUCT ID  FIRMWARE VERSION
1, 1        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 2        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 3        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 4        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 5        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 6        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 7        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 8        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 9        Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 10       Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 11       Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 12       Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 13       Optimal  68.366 GB  2 Gbps              ST373453FC  MS03
1, 14       Optimal  68.366 GB  2 Gbps              ST373453FC  MS03

DRIVE CHANNELS:

TRAY, SLOT  PREFERRED CHANNEL  REDUNDANT CHANNEL
1, 1        3                Drive path redundancy: Lost
1, 2        3                Drive path redundancy: Lost
1, 3        3                Drive path redundancy: Lost
1, 4        3                Drive path redundancy: Lost
1, 5        3                Drive path redundancy: Lost
1, 6        3                Drive path redundancy: Lost
1, 7        3                Drive path redundancy: Lost
1, 8        3                Drive path redundancy: Lost
1, 9        3                Drive path redundancy: Lost
1, 10       3                Drive path redundancy: Lost
1, 11       3                Drive path redundancy: Lost
1, 12       3                Drive path redundancy: Lost
1, 13       3                Drive path redundancy: Lost
1, 14       3                Drive path redundancy: Lost

HOT SPARE COVERAGE:
  The following volume groups are not protected: 3

  Total hot spare drives: 2
    Standby: 2
    In use: 0

  Standby drive at tray 1, slot 8 (Fibre, 68.366 GB)
    Protects the following volume groups: 2, 1
```



---

DETAILS

Drive at Tray 1, Slot 1  
Drive port: 1, Channel: 3, ID: 8/0xD9  
Drive path redundancy: Lost  
Status: Optimal  
Raw capacity: 68.366 GB  
Usable capacity: 67.866 GB  
Current data rate: 2 Gbps  
Product ID: ST373453FC  
Firmware version: MS03  
Serial number: 3HW0535L00007329LFD8  
Vendor: SEAGATE  
Date of manufacture: January 20, 2003  
World-wide name: 20:00:00:04:cf:0b:c6:0d  
Drive type: Fibre Channel  
Speed: 15015 RPM  
Mode: Assigned  
Associated volume group: volume group 2

Drive at Tray 1, Slot 2  
Drive port: 1, Channel: 3, ID: 9/0xD6  
Drive path redundancy: Lost  
Status: Optimal  
Raw capacity: 68.366 GB  
Usable capacity: 67.866 GB  
Current data rate: 2 Gbps  
Product ID: ST373453FC  
Firmware version: MS03  
Serial number: 3HW056D500007329VVAP  
Vendor: SEAGATE  
Date of manufacture: January 23, 2003  
World-wide name: 20:00:00:04:cf:0b:dc:29  
Drive type: Fibre Channel  
Speed: 15015 RPM  
Mode: Assigned  
Associated volume group: volume group 2

Drive at Tray 1, Slot 3  
Drive port: 1, Channel: 3, ID: 10/0xD5  
Drive path redundancy: Lost  
Status: Optimal  
Raw capacity: 68.366 GB  
Usable capacity: 67.866 GB  
Current data rate: 2 Gbps  
Product ID: ST373453FC  
Firmware version: MS03  
Serial number: 3HW04LMK000073290YZK  
Vendor: SEAGATE  
Date of manufacture: January 17, 2003  
World-wide name: 20:00:00:04:cf:0b:b1:f6  
Drive type: Fibre Channel  
Speed: 15015 RPM  
Mode: Unassigned  
Associated volume group: volume group None

---

```
Drive at Tray 1, Slot 4
  Drive port: 1, Channel: 3, ID: 11/0xD4
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04N2T00007329DZGZ
  Vendor: SEAGATE
  Date of manufacture: January 17, 2003
  World-wide name: 20:00:00:04:cf:0b:b1:81
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 3

Drive at Tray 1, Slot 5
  Drive port: 1, Channel: 3, ID: 12/0xD3
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04YN500007329JQYG
  Vendor: SEAGATE
  Date of manufacture: January 23, 2003
  World-wide name: 20:00:00:04:cf:0b:db:2c
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Unassigned
  Associated volume group: Volume group None

Drive at Tray 1, Slot 6
  Drive port: 1, Channel: 3, ID: 13/0xD2
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW056N300007328ZC57
  Vendor: SEAGATE
  Date of manufacture: January 23, 2003
  World-wide name: 20:00:00:04:cf:0b:db:66
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 2
```

---

```
Drive at Tray 1, Slot 7
  Drive port: 1, Channel: 3, ID: 14/0xD1
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04XKQ00007329VUR8
  Vendor: SEAGATE
  Date of manufacture: January 23, 2003
  World-wide name: 20:00:00:04:cf:0b:db:a1
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: volume group 2

Drive at Tray 1, Slot 8
  Drive port: 1, Channel: 3, ID: 15/0xCE
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04QL300007328H6BU
  Vendor: SEAGATE
  Date of manufacture: January 23, 2003
  World-wide name: 20:00:00:04:cf:0b:db:6f
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Hot spare standby
  Associated volume group: volume group None

Drive at Tray 1, Slot 9
  Drive port: 1, Channel: 3, ID: 81/0x54
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04WSE00007329EQX2
  Vendor: SEAGATE
  Date of manufacture: January 18, 2003
  World-wide name: 20:00:00:04:cf:0b:b2:5b
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Unassigned
  Associated volume group: volume group None
```

---

---

```
Drive at Tray 1, Slot 10
  Drive port: 1, Channel: 3, ID: 97/0x39
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04VSP00007329DZPH
  Vendor: SEAGATE
  Date of manufacture: January 17, 2003
  World-wide name: 20:00:00:04:cf:0b:b1:97
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: volume group 2

Drive at Tray 1, Slot 11
  Drive port: 1, Channel: 3, ID: 65/0x71
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW056N700007329T7EG
  Vendor: SEAGATE
  Date of manufacture: January 23, 2003
  World-wide name: 20:00:00:04:cf:0b:db:69
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: volume group 2

Drive at Tray 1, Slot 12
  Drive port: 1, Channel: 3, ID: 73/0x66
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04DL400007329ERF1
  Vendor: SEAGATE
  Date of manufacture: January 17, 2003
  World-wide name: 20:00:00:04:cf:0b:b1:84
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: volume group 1
```

---

```
Drive at Tray 1, Slot 13
  Drive port: 1, Channel: 3, ID: 89/0x4A
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04DJT00007329DZJF
  Vendor: SEAGATE
  Date of manufacture: January 18, 2003
  World-wide name: 20:00:00:04:cf:0b:b0:ff
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1

Drive at Tray 1, Slot 14
  Drive port: 1, Channel: 3, ID: 105/0x2D
  Drive path redundancy: Lost
  Status: Optimal
  Raw capacity: 68.366 GB
  Usable capacity: 67.866 GB
  Current data rate: 2 Gbps
  Product ID: ST373453FC
  Firmware version: MS03
  Serial number: 3HW04VAK00007329ER3P
  Vendor: SEAGATE
  Date of manufacture: January 17, 2003
  World-wide name: 20:00:00:04:cf:0b:b1:6e
  Drive type: Fibre Channel
  Speed: 15015 RPM
  Mode: Assigned
  Associated volume group: Volume group 1
```

---

## Appendix B: Example Script Files

This appendix provides example scripts for configuring a storage array. These examples show how the script commands appear in a complete script file. Also, you can copy these scripts and modify them to create a configuration unique to your storage array.

You can create a script file in two ways:

- Using the `save storageArray configuration` command
- Writing a script

By using the `save storageArray configuration` command, you can create a file that you can use to copy an existing configuration from one storage array to other storage arrays. You can also use this file to restore an existing configuration that has become corrupted. You also can copy an existing file to serve as a pattern from which you create a new script file by modifying portions of the original file. The default file extension is `.scr`.

You can create a new script file by using a text editor, such as Microsoft Notepad. The maximum line length is 256 characters. The command syntax must conform to the guidelines in Chapter 1, ["About the Command Line Interface"](#) and in Chapter 2, ["About the Script Commands"](#). When you create a new script file, you can use any file name and extension that will run on the host operating system.

This example shows how to run a script file from the command line.

```
c:\...\smX\client>smcli 123.45.67.88 123.45.67.89  
-f scriptfile.scr;
```

### Configuration Script Example 1

This example creates a new volume by using the `create volume` command in the free space of a pool.

```
Show "Create RAID 5 Volume 7 on existing Pool 1";  
//Create volume on pool created by the create  
volume drives command  
//Note: For pools that use all available  
capacity, the last volume on the group is created using  
all remaining capacity by omitting the capacity=volume  
creation parameter  
create volume pool=1 RAIDLevel=5 userLabel="7"  
owner=A segmentSize=16 cacheReadPrefetch=TRUE capacity=2GB;  
show "Setting additional attributes for volume 7";  
//Configuration settings that cannot be set during volume  
creation  
set volume["7"] cacheFlushModifier=10;  
set volume["7"] cacheWithoutBatteryEnabled=false;  
set volume["7"] mirrorEnabled=true;  
set volume["7"] readCacheEnabled=true;  
set volume["7"] writeCacheEnabled=true;  
set volume["7"] mediaScanEnabled=false;  
set volume["7"] redundancyCheckEnabled=false;  
set volume["7"] modificationPriority=high;
```



This example shows blank lines between the lines beginning with `Show`, `Create`, `//Note`, and `create`. The blank lines are included in this example only for clarity. Each command is actually written on one line in the script file; however, the size of this page has caused the command text to wrap. You might want to include blank lines in your script files to separate blocks of commands or make a comment that stands out. To include a comment, enter two forward slashes (`//`), which causes the Script Engine to treat the line as a comment.

The first line of text is the `show string` command. This command shows text that is bounded by double quotation marks (`" "`) on a display monitor when the script file runs. In this example, the text `Create RAID 5 Volume 7 on existing Pool 1` serves as a title that describes the expected results of running this script file.

The line beginning with `//Create` is a comment that explains that the purpose of this script file is to create a new volume by using the `create volume` command on an existing pool.

The line beginning with `//Note:` is a comment in the script file that explains that the size of the last volume created that uses all of the available capacity because the `capacity` parameter is not used.

The command in this example creates a new volume in pool 1. The volume has RAID Level 5. The volume name (user label) is 7. (Note the double quotation marks around the 7. The double quotation marks define that the information in the double quotation marks is a label.) The new volume is assigned to the controller in slot A in the controller module. The segment size is set to 16. The volume has a read ahead multiplier value of 256. The capacity of the volume is 2 GB.

The command takes this form:

```
create volume pool=poolNumber
userLabel=volumeName
[freeCapacityArea=freeCapacityIndexNumber]
[capacity=volumeCapacity | owner=(a | b) |
cacheReadPrefetch=(TRUE | FALSE) |
segmentSize=segmentSizeValue]
[moduleLossProtect=(TRUE | FALSE)]
```

The general form of the command shows the optional parameters in a different sequence than the optional parameters in the example command. You can enter optional parameters in any sequence. You must enter the required parameters in the sequence shown in the command descriptions.

The line showing "Setting additional attributes for volume 7" is another example of using the `show "string"` command. The reason for placing this command here is to tell the user that the `create volume` command ran successfully and that properties that could not be set by the `create volume` command are now set.

The `set volume` parameters are shown on separate lines. You do not need to use separate lines for each parameter. You can enter more than one parameter with the `set volume` command by leaving a space between the parameters, as in this example:

```
set volume["7"] cacheFlushModifier=10
cacheWithoutBatteryEnabled=false
modificationPriority=high;
```

By using separate lines, you can see more clearly the parameters that you are setting and the values to which you are setting the parameters. Blocking the parameters in this manner makes it easier to either edit the file or copy specific parameter settings for use in another script file.

---

## Configuration Script Example 2

This example creates a new volume by using the `create volume` command with user-defined drives in the storage array.

```
Show "Create RAID3 Volume 2 on existing Pool 2";
//This command creates the pool and the initial volume on that group.
//Note: For pools that use all available capacity, the last volume
on the pool is created using all remaining capacity by omitting the
capacity=volume creation parameter
create volume RAIDLevel=3 userLabel="2" drives=[0,1 0,6 1,7 1,3 2,3 2,6]
owner=B segmentSize=16 capacity=2GB;
show "Setting additional attributes for volum 7"
//Configuration settings that cannot be set during volume creation
set volume ["7"] cacheFlushModifier=10;
set volume ["7"] cacheWithoutBatteryEnabled=false;
set volume ["7"] mirrorEnabled=true;
set volume ["7"] readCacheEnabled=true;
set volume ["7"] writeCacheEnabled=true;
set volume ["7"] mediaScanEnabled=false;
set volume ["7"] redundantCheckEnabled=false;
set volume ["7"] modificationPriority=high;
```

The command in this example, like the `create volume` command in the previous example, creates a new volume. The significant difference between these two examples is that this example shows how you can define specific drives to include in the volume. Use the `show storageArray profile` command to find out what drives are available in a storage array.

The `create volume` command takes this form:

```
create volume raidLevel=(0 | 1 | 3 | 5 | 6) userLabel=volumeName
drives=(moduleID1,slotID1...moduleIDn,slotIDn)
[capacity=volumeCapacity | owner=(a | b) |
cacheReadPrefetch=(TRUE | FALSE) |
segmentSize=segmentSizeValue]
[moduleLossProtect=(TRUE | FALSE)]
```



---

## Appendix C: Asynchronous Data Replicator Software Utility

This appendix describes the host utility to achieve periodic consistency with Asynchronous Data Replicator Software configurations. This appendix also describes how to run the Asynchronous Data Replicator Software utility.

### Description of the Asynchronous Data Replicator Software Utility

The Asynchronous Data Replicator Software utility lets you periodically synchronize the Data Replicator Software pairs in your storage array. When defining a Data Replicator Software configuration, you have the option to set the write modes to either Synchronous or Asynchronous. Synchronous write mode provides the highest level security for full data recovery from the secondary storage array in the event of a disaster. Synchronous write mode does, however, reduce host I/O performance. Asynchronous write mode offers faster host I/O performance, but it does not guarantee that a copy operation has successfully completed before processing the next write request. With Asynchronous write mode, you cannot make sure that a volume, or collection of volumes, at a secondary site ever reach a consistent, recoverable state.

The Asynchronous Data Replicator Software utility enables you to bring a collection of asynchronous remote volumes into a mutually consistent and recoverable state. You can choose to run the utility based on application demands, link state and speed, and other factors that are relevant to your environment.

The Asynchronous Data Replicator Software utility has these characteristics:

- The utility is implemented as a command line-invoked Java-based application.
- The utility is bundled as part of the SANtricity ES Storage Manager installation package.
- The utility accepts a command line argument that lets you specify the name of a configuration file that contains a complete specification of the work to be carried out by the utility.
- More than one instance of the utility can run concurrently, as long as the utilities do not try to process any of the same volumes and mirrors.

---

**NOTE** The Asynchronous Data Replicator Software utility does not check to make sure that concurrently running instances of the utility are not trying to process the same volumes and mirrors. If you choose to simultaneously run more than one instance of the Asynchronous Data Replicator Software utility, you must make sure that the configuration files that you choose to run do not list the same volumes and mirrors.

---

### Operation of the Asynchronous Data Replicator Software Utility

The Asynchronous Data Replicator Software utility performs steps that generate a recoverable state for multiple mirror volumes at a secondary site. The utility runs these steps to create consistent, recoverable images of a set of volumes:

1. **On the primary storage array** – The utility reconfigures all of the participating volumes from asynchronous mirroring to synchronous mirroring. This action makes sure that the stream of write operations becomes recoverable on the secondary side.
2. **On the primary storage array** – The utility polls all of the participating volumes until the associated mirror states all have the Optimal state. In cases where the remote link is slow or the primary host I/O activity is high, one or more mirrors are likely to be in the Unsynchronized state before they transition to the Synchronized state. By waiting until all of the mirrors have Optimal status, the utility makes sure that all of the delta logs for the affected volumes are cleared, and the secondary volumes are recoverable.

3. **On the primary storage array** – The utility suspends the mirrored pairs for all of the participating volumes. This action causes updates to stop on the secondary side, leaving the secondary volumes in a recoverable state because they were being updated in Synchronous mode immediately before the suspension. By separating the mirrors in this manner, the primary-side applications run faster, while leaving the secondary volumes in a recoverable state. The delta log tracks changes made because of application writes on the primary side while in this state.
4. **On the secondary storage array** – The utility generates a snapshot of each participating volume on the secondary side, which creates point-in-time images that are recoverable.
5. **On the primary storage array** – The utility resumes the mirroring operations for all of the participating volumes. This action causes the mirrors to transition to the Synchronized state and start the process of restoring coherency between the primary site and the secondary site.
6. **On the primary storage array** – The utility reconfigures all of the affected volumes for Asynchronous mode.

## Running the Asynchronous Data Replicator Software Utility

The Asynchronous Data Replicator Software utility uses a command line argument that lets you specify the name of a configuration file. The configuration file contains a complete specification of the input parameters that are needed by the utility. To run the utility, enter this syntax:

```
asyncRVMUtil configuration_file -d debug_file
```

In this command, *configuration\_file* is the file that you provide as input. The configuration file specifies the Data Replicator Software volumes that you want to synchronize by using the utility. When you create the configuration file, use these conditions to define the volumes in the file:

- All the primary volumes in a volume set must belong to the same storage array.
- The maximum number of volume sets that you can specify in the file is four.
- The maximum number of mirrored pairs that you can specify as part of a consistency group is eight.

The optional parameter, *-d*, lets you specify a file to which you can send information regarding how the utility runs. In this example, the file name is *debug\_file*. The debug file contains trace information that can be reviewed by your Sun Customer Care Center representative to determine how well the Asynchronous Data Replicator Software utility has run.

---

**NOTE** Depending on the location of the configuration file and the debug file, you must specify the complete path with the file name.

---

To run the Asynchronous Data Replicator Software utility, you must enter the `asyncRVMUtil` command from the command line. Because UNIX operating systems are case sensitive, you must type the command exactly as shown. On Windows operating systems, you can type the command in all uppercase, in all lowercase, or in mixed case.

---

**NOTE** To use the Asynchronous Data Replicator Software utility, you must be managing the storage array by using the command line interface, not the graphical user interface of SANtricity ES Storage Manager.

---

---

## Configuration Utility

The configuration file is an ASCII flat text file that provides the information for the Data Replicator Software synchronization used by the Asynchronous Data Replicator Software utility. The file defines the mirror volume sets to be synchronized. All of the mirror volumes in the volume sets defined in the configuration file are run collectively to create a recoverable image. If any one of the mirrors in the volume set fails, the operation is stopped for this volume set and carried on to the next volume set that is listed in the configuration file.

The configuration file supports this syntax:

```
content ::= {spec}
spec ::= logSpec | volumeSetSpec
logSpec ::= "Log" "{" {logAttribute} "}"
logAttribute ::= fileSpec
fileSpec ::= "file" "=" fileName
volumeSetSpec ::= "VolumeSet" volumeSetName
               "{" {volumeSetAttribute} "}"
volumeSetAttribute ::= timeoutSpec | mirrorSpec
timeoutSpec ::= "OptimalWaitTimeLimit" "=" integer
mirrorSpec ::= "Mirror" "{" {mirrorAttribute} "}"
mirrorAttribute ::= primarySpec | secondarySpec |
                  snapshotSpec
primarySpec ::= "Primary" "=" volumeSpec
secondarySpec ::= "Secondary" "=" volumeSpec
snapshotSpec ::= "Copy" "=" volumeSpec
volumeSpec ::= storageArrayName "." volumeUserLabel
```

In this syntax, items enclosed in double quotation marks (" ") are terminal symbols. Items separated by a vertical bar (|) are alternative values (enter one or the other, but not both). Items enclosed in curly braces ({ }) are optional (you can use the item zero or more times).

These definitions are provided for non-terminals in the syntax:

- *integer* – The timeout value must be an integer (decimal digits from 0–9).
- *volumeSetName* – The name of the set of volumes on which you want to run the Asynchronous Data Replicator Software utility.
- *fileName* – The name of a file, using characters and conventions that are appropriate for the system on which the application is running.
- *storageArrayName* – The label that you have assigned for a storage array, as would be used in the CLI to specify the name of the storage array.
- *volumeUserLabel* – The label that you have assigned for a volume that uniquely identifies the volume within the storage array.

---

**NOTE** Names and labels can be any characters that are defined as appropriate for your operating system. The maximum length for a name or label is 30 characters. If the name or label contains special characters (as defined by the operating system) or period characters, you must enclose the name or label in double quotation marks (" "). You can, optionally, enclose the name or label in double quotation marks at any time.

---

These items are considered syntax errors:

- More than one *logSpec* command in the input file
- Zero or more than one *fileSpec* attribute in a *logSpec* command (you must include exactly one *fileSpec* attribute in the *logSpec* command)
- More than one *timeoutSpec* attribute in a *volumeSetSpec* command

- Zero or more than one `primarySpec` attribute in a `mirrorSpec` command (you must include exactly one `primarySpec` attribute in the `mirrorSpec` command)
- Zero or more than one `secondarySpec` attribute in a `mirrorSpec` command (you must include exactly one `secondarySpec` attribute in the `mirrorSpec` command)
- Zero or more than one `snapshotSpec` attribute in a `mirrorSpec` command (you must include exactly one `snapshotSpec` attribute in the `mirrorSpec` command)

**NOTE** In the Asynchronous Data Replicator Software utility configuration file, you must specify the primary volume, the secondary volume, and the copy (snapshot) volume. The utility does not make sure that the secondary volume is correct for the Data Replicator Software relationship. The utility also does not make sure that the snapshot volume is actually a snapshot for the secondary volume. *You must make sure that these volumes are correct.* If the volumes are not correct, the utility will run, but the volumes will not be consistent. For each mirror, the secondary volume and the copy volume must reside on the same storage array.

This example shows a configuration file for the Asynchronous Data Replicator Software utility.

```
Log{ file="d:\rvm-consistency.log" }
VolumeSet "set1" {
    optimalWaitTimeLimit = 15
    Mirror {
        Primary = LosAngelesArray.PayrollVolume
        Secondary = NewYorkArray.PayrollVolume
        Copy = NewYorkArray.PayrollVolumeImage
    }
    Mirror {
        Primary = LosAngelesArray.PayrollVolume
        Secondary = BostonArray.PayrollVolume
        Copy = BostonArray.PayrollVolumeImage
    }
}

VolumeSet "set2" {
    Mirror {
        Primary = BostonArray.HRVolume
        Secondary = LosAngelesArray.HRVolume
        Copy = LosAngelesArray.HRVolumeImage
    }
}
```

---

## Appendix D: Simplex-to-Duplex Conversion

Some models of controller modules and array modules are available in either a simplex configuration (one controller) or a duplex configuration (two controllers). You can convert a simplex configuration to a duplex configuration by installing new nonvolatile static random access memory (NVSRAM) and a second controller. This appendix explains how to convert a simplex configuration to a duplex configuration by using CLI commands or by using the storage management software.

### General Steps

You can upgrade a controller module or an array module that has a simplex configuration to a duplex configuration by performing these tasks:

1. Install new NVSRAM on the existing controller in your controller module or array module.
2. Revise the controller module configuration or the array module configuration to run with two controllers.
3. Install a second controller.
4. Connect the host cables.
5. Connect the drive module cables.
6. Run diagnostics to make sure that your new configuration is running correctly.

### Tools and Equipment

The procedures in this appendix require these items:

- Antistatic protection
- A No. 2 Phillips screwdriver
- A second controller
- Small Form-factor Pluggable (SFP) transceivers (for Fibre Channel configurations)
- Host-to-controller cables
- Controller-to-environmental services monitor (ESM) cables

### Step 1 – Installing the Duplex NVSRAM

---

**NOTE** Before trying to download NVSRAM, you must contact your Sun Customer Care Center representative to make sure that you are downloading the NVSRAM that is appropriate for the controller in your storage array.

---

NVSRAM files specify the default settings for the controller module controllers or array module controllers. Follow the instructions in this step to upgrade the NVSRAM on the controller in your controller module or your array module.

To get a copy of the latest NVSRAM, perform one of these tasks:

- Download the duplex NVSRAM by using the command line interface.
- Download the duplex NVSRAM by using the graphical user interface (GUI) of the storage management software.
- Copy the duplex NVSRAM from the installation CD in the conversion kit.

Make sure that the controller module or the array module has an Optimal status. If one or more managed devices has a Needs Attention status, determine and correct the condition that created the Needs Attention status before proceeding with this conversion instruction.

## Downloading the NVSRAM by Using the Command Line Interface

1. Make a copy of your storage array profile, and save it in the event that you might need to restore the storage array.
2. Start the command line interface.
3. On the command line, type this command, and press **Enter**. In this command, *ctlr-A\_IP\_address* is the IP address of the original simplex controller and *filename* is the complete file path and name of the file that contains the new NVSRAM. Valid file names must end with a .dlp extension. Enclose the file name in double quotation marks (" ").

```
smcli ctlr-A_IP_address -c "download storageArray NVSRAM file="filename";"
```

## Downloading the NVSRAM by Using the GUI

1. Make a copy of your storage array profile, and save it in the event that you might need to restore the storage array.
2. At the storage management station, start the SMclient software.
3. In the Array Management Window, select **Advanced >> Maintenance >> Download >> Controller NVSRAM**.
4. In the Download NVSRAM dialog, enter the NVSRAM file name in the **Selected NVSRAM** text box. If you do not know the file name, click **Browse**, and navigate to a folder with the NVSRAM files.
5. Select the file that corresponds to your storage array type.
6. Click **OK**.  
The **Confirm Download** dialog appears.
7. To start the download, click **Yes**.
8. Based on the dialog that appears after the download has completed, perform one of these actions:
  - **Download Successful dialog** – Click **Done**.
  - **Error dialog** – Read the information in the dialog, and take the appropriate action.

## Copying NVSRAM from the Installation CD

1. Make a copy of your storage array profile, and save it in the event that you might need to restore the storage array.
2. Insert the Installation CD into the CD-ROM drive.
3. At the storage management station, start the SMclient software.
4. In the Array Management Window, select **Advanced >> Maintenance >> Download >> Controller NVSRAM**.
5. In the **Download NVSRAM** dialog, select the CD-ROM drive and the `/nvram` folder. Either double-click the folder or type the folder name in the **Selected NVSRAM file** text box.
6. Select the file that corresponds to your storage array type.
7. Click **OK**.  
The **Confirm Download** dialog appears.
8. To start the download, click **Yes**.
9. Based on the dialog that appears after the download is completed, perform one of these actions:
  - **Download Successful dialog** – Click **Done**.
  - **Error dialog** – Read the information in the dialog, and take the appropriate action.

---

## Step 2 – Setting the Configuration to Duplex

After rebooting the controller module or the array module, an “alternate controller missing” error message appears. This message indicates that the controller in slot A has successfully converted to Duplex mode. This message persists until you have completed the tasks to install the second controller, installed the host cables, and installed the drive module cables.

1. Start the command line interface.
2. On the command line, type this command, and press **Enter**. In this command, *ctlr-A\_IP\_address* is the IP address of the original simplex controller.  

```
smcli ctlr-A_IP_address -c "set storageArray redundancyMode=duplex;"
```
3. Reboot the controller module or the array module.

## Step 3 – Installing the Second Controller

---

**ATTENTION Possible hardware damage** – To prevent electrostatic discharge damage to the module, use proper antistatic protection when handling module components.

---

**NOTE** For best operation, the new controller must have a part number identical to the existing controller, or the new controller must be a certified substitute. The part number is on a label on the controller. To provide full functionality in dual-controller configurations, make sure that both controllers in the controller module or the array module have the same memory capacity. Although you can install two controllers of different memories in a controller module or an array module, the mismatch disables some functions, such as cache mirroring.

---

1. Put on antistatic protection.

---

**ATTENTION Possible damage to the controller** – Do not remove the electrostatic protection until you have finished installing the controller and you have connected the host cables and the drive module cables.

---

2. Unpack the new controller.

---

**ATTENTION Possible damage to the controller** – Bumping the controller against another surface might damage the data connectors on the rear of the controller. Use caution when handling the controller.

---

3. Remove the blank controller CRU from the module by releasing the handle, and pulling the blank controller CRU out of the module.
4. Slide the new controller CRU into the empty slot by pushing the controller CRU until it snaps into place, and locking the handle into the closed position.

## Step 4 – Connecting the Host Cables

The steps in this procedure describe how to attach Fibre Channel host cables. The steps for connecting other types of host cables are similar, but they do not require the installation of Small Form-factor Pluggable (SFP) transceivers.

1. If there is a black plastic plug in the host port, remove it.
2. Install an SFP transceiver into the controller by pushing the SFP transceiver into the host port until it snaps into place.

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**ATTENTION Possible degraded performance** – To prevent degraded performance, do not twist, fold, pinch, or step on fiber-optic cables. Do not bend fiber-optic cables tighter than a 5-cm (2-in.) radius.

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3. Plug one end of the fiber-optic cable into the SFP transceiver in the host port.
4. Plug the other end of the fiber-optic cable into one of the HBAs in the host (direct topology) or into a switch (switch topology).
5. Attach a label to each end of the cable by using this scheme. A label is very important if you need to disconnect the cables later to service a controller.
  - The host name and the host bus adapter (HBA) port (if direct topology)
  - The switch name and port (if switch topology)
  - The controller ID (for example, controller A)
  - The host channel ID (for example, host channel 1)

**Example label abbreviation** – Assume that a cable is connected between port 1 in HBA 1 of a host named Engineering and host channel 1 of controller A. A label abbreviation could be as follows:

Heng-ABA1/P1, CtA-Hch1

6. Repeat step 1 through step 5 for each host channel that you intend to use.

## Step 5 – Connecting the Controller to a Drive Module

The steps in this procedure describe how to attach Fibre Channel cables to a drive module. The steps for connecting other types of drive module cables are similar, but they do not require the installation of SFP transceivers.

1. If there is a black plastic plug in the drive port of the new controller CRU, remove it.
2. Insert an SFP transceiver into the drive port on a controller CRU.
3. Plug one end of the cable into the SFP transceiver.
4. Plug the other end of the cable into the appropriate in port or out port on the environmental services monitor (ESM) in the drive module as applicable for your cabling configuration.
5. Attach a label to each end of the cable by using this scheme. A label is very important if you need to disconnect the cables later to service a controller.
  - The controller ID (for example, controller A)
  - The drive channel number and port ID (for example, drive channel 1, port 2)
  - The ESM ID (for example, ESM A)
  - The ESM port ID (for example, In, Out, 1A, or 1B)
  - The drive module ID

**Example label abbreviation** – Assume that a cable is connected between drive channel 1, port 2 of controller A to the out port of the left ESM (A) in drive module 1. A label abbreviation could be as follows:

CtA-Dch1/P2, Dm1-ESM\_A (left), Out

6. Repeat step 1 through step 5 for each drive module.
7. Remove the antistatic protection.



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## Step 6 – Running Diagnostics

1. Using the LEDs on the storage array and information provided by the storage management software, check the status of all modules in the storage array.
2. Does any component have a Needs Attention status?
  - **Yes** – Click the **Recovery Guru** toolbar button in the Array Management Window, and complete the recovery procedure. If a problem is still indicated, contact your Sun Customer Care Center representative.
  - **No** – Go to step 3.
3. Create, save, and print a new storage array profile.

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